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class KinectTracker {
    // Depth data
    int[] depth;
    PImage videoImage;

    void track() {
        // Get the raw depth as array of integers
        depth = kinect.getRawDepth();
        // Being overly cautious here
        if (depth == null) {
            println("WHHHO00000A ARRAY LENGTH MISMATCH");
            return;
        }
        // re-init presence measurements just to make sure something else isn't changing them
        presenceFront = 0;
        presenceMiddle = 0;
        presenceBack = 0;
        videoImage = kinect.getVideoImage(); // Read a new video frame
        videoImage.loadPixels(); // display the frame
        for (int x = 0; x < kw; x++) {
            for (int y = 0; y < kh; y++) {
                // Mirroring the image
                int offset = kw - x - 1 + y * kw;
                int i = offset;
                //
                int currColor = videoImage.pixels[i];
                int bkgdColor = averagePixels[i]; // turning the pixel average into an array that I

                // setting what things look like now to be referenced next frame
                int currR = (currColor >> 16) & 0xFF;
                int currG = (currColor >> 8) & 0xFF;
                int currB = currColor & 0xFF;

                // setting the currColors last frame to the bkgdColor this frame
                int bkgdR = (bkgdColor >> 16) & 0xFF;
                int bkgdG = (bkgdColor >> 8) & 0xFF;
                int bkgdB = bkgdColor & 0xFF;

                // resets the background to not see anything
                if (resetBackground) {
                    averagePixels[i] = videoImage.pixels[i];
                    ;
                }

                // subtracted background values
                int bgSubR = abs(currR - bkgdR);
                int bgSubG = abs(currG - bkgdG);
                int bgSubB = abs(currB - bkgdB);

                // background subtracted image
                bgSubAndThreshPixels[i] = 0xFF000000 | (bgSubR << 16) | (bgSubG << 8) | bgSubB;
                // threshold it!
            }
        }
    }
}

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    bgSubAndThreshPixels[i] =brightness(bgSubAndThreshPixels[i]) > thresh ? 1 : 0 ;//

    // Grabbing the raw depth
    int rawDepth = depth[offset];
    // eliminate any "background" depth measurements
    int correctedDepth = rawDepth * bgSubAndThreshPixels[offset];

    bgSubAndThreshPixels[i] =color(map(correctedDepth, 0, 2047, 0, 255));

    // start counting pixels
    if (correctedDepth > minDepth/ 2) { //map(mouseX, 0, width, 0, 2047)) {
        if (correctedDepth < minDepth) {
            presenceFront++;
        }
        else if (correctedDepth < maxDepth) {
            presenceMiddle++;
        }
        else {
            presenceBack++;
        }
    }
    else {
    }
}

if (resetBackground) {
    resetBackground =false; // turn the background reset back off
}

int []list = {
    presenceFront, presenceMiddle, presenceBack
};

int currentPos = -1;
int maxPresence =max(list);

// HERE WE NAME OUR CURRENT POSITION BASED ON PRESENCE VALUES
// LOTS OF LOGIC COMING UP!!!!
if (maxPresence < minimumPresence) {
    currentPos = NOTHING;
}
else if (maxPresence == presenceFront) {
    currentPos =ENTER;
}
else if (maxPresence == presenceMiddle) {
    currentPos = RECORDING;
}
else if (maxPresence == presenceBack) {
    currentPos = SOUND_PLAYBACK;
}

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if (currentPos == whereIsViewer) {
    // we haven't moved, so do nothing
    return;
}
// then do checks cause something changed
if (whereIsViewer == NOTHING) {
    if (currentPos ==ENTER) {
        whereIsViewer =ENTER;
        // nothing special happens here
    }
    else if (currentPos == RECORDING) {
        whereIsViewer = RECORDING;
        enteredRecordingArea();
    }
    else if ( currentPos == SOUND_PLAYBACK) {
        // this is an unusual situation .. it probably means that there was a tracking err
        enteredInvalidState();
    }
}
else if (whereIsViewer ==ENTER) {
    if (currentPos == NOTHING) {
        whereIsViewer = NOTHING;
        exited();
        // nothing special happens here
    }
    else if (currentPos == RECORDING) {
        whereIsViewer = RECORDING;
        enteredRecordingArea();
    }
    else if ( currentPos == SOUND_PLAYBACK) {
        // this is an unusual situation .. it probably means that there was a tracking err
        enteredInvalidState();
    }
}
else if (whereIsViewer == RECORDING) {
    if (currentPos == NOTHING) {
        whereIsViewer = NOTHING;
        exited();
        // nothing special happens here
    }
    else if (currentPos ==ENTER) {
        whereIsViewer =ENTER;
        /// ???????
    }
    else if ( currentPos == SOUND_PLAYBACK) {
        whereIsViewer = SOUND_PLAYBACK;
        enteredSoundPlayback();
    }
}
else if (whereIsViewer == SOUND_PLAYBACK) {
    if (currentPos == NOTHING) {

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        whereIsViewer = NOTHING;
        exited();
        // nothing special happens here
    }
    else if ( currentPos ==ENTER) {
        // we are leaving so ignore
        // it must have skipped recording.
        whereIsViewer =ENTER;
    }
    else if (currentPos == RECORDING) {
        whereIsViewer = RECORDING;
        // we are leaving so ignore
    }
}
}

void enteredRecordingArea() {
    println("ENTERED RECORDING AREA!~!!!!");
}

void enteredInvalidState() {
    //println("ENTERED INVALID STATE!!"); //though I could have it print that, it wouldn't
}

void exited() {
    println("EXITED!!");
    isRecording =false;
    currentPos = -1;
    whereIsViewer = NOTHING;
    lightsOn();
}

void enteredSoundPlayback() {
    lightsOff();
    println("ENTERED SOUND PLAYBACK AREA!~!!!!");
    setup();
}

void lightsOff() { //starts all of the things that we need to happen when the viewer ente
    port.write(0); //lights off
    println("LIGHTS OFF!!!!");
    OscMessage myMessage =new OscMessage("/play"); //sound on
    myMessage.add(1); // add an int to the osc message
    oscP5.send(myMessage, myRemoteLocation);
    println("SENT");
}

void lightsOn() { //does all of the "reseting" things that happen when the viewer leaves
    OscMessage myMessage =new OscMessage("/play"); //sound off
    myMessage.add(0); /* add an int to the osc message */
    oscP5.send(myMessage, myRemoteLocation);
}

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println("NO MORE SOUND");
port.write(255); //lights on
println("LIGHTS ON!!!!!!");
    resetBackground =true; //reset the background again, now that things have change and h
}

/* incoming osc message are forwarded to the oscEvent method. */
//just in case max wants to send us a message
void oscEvent(OscMessage theOscMessage) {
    /* print the address pattern and the typetag of the received OscMessage */
    print("### received an osc message.");
    print("  addrpattern: "+theOscMessage.addrPattern());
    println("  typetag: "+theOscMessage.typetag());
}

void quit() {
    kinect.quit();
}
}

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