# Image features exercise

Complete and hand in this completed worksheet (including its outputs and any supporting code outside of the worksheet) with your assignment submission. For more details see the <u>assignments page (https://compsci682-fa18.github.io/assignments2018/assignment1)</u> on the course website.

We have seen that we can achieve reasonable performance on an image classification task by training a linear classifier on the pixels of the input image. In this exercise we will show that we can improve our classification performance by training linear classifiers not on raw pixels but on features that are computed from the raw pixels.

All of your work for this exercise will be done in this notebook.

```
In [1]: import random import numpy as np from cs682.data_utils import load_CIFAR10 import matplotlib.pyplot as plt

from __future__ import print_function

%matplotlib inline plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots plt.rcParams['image.interpolation'] = 'nearest' plt.rcParams['image.cmap'] = 'gray'

# for auto-reloading extenrnal modules # see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython %load_ext autoreload %autoreload 2
```

#### Load data

Similar to previous exercises, we will load CIFAR-10 data from disk.

```
In [2]:
       from cs682.features import color histogram hsv, hog feature
         def get CIFAR10 data(num training=49000, num validation=1000, num test=1000):
           # Load the raw CIFAR-10 data
           cifar10 dir = 'cs682/datasets/cifar-10-batches-py'
           X train, y train, X test, y test = load CIFAR10(cifar10 dir)
           # Subsample the data
           mask = list(range(num training, num training + num validation))
           X \text{ val} = X \text{ train}[\text{mask}]
           y \text{ val} = y \text{ train}[\text{mask}]
           mask = list(range(num training))
           X train = X train[mask]
           y train = y train[mask]
           mask = list(range(num test))
           X \text{ test} = X \text{ test[mask]}
           y test = y test[mask]
           return X train, y train, X val, y val, X test, y test
         # Cleaning up variables to prevent loading data multiple times (which may cause memory issue)
         try:
          del X train, y train
          del X test, y test
          print('Clear previously loaded data.')
         except:
          pass
         X train, y train, X val, y val, X test, y test = get CIFAR10 data()
```

### **Extract Features**

For each image we will compute a Histogram of Oriented Gradients (HOG) as well as a color histogram using the hue channel in HSV color space. We form our final feature vector for each image by concatenating the HOG and color histogram feature vectors.

Roughly speaking, HOG should capture the texture of the image while ignoring color information, and the color histogram represents the color of the input image while ignoring texture. As a result, we expect that using both together ought to work better than using either alone. Verifying this assumption would be a good thing to try for your interests.

The hog\_feature and color\_histogram\_hsv functions both operate on a single image and return a feature vector for that image. The extract\_features function takes a set of images and a list of feature functions and evaluates each feature function on each image, storing the results in a matrix where each column is the concatenation of all feature vectors for a single image.

```
In [3]:
       from cs682.features import *
        num color bins = 10 # Number of bins in the color histogram
        feature fns = [hog feature, lambda img: color histogram hsv(img, nbin=num color bins)]
        X train feats = extract features(X train, feature fns, verbose=False)
        X val feats = extract features(X val, feature fns)
        X test feats = extract features(X test, feature fns)
        # Preprocessing: Subtract the mean feature
        mean feat = np.mean(X train feats, axis=0, keepdims=True)
        X train feats -= mean feat
        X val feats -= mean feat
        X test feats -= mean feat
        # Preprocessing: Divide by standard deviation. This ensures that each feature
        # has roughly the same scale.
        std feat = np.std(X train feats, axis=0, keepdims=True)
        X train feats /= std feat
        X val feats /= std feat
        X test feats /= std feat
        # Preprocessing: Add a bias dimension
        X train feats = np.hstack([X train feats, np.ones((X train feats.shape[0], 1))])
        X val feats = np.hstack([X val feats, np.ones((X val feats.shape[0], 1))])
        X test feats = np.hstack([X test feats, np.ones((X test feats.shape[0], 1))])
```

#### **Train SVM on features**

Using the multiclass SVM code developed earlier in the assignment, train SVMs on top of the features extracted above; this should achieve better results than training SVMs directly on top of raw pixels.

In [5]: # Use the validation set to tune the learning rate and regularization strength

```
from cs682.classifiers.linear_classifier import LinearSVM
learning rates = [1e-9, 1e-8, 1e-7]
regularization strengths = [5e4, 5e5, 5e6]
results = \{\}
best val = -1
best svm = None
for lr in learning rates:
  for reg str in regularization strengths:
     print("Running" + str((lr,reg str)))
     svm = LinearSVM()
     loss hist = svm.train( X train feats, y train, learning rate=lr, reg=reg str, num iters=1500, verbose=
False)
     y valid pred = svm.predict( X val feats)
     y train pred = svm.predict(X train feats)
     valid accuracy = (np.mean(y val == y valid pred))
     train accuracy = (np.mean(y train == y train pred))
     if valid accuracy > best val:
       best val = valid accuracy
       best svm = svm
     results[(lr,reg str)] = (train accuracy, valid accuracy)
# Print out results.
for lr, reg in sorted(results):
  train accuracy, val accuracy = results[(lr, reg)]
  print('lr %e reg %e train accuracy: %f val accuracy: %f % (
         lr, reg, train accuracy, val accuracy))
print('best validation accuracy achieved during cross-validation: %f % best val)
Running(1e-09, 50000.0)
Running(1e-09, 500000.0)
Running(1e-09, 5000000.0)
Running(1e-08, 50000.0)
Running(1e-08, 500000.0)
Running(1e-08, 5000000.0)
Running(1e-07, 50000.0)
Running(1e-07, 500000.0)
Running(1e-07, 5000000.0)
lr 1.000000e-09 reg 5.000000e+04 train accuracy: 0.099735 val accuracy: 0.094000
lr 1.000000e-09 reg 5.000000e+05 train accuracy: 0.123061 val accuracy: 0.124000
lr 1.000000e-09 reg 5.000000e+06 train accuracy: 0.126449 val accuracy: 0.111000
lr 1.000000e-08 reg 5.000000e+04 train accuracy: 0.097694 val accuracy: 0.093000
lr 1.000000e-08 reg 5.000000e+05 train accuracy: 0.362490 val accuracy: 0.373000
lr 1.000000e-08 reg 5.000000e+06 train accuracy: 0.402388 val accuracy: 0.392000
lr 1.000000e-07 reg 5.000000e+04 train accuracy: 0.412939 val accuracy: 0.409000
lr 1.000000e-07 reg 5.000000e+05 train accuracy: 0.417122 val accuracy: 0.428000
lr 1.000000e-07 reg 5.000000e+06 train accuracy: 0.350571 val accuracy: 0.340000
```

best validation accuracy achieved during cross-validation: 0.428000

```
In [6]: #Evaluate your trained SVM on the test set
y_test_pred = best_svm.predict(X_test_feats)
test_accuracy = np.mean(y_test == y_test_pred)
print(test_accuracy)
```

0.421

```
In [7]:
        # An important way to gain intuition about how an algorithm works is to
         # visualize the mistakes that it makes. In this visualization, we show examples
         # of images that are misclassified by our current system. The first column
         # shows images that our system labeled as "plane" but whose true label is
         # something other than "plane".
         examples per class = 8
         classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship', 'truck']
         for cls, cls name in enumerate(classes):
           idxs = np.where((y test != cls) & (y test pred == cls))[0]
           idxs = np.random.choice(idxs, examples per class, replace=False)
           for i, idx in enumerate(idxs):
              plt.subplot(examples per class, len(classes), i * len(classes) + cls + 1)
              plt.imshow(X test[idx].astype('uint8'))
              plt.axis('off')
              if i == 0:
                plt.title(cls name)
        plt.show()
```



# Inline question 1:

Describe the misclassification results that you see. Do they make sense?

They do make sense. For example, if you look at the mislabels for cat, a lot of the images are dogs. Since dogs look very close to cats (four leg animal) it make sense that the network would misclassify these.

# **Neural Network on image features**

Earlier in this assignment we saw that training a two-layer neural network on raw pixels achieved better classification performance than linear classifiers on raw pixels. In this notebook we have seen that linear classifiers on image features outperform linear classifiers on raw pixels.

For completeness, we should also try training a neural network on image features. This approach should outperform all previous approaches: you should easily be able to achieve over 55% classification accuracy on the test set; our best model achieves about 60% classification accuracy.

```
In [8]: # Preprocessing: Remove the bias dimension
# Make sure to run this cell only ONCE
print(X_train_feats.shape)
X_train_feats = X_train_feats[:,:-1]
X_val_feats = X_val_feats[:,:-1]
X_test_feats = X_test_feats[:,:-1]
print(X_train_feats.shape)

(49000, 155)
(49000, 154)
```

### In [9]: from cs682.classifiers.neural net import TwoLayerNet input size = X train feats.shape[1] num classes = 10best net = None best val = -1#I tried all of these when experimenting to find the best parameters learning rates = [1e-1,5e-1,1e0,5e0]regularization strengths = [1e-4, 1e-3, 0.0]hidden sizes = [100,250,500]epochs = [2000]dropouts = [0.5, 0.8, 1.0]#I tried all of these when experimenting to find the best parameters learning rates = [5e-1]regularization strengths = [0.0]hidden sizes = [500]epochs = [10000]dropouts = [0.8]use dropout = True for lr in learning rates: for reg str in regularization strengths: for hidden size in hidden sizes: for epoch in epochs: for dr in dropouts: print("Running" + str((lr,reg str, hidden size,epoch, dr))) net = TwoLayerNet(input size, hidden size, num classes) # Train the network stats = net.train(X train feats, y train, X val feats, y val, num iters=epoch, batch size=200,le arning rate=lr, learning rate decay=0.95, reg=reg str, verbose=False, dropout percent = dr, use dropout = use dropout) y valid pred = net.predict( X val feats) y train pred = net.predict(X train feats) valid accuracy = (np.mean(y val == y valid pred)) train accuracy = (np.mean(y train == y train pred)) if valid accuracy > best val: print("best accuracy so far: " + str(valid accuracy) ) best val = valid accuracy best net= net results[(lr,reg str)] = (train accuracy, valid accuracy)

```
Running(0.5, 0.0, 500, 10000, 0.8) best accuracy so far: 0.593
```

In [10]: #Run your best neural net classifier on the test set. You should be able # to get more than 55% accuracy.

> $test\_acc = (best\_net.predict(X\_test\_feats) == y\_test).mean()$ print(test\_acc)

0.605