Big Data Analytics

Learning theory

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Error measures and noisy targets

The bias and variance tradeoff

Learning curves

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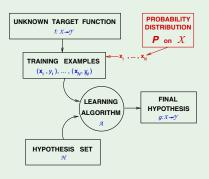
Error measures and noisy targets

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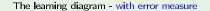
Learning diagram

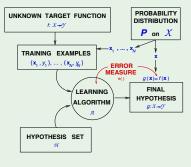
The learning diagram - where we left it



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Learning diagram (with error measure)





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How to choose the error measure?

How to choose the error measure

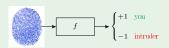
Fingerprint verification:

Two types of error:

false accept and false reject

How do we penalize each type?





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The supermarket example

The error measure - for supermarkets

Supermarket verifies fingerprint for discounts

False reject is costly; customer gets annoyed!

False accept is minor; gave away a discount and intruder left their fingerprint $\ \odot$



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The CIA example

The error measure - for the CIA

CIA verifies fingerprint for security

False accept is a disaster!

False reject can be tolerated
Try again; you are an employee ③

$$\begin{array}{c|ccccc} & & f \\ & +1 & -1 \\ \hline h & +1 & 0 & 1000 \\ -1 & 1 & 0 \\ \end{array}$$



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Noisy targets

Noisy targets

The 'target function' is not always a function

Consider the credit-card approval:

age	23 years
annual salary	\$30,000
years in residence	1 year
years in job	1 year
current debt	\$15,000

two 'identical' customers \longrightarrow two different behaviors

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Target distribution

Target 'distribution'

Instead of $y = f(\mathbf{x})$, we use target distribution:

$$P(y \mid \mathbf{x})$$

 (\mathbf{x}, y) is now generated by the joint distribution:

$$P(\mathbf{x})P(y \mid \mathbf{x})$$

Noisy target = deterministic target $f(\mathbf{x}) = \mathbb{E}(y|\mathbf{x})$ plus noise $y - f(\mathbf{x})$

Deterministic target is a special case of noisy target:

$$P(y \mid \mathbf{x})$$
 is zero except for $y = f(\mathbf{x})$

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Final learning diagram

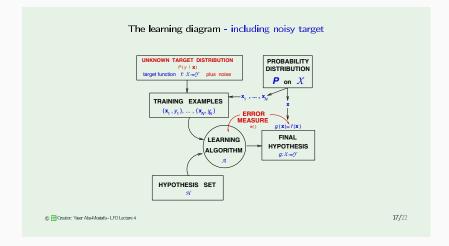


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In-sample and out-of-sample errors

Consider

$$f = \underset{h: \mathcal{X} \to \mathcal{Y}}{\operatorname{argmin}} E_{\operatorname{out}}(h),$$

$$g^* = \underset{h \in \mathcal{H}}{\operatorname{argmin}} E_{\operatorname{out}}(h),$$

and

$$g = \underset{h \in \mathcal{H}}{\operatorname{argmin}} E_{\operatorname{in}}(h).$$

Approximation-generalization tradeoff

The difference between the out-of-sample error of g and f can be decomposed as follows

$$E_{\text{out}}(g) - E_{\text{out}}(f) = \underbrace{\left[E_{\text{out}}(g^*) - E_{\text{out}}(f)\right]}_{\text{Approximation error}} + \underbrace{\left[E_{\text{out}}(g) - E_{\text{out}}(g^*)\right]}_{\text{Estimation error}}$$

- Approximation error is how far the entire hypothesis set is from f. Larger hypothesis sets have lower approximation error.
- **Estimation error** is how good *g* is with respect to the best in the hypothesis set. Larger hypothesis sets have higher estimation error because it is harder to find a good prediction function based on limited data.

This is called the **approximation-generalization** tradeoff.

Quantifying the approximation-generalization tradeoff

The VC analysis is one approach to quantify the tradeoff:

- $d_{VC} \uparrow \Longrightarrow$ better chance of **approximating** $f(E_{in} \approx 0)$
- $d_{VC} \downarrow \Longrightarrow$ better chance of **generalizing** to out-of-sample $(E_{\rm in} \approx E_{\rm out})$

The VC analysis uses binary errors (classification).

The VC analysis only depends on \mathcal{H} (through d_{VC}):

$$E_{\rm out} \leq E_{\rm in} + \Omega(d_{\rm VC})$$

 \implies Independent of the target function f, the input distribution p(x) and the learning algorithm \mathcal{A} .

Quantifying the approximation-generalization tradeoff

The **bias-variance** analysis approach is another way to quantify the tradeoff:

- How well can the learning approximate f
 - ... as opposed to how well **did** the learning approximate f in-sample (E_{in})
- How close can you get to that approximation with a finite data set
 - ... as opposed to how close is E_{in} to E_{out}

The bias-variance analysis applies to **squared errors** (classification and regression).

The bias-variance analysis can take into account the **learning** algorithm \mathcal{A} .

 Different learning algorithms can have different E_{out} when applied to the same H!

Bias and variance decomposition

Start with E_{out}

$$E_{\mathrm{Out}}(g^{(\mathcal{D})}) = \mathbb{E}_{\mathbf{x}} \Big[\big(g^{(\mathcal{D})}(\mathbf{x}) - f(\mathbf{x}) \big)^2 \Big]$$

$$\mathbb{E}_{\mathcal{D}}\left[E_{\text{out}}(g^{(\mathcal{D})})\right] = \mathbb{E}_{\mathcal{D}}\left[\mathbb{E}_{\mathbf{x}}\left[\left(g^{(\mathcal{D})}(\mathbf{x}) - f(\mathbf{x})\right)^{2}\right]\right]$$
$$= \mathbb{E}_{\mathbf{x}}\left[\mathbb{E}_{\mathcal{D}}\left[\left(g^{(\mathcal{D})}(\mathbf{x}) - f(\mathbf{x})\right)^{2}\right]\right]$$

Now, let us focus on:

$$\mathbb{E}_{\mathcal{D}}\left[\left(g^{(\mathcal{D})}(\mathbf{x}) - f(\mathbf{x})
ight)^2
ight]$$

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The average hypothesis

The average hypothesis

To evaluate
$$\mathbb{E}_{\mathcal{D}}\left[\left(g^{(\mathcal{D})}(\mathbf{x})-f(\mathbf{x})\right)^2
ight]$$

we define the 'average' hypothesis $\bar{g}(\mathbf{x})$:

$$\bar{g}(\mathbf{x}) = \mathbb{E}_{\mathcal{D}}\left[g^{(\mathcal{D})}(\mathbf{x})\right]$$

Imagine **many** data sets $\mathcal{D}_1, \mathcal{D}_2, \cdots, \mathcal{D}_K$

$$\bar{g}(\mathbf{x}) \approx \frac{1}{K} \sum_{k=1}^{K} g^{(\mathcal{D}_k)}(\mathbf{x})$$

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Using the average hypothesis

Using $\bar{g}(\mathbf{x})$

$$\mathbb{E}_{\mathcal{D}}\left[\left(g^{(\mathcal{D})}(\mathbf{x}) - f(\mathbf{x})\right)^{2}\right] = \mathbb{E}_{\mathcal{D}}\left[\left(g^{(\mathcal{D})}(\mathbf{x}) - \bar{g}(\mathbf{x}) + \bar{g}(\mathbf{x}) - f(\mathbf{x})\right)^{2}\right]$$

$$= \mathbb{E}_{\mathcal{D}}\left[\left(g^{(\mathcal{D})}(\mathbf{x}) - \bar{g}(\mathbf{x})\right)^{2} + \left(\bar{g}(\mathbf{x}) - f(\mathbf{x})\right)^{2} + 2\left(g^{(\mathcal{D})}(\mathbf{x}) - \bar{g}(\mathbf{x})\right)\left(\bar{g}(\mathbf{x}) - f(\mathbf{x})\right)\right]$$

$$= \mathbb{E}_{\mathcal{D}}\left[\left(g^{(\mathcal{D})}(\mathbf{x}) - \bar{g}(\mathbf{x})\right)^{2} + \left(\bar{g}(\mathbf{x}) - f(\mathbf{x})\right)^{2}\right]$$

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Bias and variance

Bias and variance

$$\begin{split} \mathbb{E}_{\mathcal{D}}\left[\left(g^{(\mathcal{D})}(\mathbf{x}) - f(\mathbf{x})\right)^2\right] &= \underbrace{\mathbb{E}_{\mathcal{D}}\left[\left(g^{(\mathcal{D})}(\mathbf{x}) - \bar{g}(\mathbf{x})\right)^2\right]}_{\text{var}(\mathbf{x})} + \underbrace{\left(\bar{g}(\mathbf{x}) - f(\mathbf{x})\right)^2}_{\text{bias}(\mathbf{x})} \end{split}$$
 Therefore,
$$\mathbb{E}_{\mathcal{D}}\left[E_{\text{out}}(g^{(\mathcal{D})})\right] = \mathbb{E}_{\mathbf{x}}\left[\mathbb{E}_{\mathcal{D}}\left[\left(g^{(\mathcal{D})}(\mathbf{x}) - f(\mathbf{x})\right)^2\right]\right]$$

$$= \mathbb{E}_{\mathbf{x}}[\text{bias}(\mathbf{x}) + \text{var}(\mathbf{x})]$$

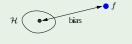
$$= \text{bias} + \text{var}$$

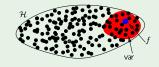
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Bias and variance tradeoff

The tradeoff

$$\mathrm{bias} = \mathbb{E}_{\mathbf{x}} \left[\left(\bar{g}(\mathbf{x}) - f(\mathbf{x}) \right)^2 \right] \qquad \qquad \mathrm{var} = \mathbb{E}_{\mathbf{x}} \left[\left. \mathbb{E}_{\mathcal{D}} \left[\left(g^{(\mathcal{D})}(\mathbf{x}) - \bar{g}(\mathbf{x}) \right)^2 \right] \right]$$





 \downarrow

 $\mathcal{H} \uparrow$



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Example: sine target

Example: sine target

$$f:[-1,1] \to \mathbb{R}$$
 $f(x) = \sin(\pi x)$

Only two training examples! $\qquad N=2$

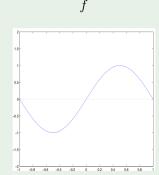
Two models used for learning:

$$\mathcal{H}_0$$
: $h(x) = b$

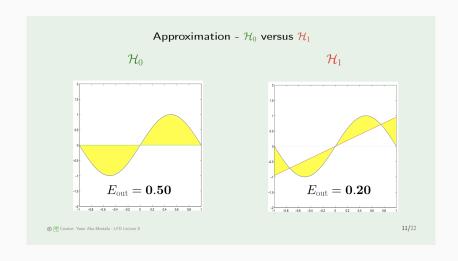
$$\mathcal{H}_1$$
: $h(x) = ax + b$

Which is better, \mathcal{H}_0 or \mathcal{H}_1 ?

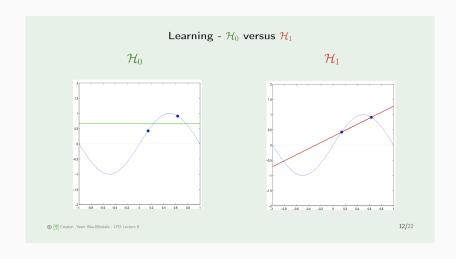
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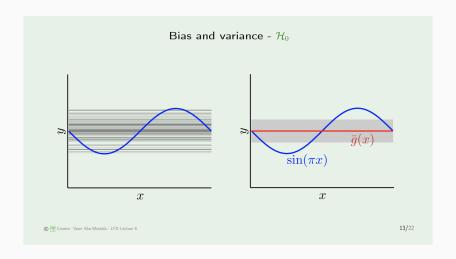
Example: Approximation



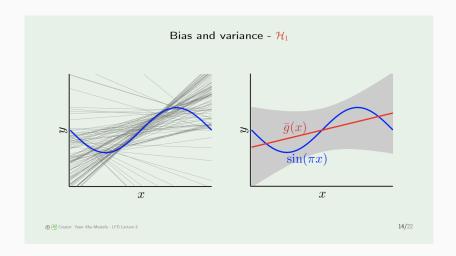
Example: Learning



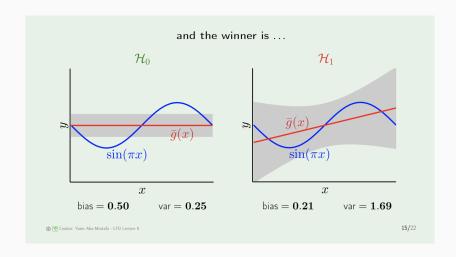
Example: Bias and variance



Example: Bias and variance



Example: Bias and variance tradeoff



Lesson learned

Lesson learned

Match the 'model complexity'

to the data resources, not to the target complexity

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Expected E_{out} and E_{in}

Data set \mathcal{D} of size N

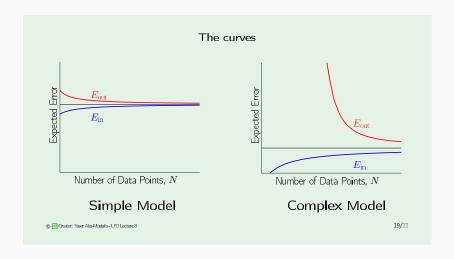
Expected out-of-sample error $\mathbb{E}_{\mathcal{D}}[E_{\mathrm{out}}(g^{(\mathcal{D})})]$

Expected in-sample error $\mathbb{E}_{\mathcal{D}}[E_{\mathrm{in}}(g^{(\mathcal{D})})]$

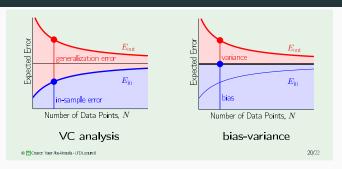
How do they vary with N?

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Learning curves



VC versus bias-variance analysis



- VC^1 : Pick \mathcal{H} that can generalize and has a good chance to fit the data.
- **Bias-variance**²: Pick $(\mathcal{H}, \mathcal{A})$ to approximate f and not behave wildly.

 $^{^1}$ We take the expected values of all quantities with respect to ${\cal D}$ of size ${\it N}.$

²we assume, for every N, the average learned hypothesis \bar{g} has the same performance as the best approximation to f in the learning model.

Linear regression case

Linear regression case

Noisy target
$$y = \mathbf{w}^{*\mathsf{T}}\mathbf{x} + \mathsf{noise}$$

Data set
$$\mathcal{D} = \{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N)\}$$

Linear regression solution: $\mathbf{w} = (X^TX)^{-1}X^T\mathbf{y}$

In-sample error vector $= X\mathbf{w} - \mathbf{y}$

'Out-of-sample' error vector $= X\mathbf{w} - \mathbf{y}'$

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Learning curves for linear regression

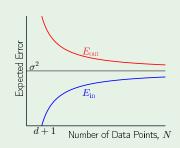
Learning curves for linear regression

Best approximation error $=\sigma^2$

Expected in-sample error $=\sigma^2\left(1-\frac{d+1}{N}\right)$

Expected out-of-sample error = $\sigma^2\left(1+\frac{d+1}{N}\right)$

Expected generalization error = $2\sigma^2\left(\frac{d+1}{N}\right)$



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