

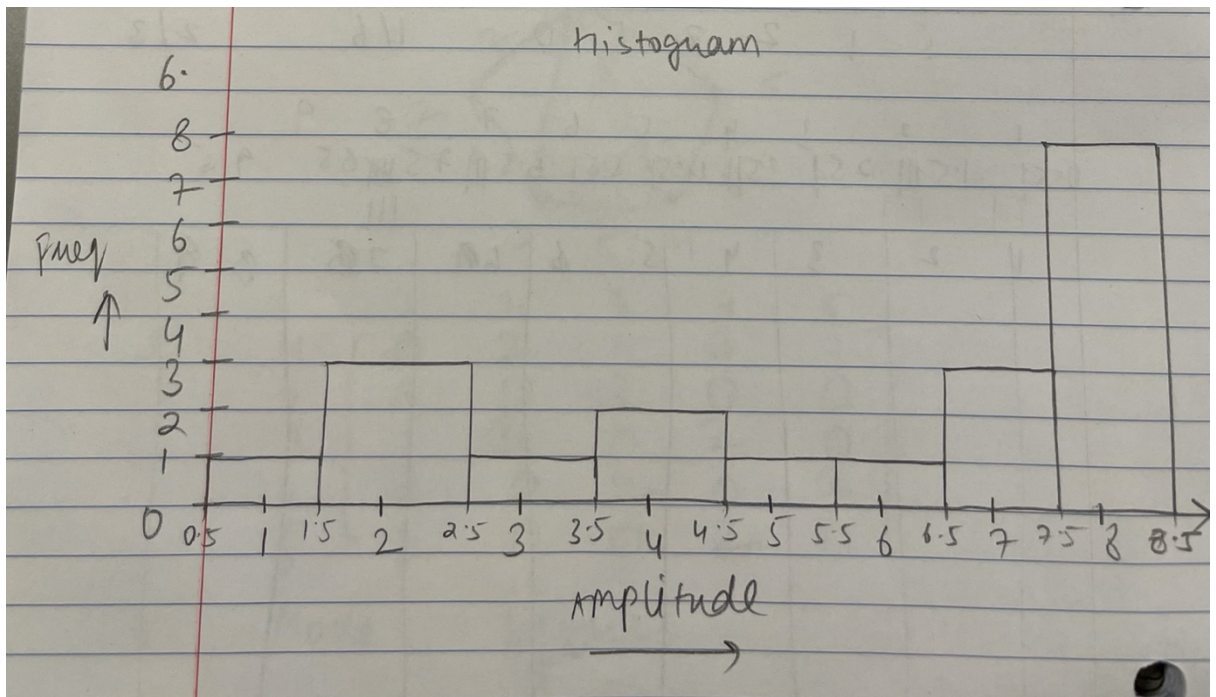
Assignment: Extraction features from Biodata

PART 1

I used matlab as a calculator for all questions.

```
x1 = [7,8,2,8,6,1,3,5,8,8,2,8,8,4,7,2,4,8,7,8];  
mean_x1 = sum(x1)/length(x1);  
  
mean_devia_x1 = 1/length(x1)* sum(abs(x1-mean_x1));  
  
skewness_x1 = 1/length(x1) * (sum((x1 - mean_x1) .^3) / (1/length(x1) * sum ((x1- mean_x1) .^2)) .^(3/2));  
  
kurtosis_x1 = (1/length(x1) * (sum((x1 - mean_x1) .^4) / (1/length(x1) * sum ((x1- mean_x1) .^2)) .^(2))) -3;  
  
flatness_x1 = exp((1/length(x1) * sum(log(x1)) )) / ((1/length(x1)) * sum(x1));
```

1. Mean = 5.7
2. Mean deviation = 2.26
3. Skewness = -0.5870
4. Kurtosis = -1.2461
5. Flatness = 0.8614
- 6.



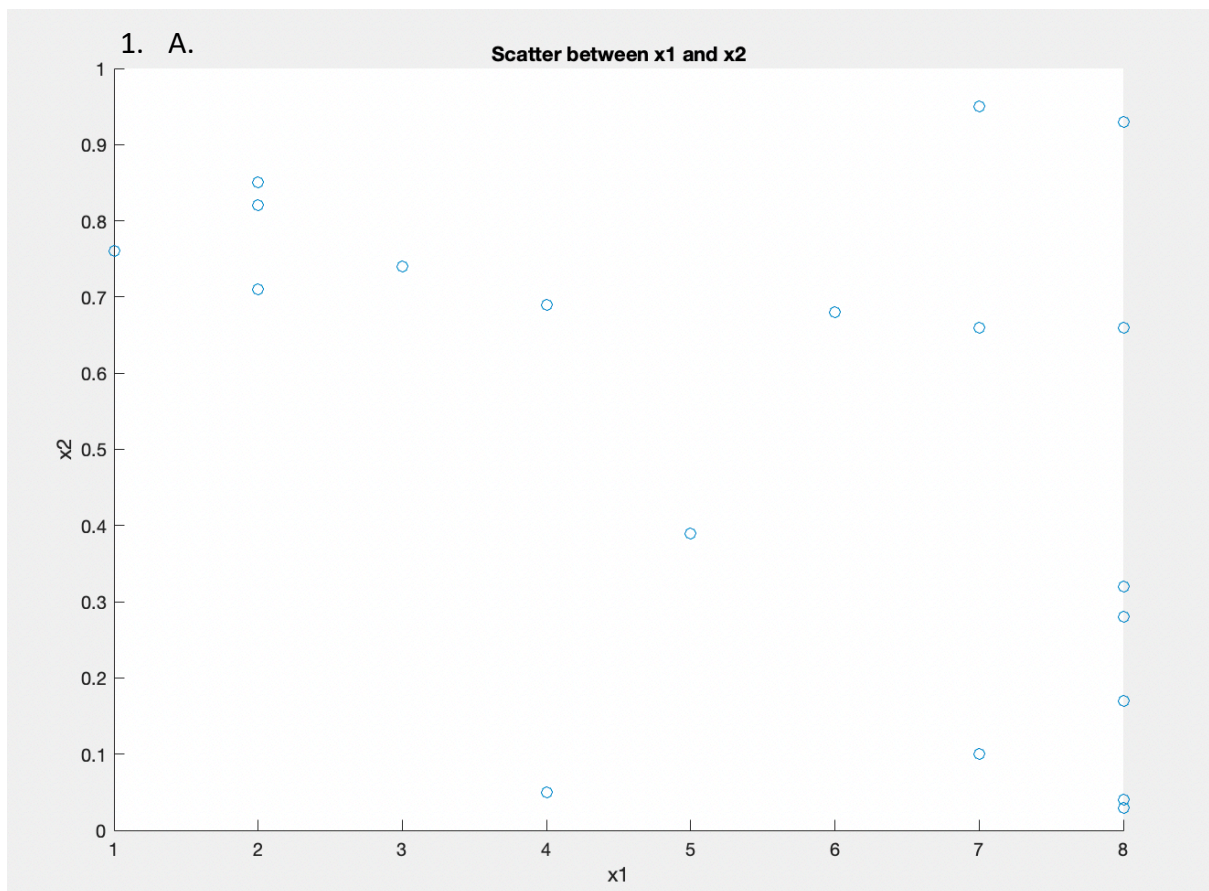
7. I made a method `corr_cal(x1,y1)` which was called to solve this question:

```
function corr_val = corr_cal(x1, y1)  
n = length(x1);  
sum_x1 = sum(x1);  
sum_y1 = sum(y1);  
sum_x1_y1 = sum (x1 .* y1);  
sum_x1_sq = sum(x1 .* x1);  
sum_y1_sq = sum(y1 .* y1);  
nu = (n * sum_x1_y1) - (sum_x1 .* sum_y1);  
de = sqrt((n * sum_x1_sq - ((sum_x1)^2)) * (n * sum_y1_sq - ((sum_y1)^2)));  
corr_val = nu/de;  
end
```

- a. `x1_delayed_0 = x1`
`corr_cal(x1,x1_delayed_0) = 1`

- b. `x1_delayed_minus_one = [8,2,8,6,1,3,5,8,8,2,8,8,4,7,2,4,8,7,8,0];`
`corr_minus_one = corr_cal(x1,x1_delayed_minus_one);`
`corr_minus_one = -0.1736`
- c. `x1_delayed_one = [0,7,8,2,8,6,1,3,5,8,8,2,8,8,4,7,2,4,8,7,8,0];`
`x1_len_21 = [7,8,2,8,6,1,3,5,8,8,2,8,8,4,7,2,4,8,7,8,0];`
`corr_one = corr_cal(x1_len_21,x1_delayed_one);`
`corr_one = -0.2118`
- d. `x1_delayed_two = [0,0,7,8,2,8,6,1,3,5,8,8,2,8,8,4,7,2,4,8,7,8];`
`x1_len_22 = [7,8,2,8,6,1,3,5,8,8,2,8,8,4,7,2,4,8,7,8,0,0];`
`corr_two = corr_cal(x1_len_22,x1_delayed_two);`
`corr_two = -0.42410`
- e. `x1_delayed_three = [0,0,0,7,8,2,8,6,1,3,5,8,8,2,8,8,4,7,2,4,8,7,8];`
`x1_len_23 = [7,8,2,8,6,1,3,5,8,8,2,8,8,4,7,2,4,8,7,8,0,0,0];`
`corr_three = corr_cal(x1_len_23,x1_delayed_three);`
`corr_three = -0.1772`

PART TWO



B. Same method used as above.

```
corr_x1_x2 = corr_cal(x1,x2);
```

```
Corr_x1_x2 = -0.482271
```

C. x1_r =

```
[11, 16.5,3,16.5,9,1,5, 8, 16.5, 16.5, 3, 16.5,16.5,6.5, 11,3,6.5,16.5,11,16.5]
```

x2_r =

```
[10.5,3,18,19,12,16,15,9,10.5,6,14,1.5,7,4,5,17,13,8,20,1.5]
```

```
corr_x1_r_x2_r = corr_cal(x1_r, x2_r);
```

```
corr_x1_r_x2_r = -0.5520
```

D. x2_delayed_0 = x2

```
corr_x1_x2_delayed_0 = -0.482271
```

```
x2_delayed_minus_one = [0.04,0.85,0.93,0.68,0.76,0.74,0.39,0.66,0.17,0.71,  
0.03,0.28,0.05,0.10,0.82,0.69,0.32,0.95,0.03,0];
```

```
corr_x1_x2_minus_one = corr_cal(x1,x2_delayed_minus_one);
```

```
corr_x1_x2_minus_one = -0.1144
```

```
x2_delayed_three = [0,0,0,0.66,0.04,0.85,0.93,0.68,0.76,0.74,0.39,0.66,  
0.17,0.71,0.03,0.28,0.05,0.10,0.82,0.69,0.32,0.95,0.03];
```

```
|  
x1_len_23 = [7,8,2,8,6,1,3,5,8,8,2,8,8,4,7,2,4,8,7,8,0,0,0];
```

```
corr_x1_x2_delayed_3 = corr_cal(x1_len_23,x2_delayed_three);
```

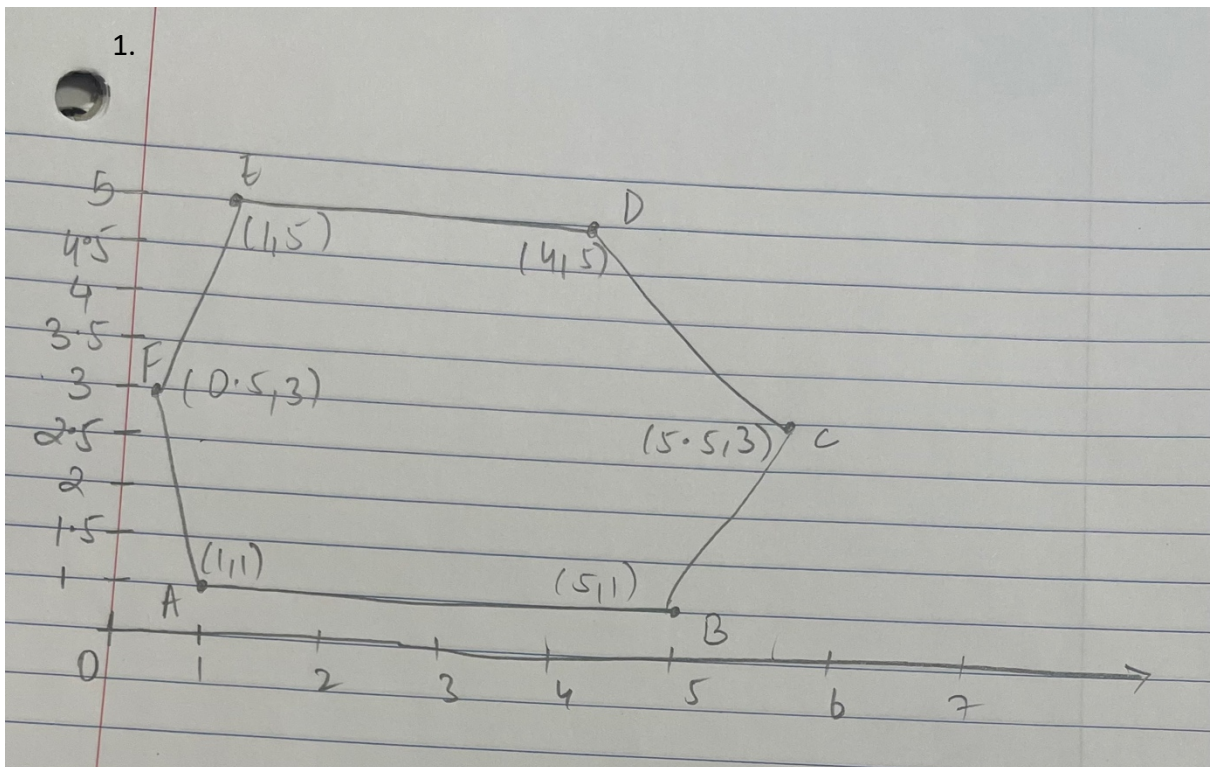
```
corr_x1_x2_delayed_3 = -0.042589074041333
```

2.

1.05	0	0	0	0	0	0	1	0	0
0.95	0	1	0	0	0	0	0	1	0
0.85	1	1	0	0	0	0	0	0	0
0.75	0	1	1	1	0	1	1	1	0
0.65	0	0	0	0	0	0	0	0	0
0.55	0	0	0	0	0	0	0	0	0
0.45	0	0	0	0	0	0	0	0	0
0.35	0	0	0	0	1	0	0	0	0
0.25	0	0	0	0	0	0	0	1	0
0.15	0	0	0	0	0	0	0	1	0
0.05	0	0	0	1	0	0	1	0	0
0.5	1.5	2.5	3.5	4.5	5.5	6.5	7.5	8.5	9.5

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PART 3



2. I made a method to calculate distance between 2 points.

```
function dist_val = distance_cal(x1,y1,x2,y2)
    dist_val = sqrt((x2-x1)^2+ (y2-y1)^2);
end
```

To calculate perimeter I ran a loop over the arrays to find the length of each side and then added those lengths up.

```
% PART THREE
heart_2d_x = [1,0.5,1,4,5.5,5,1];
heart_2d_y = [1,3,5,5,3,1,1];

for i=1:length(heart_2d_x)-1
    perimeter = perimeter + distance_cal(heart_2d_x(i),heart_2d_y(i), ...
        heart_2d_x(i+1),heart_2d_y(i+1));
end
```

perimeter = 15.684658438426492

3. Area :

$$3. \text{ Area} = \frac{1}{2} \left| (1 \cdot 3 - 1 \cdot 0.5) + (0.5 \cdot 5 - 3 \cdot 1) + (5 \cdot 5 - 5 \cdot 4) + (4 \cdot 3 - 5 \cdot 5.5) + (5.5 \cdot 3 - 5 \cdot 5) + (5 \cdot 1 - 1 \cdot 1) + (1 \cdot 1 - 1 \cdot 1) \right|$$

$$= \frac{17}{2} = 8.5$$

4. I used the same distance method here.

I have 2 nested loops to go over each combination of vertices (sides) and then did a comparison operation to find the longest one.

```
diameter = 0;
x1_pt= 0;
y1_pt = 0;
x2_pt= 0;
y2_pt = 0;

for i=1:length(heart_2d_x)
    for j = 1:length(heart_2d_x)
        dist = distance_cal(heart_2d_x(i),heart_2d_y(i),heart_2d_x(j),heart_2d_y(j));
        if(dist > diameter)
            diameter = dist;
            x1_pt = heart_2d_x(i);
            y1_pt = heart_2d_y(i);
            x2_pt = heart_2d_x(j);
            y2_pt = heart_2d_y(j);
        end
    end
end
```

Diameter = 5.656854249492381 (from (1,5) to (5,1))

5. The second longest cord that is perpendicular to the diameter is the cord from (4,5) to (1,1)

Therefore ,

```
cordB = distance_cal(4,5,1,1);
cordB = 5
eccentricity = diameter/cordB;
Eccentricity = 1.131370849898476
```

6. Compactness = perimeter^2/area = 14.471088842947257

```
centroid = [sum(heart_2d_x)/length(heart_2d_x),sum(heart_2d_y)/length(heart_2d_y)];
Centroid = [2.571428571428572,2.714285714285714]
```

8. I made a method to calculate the angle between the centroid and all the points and the slope of lines.

```
function angle = angle_cal(slope_line1, slope_line2)
    angle_rad = atan(abs((slope_line2 - slope_line1) / (1 + slope_line1 * slope_line2)));

    if slope_line1 * slope_line2 < 0
        angle_rad = pi - angle_rad;
    end
    angle = rad2deg(angle_rad);
end

function slopes = slope_cal(x1,x2,y1,y2)
    slopes = (y2 - y1) / (x2 - x1);
end

CG = distance_cal(centroid(1,1),5.5,centroid(1,2),3);

DG = distance_cal(centroid(1,1),4,centroid(1,2),5);
EG = distance_cal(centroid(1,1),1,centroid(1,2),5);
FG = distance_cal(centroid(1,1),0.5,centroid(1,2),3);
AG = distance_cal(centroid(1,1),1,centroid(1,2),1);

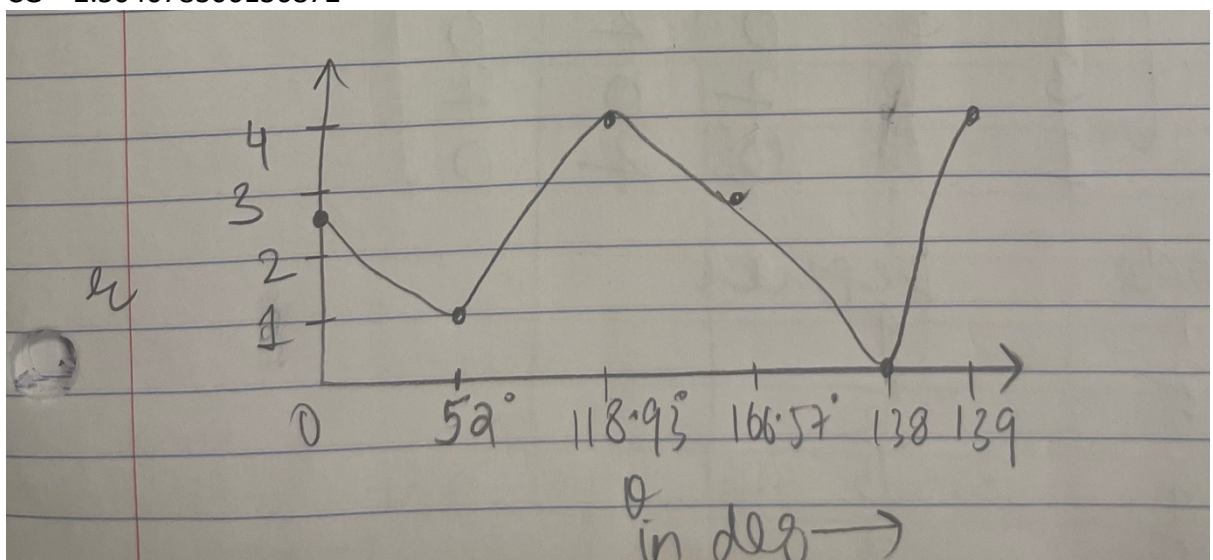
slope_GC = slope_cal(centroid(1,1),5.5,centroid(1,2),3);

angle_GC_GD = angle_cal(slope_GC,slope_cal(centroid(1,1),4,centroid(1,2),5));
angle_GC_GE = angle_cal(slope_GC,slope_cal(centroid(1,1),1,centroid(1,2),5));
angle_GC_GF = angle_cal(slope_GC,slope_cal(centroid(1,1),0.5,centroid(1,2),3));
angle_GC_GA = angle_cal(slope_GC,slope_cal(centroid(1,1),1,centroid(1,2),1));
angle_GC_GB = angle_cal(slope_GC,slope_cal(centroid(1,1),5,centroid(1,2),1));
```

I find the angle that the line GC forms with each of the other points and I get:

angle_GC_GD = 52.422418987952720
 angle_GC_GE = 118.9363251837
 angle_GC_GF = 166.5744888
 angle_GC_GA = 138.0826
 angle_GC_GB = 139.2102

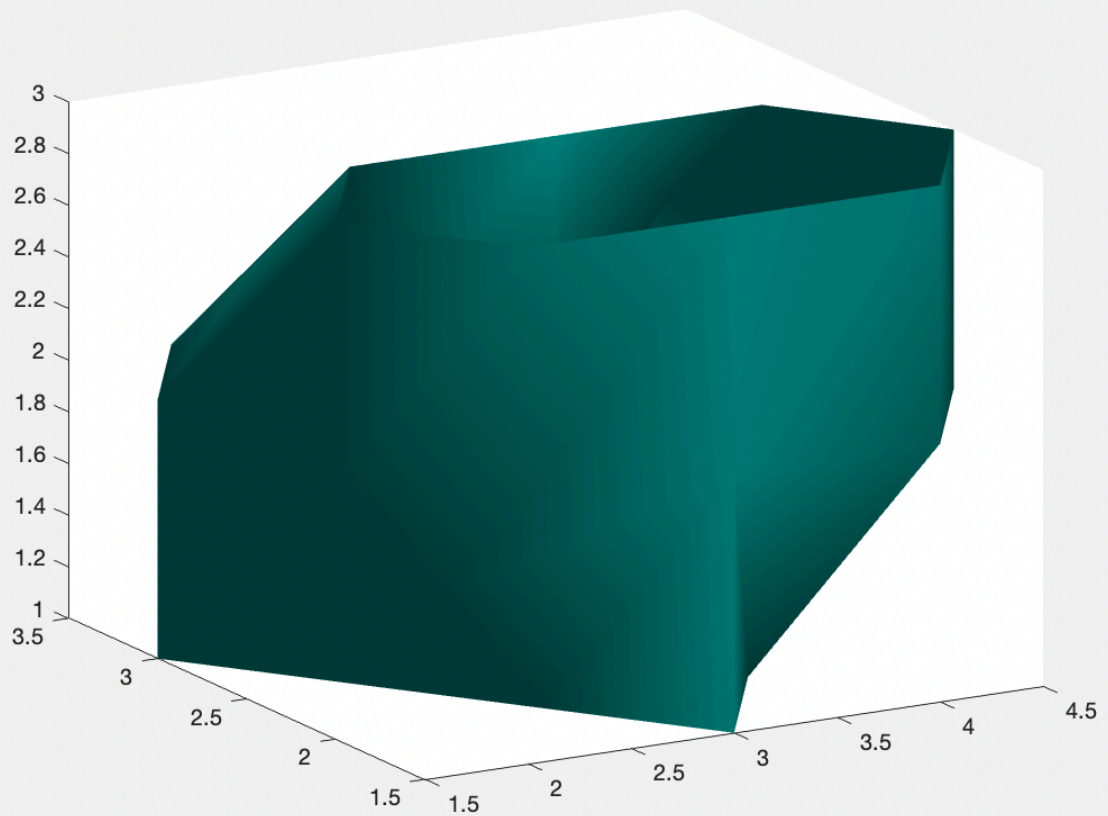
DG = 1.010152544552211
 EG = 4.002550207463400
 FG = 2.504078306136872
 AG = 0.142857142857143
 CG = 2.504078306136872



PART 4

```
1. slice_z1 = [  
    0 0 0 0 0;  
    0 0 1 0 0;  
    0 1 1 1 0;  
    0 0 0 0 0;  
];  
  
slice_z2 = [  
    0 0 0 0 0;  
    0 1 1 1 0;  
    0 1 0 1 0;  
    0 0 0 0 0;  
];  
  
slice_z3 = [  
    0 0 0 0 0;  
    0 1 1 1 0;  
    0 0 0 0 0;  
    0 0 0 0 0;  
];  
  
SHAPE = cat(3, slice_z1, slice_z2, slice_z3);
```

2.



3. I made 3 methods to calculate the u (μ_{cal}) and m (m_{cal}) values respectively.

```
function mu_val = mu_cal(p,q,r,xbar,ybar,zbar,SHAPE)
mu_val = 0;
for x = 1:4
    for y = 1:5
        for z = 1:3
            mu_val = mu_val + ((x-xbar)^p * (y-ybar)^q * (z-zbar)^r * SHAPE(x,y,z));
        end
    end
end

function m_val = m_cal(p,q,r,SHAPE)
m_val = 0;
for x = 1:4
    for y = 1:5
        for z = 1:3
            m_val = m_val + (x^p * y^q * z^r * SHAPE(x,y,z));
        end
    end
end
end
```

```
mu_000 = mu_cal(0,0,0,xbar,ybar,zbar,SHAPE);
```

```
mu_000 = 12
```

```
4. mu_200 = mu_cal(2,0,0,xbar,ybar,zbar,SHAPE);
mu_200 = 2.916666666666667
```

```
5. mu_020 = mu_cal(0,2,0,xbar,ybar,zbar,SHAPE);
mu_020 = 8
```

```
6. mu_002 = mu_cal(0,0,2,xbar,ybar,zbar,SHAPE);
mu_002 = 6.916666666666666
```

```
7. J1 = mu_200 + mu_020 + mu_002;
J1 = 17.833333333333336
```

```
8. xbar = m_cal(1,0,0,SHAPE)/m_cal(0,0,0,SHAPE);
ybar = m_cal(0,1,0,SHAPE)/m_cal(0,0,0,SHAPE);
zbar = m_cal(0,0,1,SHAPE)/m_cal(0,0,0,SHAPE);
Xbar = 2.416666666666667
Ybar = 3
Zbar = 1.916666666666667
```

Hence, centroid = [2.416, 3, 1.916]

PART 5

1.

	1	2	3	4	5
1	0	2	1	3	1
2	2	0	3	0	0
3	1	3	0	2	0
4	3	0	2	0	2
5	1	0	0	2	0

2.

Node	Degree
1	4
2	2
3	3
4	3
5	2

3. $3 * \text{Number to triangles} / \# \text{ pats with length } 2$
 $= 3 * 3 / 14 = 9/14$

4. $C_1 = 3/6 = 1/2$, $C_2 = 2/3$

5. $\# \text{ connections} / \# \text{ possible connections} = 7 / (5 * 4 / 2) = 7/10$

6.

		Distance					Closeness	Normalized
		1	2	3	4	5		
From node	1	0	1	1	1	1	1/4	1
	2	1	0	1	2	2	1/6	2/3
	3	1	1	0	1	2	1/5	4/5
	4	1	2	1	0	1	1/5	4/5
	5	1	2	2	1	0	1/6	2/3