7 Gaussian Elimination and LU Factorization

In this final section on matrix factorization methods for solving Ax = b we want to take a closer look at Gaussian elimination (probably the best known method for solving systems of linear equations).

The basic idea is to use left-multiplication of $A \in \mathbb{C}^{m \times m}$ by (elementary) lower triangular matrices, $L_1, L_2, \ldots, L_{m-1}$ to convert A to upper triangular form, i.e.,

$$\underbrace{L_{m-1}L_{m-2}\dots L_2L_1}_{=\widetilde{L}}A=U.$$

Note that the product of lower triangular matrices is a lower triangular matrix, and the inverse of a lower triangular matrix is also lower triangular. Therefore,

$$\widetilde{L}A = U \iff A = LU,$$

where $L = \widetilde{L}^{-1}$. This approach can be viewed as triangular triangularization.

7.1 Why Would We Want to Do This?

Consider the system Ax = b with LU factorization A = LU. Then we have

$$L\underbrace{Ux}_{=y} = b.$$

Therefore we can perform (a now familiar) 2-step solution procedure:

- 1. Solve the lower triangular system Ly = b for y by forward substitution.
- 2. Solve the upper triangular system Ux = y for x by back substitution.

Moreover, consider the problem AX = B (i.e., many different right-hand sides that are associated with the same system matrix). In this case we need to compute the factorization A = LU only once, and then

$$AX = B \iff LUX = B$$
,

and we proceed as before:

- 1. Solve LY = B by many forward substitutions (in parallel).
- 2. Solve UX = Y by many back substitutions (in parallel).

In order to appreciate the usefulness of this approach note that the operations count for the matrix factorization is $\mathcal{O}(\frac{2}{3}m^3)$, while that for forward and back substitution is $\mathcal{O}(m^2)$.

Example Take the matrix

$$A = \left[\begin{array}{rrr} 1 & 1 & 1 \\ 2 & 3 & 5 \\ 4 & 6 & 8 \end{array} \right]$$