



- static type binding (at compile time)

Implicit declaration  $\rightarrow$  perl (  $\$--$  ) scalar type  
(  $@--$  ) array type

29 C#

```
var sum = 0;  
var total = 0.0;  
var name = "Fred";  
      \string
```

~~40-100~~ aliases

name 1 →  Same mem. location  
name 2 →   
⋮  
⋮

dynamic type binding — for interpreter based lang. only.  
(at run time (python, Ruby, javascript)..  
(via assign-st.

- [-adv. — flexible
- [-disadv. — less reliable

4) list = [10.2, 3.5];  
list = 47

error detection at Compile time is difficult.

Storage binding

— static var. — no recursion

- Stack dynamic var (— alloc. <sup>in</sup> run time stack (A.R.)  
— recursion possible.

- explicit heap dynamic vars

nameless mem. cells      new/delete

- implicit heap dynamic vars

bound to heap only when assigned values

ex) javascript: highs = [74, 84, 86, --]

## Scope (of vars)

### static scope rule

- [- nested scope — subprograms can be nested — <sup>ex</sup>python
- [- non-nested scope — C/C++/java

for ~~ex~~ non-locals in a subprog,

Search (static parent — static scope  
caller's environment — dynamic scope.

blocks {    } — nested static scope

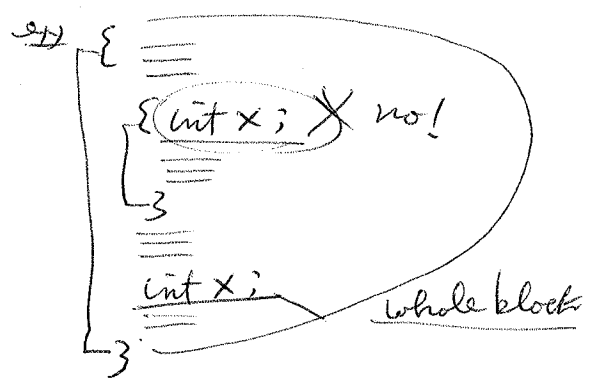
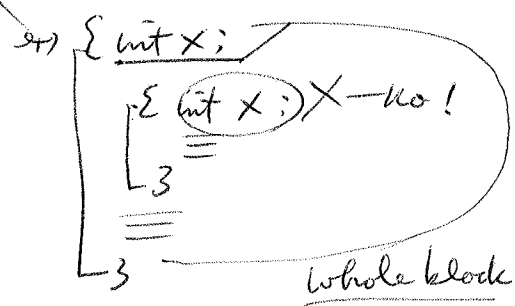
### declaration order

<sup>ex</sup> C — all decl. at the begining of a func.  
C++/java, ... — decl. at anywhere

C  
{ ' <decl-list> <state-list> } — terminal  
C++  
{ ' { <decl-list> | <state-list> } } — terminal  
terminal / or more

### scope of local var

- [- C/C++/java — from decl. to the end of block
- [- C# — whole block



### global scope

extern int x; , C++ :: x = 5 , PHP way of access global's.

- referencing environment of a statement

a collection of all vars that are visible in the statement.

(dynamic/static scope lang's) → different

examples

## Data Types - Ch 6

- primitive types

- char. string types - seq. of chars

- type conversion

  + coercion - auto type conversion

  + type casting - explicit type conversion

- short-circuit eval. of Boolean expression.

||, &&.   if (○ || ○ ...)

          if (○ && ○ ...)

## Array types

- static array - storage alloc. is static (at compile time)

- fixed stack-dynamic array - storage alloc. during exec.

- fixed heap-dynamic array - \*) new/delete (run time stack)

- heap-dynamic array - storage alloc. - dynamic and  
\*) C#.   Can change any # of times during execution.

- slices - substructures of an array as a unit

Range and storage (size).

ex) python

vector = <sup>[0] [1]</sup> [2, 4, 6, 8, 10, 12, 14]

vector [3:6] = [8, 10, 12] → [3, 6]

1st index not included

# Array Implementation

## 1-D array layout

lower bound = 0 case:

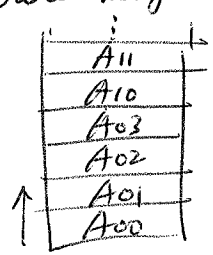
$$\boxed{\text{addr. of } A[i] = i * \underbrace{(w)}_{\text{size of ele (in bytes)}} + \text{base}}$$

## 2-D array layout

ex) int A[3][4]

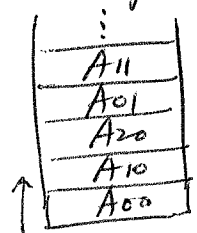
A <sub>00</sub>	A <sub>01</sub>	A <sub>02</sub>	A <sub>03</sub>
A <sub>10</sub>	A <sub>11</sub>	A <sub>12</sub>	A <sub>13</sub>
A <sub>20</sub>	A <sub>21</sub>	A <sub>22</sub>	A <sub>23</sub>

### row-major layout



$$\begin{aligned} \text{addr. of } A[i_1][i_2] &= [(i_1 * \underbrace{H_2}_{\text{\#cols}}) + i_2] * \underbrace{(w)}_{\text{ele.size}} + \text{base} \end{aligned}$$

### col-major layout



$$\begin{aligned} \text{addr. of } A[i_1][i_2] &= [i_1 + (i_2 * \underbrace{H_1}_{\text{\#rows}})] * \underbrace{(w)}_{\text{ele.size}} + \text{base} \end{aligned}$$

## array bound evaluation

- (at compile time (static)) — ex. int A[10];
- (at run time (dynamic)) — ex. --- new int [10];

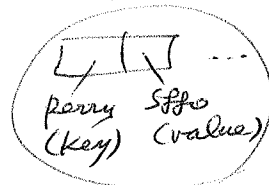
Java int[] A = new int [10];

## Associative array

Perl — hash var starts with %

ex) %salaries = ("Gary" => 7500, "Perry" => 5700, ...);

!\$salaries{"Perry"} = 5880;  
scalar var



python — dictionary — {...}

C++ — unordered\_map —  $\langle P, P \rangle$   
key value  
(can be structure)

## Heap memory management

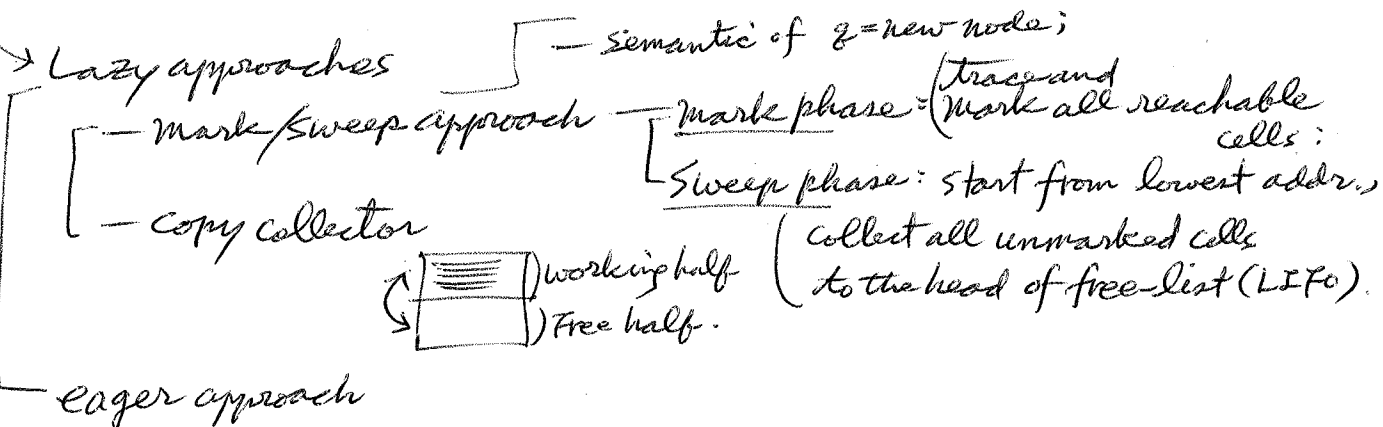
explicit — new/delete — C++

implicit deallocation — (Java garbage collector  
LISP)

## pointers/reference types

dangling pointers/memory leaks

array (index) vs. pointers in C — class example



## Imperative lang features — ch 7, 8,

- expressions
- overloaded operations
- type conversions  
explicit/implicit
- short-circuit eval. of Boolean expr.

✓ already covered

### multiple assignment

ex) perl:  $(a, b, c) = (0, 0, 0);$

— swap operation:  
in 1 statement  $(A, B) = (B, A);$

### syntax-directed control structures

loop constructs — 1 entry/1 exit

— handling special case in the loop — using "break".

(breaks 1 entry/1 exit rule of a loop construct.

## Subprograms — ch 9.

### parameter passing methods

- call by value
- call by reference
- call by value-result

use swap operation example

— macro-expansion

— call by name — keep uniq names

— multi-dimensional array as parameter

C++, java examples

— parameters that are subprograms  
JavaScript example.

*(signature)*

## parameter passing

### — 1. Call by value

- (1)  $\text{formals} \leftarrow \text{r-value of arguments}$
- (2) body execution

### — 2. Call by reference

- (1) formals:  
 $\text{l-value of formals} \leftarrow \text{l-value of arguments}$
- (2) body execution

### — 3. Call by value result

- (1) copy-in phase:  
  - $\text{formals} \leftarrow \text{r-value of arguments}$
  - save l-value of arguments for formals
- (2) body execution
- (3) copy-out phase:  
 $\text{final values of formals} \rightarrow \text{saved l-values of arguments}$

### — 4. Macro-expansion

- (1) text of arguments  $\rightarrow$  formals/body
- (2) text of callee's body  $\rightarrow$  call statement  
(Substitutes)
- (3) body execution

### — 5. Call by name

- (1) text of arguments  $\rightarrow$  formals/body  
if name conflicts, rename locals in the callee.
- (2) text of callee's body  $\rightarrow$  call statement  
if name conflict (locals in caller  $\leftrightarrow$  non-locals in callee),  
rename locals in caller.
- (3) body execution.

## §9.6 — parameters that are subprograms — in nested subprograms lang. e.g. javascript

```

function sub1()
{
  var x;
  function sub2()
  {
    alert(x);
  };
  function sub3()
  {
    var x;
    x = 3;
    sub4(sub2);
  };
  function sub4(subx)
  {
    var x;
    x = 4;
    subx(); // actually, sub2 is called
  };
  x = 1;
  sub3();
};
  
```

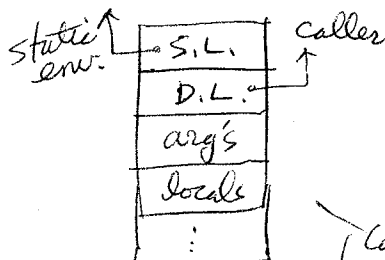
- 3 choices of binding non locals
1. Shallow binding — caller's env.
  2. deep binding — static env.
  3. Ad hoc binding — bound to env. in which the call statement passed the subprog. as a parameter.

output under

1. — [4]
2. — [1]
3. — [3]

## Ch10 — Implementing Subprograms

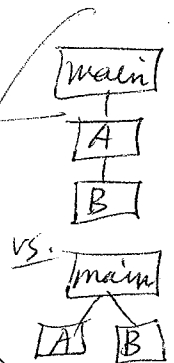
— A.R. and runtime stack



— Snapshots of A.R. runtime stack

— activation tree

{ caller sets S.L., D.L., parameters, return addr.  
(Callee sets remaining fields (locals))





— run-time stack (ARs)

with parameter (pass by value  
vs pass by reference) — class example.

(4) binary search program (homework)

Activation tree / run time stack for recursive func.

(static links) for (nested) static scope  
(dynamic links) (dynamic scope)

— nested static scope (Pascal, ... python)

How to set S.L. of callee

1. Compute static distance  

$$d = \text{nesting\_level of caller} - \text{nesting\_level of callee} + 1$$
2. start from caller's AR (S.L.),  
 trace S.L. (d) times.

