
- * Shared-mem Programming with Pthreads
 - issues: critical section, thread synchronization
 - static vs. dynamic threads
 - each thread has its own stack/heap (private space)
 - matrix-vector multiplication, matrix multiplication, pi computation in Pthreads
 - critical section and mutex in Pthreads
 - producer-consumer synchronization and semaphore in Pthreads
 - barrier synchronization and condition var in Pthreads
 - read-write locks in Pthreads
 - cache access pattern, cache coherence, and false sharing
- * Shared-mem Programming in OpenMP
 - pragma omp parallel block and team
 - trapezoid computation (integral) in OpenMP versions: ref para, return type slave func, reduction in main(), par-for in main()
 - parallel-for directive and loop-carried dependence pi computation
 - scope of vars
 - loops in OpenMP parallel sorting algorithms
 - scheduling loops: static/dynamic/guided scheduling
 - producer-consumer synchronization in OpenMP: enqueue(), dequeue()
 - nested critical and deadlock
- * Interconnection Networks
 - shared-mem IN: bus, X-bar
 - distributed-mem IN: static (direct), dynamic (indirect)
 - terminology: node degree, network diameter, bisection width
 - static (direct) IN and routing schemes:

completely connected linear array: E-W routing ring: tag +/- 1 MOD N 2D mesh: E/W and X/Y routing 3D mesh: E/W, X/Y, in/out routing 2D/3D torus: mesh + ring hypercubes (1-4D) cube-connected-cycle (CCC) tree (binary, m-ary)

tree (omary, m-ary)

star

- dynamic (indirect) IN and routing scheme:

bus, crossbar, MIN

MIN: shuffle, inverse-shuffle

Omega network: # of stages/switches, dest_id routing

Benes network: # of stages/switches, routing mechanism, total # of paths