#### **NAME**

CUTEST\_ceh\_threaded - CUTEst tool to evaluate the sparse Lagrangian Hessian matrix in finite element format.

### **SYNOPSIS**

CALL CUTEST\_ceh\_threaded( status, n, m, X, Y, ne, lhe\_ptr, HE\_row\_ptr, HE\_val\_ptr, lhe\_row, HE\_row, lhe\_val, HE\_val, byrows, thread)

#### DESCRIPTION

The CUTEST ceh threaded subroutine evaluates the Hessian matrix of the Lagrangian function  $l(x, y) = f(x) + y^T c(x)$  for the problem decoded into OUTSDIF, d at the point (x, y) = (X, Y). This Hessian matrix is stored as a sparse matrix in finite element format

$$H = \sum_{e=1}^{ne} H_{e},$$

 $H = \sum_{e=1}^{ne} H_{e},$  where each square symmetric element  $H_e$  involves a small subset of the rows of the Hessian matrix.

The problem under consideration consists in minimizing (or maximizing) an objective function f(x) over all  $x \in \mathbb{R}^n$  subject to general equations  $c_i(x) = 0$ ,  $(i \in 1, ..., m_E)$ , general inequalities  $c_i^l(x) \le c_i(x) \le c_i^u(x)$ ,  $(i \in m_F + 1, \dots, m)$ , and simple bounds  $x^l \le x \le x^u$ . The objective function is group-partially separable and all constraint functions are partially separable.

### **ARGUMENTS**

The arguments of CUTEST\_ceh\_threaded are as follows

status [out] - integer

the outputr status: 0 for a successful call, 1 for an array allocation/deallocation error, 2 for an array bound error, 3 for an evaluation error, 4 for an out-of-range thread,

n [in] - integer

the number of variables for the problem,

m [in] - integer

the total number of general constraints,

**X** [in] - real/double precision

an array which gives the current estimate of the solution of the problem,

Y [in] - real/double precision

an array which gives the Lagrange multipliers,

ne [out] - integer

the number, ne, of "finite-elements" used,

**lhe\_ptr** [in] - integer

the actual declared dimensions of HE\_row\_ptr and HE\_val\_ptr,

**HE\_row\_ptr** [out] - integer

HE row ptr(i) points to the position in HE row of the first row index involved with element number e: the row indices of element number e are stored in HE\_row between the indices HE\_row\_ptr(e) and HE\_row\_ptr(e+1)-1. HE\_row\_ptr(ne+1) points to the first empty location in HE\_row,

**HE** val ptr [out] - integer

HE val ptr(i) points to the position in HE val of the first nonzero involved with element number i: the values involved in element number e are stored in HE val between the indices HE val ptr(e) and HE\_val\_ptr(e+1)-1. HE\_val\_ptr(ne+1) points to the first empty location in HE\_val,

lhe\_row [in] - integer

the actual declared dimension of HE\_row,

**HE\_row** [out] - integer

an array which holds a list of the row indices involved which each element. Those for element e directly preced those for element e+1, e = 1, ..., ne-1. Since the elements are symmetric, HE\_row is also the list of column indices involved with each element.

### lhe\_val [in] - integer

the actual declared dimension of HE\_val,

### **HE\_val** [out] - real/double precision

an array of the nonzeros in the upper triangle of  $H_e$ , evaluated at X and stored by rows, or by columns. Those for element e directly proceed those for element, e+1, i=1, ..., ne-1. Element number e contains the values stored between

```
HE_val( HE_val_ptr(e) ) and HE_val( HE_val_ptr(e+1)-1 )
```

and involves the rows/columns stored between

```
HE\_row(\ HE\_row\_ptr(e)\ ) and HE\_row(\ HE\_row\_ptr(e+1)-1\ ).
```

# byrows [in] - logical

must be set to .TRUE. if the upper triangle of each H\_e is to be stored by rows, and to .FALSE. if it is to be stored by columns,

## thread [in] - integer

thread chosen for the evaluation; threads are numbered from 1 to the value threads set when calling CUTEST\_csetup\_threaded.

### **AUTHORS**

I. Bongartz, A.R. Conn, N.I.M. Gould, D. Orban and Ph.L. Toint

#### **SEE ALSO**

CUTEr (and SifDec): A Constrained and Unconstrained Testing Environment, revisited, N.I.M. Gould, D. Orban and Ph.L. Toint,

ACM TOMS, 29:4, pp.373-394, 2003.

CUTE: Constrained and Unconstrained Testing Environment, I. Bongartz, A.R. Conn, N.I.M. Gould and Ph.L. Toint, TOMS, 21:1, pp.123-160, 1995.

cutest\_ueh\_threaded(3M), sifdecode(1).

#### **NAME**

CUTEST\_ceh\_threaded - CUTEst tool to evaluate the sparse Lagrangian Hessian matrix in finite element format.

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CALL CUTEST\_ceh\_threaded( status, n, m, X, Y, ne, lhe\_ptr, HE\_row\_ptr, HE\_val\_ptr, lhe\_row, HE\_row, lhe\_val, HE\_val, byrows, thread)

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$$H = \sum_{e=1}^{ne} H_{e},$$

 $H = \sum_{e=1}^{ne} H_{e},$  where each square symmetric element  $H_e$  involves a small subset of the rows of the Hessian matrix.

The problem under consideration consists in minimizing (or maximizing) an objective function f(x) over all  $x \in \mathbb{R}^n$  subject to general equations  $c_i(x) = 0$ ,  $(i \in 1, ..., m_E)$ , general inequalities  $c_i^l(x) \le c_i(x) \le c_i^u(x)$ ,  $(i \in m_F + 1, \dots, m)$ , and simple bounds  $x^l \le x \le x^u$ . The objective function is group-partially separable and all constraint functions are partially separable.

### **ARGUMENTS**

The arguments of CUTEST\_ceh\_threaded are as follows

status [out] - integer

the outputr status: 0 for a successful call, 1 for an array allocation/deallocation error, 2 for an array bound error, 3 for an evaluation error, 4 for an out-of-range thread,

n [in] - integer

the number of variables for the problem,

m [in] - integer

the total number of general constraints,

**X** [in] - real/double precision

an array which gives the current estimate of the solution of the problem,

Y [in] - real/double precision

an array which gives the Lagrange multipliers,

ne [out] - integer

the number, ne, of "finite-elements" used,

**lhe\_ptr** [in] - integer

the actual declared dimensions of HE\_row\_ptr and HE\_val\_ptr,

**HE\_row\_ptr** [out] - integer

HE row ptr(i) points to the position in HE row of the first row index involved with element number e: the row indices of element number e are stored in HE\_row between the indices HE\_row\_ptr(e) and HE\_row\_ptr(e+1)-1. HE\_row\_ptr(ne+1) points to the first empty location in HE\_row,

**HE** val ptr [out] - integer

HE val ptr(i) points to the position in HE val of the first nonzero involved with element number i: the values involved in element number e are stored in HE val between the indices HE val ptr(e) and HE\_val\_ptr(e+1)-1. HE\_val\_ptr(ne+1) points to the first empty location in HE\_val,

lhe\_row [in] - integer

the actual declared dimension of HE\_row,

**HE\_row** [out] - integer

an array which holds a list of the row indices involved which each element. Those for element e directly preced those for element e+1, e = 1, ..., ne-1. Since the elements are symmetric, HE\_row is also the list of column indices involved with each element.

### lhe\_val [in] - integer

the actual declared dimension of HE\_val,

### **HE\_val** [out] - real/double precision

an array of the nonzeros in the upper triangle of  $H_e$ , evaluated at X and stored by rows, or by columns. Those for element e directly proceed those for element, e+1, i=1, ..., ne-1. Element number e contains the values stored between

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HE_val( HE_val_ptr(e) ) and HE_val( HE_val_ptr(e+1)-1 )
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HE\_row(\ HE\_row\_ptr(e)\ ) and HE\_row(\ HE\_row\_ptr(e+1)-1\ ).
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thread chosen for the evaluation; threads are numbered from 1 to the value threads set when calling CUTEST\_csetup\_threaded.

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