

# Dynamic Programming

Part 1: Exercise 1 & 2 (week 7)

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# Plan for today

- A bit about me
- Plan for exercises generally
- Coding tips
- A bit about dynamic programming as a course and a “concept”
- Exercise 1 & 2: Cake-eating in finite and infinite horizon



# Who is your TA?

- 2nd year Master student in Economics
- Interests in macroeconomics, computational methods, (structural) econometrics, mathematical finance
- Been “around the block” TA-wise:
  - Macroeconomics 1 & 2 (Math-Econ)
  - Introduction to Social Data Science
  - Macroeconomics III
  - Probability Theory and Statistics
  - And now: Dynamic Programming
- Research Assistant for Assoc. Prof. Jeppe Druedahl, working with dynamic programming and deep reinforcement learning
- Can contact me on absalon or mail: [qxb650@ku.dk](mailto:qxb650@ku.dk)

## Plan for exercises

- Wednesdays 8:15 - 10 (class 1) and Thursdays 8:15 - 10 (class 2)
- Hands-off approach from my side → Exercises for coding!
  - Brief introduction to topic/model in beginning of class (5-15 min)
- Problem sets are in notebooks and py-files (to be filled out)
- Exercises are divided into 3 parts/blocks, each of 3-4 weeks:
  1. Theory and tools
  2. Dynamic Discrete Choice (structural econometrics)
  3. Discrete-Continuous Choice (more advanced applications)
- No exercices in games → See my term paper for inspiration :)
- Exercises are all python-based
- No assignments

# Coding tips

- Work-flow: Fill out notebooks and py-files (structure for project)
  - ex\_ante folder contains “unsolved” notebooks
  - ex\_post folder contains notebooks with solutions → Check!
- First cell in each notebook: Notebook checks changes in py-files.

```
%load_ext autoreload  
%autoreload 2
```

- If you use CoPilot: Disable while solving exercises since CoPilot looks in ex\_post and inserts solution
- Small guide on smart use of GitHub repository

# What is Dynamic Programming?

- Dynamic programming  $\approx$  Dynamic optimization

(US military lingo: “*finding the optimal program*”, [link for story](#))

(Dynamic: “*over time / multi-stage*”, [another story](#))

- Want to find  $\{c_t^*\}_{t=1}^T$  that maximizes  $\mathbb{E}[\sum_{t=1}^T \beta^{t-1} u_t(c_t)]$
- Reformulate problem with **Bellman equation** (general form):

$$V_t(s_t) = \max_{c_t} u_t(c_t, s_t) + \beta \mathbb{E}_t[V_{t+1}(s_{t+1})] \quad \text{s.t. } s_{t+1} = f(s_t, c_t)$$

→ An application of Bellman’s **Principle of Optimality**:

*When we optimize in period t, we don’t have to think about the past or how we got “here”, only that the future actions are optimal*

## Exercise 1: Cake-eating in a finite horizon

We have a cake with  $W$  slices. We want to optimally eat the cake over  $T$  periods, we receive utility  $u(c_t) = \sqrt{c_t}$ . Find the optimal policy  $\{c_t^*\}_{t=1}^T$  such that:

$$\max_{\{c_t\}_{t=1}^T} \sum_{t=1}^T \beta^{t-1} \sqrt{c_t} \quad \text{s.t.} \quad \underbrace{W = \sum_{t=1}^T c_t}_{\text{Can't eat more than } W}, \quad \underbrace{c_t \in \mathbb{N}_0 \ \forall t}_{\text{Can only eat "full" slices}}$$

Express with **Bellman equation** with state  $W_t$  and state transition for  $W_{t+1}$

$$V_t(W_t) = \max_{c_t \in \mathbb{N}_0, c_t \leq W_t} \{\sqrt{c_t} + \beta V_{t+1}(W_{t+1})\} \quad \text{s.t. } W_{t+1} = W_t - c_t$$

## Exercise 1: Backwards Induction algorithm

1. In last period  $T$ , it is always optimal to eat what is left, i.e.

$$c_T^* = W_T \text{ and } \Rightarrow V_T(W_T) = \sqrt{W_T}$$

2. Go to period  $T - 1$  and solve:

$$V_{T-1}(W_{T-1}) = \max_{c_{T-1} \in \mathbb{N}_0, c_{T-1} \leq W_{T-1}} \{ \sqrt{c_{T-1}} + \beta V_T(\overbrace{W_{T-1} - c_{T-1}}^{=W_T}) \}$$

Since  $c_{T-1} \in \mathbb{N}_0$ , we do a grid search, i.e. “guessing” each  $c_{T-1} \leq W_{T-1}$  and “choosing” the one with the largest “value guess”.

For period  $T - 2, T - 3, \dots, 1$ : Do the same as above, given that we know the value function for all subsequent periods.

## Exercise 2: Cake-eating in an infinite horizon

Exactly the same problem as in exercise 1, except we let  $T = \infty$ .

Need another solution method → Value Function Iteration (VFI)

**Idea/Intuition:** With an infinite horizon, we “dont care” whether we are in period  $t$  and have  $W_t = 2$  slices left, or we are in period  $t + 1$  and have  $W_{t+1} = 2$ . The specific period becomes irrelevant.

→ Formulate Bellman equation without time subscripts

$$V(W) = \max_{c \in \mathbb{N}_0, c \leq W} \{\sqrt{c} + \beta V(W - c)\}$$

→ Find fixed point in **Bellman operator**  $V = \Gamma(V)$

If  $\beta \in [0, 1)$  and some technical stuff, the fixed point is unique

## Exercise 2: Value Function Iteration Algorithm

1. Make arbitrary guess on value function, e.g.  $V^{guess}(W) = 0 \forall W$
2. Use  $V^{guess}(W)$  on RHS of Bellman equation.

$$V(W) = \max_{c \in \mathbb{N}_0, c \leq W} \{ \sqrt{c} + \beta V^{guess}(W - c) \}$$

3. Check convergence  $\max\{|V(W) - V^{guess}(W)|\}$
4. Update  $V^{guess}(W)$  with new  $V(W)$
5. Keep iterating and check convergence below some threshold

Your time to shine!