

// ProceduralTerrain

For each vertex we:

1. Generate perlin noise
2. Shift the value range from 0 - 1 to -0.5 - 0.5
3. Determine the difference between the falloff value and the height value
4. Clamp that value between 0 and 1

```
frequency *= Lacunarity;
}

if (UseFalloffMap) {
    float falloff_00 = Mathf.PerlinNoise(x, z) - 0.5f;
    float falloff_01 = Mathf.PerlinNoise(x, z + 1f) - 0.5f;
    float falloff_10 = Mathf.PerlinNoise(x + 1f, z) - 0.5f;
    float falloff_11 = Mathf.PerlinNoise(x + 1f, z + 1f) - 0.5f;

    height00 -= Mathf.Clamp01(height00 - falloff_00) * 0.5f;
    height01 -= Mathf.Clamp01(height01 - falloff_01) * 0.5f;
    height10 -= Mathf.Clamp01(height10 - falloff_10) * 0.5f;
    height11 -= Mathf.Clamp01(height11 - falloff_11) * 0.5f;
}

int x0 = x * CellSize;
```

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```
frequency *= Lacunarity;  
}
```

```
if (UseFalloffMap) {  
    float falloff_00 = Mathf.PerlinNoise(x, z) - 0.5f;  
    float falloff_01 = Mathf.PerlinNoise(x, z + 1f) - 0.5f;  
    float falloff_10 = Mathf.PerlinNoise(x + 1f, z) - 0.5f;  
    float falloff_11 = Mathf.PerlinNoise(x + 1f, z + 1f) - 0.5f;  
  
    height00 -= Mathf.Clamp01(height00 - falloff_00) * 0.5f;  
    height01 -= Mathf.Clamp01(height01 - falloff_01) * 0.5f;  
    height10 -= Mathf.Clamp01(height10 - falloff_10) * 0.5f;  
    height11 -= Mathf.Clamp01(height11 - falloff_11) * 0.5f;  
}
```

```
int x0 = x * CellSize;
```

For each vertex we:

1. Generate perlin noise
2. Shift the value range from 0 - 1 to -0.5 - 0.5
3. Determine the difference between the falloff value and the height value
4. Clamp that value between 0 and 1
5. Half the clamped value