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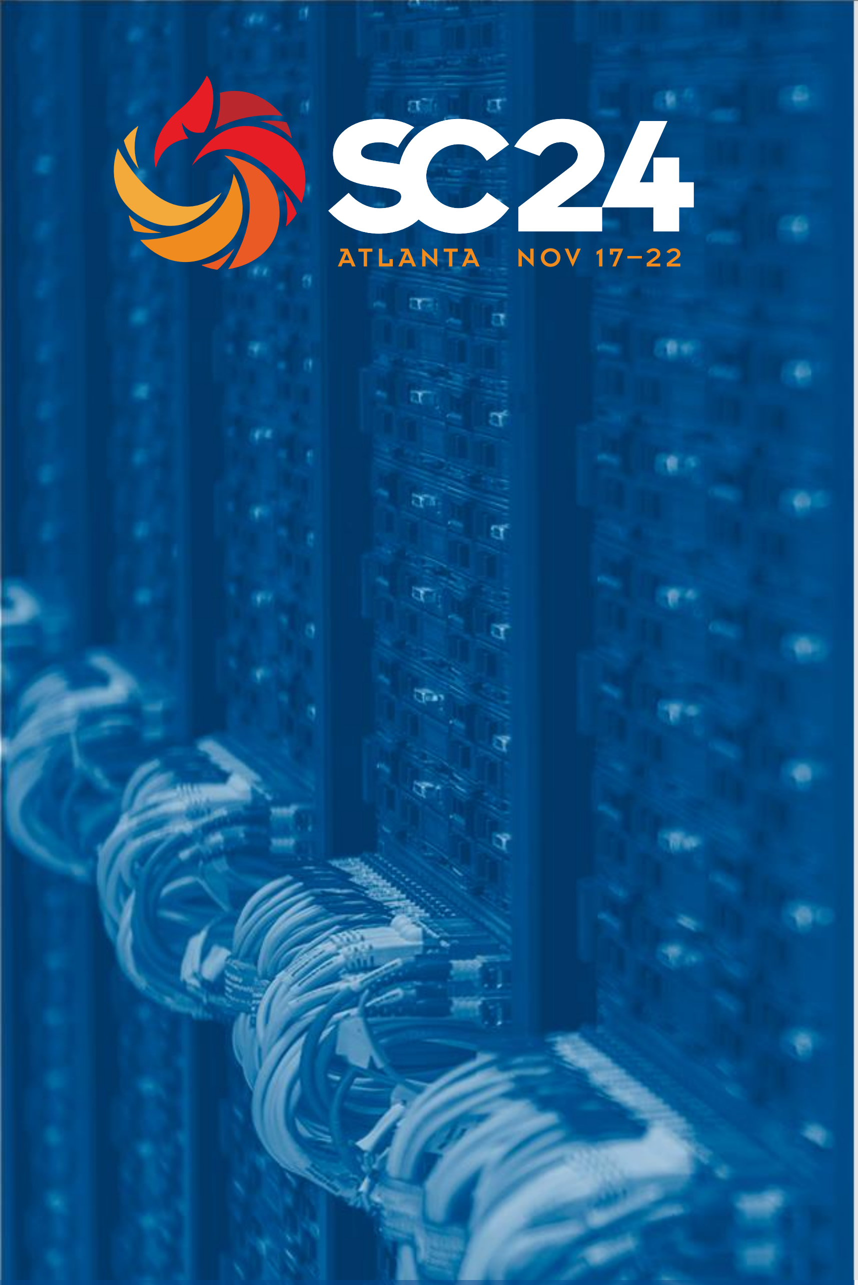

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Optimising workflow lifecycle management: development, HPC-ready containers deployment and reproducibility

Raül Sirvent, Rosa M Badia

18/11/2024

SC24 tutorial, Atlanta, 18 Novembre 2024

Tutorial website

https://github.com/bsc-wdc/Tutorial_SC24

Agenda

8:30 – 8:45	Overview of tutorial agenda	Rosa M Badia
8:45 – 9:15	Part 1.1: Hybrid HPC+AI+DA workflow development with PyCOMPSs - Context of the workflows at BSC - Overview of workflow development with PyCOMPSs - Extensions for the integration of HPC with AI and DA	Rosa M Badia
9:15 – 9:45	Part 1.2: Workflows' reproducibility through provenance - Motivation for workflow provenance - Design of the recording mechanism - Sharing experiments for reproducibility	Raül Sirvent
9:45 - 10:00	Part 1.3: HPC ready container images - Motivation for architecture specific containers - Overview of the Container Image Creation service - Example of HPC ready container generation - Workflow example for hands-on	Rosa M Badia
10:00 - 10:30	Coffee break	

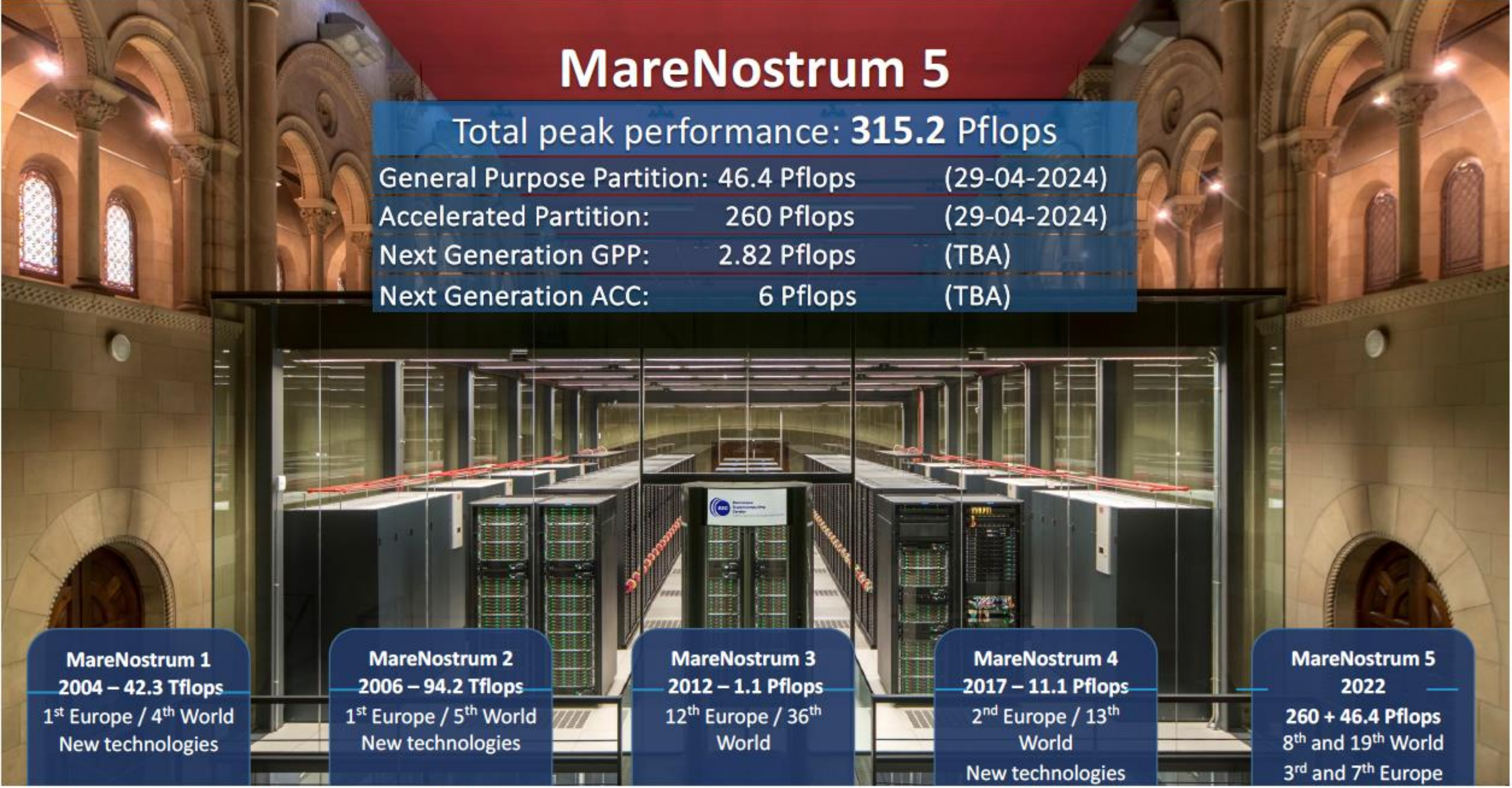
Agenda

10:30 – 10:45	Hands-on preparation (credentials distribution, how to access, etc)	All presenters
10:45 – 11:15	Part 2.1: Hands-on session: Sample workflows with PyCOMPSs, execution with containers, task-graph generation, tracefile generation (optional)	Rosa M Badia
11:15 – 11:55	Part 2.2: Hands-on session: How to automatically record workflow provenance and use it to share experiments in WorkflowHub	Raül Sirvent
11:55 - 12:00	Tutorial conclusions	All presenters

EuroHPC JU systems

		Status	Country	Peak performance	Architecture
Pre-Exascale	LUMI	Operational	Finland	539.13 petaflops	64-core AMD EPYC™ CPUs + AMD Instinct™ GPU
	Leonardo	Operational	Italy	315.74 petaflops	Int[illegible]l Ice-Lake, Intel Sapphire Rapids + [illegible]IA Ampere
	MareNostrum 5	Operational	Spain	[illegible]	[illegible] Sapphire Rapids, NVIDIA Hopper, [illegible]A Grace, Intel Emeralds, Intel
Petascale	Meluxina	Op[illegible]	[illegible]	[illegible]	[illegible]D EPYC + NVIDIA Ampere A100
	Vega	Ope[illegible]	[illegible]	[illegible]0.05 petaflops	AMD Epyc 7H12 + Nvidia A100
	Karolina	Opera[illegible]	[illegible]zech Republic	12.91 petaflops	AMD + Nvidia A100
	Discoverer	Operational	Bulgaria	5.94 petaflops	AMD EPYC
	Deucalion	Operational	Portugal	5.01 petaflops	A64FX, AMD EPYC, Nvidia Ampere

JUPITER, First European Exascale Supercomputer to be installed in Jülich, Germany



MareNostrum 5

Total peak performance: **315.2** Pflops		
General Purpose Partition:	46.4 Pflops	(29-04-2024)
Accelerated Partition:	260 Pflops	(29-04-2024)
Next Generation GPP:	2.82 Pflops	(TBA)
Next Generation ACC:	6 Pflops	(TBA)

MareNostrum 1
2004 – 42.3 Tflops
1st Europe / 4th World
New technologies

MareNostrum 2
2006 – 94.2 Tflops
1st Europe / 5th World
New technologies

MareNostrum 3
2012 – 1.1 Pflops
12th Europe / 36th World

MareNostrum 4
2017 – 11.1 Pflops
2nd Europe / 13th World
New technologies

MareNostrum 5
2022
260 + 46.4 Pflops
8th and 19th World
3rd and 7th Europe

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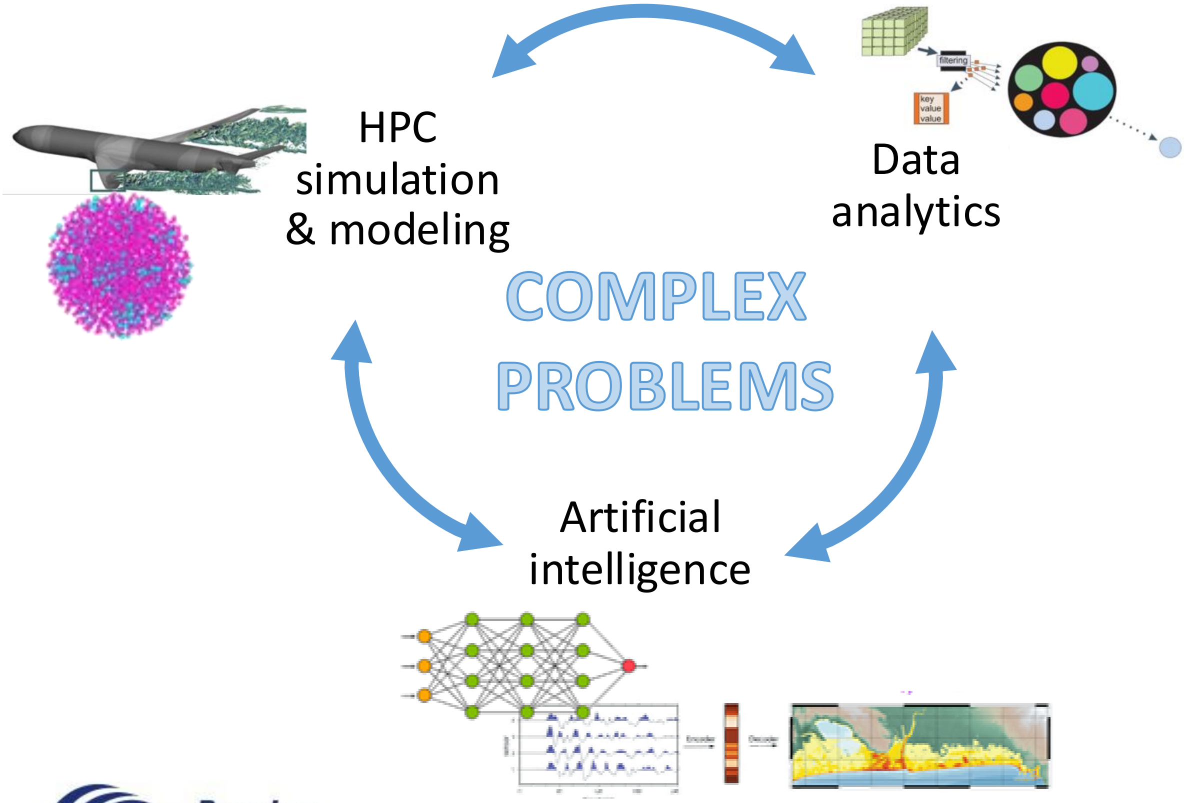
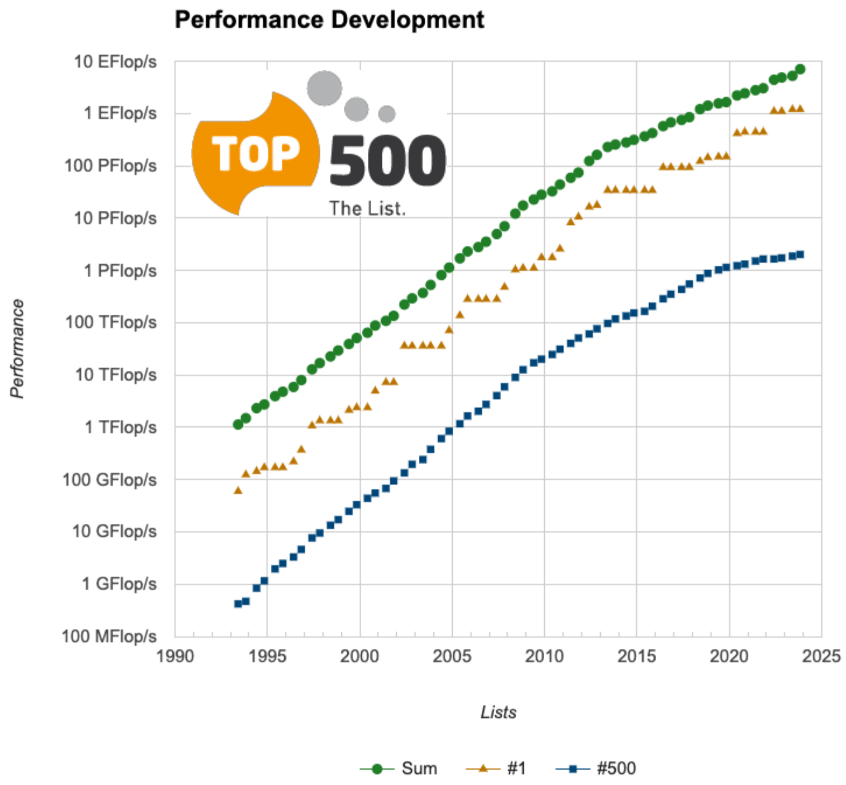
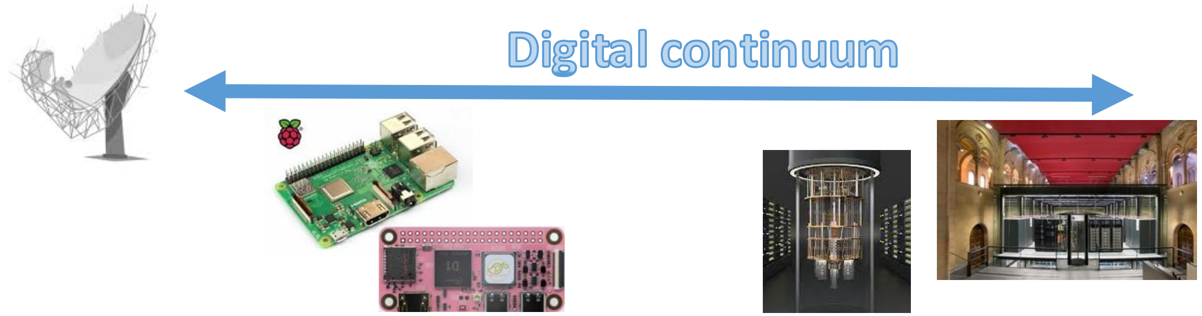
Complex problems for complex computing infrastructures







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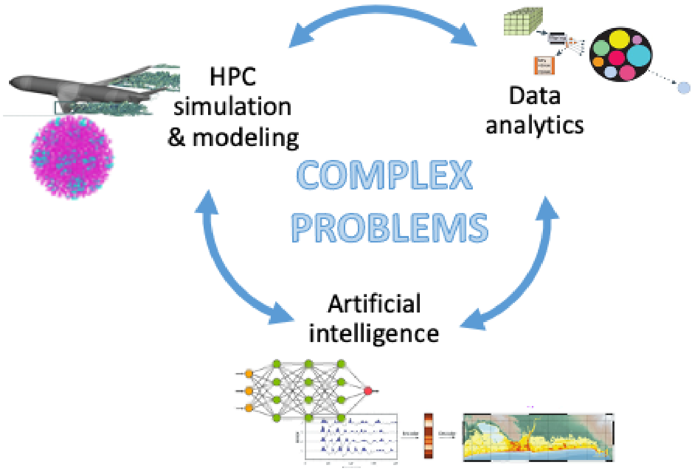
Workflow lifecyle challenges



- Workflow development
  - Different programming models and environments
- Workflow deployment
  - Can we make it easier to new HPC users?
- Workflow operation
  - Go beyond static workflows
  - Not only computational aspects, data management as well

- Sample projects:

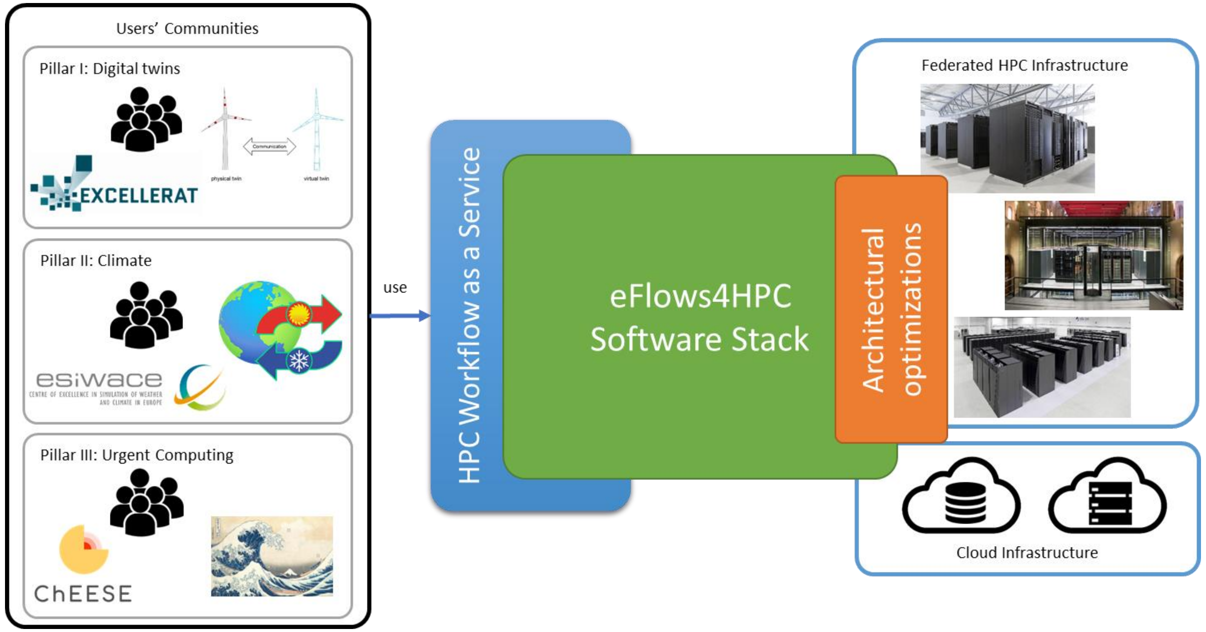
eFlows4HPC

caelestis

DT-GEO

eFlows4HPC in a nutshell

- Software tools stack that makes easier the development and management of complex workflows:
  - Combine different aspects
    - HPC, AI, data analytics
  - Reactive and dynamic workflows
    - Autonomous workflow steering
  - Full lifecycle management
    - Not just execution
    - Data logistics and Deployment
- HPC Workflows as a Service:
  - Mechanisms to make easier the use and reuse of HPC by wider communities
- Architectural Optimizations:
  - Selected HPC – AI Kernels Optimized for GPUs, FPGA, EPI
- Validation Pillar's
  - End-user workflows linked to CoEs



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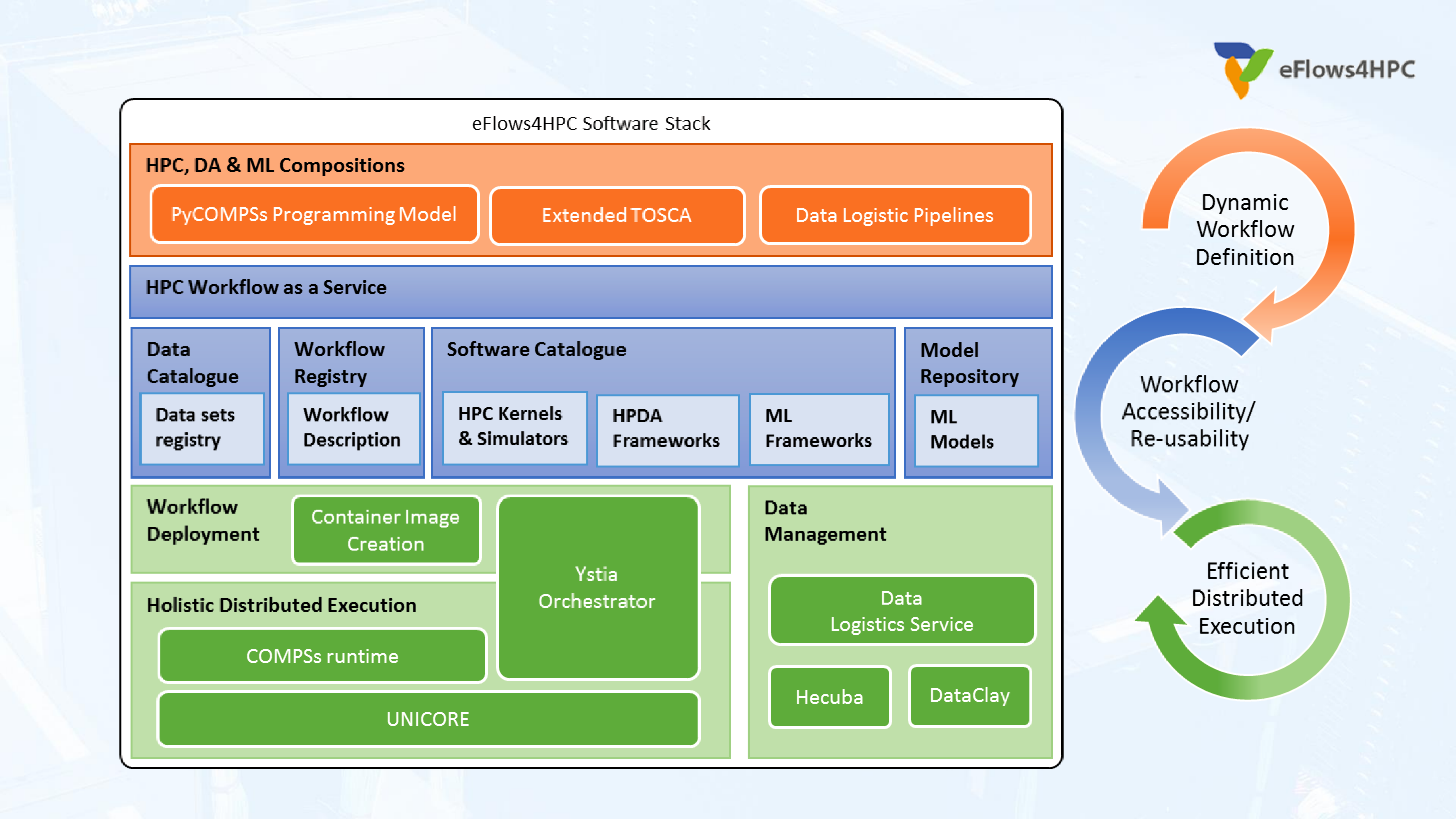
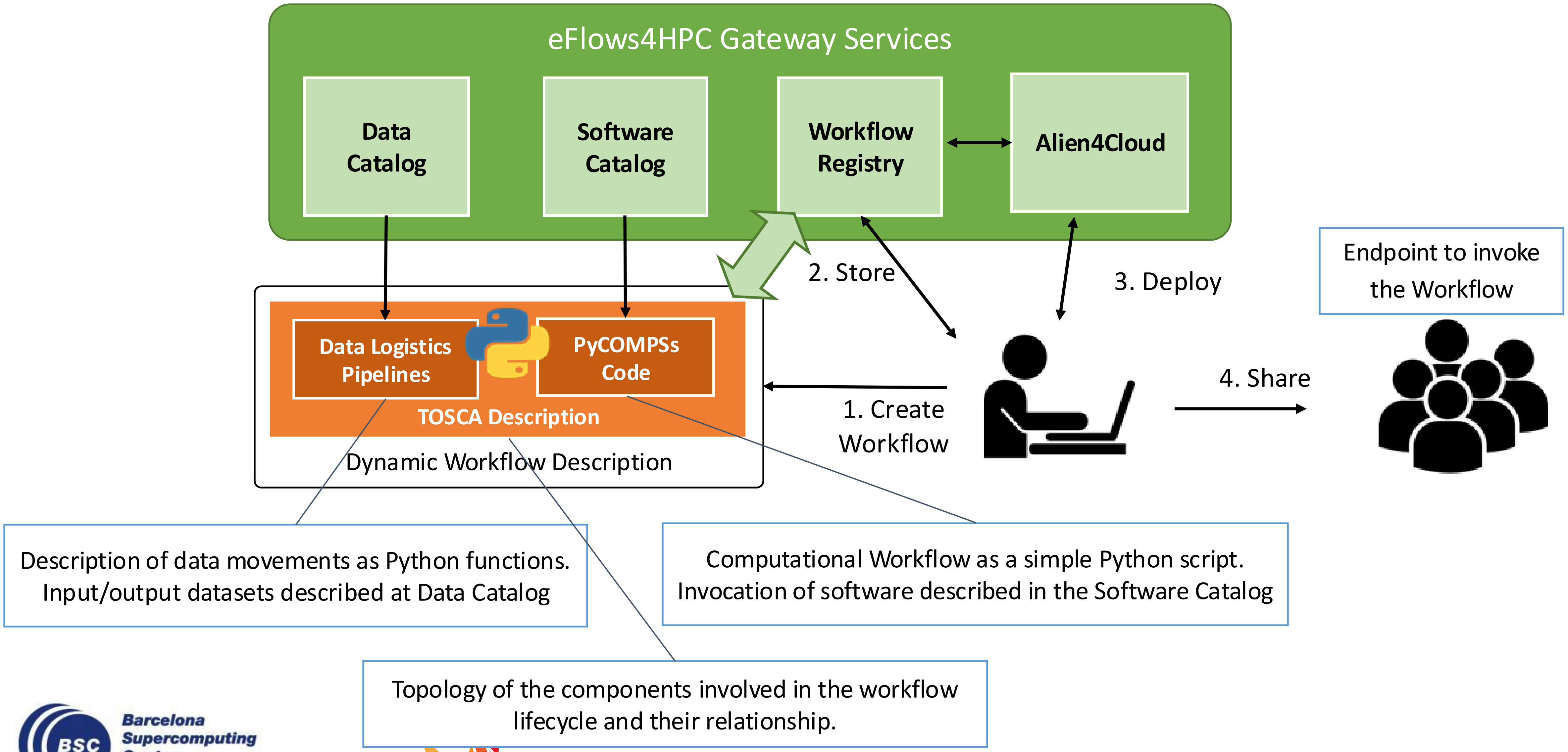

eFlows4HPC
eFlows4HPC Software Stack
HPC, DA & ML Compositions
PyCOMPSs Programming Model
Extended TOSCA
Data Logistic Pipelines
HPC Workflow as a Service
Data Catalogue
Data sets registry
Workflow Registry
Workflow Description
Software Catalogue
HPC Kernels & Simulators
HPDA Frameworks
ML Frameworks
Model Repository
ML Models
Workflow Deployment
Container Image Creation
Ystia Orchestrator
Holistic Distributed Execution
COMPSs runtime
UNICORE
Data Management
Data Logistics Service
Hecuba
DataClay
Dynamic Workflow Definition
Workflow Accessibility/ Re-usability
Efficient Distributed Execution

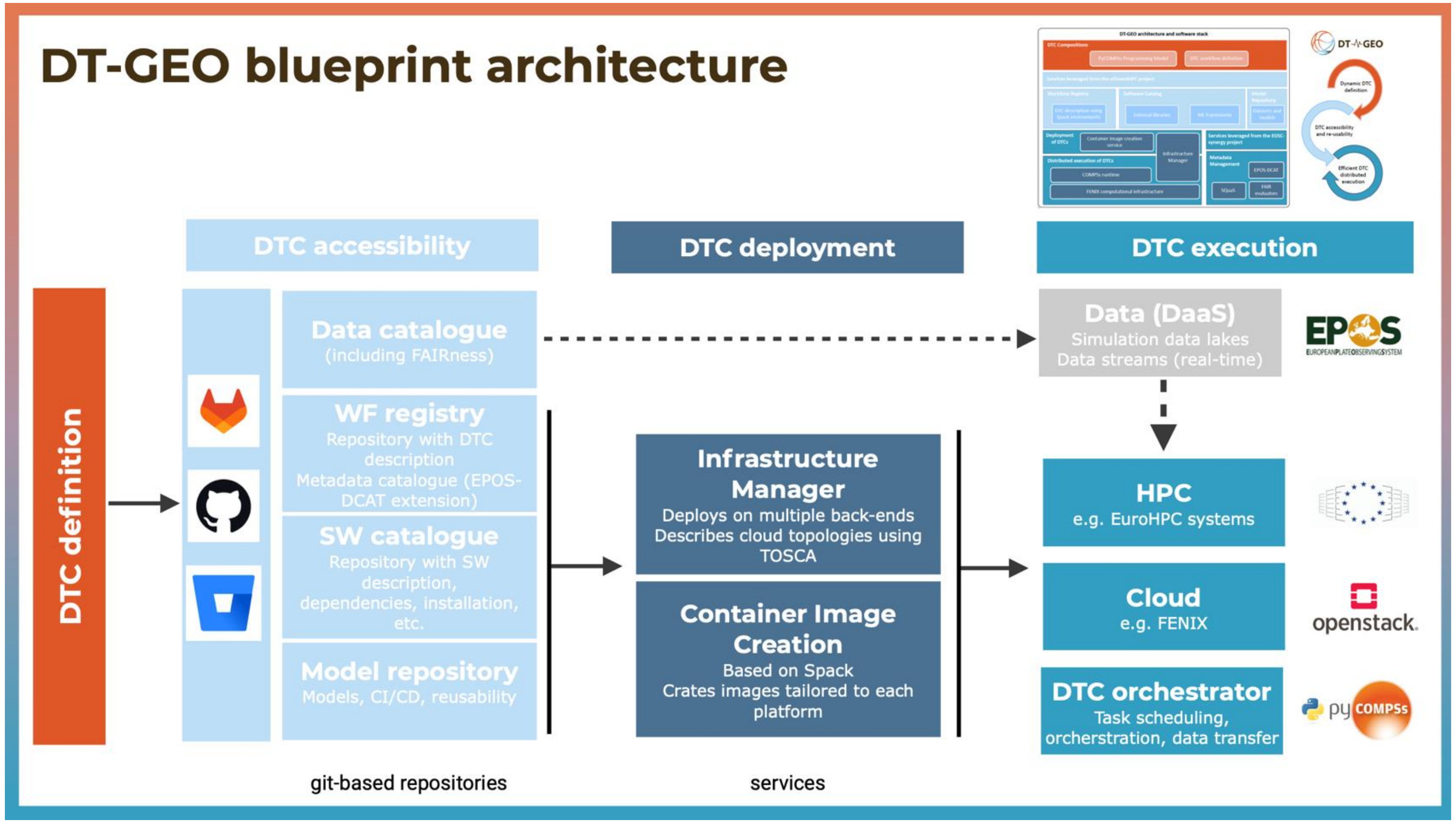
HPCWaaS: Workflow lifecycle overview

eFlows4HPC



DT-GEO: implementing a geophysical extremes digital twin

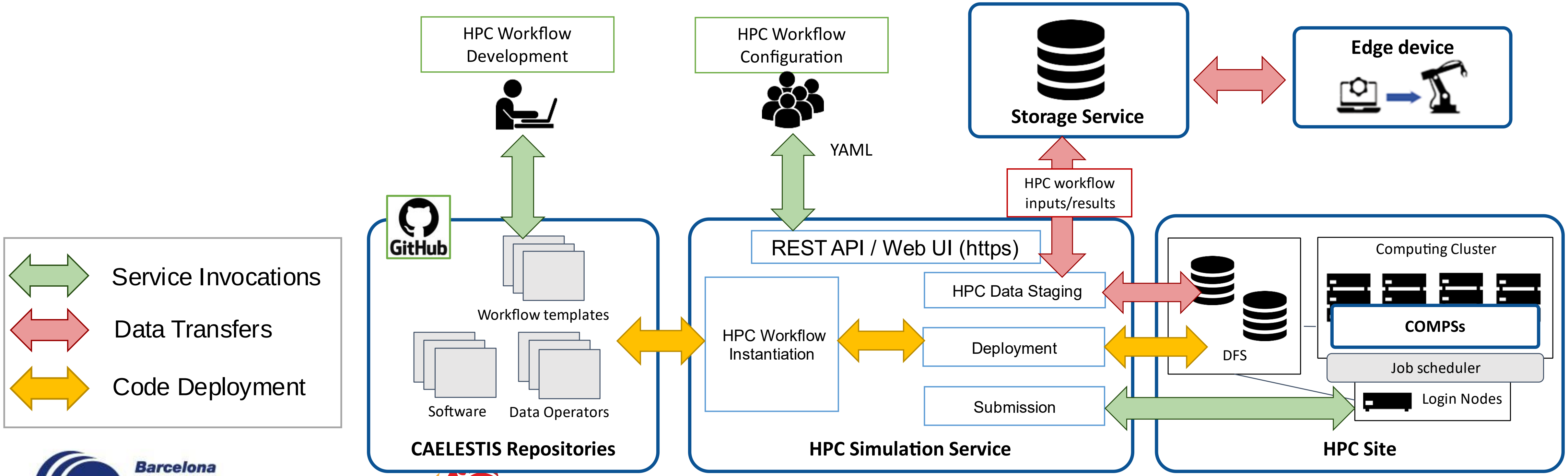
- 12 Digital Twin Components (DTCs) addressing specific hazardous phenomena from
  - Volcanoes,
  - Tsunamis
  - Earthquakes, and
  - Anthropogenically-induced extremes
- DTCs implemented as workflows, many of them inheriting the eFlows4HPC architecture and services



CAELESTIS Simulation Ecosystem

caelestis

- Design and develop a digital ecosystem to enable the flexible integration of product and process simulation tools and industry-driven product and process optimization services on demand at HPC



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A workflow example in the hands-on!

Integrating different computations in PyCOMPSs

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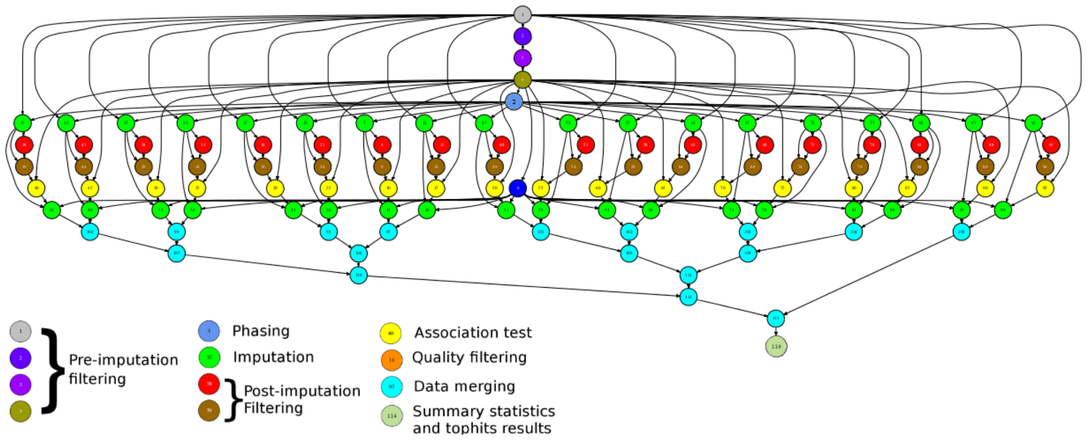
Workflows in PyCOMPSs

- Sequential programming, parallel execution
  - General purpose programming language + annotations/hints
- Task-based parallelization
  - Automatic generation of task graph
  - Coarse grain tasks: methods and web services
  - Sequential and parallel tasks
- Offers a shared memory illusion in a distributed system
  - Can address larger dataset than storage space
- Agnostic of computing platform
  - Clusters, clouds and cluster containers
- Based in Python
  - Further extended in eFlows4HPC for better integration of HPC, AI and Big Data

```
@task(c=INOUT)
def multiply(a, b, c):
      c += a*b
```



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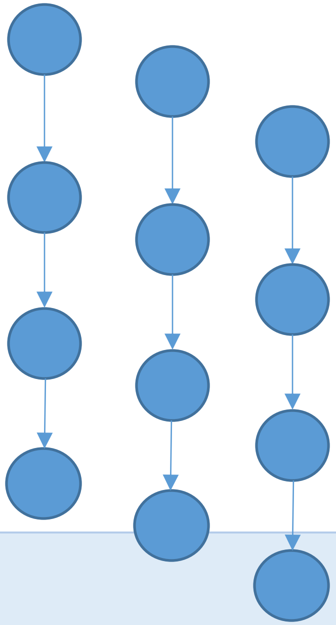
PyCOMPSs syntax

- Use of **decorators** to annotate tasks and to indicate arguments directionality
- Small API for data synchronization



Tasks definition

```
@task(c=INOUT)
def multiply(a, b, c):
    c += a*b
```

Main Program

```
initialize_variables()
startMulTime = time.time()
for i in range(MSIZE):
   for j in range(MSIZE):
      for k in range(MSIZE):
         multiply (A[i][k], B[k][j], C[i][j])
compss_barrier()
mulTime = time.time() - startMulTime
```

Other interesting annotations

Task constraints: enable to define HW or SW requirements

```
@constraint (ComputingUnits="8", MemorySize=6.0)
@task (c=INOUT)
def myfunc(a, b, c):
    ...
```

Linking with other programming models

```
@constraint (computingUnits= "248")
@mpi (binary="mySimulator", runner="mpirun", computingNodes= "16", ...)
@task (returns=int, stdOutFile=FILE_OUT_STDOUT, ...) def
nems(stdOutFile, stdErrFile):
    pass
```

Task failure management

```
@task(file_path=FILE_INOUT, on_failure='CANCEL_SUCCESSORS')
def task(file_path):
    ...
    if cond :
        raise Exception()
```

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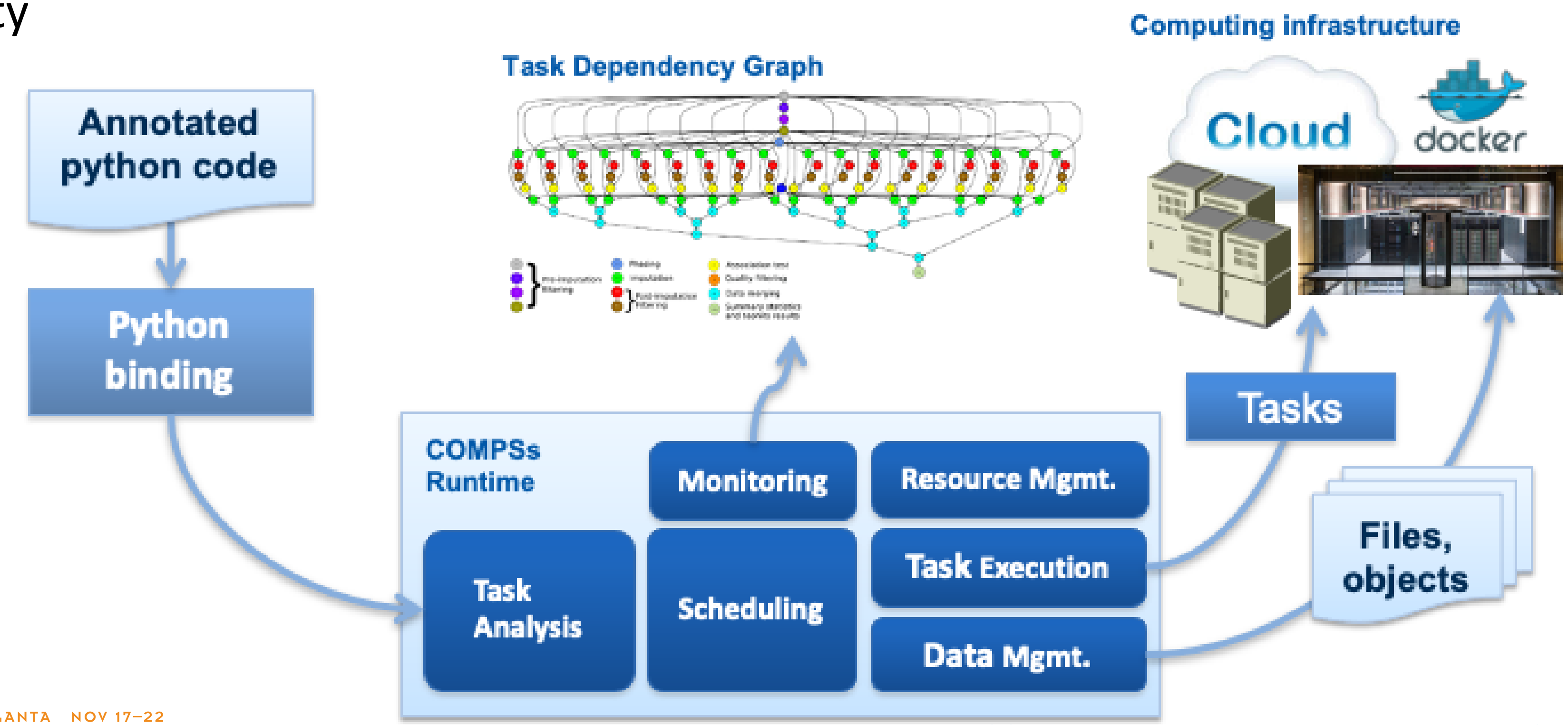
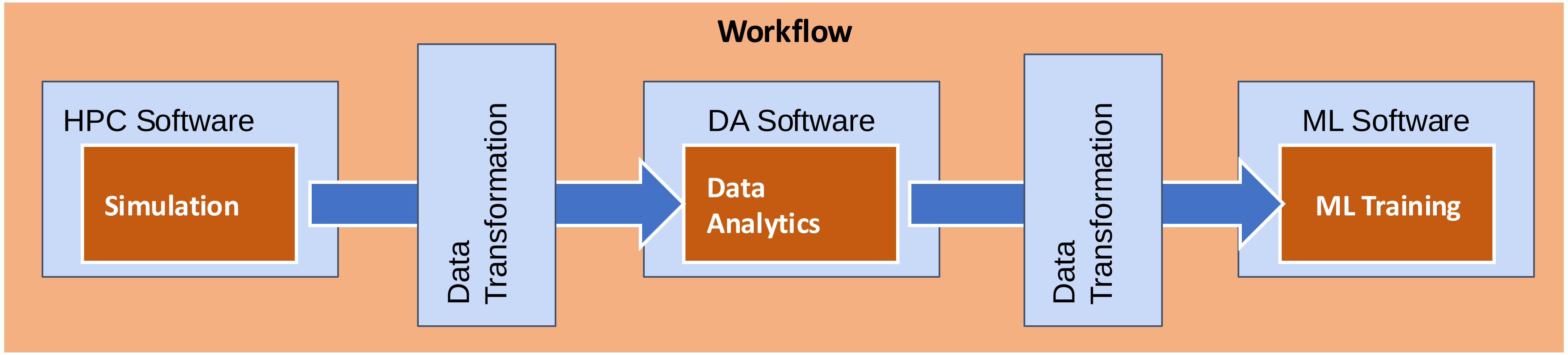
PyCOMPSs runtime

- Runtime deployed as a distributed master-worker
  - Description of computational infrastructure in an XML file
- Sequential execution starts in master node and tasks are offloaded to worker nodes
- All data scheduling decisions and data transfers are performed by the runtime
- Support for horizontal elasticity
- Support for containers



*https://compss-doc.readthedocs.io/

Interfaces to integrate HPC/DA/ML



- Goal:
  - Reduce the required glue code to invoke multiple complex software steps
  - Developer can focus in the functionality, not in the integration
  - Enables reusability
- Two paradigms:
  - Software invocation
  - Data transformations

workflow steps defined as tasks

```
@data_transformation (input_data, transformation description)
@software (invocation description)
def data_analytics (input_data, result):
    pass

simulation (input_cfg, sim_out)
data_analytics (sim_out, analysis_result)
ml_training (analysis_result, ml_model)
```

workflow body

Software Invocation description

eFlows4HPC

Admin/user code

```
{
  "type":"mpi",
  "properties":{
     "runner": "mpirun",
     "processes": "$SW_PROCS"
     "binary": "mpi_sofware.x",
     "params": "-d {{param}}",
     "working_dir": "{{working_dir}}"},
  "prolog":{
      "binary":"mkdir",
      "params":"{{working_dir}}"},
   "epilog":{
      "binary":"tar",
      "params":"zcvf {{out_tgz}}" {{working_dir}}},
  "constraints":{
     "computing_units": $SW_THREADS}
}
```

Software invocation description

Stored in software catalog

Workflow Code

PyCOMPSs Code

User code

```
#workflow steps defined as tasks
@software(config_file="invocation.json")
def mpi_exec(work_dir, param, out_tgz):
    pass


#workflow body
...
mpi_exec('my_folder', 'hello_world')
...
```

Computing Infrastructure

COMPSs runtime → Software Invocation

```
mkdir working_dir
cd working_dir
export OMP_NUM_THREADS=$SW_THREADS
mpirun -n $SW_PROCS mpi_software.x -d param
tar zcvf out_tgz working_dir
```

Automatically generated

- Converts a Python function of a software invocation to a PyCOMPSs task
- Takes information from the description in json
- Enables reuse in multiple workflows

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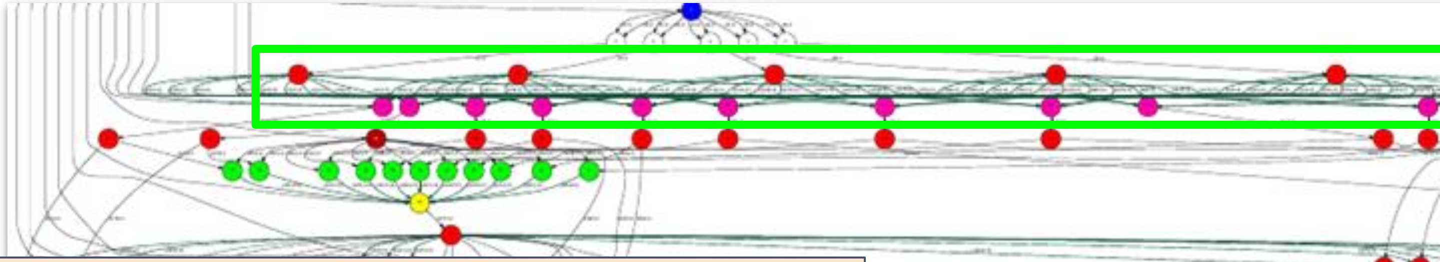
Data transformations

- A data transformation changes the data without requiring extra programming from the developer

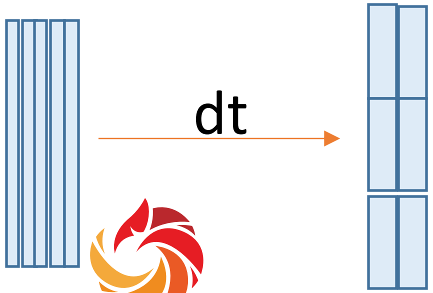
Admin/user code

```
def load_blocks_rechunk(blocks, shape, block_size, new_block_size):
   ...
   SnapshotMatrix = load_blocks_array (final_blocks, shape, block_size);
   return SnapshotMatrix
```



```
@dt("blocks", load_blocks_rechunk, shape=expected_shape, block_size=simulation_block_size,
  new_block_size=desired_block_size, is_workflow=True)
@software(config_file = SW_CATALOG + "/dislib/dislib.json")
def rSVD(blocks, desired_rank=30):
   u,s = rsvd(blocks, desired_rank, A_row_chunk_size, A_column_chunk_size)
   return u
```

User code



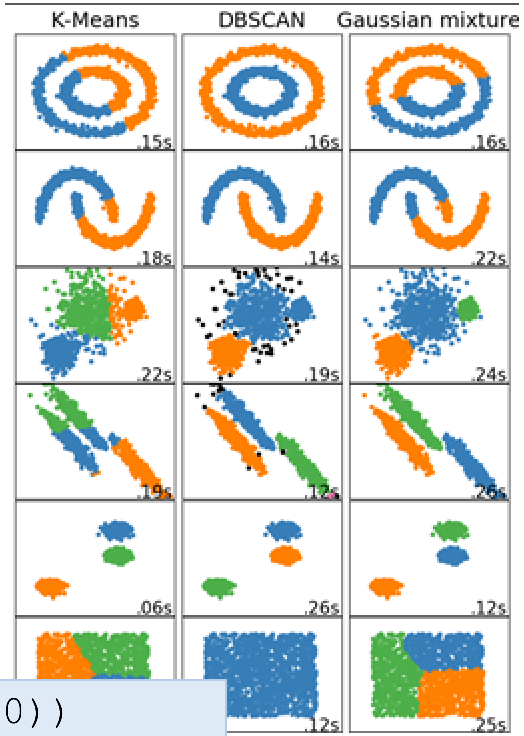

```
...
model, parameters = load_model_parameters(model_file)
for cfg in sim_cfgs:
        sim_results.append(execute_FOM_instance(model,parameters,[cfg]))
rom = rSVD(sim_results, desired_rank)
...
```

User code

Main workflow program

Dislib: parallel machine learning

- dislib: Collection of machine learning algorithms developed on top of PyCOMPSs
  - Unified interface, inspired in scikit-learn (fit-predict)
  - Based on a distributed data structure (ds-array)
  - Unified data acquisition methods
  - Parallelism transparent to the user – PyCOMPSs parallelism hidden
  - Open source, available to the community
- Provides multiple methods:
  - Data initialization
  - Clustering
  - Classification
  - Model selection, ...

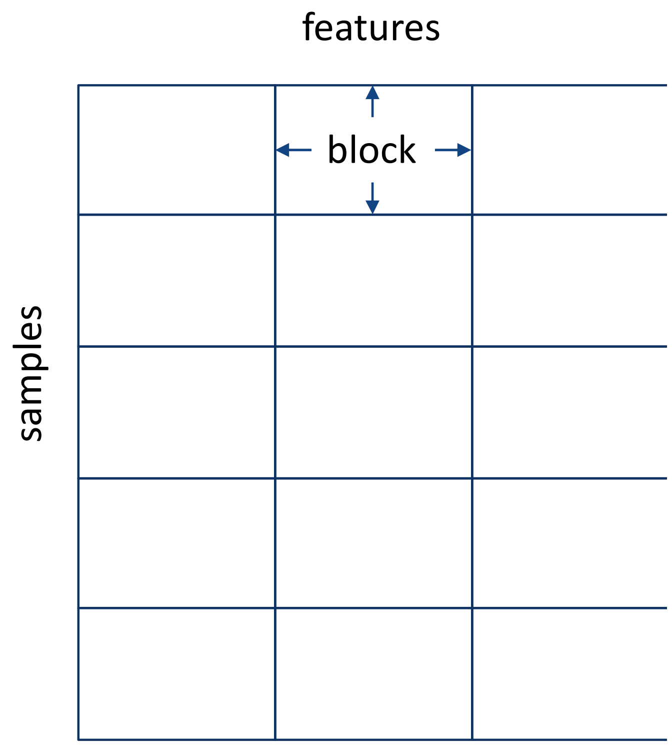



```
x = load_txt_file("train.csv", (10, 780))
x_test = load_txt_file("test.csv", (10, 780))

kmeans = KMeans(n_clusters=10)
kmeans.fit(x)
kmeans.predict(x_test)
```

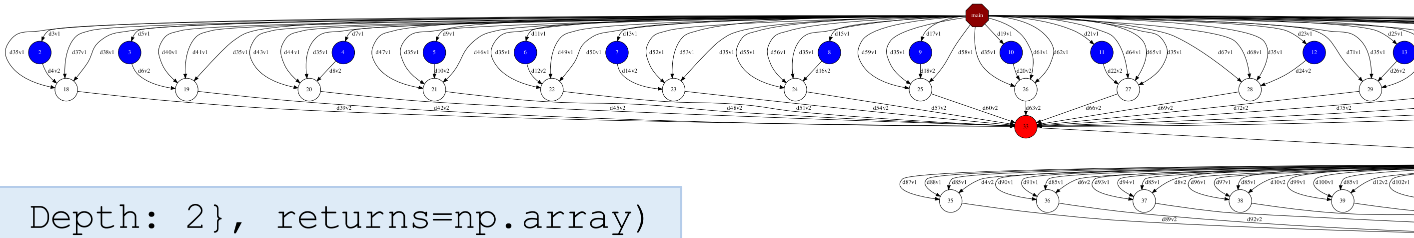
Dislib data structure: Distributed arrays (ds-arrays)

- 2-dimensional structure (i.e., matrix)
  - Divided in blocks (NumPy arrays)
- Works as a regular Python object
  - But not stored in local memory!
- Methods for instantiation and slicing with the same syntax of numpy arrays:
  - Internally parallelized with PyCOMPSs:
  - Loading data (e.g. from a text file)
  - Indexing (e.g., x[3], x[5:10]
  - Operators (e.g., x.min(), x.transpose())
- ds-arrays can be iterated efficiently along both axes
- Samples and labels can be represented by independent distributed arrays



Internally parallelized with PyCOMPSs

Computes pair wise distances of points to centers and accumulates new values to compute new centers (partials)



```
@task(blocks={Type: COLLECTION_IN, Depth: 2}, returns=np.array)
def _partial_sum(blocks, centers):
...
    return partials
```

x: ds-array

```
@task(returns=dict)
def _merge(*data):
...
    return accum
```

Reduces values of centers through merge task

```
def fit(self, x, y=None):
    """ Compute K-means clustering.
    old_centers = None
    iteration = 0

    while not self._converged(old_centers, iteration):
            old_centers = self.centers.copy()
            partials = []
            for row in x._iterator(axis=0):
                partial = _partial_sum(row._blocks, old_centers)
                partials.append(partial)
            self._recompute_centers(partials)
            iteration += 1
    self.n_iter = iteration
    return self
```

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dislib

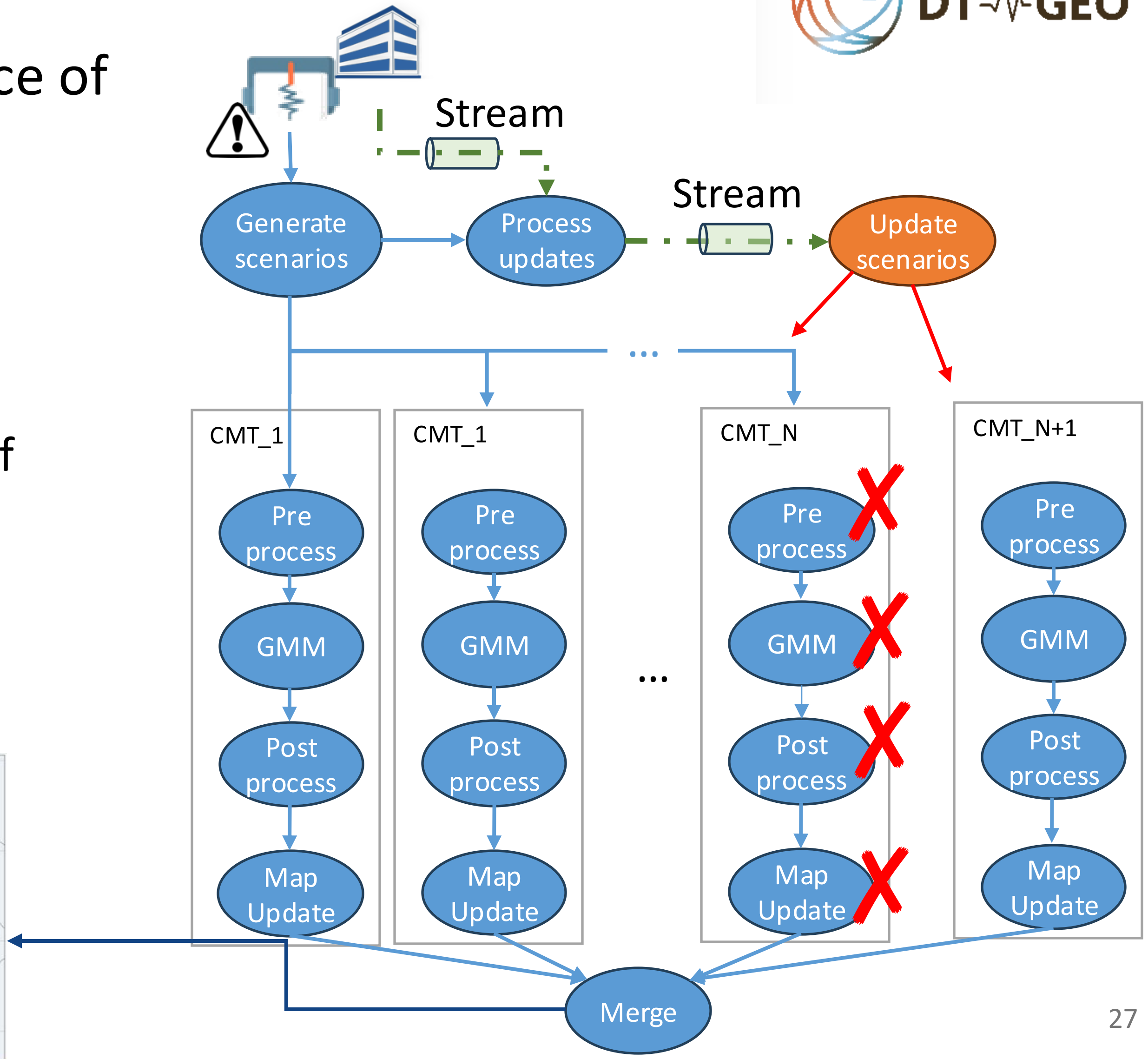
Sample workflows

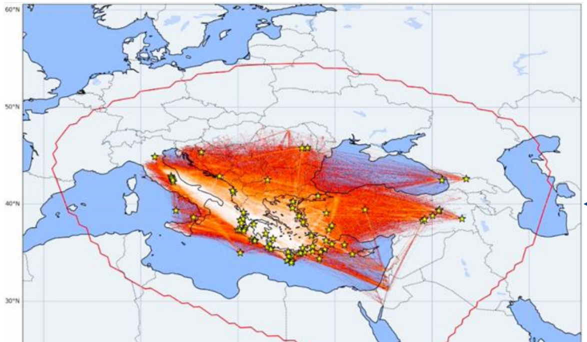
- UCIS4EQ – Earthquake simulation – eFlows4HPC and DT-GEO
- CAELESTIS – Surrogate model creation

Event-driven cancellation/creation

UCIS4EQ: HPC-based urgent seismic simulation workflow

- Evaluation of scenarios after the occurrence of a seismic event
- Combines multiple web services and HPC simulation (Salvus)
- Workflow Dynamicity:
  - Usage of **data streaming** for communication of events
  - On event occurrence API supports:
    - **Dynamic cancellation** of task groups
    - **Dynamic creation** of new set of tasks





Workflow templates

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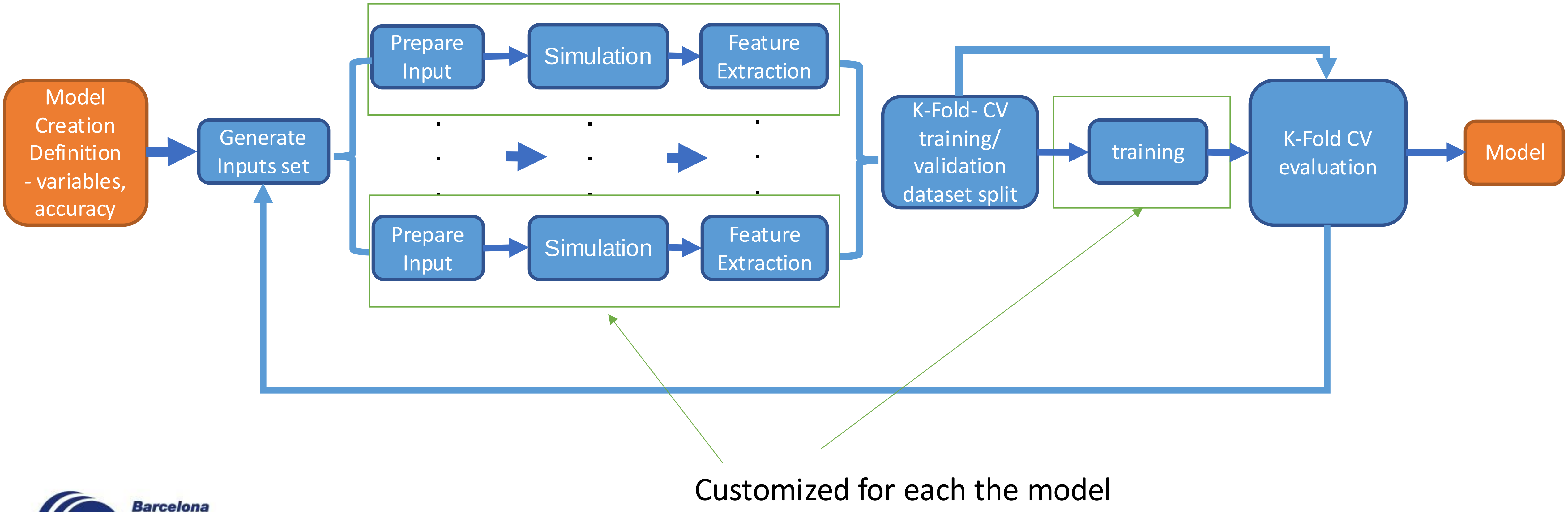
Surrogate Model Creation Workflow



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Actual problem: open hole tension

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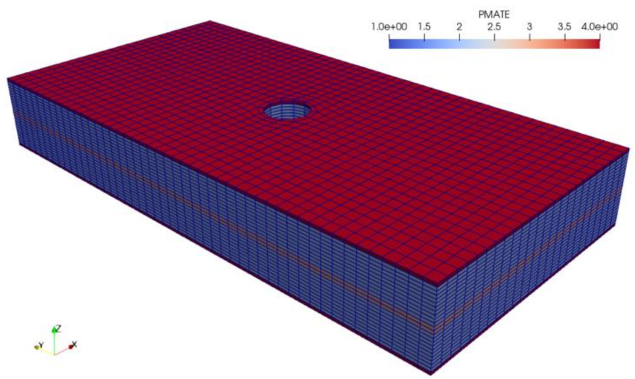
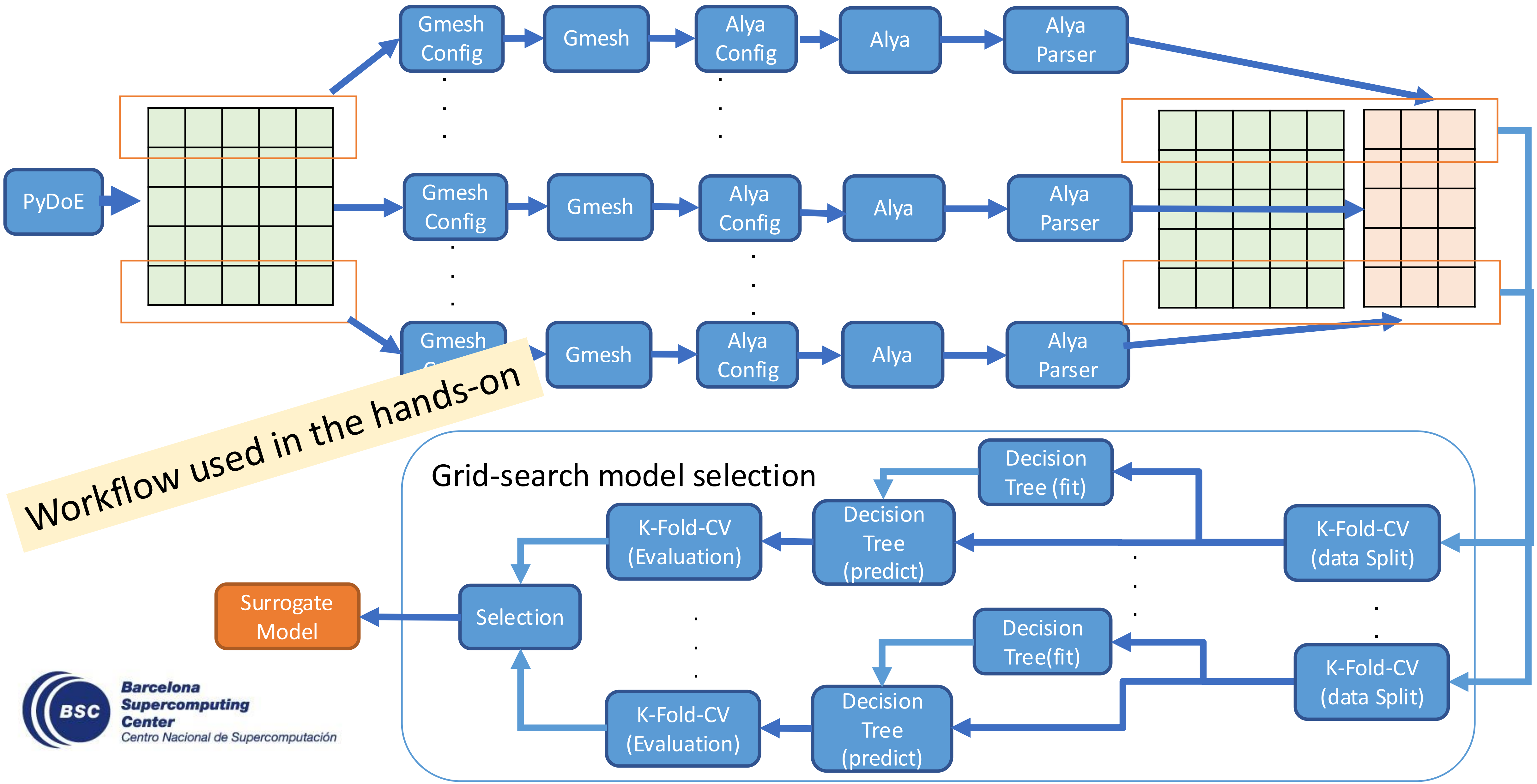
- Open hole geometry: test specimen with a hole in the middle
  - The simulation mechanically sets it under tension until it breaks
    - all virtually, numerically
- The workflow generates synthetic data which is simulated with Alya and subsequently trains a model
- The trained model is able to predict predict the maximum load at which the specimen will break given some inputs

- Mesh
  - Global element size: 0.5 mm x 0.5 mm x 0.13 mm
  - Total elements: 54332
  - Element types: Hexahedrons



Specific workflow instance



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Further Information

- Project page: http://www.bsc.es/compss
  - Documentation
  - Virtual Appliance for testing & sample applications
  - Tutorials
- Source Code

  https://github.com/bsc-wdc/compss
- Docker Image

  https://hub.docker.com/r/compss/compss
- Applications

  https://github.com/bsc-wdc/apps

  https://github.com/bsc-wdc/dislib
- Dislib
  - https://dislib.readthedocs.io/en/latest/

ACKs

DT-GEO

CEEC

Colmena

HP2C-DT

CyclOps

DISCOVER US

CAELESTIS

ICOS

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MareNostrum 5

Thanks!

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rosa.m.badia@bsc.es