Education

2017-current PhD Robotics, University of Michigan, Ann Arbor.

ARM lab

Path planning for manipulation

2015–2017 Master's of Robotics, Carnegie Mellon, Pittsburgh.

Biorobotics lab

Path planning and precision localization in confined spaces

2008–2012 **BS Mechanical Engineering**, *Caltech*, Pasadena.

Work Experience

2014–2015 **Software Development Engineer**, Amazon, Seattle.

I created software for the Amazon Kindle E-Readers and Tablets.

Robotics Engineer, Electroimpact, Seattle.

I designed, built, and programmed robots that build airplanes

2010–2012 **Research Fellow**, *Caltech*, Pasadena.

Fluid Dynamics Research

Skills

Programming Git, ROS, Tensorflow, OpenCV, C++, Python, Java, Matlab

Deployment Deployment to production environments of both software and hardware to millions of machines (Kindle)

and machines worth millions of dollars (aerospace robots)

Robotics Path Planning with Uncertainty, Sensor Fusion, Localization, Autonomous Vision and Navigation

Publications

2018 Brad Saund and Dmitry Berenson "Motion Planning for Manipulation with Uncertainty from Contact Sensing" 2018, ISER

2017 Shiyuan Chen, Brad Saund, and Reid Simmons "The datum particle filter: Localization for objects with coupled geometric datums" 2017,

Brad Saund "Planning and Localizing under Contact Uncertainty". 2017, Carnegie Mellon Master's Thesis

Alex Ansari, Julian Whitman, and Brad Saund. "Modular platforms for advanced inspection, locomotion, and manipulation" 2017. Waste Management Symposium

2016 Brad Saund, Shiyuan Chen, and Reid Simmons. "Touch based localization of parts for high precision manufacturing", 2016 ICRA

2013 Brad Saund and Russell DeVlieg. "High Accuracy Articulated Robots with CNC Control Systems", 2016 SAE-Aerotech

Service

2013-current Volunteer Mentor, FIRST Robotics.

2011–2012 House President, Caltech Student Government.

References

U. Michigan Carnegie Mellon Electroimpact Caltech

 Reid Simmons Russ DeVlieg Matthew Heverly Dmitry Berenson

Howie Choset