

BEOMSEOK KIM

“Pursue Relentless Improvement”

Master of Science in Engineering
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Education

- **M.S., Mechanical Engineering (Specialization: Autonomous Driving)** *Apr 2023 – Mar 2025*
The University of Tokyo, Tokyo, Japan
GPA: 3.7/4.0
Academic Advisor: Prof. Kimihiko Nakano
- **B.S., Mechanical Engineering** *Mar 2016 – Feb 2022*
Soongsil University, Seoul, Korea
GPA: 4.0/4.5 (**Magna cum laude**)
Academic Advisor: Prof. Hyeongjoon Ahn

Research Interest

As someone deeply passionate about establishing a pervasive **Shared Environment** where humans and various autonomous systems—including automated vehicles, robots and intelligent infrastructures—interact harmoniously, I have been interested in **Autonomous Driving (AD)**, **Connected and Automated Vehicles (CAV)** and **Artificial Intelligence** to achieve this vision. My work has centered on **perception** and **decision-making**. Recently, I've been particularly interested in **End-to-End (E2E) driving**, putting a lot of effort into gaining expertise and hands-on experience in both the academic and industrial sectors.

Keywords: Autonomous Driving, Connected and Automated Vehicles, Artificial Intelligence

Research and Working Experience

- **Software Engineering Intern, TIER IV, Tokyo, Japan** *Dec 2024 – May 2025*
End-to-End Driving
 - Survey and inference of state-of-the-art E2E driving models
- **Software Engineering Intern, BOSCH, Tokyo, Japan** *Apr 2023 – Mar 2024*
Automated Valet Parking System
 - Enhanced Depth Estimation for Stereo Vision Using Disparity Maps from Diverse Floor Patterns
 - Path-Planning using A* and Artificial Potential Field
 - Preliminary Field Implementation in the Commercial Sector at Haneda Airport Parking Area, Tokyo
- **Graduate Researcher, The University of Tokyo, Japan** *Apr 2023 – Mar 2025*

Nakano Lab (Intelligent Transportation System Lab)

Perception and Decision-Making

- Salient Object Detection for Autonomous Driving: Identifying and Prioritizing Crucial Objects Using Salient Object Detection to Enhance Decision-Making
- End-to-End driving to Avoid Parked Vehicles on Two-Lane, Two-Way Roads
- Deep Learning-based Pedestrian Trajectory Prediction for Autonomous Tram

- **Internship Student, The University of Tokyo, Japan**
Nakano Lab (Intelligent Transportation System Lab)

Apr 2022 – Mar 2023

Decision-Making for Autonomous Driving

- Decision-Making to Avoid Parked Vehicles on Two-Lane, Two-Way Roads for Autonomous Bus

- **Undergraduate Researcher, Soongsil University, Korea**
Intelligent Mechatronics System Lab

Sep 2020 – Feb 2022

Control Systems

- Development of Affordable and User-Friendly Inverted Pendulum Control Kits for Undergraduate Students
- Prediction of Performance Metrics for Precision Reducers by Measuring Noncontact Tooth Profiles and Analyzing Three-Dimensional Tooth Engagement

Other Professional Experience

- **Republic of Korea Army (ROKA), Korea**
Sergeant, Auxiliary Police Officer, Suseo Police Station
- **Teaching Assistant, Soongsil University, Korea**
Subject: **Mechatronics**
Responsibilities: Assisted in grading, tutoring, and lecture preparation
- **Teaching Assistant, The University of Tokyo, Japan**
Subject: **Mathematics 2B**
Responsibilities: Assisted in grading and lecture preparation

Aug 2017 – Apr 2019

Mar 2021 – June 2021

Apr 2024 – July 2024

Publication and Conference

- [1] **Beom-Seok Kim**, Seung-Tae Jeong, and Hyeong-Joon Ahn. "The prediction of the angular transmission error of a harmonic drive by measuring noncontact tooth profile and considering three-dimensional tooth engagement." International Journal of Precision Engineering and Manufacturing 24.3 (2023): 371-378.
<https://doi.org/10.1007/s12541-022-00760-w>
- [2] **Beomseok Kim**, Nelson Changgraini, and Kimihiko Nakano. "Leveraging Saliency Prediction to Enhance Behavioral Decision-Making for Parked Vehicle Avoidance on Two-Lane Two-Way Roads." Transportation and Logistics Division Conference, Tokyo, Japan (2024)

Skills and Languages

- **Programming:** Python, C++, Matlab
- **AI / ML Tools:** PyTorch, TensorFlow, ONNX, TensorRT
- **Languages:** Korean (Native), English (Fluent), Japanese (Fluent)

Award and Honor

- Half Tuition Fee Scholarship for Academic Excellence *Fall Semester 2016*
- Half Tuition Fee Scholarship for Academic Excellence *Spring Semester 2020*
- A Bronze Prize in the Hyungnam Science Award in Soongsil University *Fall Semester 2020*
- Japanese Government (Monbukagakusho: MEXT) Scholarship Student *Apr 2022 – Mar 2025*

External Online Coursework

- Self-Driving Cars Specialization: Faculty of Applied Science and Engineering, University of Toronto
- Deep Learning Specialization: Prof. Andrew NG, Stanford University
- Machine Learning Specialization: Prof. Andrew NG, Stanford University

Reference

- **Prof. Kimihiko Nakano, Ph.D.**
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