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Seungjae Baek

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EDUCATION

Carnegie Mellon University

Pittsburgh, PA

Visiting graduate student in School of Computer Science

Aug. 2024 - Feb. 2025

Collaborator: Sebastian Scherer

Ulsan National Institute of Science and Technology

Ulsan, Korea

M.S. in Artificial Intelligence

Aug. 2023 - Feb. 2026 (exp.)

Advisor: Jeong hwan Jeon Cumulative GPA: $4.0/4.0^{1}$ B.S. in Electrical Engineering

Feb. 2017 - Aug. 2023²

Cumulative GPA: 3.51/4.0¹, Major GPA: 3.63/4.0¹, Advanced GPA: 3.76/4.0¹

 $Graduated\ Cum\ Laude$

B.S. Thesis: Applying VDN and QMIX in SMAC: A Multi-Agent Reinforcement Learning study

RESEARCH INTERESTS

Planning Informative Path Planning (IPP), Motion Planning

 ${\bf Reinforcement\ Learning} \qquad \qquad {\rm Model\text{-}Free\ Learning,\ Multi\text{-}Agent\ Reinforcement\ Learning\ (MARL)}$

Autonomous System Unmanned Aerial Vehicles (UAVs), Autonomous Vehicles (AVs)

PUBLICATIONS

Journals

1. Kangbeen Lee*, **Seungjae Baek***, Philjoon Jung, Tae-Hyun Kim, Jeong hwan Jeon[†]
Cooperative Multi-Agent Reinforcement Learning for Multiple Anti-Aircraft Target Surveillance

Journal of Institute of Control, Robotics and Systems, 30(6), 587-595, 10.5302/J.ICROS.2024.24.0009

Preprints

1. **Seungjae Baek***, Brady Moon*, Seungchan Kim*, Muqing Cao, Cherie Ho, Sebastian Scherer, Jeong hwan Jeon

PIPE Planner: Pathwise Information Gain with Map Predictions for Large Indoor Exploration

Submitted to 2025 International Conference on Intelligent Robots and System (IROS) arXiv:2503.07504

Manuscripts in preparation

Jungeun Lee*, Seungjae Baek*, Jeong hwan Jeon
 Deep Reinforcement Learning based Autonomous Ride-Sharing System

¹ GPA converted from a 4.3 scale to a 4.0 scale for standardization.

² Including mandatory military service, Republic of Korea Army, Feb. 2020 - Sep. 2021

^{*} Equal contributions

RESEARCH EXPERIENCES

Carnegie Mellon University

AirLab

Visiting Researcher Aug. 2024 - Feb. 2025

- Developed an algorithm which optimize indoor exploration via path-wise information gain from predicted global maps
- Participating AirStack, a project for end-to-end multi-drone 3D exploration simulation

Ulsan National Institute of Science and Technology

Robotics & Mobility Lab

Graduate Research Assistant

Ulsan, Korea

Pittsburgh, PA

Aug. 2023 - Present

- Developed multi-agent reinforcement learning algorithms for cooperative control of UAVs
- Conducting experiments and simulations for multi-objective ride-sharing RL algorithms with Python

Undergraduate Research Assistant

Jul. 2022 - Aug. 2023

- Adapted CTDE (Centralized Training Decentralized Execution) MARL method in video game simulations
- Developed and conducted Python experiments using the CARLA AV simulator

TEACHING & WORKING EXPERIENCES

Ulsan National Institute of Science and Technology

ITP117: Introduction to AI Programming II, Head Teaching Assistant

Ulsan, Korea Feb. 2024 - Jul. 2024

- Assisted in teaching a course with 120 students alongside 4 other teaching assistants
- Lectured on MLP, CNN and RNN using Tensorflow and Pytorch in English

EEE351: Automatic Control, Student Lecturer of AFEE

Aug. 2022 - Dec. 2022

- AFEE is an official student organization under the Electrical Engineering at UNIST
- Organized and facilitated group study sessions for both domestic and international students

Clinomics Inc.

Project Based Learning (PBL) Teaching Assistant

Ulsan, Korea

Feb. 2023 - Jul. 2023

- Supported a project collaborating with office workers to integrate AI solutions into their workflows
- $\bullet~$ Using AnoGAN and VAE to generate hypothetical disease-associated DNA methylation data

ACHIEVEMENTS

Honors

• AI Excellence Global Innovative Leader Education Fellowship (total \$40,000) Sogang University & Ministry of Science and ICT, The Government of the Republic of Korea

Aug. 2024 - Feb. 2025

- Government-funded Graduate Scholarship (Full-funded)
 Ministry of Science and ICT, The Government of the Republic of Korea
- Ministry of Science and ICT, The Government of the Republic of Korea
 UNIST Academic Performance Scholarship (4-Year Full-funded)

Aug. 2023 - Present

Ulsan National Institute of Science and Technology

Feb. 2017 - Aug. 2023

Awards

• Undergraduate Research Excellent Poster Session Award
Department of Electrical Engineering, Ulsan National Institute of Science and Technology

Jul. 2023

SKILLS & SERVICES

Languages

 \cdot Korean: Native

· English: Advanced (TOEFL: 106 of 120, Reading: 28, Listening: 29, Speaking: 24, Writing: 25)

 $\textbf{Programming Languages: } C++, \ Python \\$

 $\textbf{Software and Tools:} \ \text{MATLAB, ROS, Git, Docker, CARLA, SUMO, NVIDIA Isaac-sim, PyTorch, Tensorflowng and Tools:} \ \text{MATLAB, ROS, Git, Docker, CARLA, SUMO, NVIDIA Isaac-sim, PyTorch, Tensorflowng and Tools:} \ \text{MATLAB, ROS, Git, Docker, CARLA, SUMO, NVIDIA Isaac-sim, PyTorch, Tensorflowng and Tools:} \ \text{MATLAB, ROS, Git, Docker, CARLA, SUMO, NVIDIA Isaac-sim, PyTorch, Tensorflowng and Tools:} \ \text{MATLAB, ROS, Git, Docker, CARLA, SUMO, NVIDIA Isaac-sim, PyTorch, Tensorflowng and Tools:} \ \text{MATLAB, ROS, Git, Docker, CARLA, SUMO, NVIDIA Isaac-sim, PyTorch, Tensorflowng and Tools:} \ \text{MATLAB, ROS, Git, Docker, CARLA, SUMO, NVIDIA Isaac-sim, PyTorch, Tensorflowng and Tools:} \ \text{MATLAB, ROS, Git, Docker, CARLA, SUMO, NVIDIA Isaac-sim, PyTorch, Tensorflowng and Tools:} \ \text{MATLAB, ROS, Git, Docker, CARLA, SUMO, NVIDIA Isaac-sim, PyTorch, Tensorflowng and Tools:} \ \text{MATLAB, ROS, Git, Docker, CARLA, SUMO, NVIDIA Isaac-sim, PyTorch, Tensorflowng and Tools:} \ \text{MATLAB, ROS, Git, Docker, CARLA, SUMO, NVIDIA Isaac-sim, PyTorch, Tensorflowng and Tools:} \ \text{MATLAB, ROS, Git, Docker, CARLA, SUMO, NVIDIA Isaac-sim, PyTorch, Tensorflowng and Tools:} \ \text{MATLAB, ROS, Git, Docker, CARLA, SUMO, NVIDIA Isaac-sim, PyTorch, Tensorflowng and Tools:} \ \text{MATLAB, ROS, Git, Docker, CARLA, SUMO, NVIDIA Isaac-sim, PyTorch, Tensorflowng and Tools:} \ \text{MATLAB, PyTorch, Tensorflowng and Tools:} \ \text{MATLAB, PyTorch, Tensorflowng and Tensorflowng$

Reviewer: IROS (2025)