# **Dynamic Programming Exercise Class 8**

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#### Return of the Deaton model

We focus on how we can efficiently solve consumption-savings models like the one below. We focus on finite horizon for now:

$$V_t(M_t) = \max_{C_t} \frac{C_t^{1-
ho}}{1-
ho} + \beta E_t[V_{t+1}(M_t+1)]$$
 s.t  $M_{t+1} = R(M_t - C_t) + Y_{t+1}$   $Y_{t+1} = \exp(\xi_{t+1})$   $\xi_{t+1} \sim N(\mu, \sigma_{\xi}^2)$   $A_t = M_t - C_t \ge 0$ 

FOC:

$$C_t^{-\rho} = \beta R E_t [C_{t+1}^{-\rho}]$$

Algorithm in finite horizon works as follows:

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- 3.2 Save  $C_t^*$  into policy.
- 3.3 Compute value function as the value of the RHS of the bellman equation for  $C_t^*$ .

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- 4. Add a point at  $M_t = 0$ ,  $C_t^* = 0$  to both the endogenous  $M_t$ -grid and to the policy function to handle the constraint.