

COMP SUPERSCALAR

COMPSs at MareNostrum Manual

Version: 1.3

August 17, 2015



This manual only provides information about the COMPSs usage at MareNostrum. Specifically, it details the available COMPSs modules, how to load them and how to create and track a COMPSs job.

If you want to install COMPSs at your local machine please refer to the *COMPSs Installation Manual* available at our webpage http://compss.bsc.es.

For further information about the application execution please refer to the *COMPSs User Manual: Application execution guide* available at http://compss.bsc.es.

For further information about the application development please refer to the *COMPSs User Manual: Application development guide* available at http://compss.bsc.es/.

For full COMPSs application examples (codes, execution commands, results, logs, etc.) please refer to the *COMPSs Sample Applications* available at http://compss.bsc.es/

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1 COMP Superscalar (COMPSs)

COMP Superscalar (COMPSs) is a programming model which aims to ease the development of applications for distributed infrastructures, such as Clusters, Grids and Clouds. COMP Superscalar also features a runtime system that exploits the inherent parallelism of applications at execution time.

For the sake of programming productivity, the COMPSs model has four key characteristics:

- Sequential programming: COMPSs programmers do not need to deal with the typical duties of parallelization and distribution, such as thread creation and synchronization, data distribution, messaging or fault tolerance. Instead, the model is based on sequential programming, which makes it appealing to users that either lack parallel programming expertise or are looking for better programmability.
- Infrastructure unaware: COMPSs offers a model that abstracts the application from the underlying distributed infrastructure. Hence, COMPSs programs do not include any detail that could tie them to a particular platform, like deployment or resource management. This makes applications portable between infrastructures with diverse characteristics.
- Standard programming languages: COMPSs is based on the popular programming language Java, but also offers language bindings for Python and C/C++ applications. This facilitates the learning of the model, since programmers can reuse most of their previous knowledge.
- No APIs: In the case of COMPSs applications in Java, the model does not require to use any special API call, pragma or construct in the application; everything is pure standard Java syntax and libraries. With regard the Python and C/C++ bindings, a small set of API calls should be used on the COMPSs applications.

2 COMPSs Modules

2.1 Available modules

COMPSs is configured in MareNostrum (MN3) as a Linux Module. Type $module\ available\ COMPSs$ to list the available COMPSs modules through Linux Module configuration and $module\ load\ COMPSs/iversion_{\dot{c}}$ to load it.

```
$ module available COMPss
          - /apps/modules/modulefiles/tools -
COMPSs/0.0
COMPSs/0.1
COMPSs/0.2_Nested
COMPSs/1.1.2_gpfs
COMPSs/1.1.2 \_scratch
COMPSs/1.2
COMPSs/1.3
COMPSs/release (default)
COMPSs/trunk
$ module load COMPSs/release
load java/1.7.0u55 (PATH, MANPATH, JAVA_HOME, JAVA_ROOT, JAVA_BINDIR,
                    SDK.HOME, JDK.HOME, JRE.HOME)
load MKL/11.0.1 (LD_LIBRARY_PATH)
load PYTHON/2.7.3 (PATH, MANPATH, LD_LIBRARY_PATH, C_INCLUDE_PATH)
load COMPSs/release (PATH, MANPATH, IT_HOME)
```

The following command can be run to check if the correct COMPSs version has been loaded:

```
$ runcompss — version COMPSs version 1.3
```

2.2 Configuration

The COMPSs module contains **all** the COMPSs dependencies, including Java, Python and MKL. Modifying any of these dependencies can cause execution failures and thus, we **do not** recomend to change them. Before running any COMPSs job please check your environment and, if needed, comment out any line inside the *.bashrc* file loading custom COMPSs, Java, Python and/or MKL modules.

The COMPSs module needs to be loaded in all the nodes that will run a COMPSs job. Consequently, the *module load* **must** be included in your *.bashrc* file. To do so please run the following command:

```
$ cat "module load COMPSs/release" >> ~/.bashrc
```

Log out and back in again to check that the file has been correctly edited:

Please remember that COMPSs runs in several nodes and your current environment is not exported to them. Thus, all the needed environment variables **must** be loaded through the *.bashrc* file.

3 COMPSs Jobs

COMPSs jobs can be easily submitted by running the **enqueue_compss** command. This command allows to configure any **runcompss** option and some particular queue options such as the queue system, the number of nodes, the wallclock time, the master working directory, the workers working directory and number of tasks per node.

Next, we provide detailed information about the enqueue_compss command:

```
$ enqueue_compss —help
Usage: /apps/COMPSs/1.3/Runtime/scripts/user/enqueue_compss
         [queue_system_options] [COMPSs_options]
         application_name application_arguments
* Options:
  General:
   --help, -h
                                               Print this help message
 Queue system configuration:
    - -exec_time=<minutes>
                                               Expected execution time of
                                               the application (in minutes)
                                               Default: 10
   - \text{-num\_nodes} = \langle \text{int} \rangle
                                                Number of nodes to use
                                               Default: 2
                                               Queue system to use:
   - -queue_system=<name>
                                               lsf | pbs | slurm
                                               Default: 1sf
                                               Maximum number of simultaneous
   - tasks_per_node = <int>
                                               tasks running on a node
                                               Default: 16
                                               Working directory of the
   - - master_working_dir=<path>
                                               application
                                               Default: .
   - -worker_working_dir=<name>
                                               Worker directory.
                                               Use: scratch | gpfs
                                               Default: scratch
   - - tasks_{in} - master = < int >
                                               Maximum number of tasks that
                                               the master node can run as
                                               worker. Cannot exceed
                                               tasks_per_node.
                                               Default: 0
    - -network=<name>
                                               Communication network for
                                               transfers:
                                               default | infiniband | data.
                                               Default: default
  Runcompss catched parameters:
```

$\log_{-}\text{level} \Rightarrow ,\text{debug}$	Set the debug level: off info debug Default: off		
- $-$ tracing= $<$ true false >	Enable tracing: true false Default: false		
comm= <path></path>	Class that implements the adaptor for communications Default: integrated to olkit.nio.master.NIOAdaptor		
library_path= <path></path>	Non-standard directories to search for libraries (e.g. Java JVM library, Python library, C binding library) Default: .		
classpath= <path></path>	Path for the application classes / modules Default: .		
Runcompss delegated parameters:			
Runtime configuration options:project= <path></path>	Path to the project XML file Default: /opt/COMPSs/Runtime/ configuration/xml/projects /project.xml		
resources= <path></path>	Path to the resources XML file Default: /opt/COMPSs/Runtime/ configuration/xml/resources/ resources.xml		
lang= <name></name>	Language of the application (java/c/python) Default: java		
$-\log_{-} \text{level} >$, $-\text{debug}$, $-\text{d}$	Set the debug level: off info debug Default: off		
Tools enablers:			
graph= <bool>,graph, -g</bool>	Generation of the complete graph (true/false) When no value is provided it is set to true Default: false		
- -tracing= $<$ bool>, $-$ -tracing, $-$ t	Generation of traces (true/false) When no value is provided it is set to true Default: false		
monitoring= <int>,monitoring, -m</int>	Period between monitoring		

samples (milliseconds) When no value is provided it is **set** to 2000 Default: 0 Advanced options: Class that implements the - -comm=<path> adaptor for communications Default: integrated to olkit. nio. master. NIOAdaptor - -library_path=<path> Non-standard directories to search for libraries (e.g. Java JVM library, Python library, C binding library) Default: . - - classpath = < path >Path for the application classes / modules Default: . $- - task_count = < int >$ Only for C/Python Bindings. Maximum number of different functions/methods invoked from the application that have been selected as tasks Default: 50 $- \text{-uuid} = \langle \text{int} \rangle$ Preset an application UUID Default: Automatic random generation * Application name: For Java applications: Fully qualified name of the application For C applications: Path to the master binary For Python applications: Path to the .py file containing the main program * Application arguments: Command line arguments to pass to the application. Can be empty.

Please find more details on the COMPSs framework at

http://compss.bsc.es