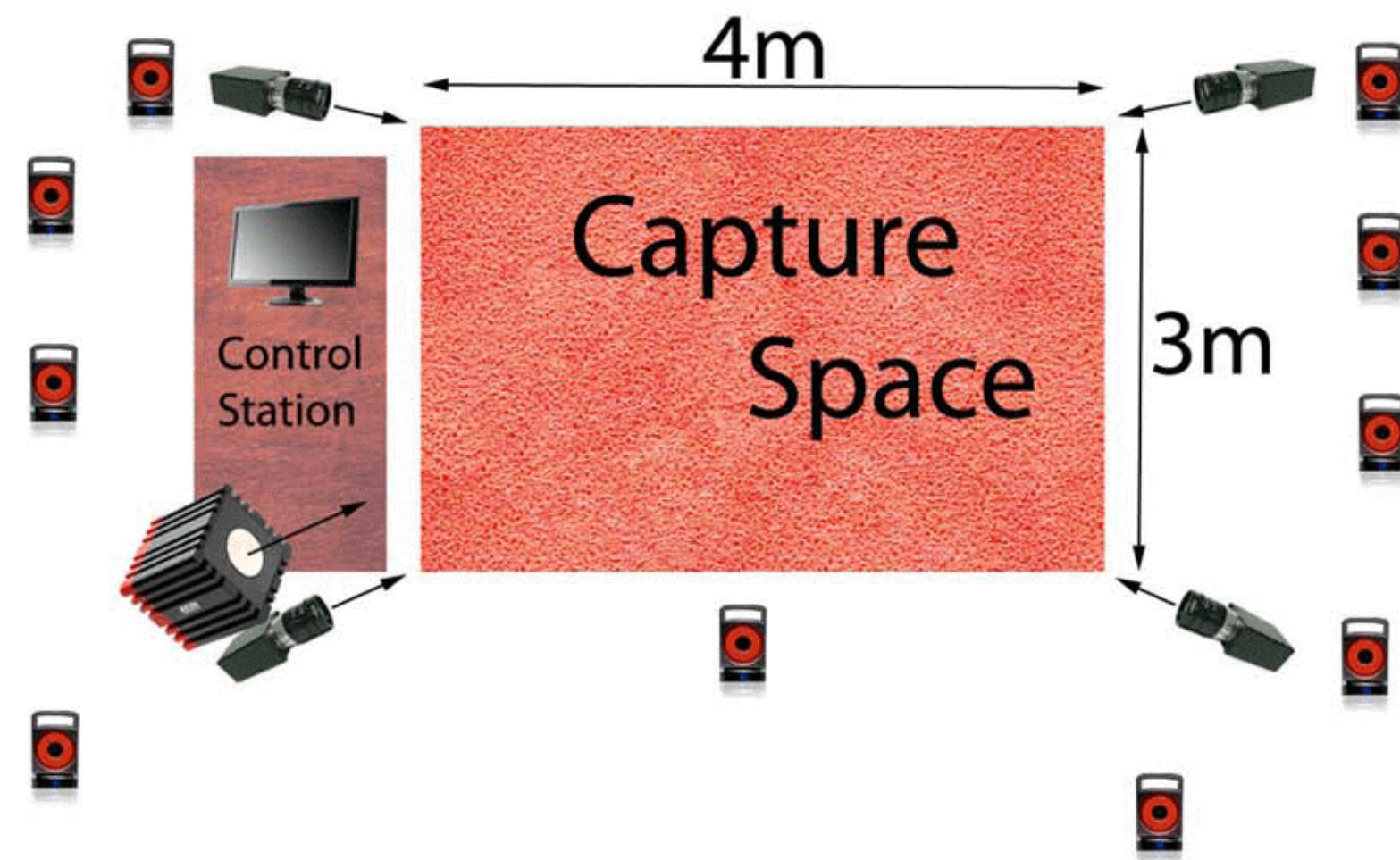


| Type of action | Scenarios | Train | Validation | Test |
|------------------------------------|---------------|-----------|------------|-----------|
| Upper body movement | Directions | 83,856 | 50,808 | 114,080 |
| | Discussion | 154,392 | 68,640 | 140,764 |
| Full body upright variations | Greeting | 69,984 | 33,096 | 84,980 |
| | Posing | 70,948 | 25,800 | 85,912 |
| | Purchases | 49,096 | 33,268 | 48,496 |
| | Taking Photo | 67,152 | 38,216 | 89,608 |
| | Waiting | 98,232 | 54,928 | 123,432 |
| Walking variations | Walking | 114,468 | 47,540 | 93,320 |
| | Walking Dog | 77,068 | 30,648 | 59,032 |
| | Walking Pair | 76,620 | 36,876 | 52,724 |
| Variations while seated on a chair | Eating | 109,360 | 39,372 | 97,192 |
| | Phone Talk | 132,612 | 39,308 | 92,036 |
| | Sitting | 110,228 | 46,520 | 89,616 |
| | Smoking | 138,028 | 50,776 | 85,520 |
| Sitting on the floor | Sitting Down | 112,172 | 50,384 | 105,396 |
| Various Movements | Miscellaneous | - | - | 105,576 |
| Total | | 1,464,216 | 646,180 | 1,467,684 |

(a) The number of 3D human poses in Human3.6M in training, validation and testing aggregated over each scenario. We used 5 subjects for training (2 female and 3 male), 2 for validation (1 female and 1 male) and 4 subjects for testing (2 female and 2 male). The number of video frames is the same as the number of poses (4 cameras capturing at 50Hz). The number of TOF frames can be obtained by dividing the table entries by 8 (1 sensor capturing at 25Hz).

| MoCap System | | DV System | |
|--------------|-----------------|---------------|--------------------|
| No x Sensor | 10 x Vicon T40 | No x Sensor | 4 x Basler piA1000 |
| Resolution | 4 Megapixels | Resolution | 1000x1000 |
| Freq. | 200Hz | Freq. | 50Hz |
| Sync | hardware | Sync | hardware |
| TOF System | | Body Scanner | |
| No x Sensor | 1 x Mesa SR4000 | Sensor | Vitus Smart LC3 |
| Resolution | 176x144 | No. Lasers | 3 |
| Freq. | 25Hz | Point Density | 7dots/cm3 |
| Sync | software | Tolerance | < 1mm |

(b) Technical summary of our different sensors.



(c) Floor plan showing the capture region and the placement of the video, MoCap and TOF cameras.