# **Newton Method Computation**

Training Sample:

$$\begin{array}{c} x = 2 \\ y = 200 \end{array}$$

Parameters:

$$egin{array}{l} w_1=3\ w_2=5\ w_3=7 \end{array}$$

$$w_2 = 3$$
  
 $w_3 = 7$ 

All activation functions are linear:

$$\phi_k(x) = x$$

Squared error is used as a loss function:

$$L(y,\hat{y}) = (y - \hat{y})^2$$

## **Forward Propagation**

First, forward values are computed, storing intermediate values for use during backpropagation.

$$a_1 = xw_1 = 6$$

$$h_1 = \phi_1(a_1) = 3$$

$$a_2 = h_1w_2 = 30$$

$$h_2 = \phi_2(a_2) = 30$$

$$a_3 = h_2w_3 = 210$$

$$h_3 = \phi_3(a_3) = 210$$

$$L = (y - h_3)^2 = 100$$

## **Backpropagation**

Next, first- and second-order derivatives are computed from the loss function backwards, starting with the seed the value of 1. All first and second order derivatives are stored for use in future computations.

#### Layer 3

$$\frac{\partial L}{\partial L} = 1, \frac{\partial^2 L}{\partial L^2} = 1$$

$$rac{\partial L}{\partial h_3} = 2(h_3 - y) = 20$$

• Look-up the derivative of the loss function and evaluate at the point  $h_3=210$ .

$$\frac{\partial^2 L}{\partial h_3^2}=2$$

• Look-up second-order derivative of the loss function and evaluate at the point  $h_3=210$ . Here, the second order derivative is constant, because the loss function is quadratic.

$$\frac{\partial L}{\partial a_3} = \frac{\partial h_3}{\partial a_3} \frac{\partial L}{\partial h_3} = 1 \cdot 20 = 20$$

- Compute the local derivative  $\frac{\partial h_3}{\partial a_3}$  by looking up the derivative of  $\phi_3$  and evaluating it at the point  $a_3$ .
- Multiply by the previously computed value  $\frac{\partial L}{\partial h_2}$ .

$$rac{\partial^2 L}{\partial a_3^2} = \left(rac{\partial h_3}{\partial a_3}
ight)^2 rac{\partial^2 L}{\partial h_3^2} + rac{\partial^2 h_3}{\partial a_3^2} rac{\partial L}{\partial h_3} = 1^2 \cdot 2 = 2$$

• We just computed the local derivative  $\frac{\partial h_3}{\partial a_3}$ , multiply the same value by the previously computed value  $\frac{\partial^2 L}{\partial h_2^2}$ 

• The term  $\frac{\partial^2 h_3}{\partial a_3^2}$  is the second-order local derivative of the activation function  $\phi_k$ . In this example,  $\phi_k$  is linear, so the second-order derivative is always 0. Future expressions will omit this term.

$$\frac{\partial L}{\partial w_3} = \frac{\partial a_3}{\partial w_3} \frac{\partial L}{\partial a_3} = 30 \cdot 20 = 600$$

- Compute the local derivative  $\frac{\partial a_3}{\partial w_3}$  by looking up the forward propagated value  $h_2$ .  $a_3=w_3h_2$  so the local first order derivative is just  $h_2$
- Multiply by the previously computed value  $\frac{\partial L}{\partial a_3}$

$$\frac{\partial^2 L}{\partial w_2^2} = \left(\frac{\partial a_3}{\partial w_3}\right)^2 \frac{\partial^2 L}{\partial a_2^2} + \frac{\partial^2 a_3}{\partial w_2^2} \frac{\partial L}{\partial a_3} = h_2^2 \frac{\partial^2 L}{\partial a_2^2} = 30^2 \cdot 2 = 1800$$

- $\frac{\partial^2 a_3}{\partial w_2^2}$  is the local second order derivative of the linear function  $w_3h_2$ , which is always 0.
- We just computed  $\frac{\partial a_3}{\partial w_3}$ , multiply this by the previously computed  $\frac{\partial^2 L}{\partial a_3^2}$ .

#### Layer 2

$$\frac{\partial L}{\partial h_2} = \frac{\partial a_3}{\partial h_2} \frac{\partial L}{\partial a_3} = 7 \cdot 20 = 140$$

- The local derivative  $\frac{\partial a_3}{\partial h_2}$  is the weight of the edge,  $w_3$ .
- As above, compute the local derivative, multiply by the accumulated derivative

$$\frac{\partial^2 L}{\partial h_2^2} = \left(\frac{\partial a_3}{\partial h_2}\right)^2 \frac{\partial^2 L}{\partial a_2^2} + \frac{\partial^2 a_3}{\partial h_2^2} \frac{\partial L}{\partial a_3} = 7^2 \cdot 2 = 98$$

- The local derivative  $\frac{\partial a_3}{\partial h_2}$  was just computed, multiply it by the accumulated second-order derivative.
- The second order local derivative  $\frac{\partial^2 a_3}{\partial h_2^2}$  is always zero, as we are crossing a linear function.

$$\frac{\partial L}{\partial a_2} = \frac{\partial h_2}{\partial a_2} \frac{\partial L}{\partial h_2} = 1 \cdot 140 = 140$$

· Zero term is omitted as explained above.

$$\frac{\partial^2 L}{\partial a_2^2} = \left(\frac{\partial h_2}{\partial a_2}\right)^2 \frac{\partial^2 L}{\partial h_2^2} = 1^2 \cdot 98 = 98$$

· Zero term also omitted as explained above.

$$\frac{\partial L}{\partial w_2} = \frac{\partial a_2}{\partial w_2} \frac{\partial L}{\partial a_2} = 6 \cdot 140 = 840$$

· Same pattern as above, multiply the local derivative by the previously computed value.

$$\frac{\partial^2 L}{\partial w_2^2} = \left(\frac{\partial a_2}{\partial w_2}\right)^2 \frac{\partial^2 L}{\partial a_2^2} = 6^2 \cdot 98 = 3528$$

- · Zero term also omitted as explained above.
- Reusing already computed local derivative and previously computed second-order derivative.

$$rac{\partial^2 L}{\partial w_3 \partial w_2} = rac{\partial h_2}{\partial w_2} rac{\partial L}{\partial a_3} + rac{\partial a_3}{\partial w_3} rac{\partial a_3}{\partial w_2} rac{\partial^2 L}{\partial a_3^2} = 6 \cdot 20 + 30 \cdot 42 \cdot 2 = 2640$$

- The first "bridge" term  $\frac{\partial h_2}{\partial w_2} = \frac{\partial a_2}{\partial w_2} \frac{\partial h_2}{\partial a_2}$  is a product of local derivatives we previously computed.
- $\frac{\partial a_3}{\partial w_3} = h_2$  is looked up from previously computed forward values.
- $\frac{\partial a_3}{\partial w_2} = \frac{\partial a_2}{\partial w_2} \frac{\partial h_2}{\partial a_2} \frac{\partial a_3}{\partial h_2}$  is product of previously computed values, a "bridge" term between the positions of  $w_1$  and  $w_2$ .

•  $\frac{\partial^2 L}{\partial a_z^2}$  is a previously computed second order derivative.

#### Layer 1

All computations follow the same pattern as above, computing additional terms and multiplying them be previously computed values.

$$\begin{split} \frac{\partial L}{\partial h_1} &= \frac{\partial a_2}{\partial h_1} \frac{\partial L}{\partial a_2} = 5 \cdot 140 = 700 \\ \frac{\partial^2 L}{\partial h_1^2} &= \left(\frac{\partial a_2}{\partial h_1}\right)^2 \frac{\partial L}{\partial a_2^2} = 5^2 \cdot 98 = 2450 \\ \frac{\partial L}{\partial a_1} &= \frac{\partial h_1}{\partial a_1} \frac{\partial L}{\partial h_1} = 1 \cdot 700 = 700 \\ \frac{\partial^2 L}{\partial a_1^2} &= \left(\frac{\partial h_1}{\partial a_1}\right)^2 \frac{\partial^2 L}{\partial h_1^2} = 1^2 \cdot 2450 = 2450 \\ \frac{\partial L}{\partial w_1} &= \frac{\partial a_1}{\partial w_1} \frac{\partial L}{\partial a_1} = 2 \cdot 700 = 1400 \\ \frac{\partial^2 L}{\partial w_1^2} &= \left(\frac{\partial a_1}{\partial w_1}\right)^2 \frac{\partial^2 L}{\partial a_1^2} = 2^2 \cdot 2450 = 9800 \end{split}$$

$$\frac{\partial^2 L}{\partial w_2 \partial w_1} = \frac{\partial h_1}{\partial w_1} \frac{\partial L}{\partial a_2} + \frac{\partial a_2}{\partial w_2} \frac{\partial a_2}{\partial w_1} \frac{\partial^2 L}{\partial a_2^2} = 2 \cdot 140 + 6 \cdot 10 \cdot 98 = 6160$$

$$\frac{\partial^2 L}{\partial w_3 \partial w_1} = \frac{\partial h_2}{\partial w_1} \frac{\partial L}{\partial a_3} + \frac{\partial a_3}{\partial w_3} \frac{\partial a_3}{\partial w_1} \frac{\partial^2 L}{\partial a_3^2} = 10 \cdot 20 + 30 \cdot 70 \cdot 2 = 4400$$

• Here the bridge terms  $\frac{\partial h_2}{\partial w_1}$  and  $\frac{\partial a_3}{\partial w_1}$  are longer because they span from the first layer to the third, but still consist of previously computed values.

## Output

We have now computed the lower triangle of the Hessian matrix and may fill in the remaining entries by symmetry.

$$H_{L} = \begin{bmatrix} \frac{\partial L^{2}}{\partial w_{1}^{2}} & \frac{\partial L^{2}}{\partial w_{1} \partial w_{2}} & \frac{\partial L^{2}}{\partial w_{1} \partial w_{3}} \\ \frac{\partial L^{2}}{\partial w_{2} \partial w_{1}} & \frac{\partial L^{2}}{\partial w_{2}^{2}} & \frac{\partial L^{2}}{\partial w_{2} \partial w_{3}} \\ \frac{\partial L^{2}}{\partial w_{3} \partial w_{1}} & \frac{\partial L^{2}}{\partial w_{3} \partial w_{2}} & \frac{\partial L^{2}}{\partial w_{3}^{2}} \end{bmatrix} = \begin{bmatrix} 9800 & 6160 & 4400 \\ 6160 & 3528 & 2640 \\ 4400 & 2640 & 1800 \end{bmatrix}$$

The algorithm returns the first-order derivatives and the Hessian matrix of second-order derivatives for use in gradient descent.