NAME
CUTEST_ugreh – CUTEst tool to evaluate the gradient and sparse Hessian matrix in finite element format.

SYNOPSIS
CALL CUTEST_ugreh(data, status, n, X, G, ne, lhe_ptr, HE_row_ptr, HE_val_ptr, lhe_row, HE_row, lhe_val, HE_val, byrows)

DESCRIPTION
The CUTEST_ugreh subroutine evaluates the gradient and Hessian matrix of the objective function of the problem decoded from a SIF file by the script *sifdecode* at the point X. This Hessian matrix is stored as a sparse matrix in finite element format

$$H = \sum_{e=1}^{ne} H_{e,}$$

where each square symmetric element *H sub e* involves a small subset of the rows of the Hessian matrix.

The problem under consideration is to minimize or maximize an objective function $f(x)$ over all $x \in R^n$ subject to the simple bounds $x^l \leq x \leq x^u$. The objective function is group-partially separable.

ARGUMENTS
The arguments of CUTEST_ugreh are as follows

data [inout] - CUTEST_data_type derived type
   problem-specific private data,

status [out] - integer
   the outputr status: 0 for a succesful call, 1 for an array allocation/deallocation error, 2 for an array bound error, 3 for an evaluation error,

n [in] - integer
   the number of variables for the problem,

X [in] - real/double precision
   an array which gives the current estimate of the solution of the problem,

G [out] - real/double precision
   an array which gives the value of the gradient of the objective function evaluated at X

ne [out] - integer
   the number, ne, of "finite-elements" used,

lhe_ptr [in] - integer
   the actual declared dimensions of HE_row_ptr and HE_val_ptr,

HE_row_ptr [out] - integer
   HE_row_ptr(i) points to the position in HE_row of the first row index involved with element number e: the row indices of element number e are stored in HE_row between the indices HE_row_ptr(e) and HE_row_ptr(e+1)-1. HE_row_ptr(ne+1) points to the first empty location in HE_row,

HE_val_ptr [out] - integer
   HE_val_ptr(i) points to the position in HE_val of the first nonzero involved with element number i: the values involved in element number e are stored in HE_val between the indices HE_val_ptr(e) and HE_val_ptr(e+1)-1. HE_val_ptr(ne+1) points to the first empty location in HE_val,

lhe_row [in] - integer
   the actual declared dimension of HE_row,

HE_row [out] - integer
   an array which holds a list of the row indices involved which each element. Those for element e directly preceed those for element e+1, e = 1, ..., ne-1. Since the elements are symmetric, HE_row is also the list of column indices involved with each element.

lhe_val [in] - integer
>   the actual declared dimension of HE_val,

HE_val [out] - real/double precision
>   an array of the nonzeros in the upper triangle of H_e, evaluated at X and stored by rows, or by columns. Those for element e directly proceed those for element, e+1, i = 1, ..., ne-1. Element number e contains the values stored between
>
>   HE_val(HE_val_ptr(e)) and HE_val(HE_val_ptr(e+1)-1)
>
>   and involves the rows/columns stored between
>
>   HE_row(HE_row_ptr(e)) and HE_row(HE_row_ptr(e+1)-1).

byrows [in] - logical
>   must be set to .TRUE. if the upper triangle of each H_i is to be stored by rows, and to .FALSE. if it is to be stored by columns.

NOTE
>   Calling this routine is more efficient than separate calls to CUTEST_ugr and CUTEST_ueh.

AUTHORS
>   I. Bongartz, A.R. Conn, N.I.M. Gould, D. Orban and Ph.L. Toint

SEE ALSO
>   *CUTEr (and SifDec): A Constrained and Unconstrained Testing Environment, revisited*,
>   N.I.M. Gould, D. Orban and Ph.L. Toint,
>   ACM TOMS, **29**:4, pp.373-394, 2003.
>
>   *CUTE: Constrained and Unconstrained Testing Environment*, I. Bongartz, A.R. Conn, N.I.M. Gould and Ph.L. Toint, TOMS, **21**:1, pp.123-160, 1995.
>
>   cutest_csgreh(3M), sifdecode(1).

NAME

CUTEST_ugreh – CUTEst tool to evaluate the gradient and sparse Hessian matrix in finite element format.

SYNOPSIS

CALL CUTEST_ugreh(data, status, n, X, G, ne, lhe_ptr, HE_row_ptr, HE_val_ptr, lhe_row, HE_row, lhe_val, HE_val, byrows)

DESCRIPTION

The CUTEST_ugreh subroutine evaluates the gradient and Hessian matrix of the objective function of the problem decoded from a SIF file by the script *sifdecode* at the point X. This Hessian matrix is stored as a sparse matrix in finite element format

$$H = \sum_{e=1}^{ne} H_{e,}$$

where each square symmetric element *H sub e* involves a small subset of the rows of the Hessian matrix.

The problem under consideration is to minimize or maximize an objective function $f(x)$ over all $x \in R^n$ subject to the simple bounds $x^l \le x \le x^{u.}$ The objective function is group-partially separable.

ARGUMENTS

The arguments of CUTEST_ugreh are as follows

data [inout] - CUTEST_data_type derived type
problem-specific private data,

status [out] - integer
the outputr status: 0 for a succesful call, 1 for an array allocation/deallocation error, 2 for an array bound error, 3 for an evaluation error,

n [in] - integer
the number of variables for the problem,

X [in] - real/double precision
an array which gives the current estimate of the solution of the problem,

G [out] - real/double precision
an array which gives the value of the gradient of the objective function evaluated at X

ne [out] - integer
the number, ne, of "finite-elements" used,

lhe_ptr [in] - integer
the actual declared dimensions of HE_row_ptr and HE_val_ptr,

HE_row_ptr [out] - integer
HE_row_ptr(i) points to the position in HE_row of the first row index involved with element number e: the row indices of element number e are stored in HE_row between the indices HE_row_ptr(e) and HE_row_ptr(e+1)-1. HE_row_ptr(ne+1) points to the first empty location in HE_row,

HE_val_ptr [out] - integer
HE_val_ptr(i) points to the position in HE_val of the first nonzero involved with element number i: the values involved in element number e are stored in HE_val between the indices HE_val_ptr(e) and HE_val_ptr(e+1)-1. HE_val_ptr(ne+1) points to the first empty location in HE_val,

lhe_row [in] - integer
the actual declared dimension of HE_row,

HE_row [out] - integer
an array which holds a list of the row indices involved which each element. Those for element e directly preceed those for element e+1, e = 1, ..., ne-1. Since the elements are symmetric, HE_row is also the list of column indices involved with each element.

lhe_val [in] - integer
> the actual declared dimension of HE_val,

HE_val [out] - real/double precision
> an array of the nonzeros in the upper triangle of H_e, evaluated at X and stored by rows, or by columns. Those for element e directly proceed those for element, e+1, i = 1, ..., ne-1. Element number e contains the values stored between

> HE_val(HE_val_ptr(e)) and HE_val(HE_val_ptr(e+1)-1)

> and involves the rows/columns stored between

> HE_row(HE_row_ptr(e)) and HE_row(HE_row_ptr(e+1)-1).

byrows [in] - logical
> must be set to .TRUE. if the upper triangle of each H_i is to be stored by rows, and to .FALSE. if it is to be stored by columns.

NOTE
> Calling this routine is more efficient than separate calls to CUTEST_ugr and CUTEST_ueh.

AUTHORS
> I. Bongartz, A.R. Conn, N.I.M. Gould, D. Orban and Ph.L. Toint

SEE ALSO
> *CUTEr (and SifDec): A Constrained and Unconstrained Testing Environment, revisited*,
>   N.I.M. Gould, D. Orban and Ph.L. Toint,
>   ACM TOMS, **29**:4, pp.373-394, 2003.

> *CUTE: Constrained and Unconstrained Testing Environment*, I. Bongartz, A.R. Conn, N.I.M. Gould and Ph.L. Toint, TOMS, **21**:1, pp.123-160, 1995.

> cutest_csgreh(3M), sifdecode(1).