NAME

CUTEST_ccfg – CUTEst tool to evaluate constraint functions values and possibly gradients.

SYNOPSIS

CALL CUTEST_ccfg(status, n, m, X, C, jtrans, lj1, lj2, J_val, grad)

DESCRIPTION

The CUTEST_ccfg subroutine evaluates the values of the constraint functions of the problem decoded from a SIF file by the script *sifdecoder* at the point X, and possibly their gradients. The problem under consideration is to minimize or maximize an objective function $f(x)$ over all $x \in R^n$ subject to general equations $c_i(x) = 0$, $(i \in 1, \ldots, m_E)$, general inequalities $c_i^l(x) \le c_i(x) \le c_i^u(x)$, $(i \in m_E + 1, \ldots, m)$, and simple bounds $x^l \le x \le x^u$. The objective function is group-partially separable and all constraint functions are partially separable.

ARGUMENTS

The arguments of CUTEST_ccfg are as follows

status [out] - integer
the outputr status: 0 for a succesful call, 1 for an array allocation/deallocation error, 2 for an array bound error, 3 for an evaluation error,

n [in] - integer
the number of variables for the problem,

m [in] - integer
the total number of general constraints,

X [in] - real/double precision
an array which gives the current estimate of the solution of the problem,

C [out] - real/double precision
an array which gives the values of the general constraint functions evaluated at X. The i-th component of C will contain the value of $c_i(x)$,

jtrans [in] - logical
a logical variable which should be set .TRUE. if the transpose of the constraint Jacobian is required and .FALSE. if the Jacobian itself is wanted. The Jacobian matrix is the matrix whose i-th row is the gradient of the i-th constraint function,

lj1 [in] - integer
the actual declared size of the leading dimension of J_val (with lj1 no smaller than n if jtrans is .TRUE. or m if jtrans is .FALSE.),

lj2 [in] - integer
the actual declared size of the second dimension of J_val (with lj2 no smaller than m if jtrans is .TRUE. or n if jtrans is .FALSE.),

J_val [out] - real/double precision
a two-dimensional array of dimension (lj1, lj2) which gives the value of the Jacobian matrix of the constraint functions, or its transpose, evaluated at X. If jtrans is .TRUE., the i,j-th component of the array will contain the i-th derivative of the j-th constraint function. Otherwise, if jtrans is .FALSE., the i,j-th component of the array will contain the j-th derivative of the i-th constraint function,

grad [in] - logical
a logical variable which should be set .TRUE. if the gradient of the constraint functions are required and .FALSE. otherwise.

AUTHORS

I. Bongartz, A.R. Conn, N.I.M. Gould, D. Orban and Ph.L. Toint

SEE ALSO

CUTEst: a Constrained and Unconstrained Testing Environment with safe threads,
N.I.M. Gould, D. Orban and Ph.L. Toint,

Technical Report, Rutherford Appleton Laboratory, 2013.

CUTEr (and SifDec): A Constrained and Unconstrained Testing Environment, revisited,
  N.I.M. Gould, D. Orban and Ph.L. Toint,
  ACM TOMS, **29**:4, pp.373-394, 2003.

CUTE: Constrained and Unconstrained Testing Environment, I. Bongartz, A.R. Conn, N.I.M. Gould and
Ph.L. Toint, ACM TOMS, **21**:1, pp.123-160, 1995.

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AUTHORS

I. Bongartz, A.R. Conn, N.I.M. Gould, D. Orban and Ph.L. Toint

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