

# Device for Movement Analysis Using Inertial Sensors

BEDŘICH SAID

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## Abstract

Currently, the inertial sensors are more widely used, and their price is decreasing. The lower price allows creating new solutions with lower costs. Some examples can be found in wearable devices, mobile phones, navigation or control systems. There are several devices for various use cases on the market.

These devices usually cover their use cases and do not have any additional features like power independence, enough logging memory or openness for user code. The remaining hardware that fulfills all the conditions above is usually expensive.

I have developed a new wearable independent device for capturing and processing the measured data. The independence means no external wires and no external power supply here. The device is able to work outdoors, to log the measured data and to provide a direct output based on internal computations. The user can choose between completely wireless communication or wired connection to other electronics. The sensors measure inertial, attitude, position and atmospheric values.

For outdoor testing of the device I have selected the task about movement analysis of a horse. I placed the devices on the horse's body as wearable devices and I was developing algorithms for determination of the basic types of its movement – stand, walk, trot, canter or gallop.

In general, the developed device can be used for capturing data from sensors, onboard data processing, navigation or control of moving mechanics. The electronics work independently, so it is easy to install it on the measured or controlled objects.

## Keywords

Electronic Device, Printed Circuit Board, Inertial Sensors, Inertial Measurement Unit, Internet of Things, Movement Analysis, Horse



Contact / Email:  
Zdeněk Matěj  
xmatejz@mail.muni.cz

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### **Thesis evaluation – Bedřich Said**

The goal of the thesis was to create an inertial sensors data logging hardware and to measure some data with it. The student successfully developed the device and used it during measurements. The functionality of the electronics was demonstrated with running analysis of a horse movement. The algorithm was running on the device in real-time and it was able to distinguish between different types of a movement of a horse.

The work exceeded the amount of work required by diploma thesis and there are presented several examples of using the hardware in a different way. These examples show the high versatility of the developed device and I think that there is a wide spectrum of usages in science or technology.

The attachments of the thesis contain important information, too. The external sources are correctly quoted. The text still contains few typing errors.

**RNDr. Zdeněk Matěj, Ph.D.**