

---

# Function: fatigueLife

This script calculates the infinite life safety factor of a rotating cylindrical shaft using the Modified Goodman Failure Criteria. All units are in MPa. Sut is the ultimate tensile strength, Smax is the Maximum bending stress, Smin is the minimum bending stress. NO Axial Stress. TauMax is the shear stress due to torque from the motor. Kf and Kfs are fatigue stress concentrations for bending and shear. Finish should be 1 (ground), 2 (machined or CD), 3 (Hot-Rolled), 4 (As-Forged).

## Code

```
function fatigueLife(Sut, Smax, Smin, TauMid, finish, diam, Kf, Kfs)

Sy = 580; % MPa

% Initialize Parameters
a = 0;
b = 0;
Se = 0;
Ka = 0;
Kb = 0;

%Midrange and Alternating Stresses

Smid = (Smax+Smin)/2;
Salt = abs(Smax-Smin)/2;

%Von Mises Alternating and Midrange stress
SaVM = Kf*Salt;
SmidVM = sqrt( (Kf*Smid)^2 + 3*(TauMid*Kfs)^2);

%Switch case takes material finish code and sets parameters for Surface
%Finish.
switch finish
    case 1
        a = 1.58;
        b = -0.085;
    case 2
        a = 4.51;
        b = -.265;
    case 3
        a = 57.7;
        b = -.718;
    case 4
        a = 272;
        b = -.995;
    otherwise
        'Invalid material finish.';
end

% Ka is the Surface Factor
Ka = a*Sut^b;
```

```
% Kb is the Size Factor
if( 2.79<= diam <=51)
    Kb = 1.24*diam^-0.107;
elseif( 51< diam <254)
    Kb = 1.51*diam^-0.157;
end

if (Sut > 1400)
    Se = 700*Ka*Kb;
else
    Se = 0.5*Sut*Ka*Kb;
end

nYield = Sy / (SaVM + SmidVM)

nGoodman = ( (SaVM / Se) + (SmidVM/Sut) ) ^ (-1)

nGerber = 0.5*((Sut/SmidVM)^2)*(SaVM/Se)*(-1 + sqrt(1+( 2*SmidVM*Se) / (Sut*SaVM))

end

Error using fatigueLife (line 19)
Not enough input arguments.
```

*Published with MATLAB® R2014b*

---

# Function: plot\_sf

Plots the Shear, Moment, Torque and M/I diagrams. Parameters - singularity functions for T,V,M and M/I; x is the position vector

## Code

```
function plot_sf = plot_sf(T,V,M,M_over_I,x)
    % Setting up
    L = 40; % cm, shaft length

    % Shear Diagram
    figure(1)
    subplot(2,2,1)
    plot(x,V)
    axis([0 L min(V)-50 max(V)+50]) % for making the plots more appealing
    title('Shear Diagram')
    ylabel('Shear (N)')
    xlabel('Position on shaft (cm)')

    % Torque
    subplot(2,2,2)
    plot(x,T, 'g')
    axis([0 L -1 max(T)+1])
    title('Torque Diagram')
    ylabel('Torque (N*m)')
    xlabel('Position on shaft (cm)')

    % Moment Diagram
    subplot(2,2,[3,4])
    plot(x,M, 'r')
    axis([0 L -2 max(M)+2])
    title('Moment Diagram')
    ylabel('Moment (N*m)')
    xlabel('Position on shaft (cm)')

    % M over I diagram
    figure(2)
    plot(x,M_over_I, 'c')
    title('Moment over I Diagram')
    ylabel('M/I (N/m^3)')
    xlabel('Position on shaft (cm)')
end
```

*Error using plot\_sf (line 15)  
Not enough input arguments.*

*Published with MATLAB® R2014b*