

[]HelloWorldp0-
q0=
s(p1-
p0)-
t(q1-
q0)
p0-
q0=
(x0y0z0)
(x0y0z0)=
s(pxpypz)-
t(qxqyqz)-
x0=
sp_x-
tq_x=
y0=
sp_y-
tq_y=
z0=
sp_z-
tq_z=
(1)