// MinTuts/Procedural Terrain.shader

```
Shader "MinTuts/Procedural Terrain" {
  SubShader {
    Pass {
      CGPROGRAM

        #pragma vertex   vert
        #pragma fragment frag

        #include "UnityCG.cginc"

        struct v2f {
          float4 pos  : SV_POSITION;
          float3 wpos : POSITION1;
        };

        v2f vert(float4 vertex : POSITION) {
          v2f o;

          o.pos  = UnityObjectToClipPos(vertex);
          o.wpos = mul(unity_ObjectToWorld, vertex);

          return o;
        }

        float4 frag(v2f i) : COLOR {
          float  p = i.wpos.y * 0.015;
          float3 y = float3(p, p, p);

          return float4(y, 1);
        }

      ENDCG
    }
  }
}
```

Here we are defining a data structure

This data structure is named **v2f**; which is short for *vertex2fragment*

It has two properties; **pos** (*of type* ***float4***) and **wpos** (*of type* ***float3***)

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These properties have **semantic**s along with their types

The best way to think about **semantic**s is as a *filter on top of a type*

For example: **pos** has a type of **float4** with a **semantic** filter of **SV_POSITION**
The **semantic** meaning of **SV_POSITION** is: *clip space position*, or where the *current* **vertex** is located *relative to the cameras field of view*
Another example: **wpos** has a type of **float3** with a **semantic** filter of **POSITION1**
The **semantic** meaning of **POSITION1** is: *world space position*, or where the *current* **vertex** is located *in the world*