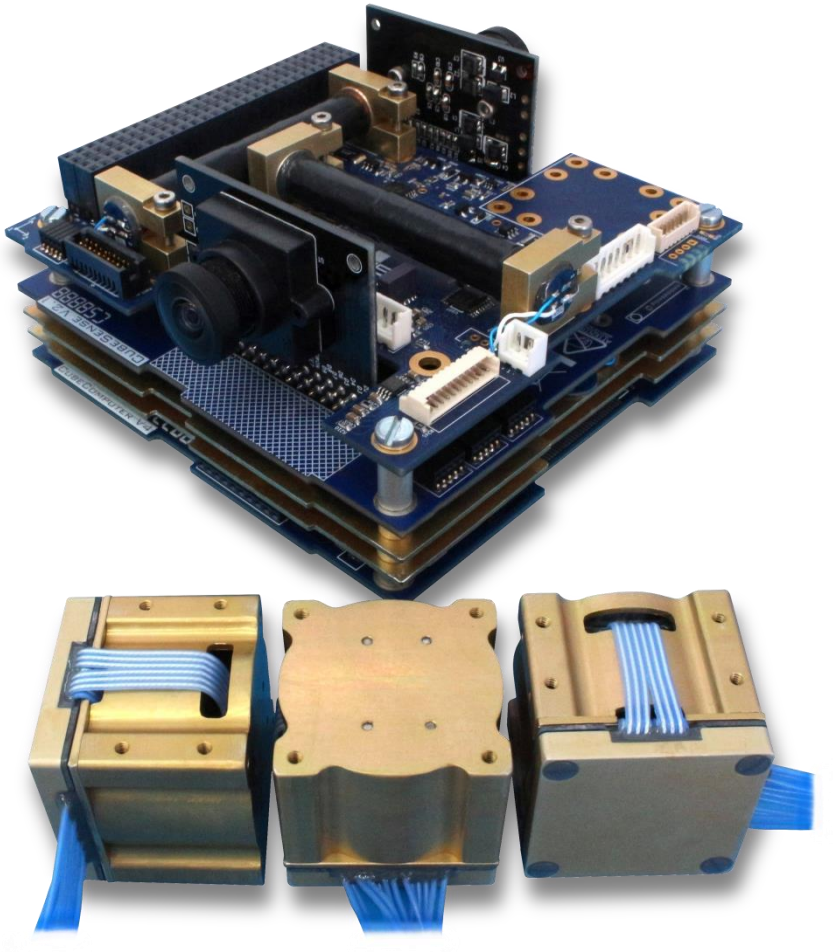
CUBE SPACE

# CubeADCS

## The complete ADCS solution



## Health Check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|---|---|
| **Document** | CubeADCS Health Check |
| **Version** | 3.15 |
| **Domain** | Public |
| **Date modified** | 19 April 2018 |
| **Approved by** | Name: Mike-Alec Kearney |
| | Signature:  |

# List of Acronyms/Abbreviations

| | |
|---|---|
| ACP | ADCS Control Program |
| ADCS | Attitude and Determination Control System |
| CSS | Coarse Sun Sensor |
| MCU | Microcontroller Unit |
| PCB | Printed Circuit Board |
| TC | Telecommand |
| TLM | Telemetry |
| UART | Universal Asynchronous Receiver/Transmitter |

# Table of Contents

# 1. Health Check Details

**CubeADCS unit number:** 1812

**Date of CubeSpace Health Check:** 9 May 2018

**Name(s) of CubeSpace engineer(s):** Hein Wessels & Christo Groenewald

**Signature(s) of CubeSpace engineer(s):** H Wessels & C Groenewald

**Date of client Health Check:**

**Name(s) of client engineer(s):**

**Signature(s) of client engineer(s):**

# 2. Introduction

This document will provide the instructions and results of the health check of the CubeADCS unit. The instructions provided must be followed exactly and the observed results must be indicated as is.

## 2.1 Handling

**The CubeADCS unit contains electrostatic sensitive components. Under no circumstances should the unit be handled without anti-static protection.**

**The CubeADCS unit is a delicate mechanical assembly. Always handle with great care, preferably using anti-static gloves.**

**When handling the CubeADCS unit, always place the unit on an anti-static mat in a clean environment, as required for flight-model components.**

## 2.2 Test requirements

The following items are required when performing the health check:

- Power supply ($V_{max}$ > 10 V, $I_{max}$ > 1 A).
- An appropriate power distribution platform with 5 V and 3.3 V regulators.
- Latest CubeSupport software (Provided on USB with CubeADCS).
- The supplied UART-to-USB cable.
- The supplied CubeADCS unit and all peripherals.
- Any means of measuring the direction of a magnetic field, for example a normal field compass.
- A small bright light source to stimulate the Coarse Sun Sensors and Sun cameras (if any). Typically, a modified LED flash light (see Figure 1) to create a narrow source, or mobile phone flash, will suffice.

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**Figure 1 – Example of modified LED Torch**

- A broad bright light source to stimulate the Nadir camera's (if any). Typically, a desk lamp covered with paper will suffice (see Figure 2).

**Figure 2 – Example of modified Desk Lamp**

## 2.3 Preparation

Follow the instructions below to prepare the CubeADCS for the health check:

- Connect all peripherals to the CubeADCS. This normally includes:
  - Magnetometer
  - Coarse Sun Sensors
  - CubeSense (typically if 3-Axis and/or Y-Momentum capable)
  - Redundant Magnetometer (optional)
  - GPS (optional)
  - Multiple reaction wheels (typically if 3-Axis capable)
  - CubeStar (optional if 3-Axis capable)
- Set the power supply to the correct battery voltage and the current limit to $I_{max}$ = 1 A and connect the supply to the power distribution platform.
- Power down the power supply while it is being connected to the CubeADCS
- Connect power leads to the appropriate PC104 pins on the CubeADCS unit. Refer to the CubeADCS Interface Control Document and the Option Sheet for the relevant PC104 pin locations.
- Connect the UART-to-USB cable to CubeComputer. **NB: The black wire (Ground) should be connected to the pin closest to the corner of the PCB farthest away from the PC104 connector.**

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# 3. CubeComputer

Once the preparation in the preceding section has been completed the CubeADCS should be ready for the health check to start. Before powering on the ADCS read though the following subsection to insure everything is clear before you start the procedure. Please look at the last check list before starting the health test.

- Power supply is set to correct battery voltage
- Power supply current limit is set to 1A or more
- Power supply is off
- Power leads connecting to CubeADCS are short to keep series resistance as small as possible
- All peripherals are securely connected to the ADCS
- CubeADCS is placed in a secure clean grounded are with enough room for users to move a light source around the ADCS and the peripherals are placed for easy access and control.
- CubeADCS is connected to PC though UART to Serial cable.
- Do not power on the CubeADCS.

## 3.1 The Bootloader

Once power is turned on, the bootloader will initialize. If the bootloader does not receive communications within 5 seconds it will load the previously specified application. The bootloader will boot the same project only four times before the boot counter runs out. Once the boot counter runs out the bootloader will not boot the specified application automatically, this will result with the bootloader waiting for the user to specify that the application should be loaded again.

For the health check first connect to the bootloader and specify that the ACP should be loaded. This is achieved with the following steps.

Before powering on the ADCS, ready the CubeSupport application on the PC. The CubeSupport application is supplied on a USB along with the bundle. Launch the CubeSupport application .exe which can be found in the CubeSupport folder on the CubeSpace USB. The CubeSupport application will open a window as shown in Figure 3.

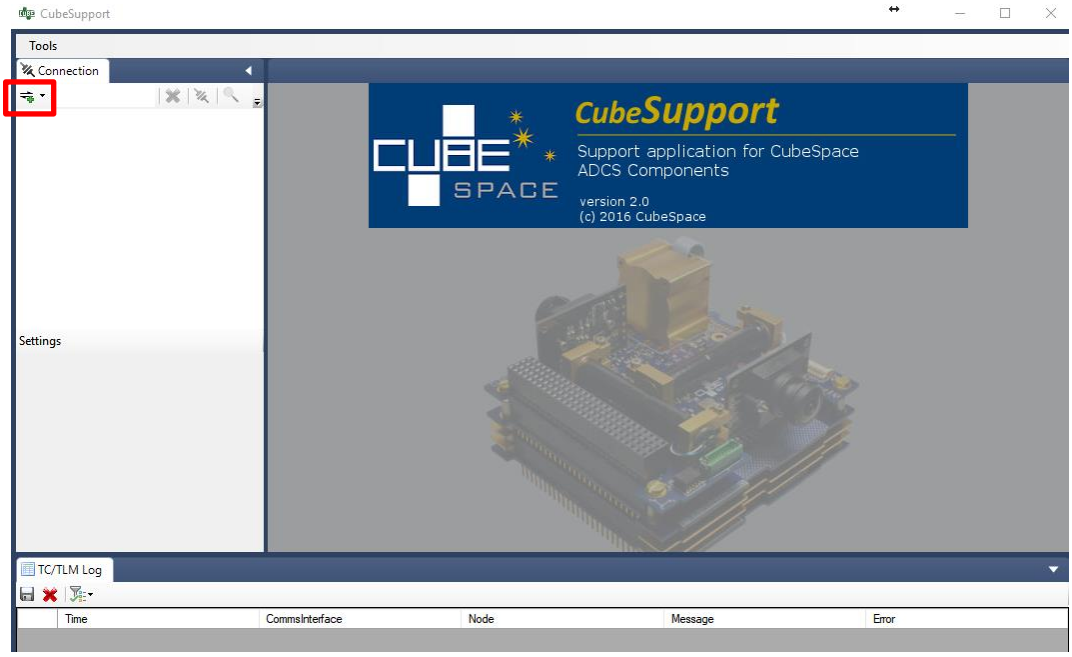


**Figure 3 – Add connection to CubeSupport**

Click on the add connection icon  in CubeSupport as shown with the red rectangle in Figure 3.This will detect the UART to Serial cable and show the connection in the list.

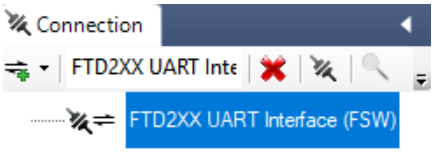


**Figure 4 – New Connection in list**

**Now Power on die CubeADCS and wait 1 second for everything to power on,** connect to the ADCS with CubeSupport within the first five seconds of power on by clicking on the connect button  . CubeSupport should catch the bootloader and connect to the ADCS bootloader, the bootloader menu will be displayed as shown in Figure 5.

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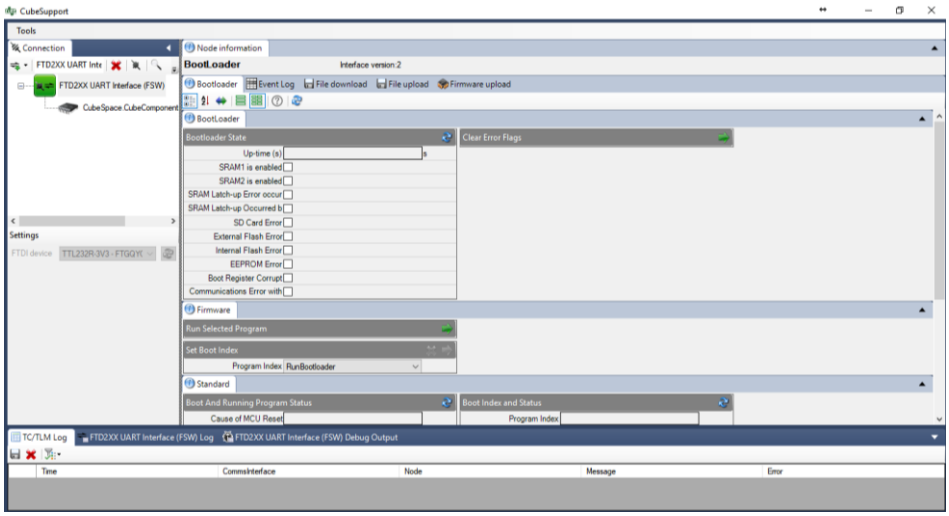


**Figure 5 – CubeSupport Bootloader Interface**

On the Bootloader tab there are a couple of telemetry windows which displays the bootloader information. Click on the refresh icon  to read the data from CubeComputer. Ensure that the data is the same as given in Table 1.

**Table 1 - Bootloader data**

| Variable | Expected Result | Observed Result | User Observed Result |
|---|---|---|---|
| **Bootloader -> Bootloader State** | | | |
| **Up-time (s)** | Incrementing every second | ✓ | ✓ |
| **SRAM 1 is enabled** | Checked | ✓ | ✓ |
| **SRAM 2 is enabled** | Checked | ✓ | ✓ |
| **SRAM Latch-up Error occurred** | Unchecked | ✓ | ✓ |
| **SRAM Latch-up Occurred b** | Unchecked | ✓ | ✓ |
| **SD card Error** | Unchecked | ✓ | ✓ |
| **External Flash Error** | Unchecked | ✓ | ✓ |
| **Internal Flash Error** | Unchecked | ✓ | ✓ |
| **EEPROM Error** | Unchecked | ✓ | ✓ |
| **Boot Register Corrupt** | Unchecked | ✓ | ✓ |
| **Communications Error** | Unchecked | ✓ | ✓ |
| **Standard-> Boot and Running Program Status** | | | |
| **Cause of MCU Reset** | PowerOnReset | ✓ | ✓ |
| **Boot Cause** | Unexpected | ✓ | ✓ |
| **Boot Counter** | Incrementing at every reset | ✓ | ✓ |
| **Boot Program Index** | RunEeprom | ✓ | ✓ |
| **Firmware version (Major)** | 2 | ✓ | ✓ |

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| | | | |
|---|---|---|---|
| **Firmware version (Minor)** | 1 | ✓ | ✓ |
| **Standard -> Boot Index and Status** | | | |
| **Program Index** | RunInternalFlashProgram | ✓ | ✓ |
| **Boot Status** | BootSuccess | ✓ | ✓ |
| **Standard – Satellite State** | | | |
| **Telecommand counter** | 0 | ✓ | ✓ |
| **Telemetry request counter** | Incrementing after every refresh | ✓ | ✓ |
| **TC buffer overrun** | Unchecked | ✓ | ✓ |
| **UART protocol error** | Unchecked | ✓ | ✓ |
| **UART incomplete message** | Unchecked | ✓ | ✓ |

In the Firmware section under the Set Boot Index sub-section set the program index to *RunInternalFlashProgram* as shown in Figure 6.

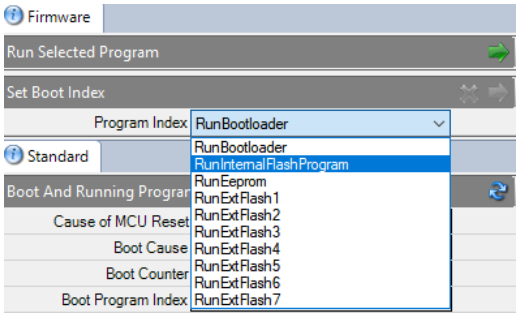
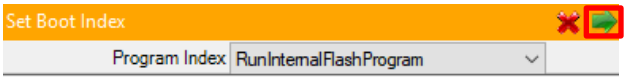



**Figure 6 – Set boot index**

Transmit the command by clicking on the green arrow after setting the boot index.




The ADCS is delivered with the ACP pre-loaded into the internal flash and setting the boot index to the internal flash will insure that the application is executed.

Power off the CubeADCS and disconnect the CubeSupport by clicking on the disconnect icon .

Turn on the CubeADCS and wait for 6 seconds to pass before attempting to connect with CubeSupport. The bootloader will execute the ACP after 5 seconds. The CubeSupport application can connect to the ACP application and the CubeSupport will display the window shown in Figure 7.

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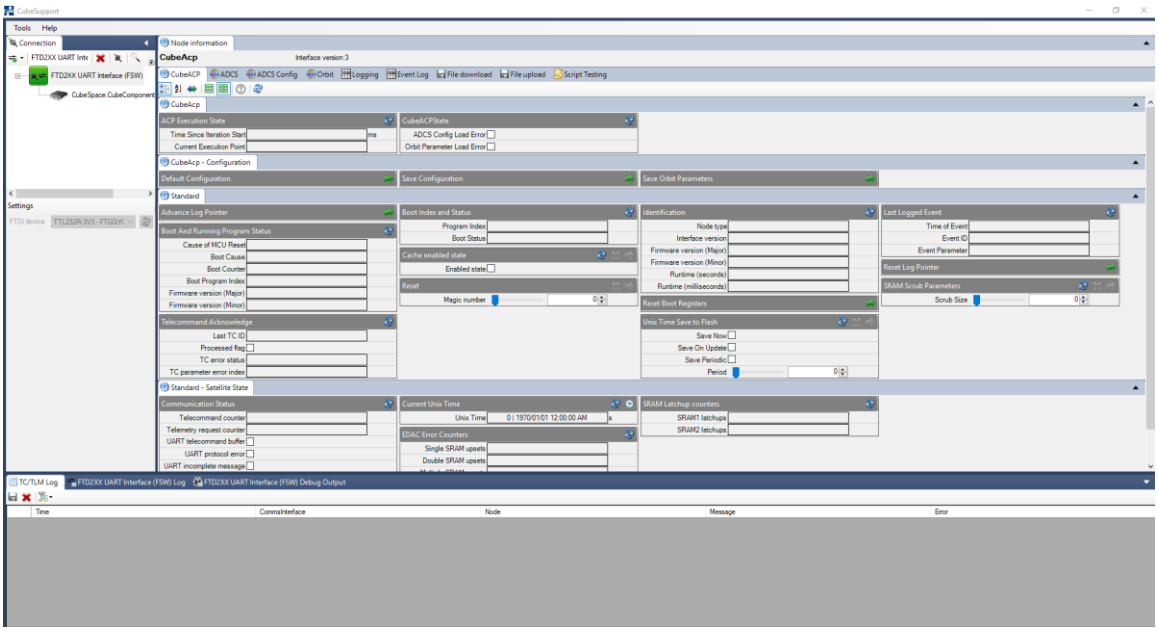


**Figure 7 – CubeSupport Connected to ACP**

Alternative to turning the CubeADCS off and on, the *Program Index* can be set and the *Run Selected Program* command can be transmitted. This will cause the bootloader to boot the application.

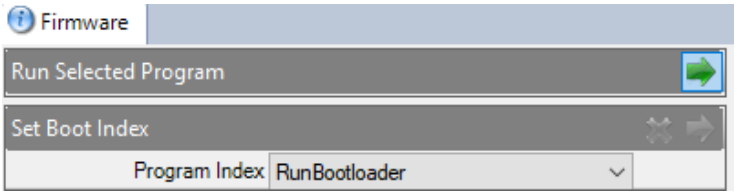
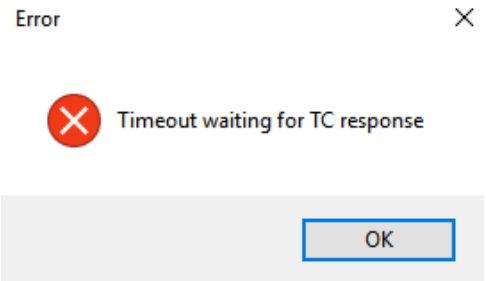



**Figure 8 – Run Selected Program**

An error message will be display reporting that the no response was obtained since the bootloader started to boot the ACP.




Click "OK", disconnect  and reconnect  to connect to the ACP and show the ACP interface.

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## 3.2 The CubeACP

Verify that the CubeSupport connects to the ACP.

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| CubeComputer connects to the CubeSupport application. | ✓ | ✓ | ✓ |

- Navigate to the *CubeACP* tab.
- Verify the following under the *CubeACP* tab by refreshing the data in the relevant box several times (click on the  button to refresh the data):

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **CubeACP → ACP Execution State** | | | |
| **Time Since Iteration Start** | 0-1000 | ✓ | ✓ |
| **Current Execution Point** | Idle | ✓ | ✓ |
| **Standard → Boot and Running Program Status** | | | |
| **Cause of MCU Reset** | Power on reset | ✓ | ✓ |
| **Boot Cause** | Unexpected | ✓ | ✓ |
| **Boot Counter** | Increment after every reset | ✓ | ✓ |
| **Boot Program Index** | RunInternalFlashProgram | ✓ | ✓ |
| **Firmware Version (Major)** | 3 | ✓ | ✓ |
| **Firmware Version (Minor)** | 11 | ✓ | ✓ |
| **Standard → Identification** | | | |
| **Node type** | 10 | ✓ | ✓ |
| **Interface Version** | 3 | ✓ | ✓ |
| **Runtime (seconds)** | Incrementing every second | ✓ | ✓ |
| **Runtime (milliseconds)** | 0 – 1000 | ✓ | ✓ |
| **Standard → Boot Index and Status** | | | |
| **Program Index** | RunInternalFlashProgram | ✓ | ✓ |
| **Boot Status** | BootSuccess | ✓ | ✓ |
| **Standard → Satellite State → Communication Status** | | | |
| **Telecommand counter** | 0 | ✓ | ✓ |

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| | | | |
|---|---|---|---|
| **Telemetry request counter** | Incrementing | ✓ | ✓ |
| **TC buffer overrun** | Unchecked | ✓ | ✓ |
| **UART protocol error** | Unchecked | ✓ | ✓ |
| **UART incomplete message** | Unchecked | ✓ | ✓ |
| **Standard → Satellite State → Current Unix Time** | | | |
| **Unix Time** | Incrementing | ✓ | ✓ |
| **Standard → Satellite State → SRAM Latchup Counters** | | | |
| **SRAM1 Latchups** | 0 | ✓ | ✓ |
| **SRAM2 Latchups** | 0 | ✓ | ✓ |
| **Standard → Satellite State → EDAC Error Counters** | | | |
| **Single SRAM upsets** | 0 | ✓ | ✓ |
| **Double SRAM upsets** | 0 | ✓ | ✓ |
| **Multiple SRAM upsets** | 0 | ✓ | ✓ |

- Navigate to the *ADCS* tab.
- Verify the following under the *ADCS* tab by refreshing the data in the relevant box several times:

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **Adcs 3-Axis → ADCS Power Control** | | | |
| **All nodes indicate PowOff** | PowOff | ✓ | ✓ |
| **Adcs 3-Axis → ADCS State → Current ADCS State** | | | |
| **ADCS Run Mode** | AdcsOff | ✓ | ✓ |
| **Attitude Estimation Mode** | EstNone | ✓ | ✓ |
| **Control Mode** | ConNone | ✓ | ✓ |
| **All other states indicated with check boxes** | Unchecked | ✓ | ✓ |

Once all the parameters above have been verified, it can be confirmed that CubeADCS is operating normally. The following sections of this Health Check document will be dedicated to testing the functionality of the other ADCS nodes in the CubeADCS unit.

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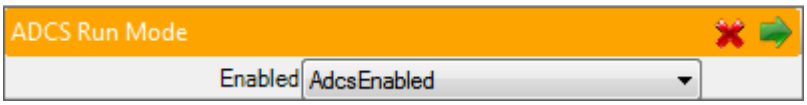
# 4. CubeSense

Follow the instructions below to perform the CubeSense health check (if the CubeADCS is equipped with a CubeSense):

- Navigate to the *ADCS* tab.
- In the *Adcs 3-Axis → ADCS Run Mode* box, switch the run mode to *AdcsEnabled*. Note that the top of the box turns orange with a red cross and a green arrow once the relevant run mode has been selected. **Click on the green arrow to confirm and send the command to the CubeADCS unit**. Conversely, clicking on the red cross will ignore and discard the command.




Confirm that the ADCS is enabled by reading the values indicated in the tables below (refresh the data in the relevant boxes).

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **Adcs 3-Axis → ADCS Execution Times** | | | |
| **Time to Perform ADCS update** | 105 ± 25 ms | 85 ms ✓ | 85 ms |
| **Time to Perform Sensor/Act** | 3 ± 3 ms | 0 ms ✓ | 0 ms |
| **Time to Execute SGP4 Prop** | 46 ± 10 ms | 42 ms ✓ | 42 ms |
| **Time to Execute IGRF Mode** | 50 ± 10 ms | 42 ms ✓ | 42 ms |
| **Adcs 3-Axis → ADCS State → Current ADCS State** | | | |
| **ADCS Run Mode** | AdcsEnabled | ✓ | ✓ |
| **Attitude Estimation Mode** | EstNone | ✓ | ✓ |
| **Control Mode** | ConNone | ✓ | ✓ |
| **Sun is Above Local Horizon*** | Checked | ✓ | ✓ |
| **All other Checkboxes**** | Unchecked | ✓ | ✓ |

* If ***Sun is Above Local Horizon*** is **not** checked the *CubeADCS* expects to be in the eclipse part of its orbit according to the Unix time (or when ***Capture Status*** reads ***CaptureStartup***). This means the CubeACP will **not** sample the raw CubeSense outputs. If this happens change the *CubeACP*'s Unix time to "move" the satellite out of eclipse. This is done at *CubeACP → Standard → Satellite State → Current Unix Time*. (Normal flight software is used for Health Check).

** Note that the following flags can be ignored, as they are dependent on the setup, environment, and stimulus:

1. Magnetometer Range Error
2. Cam1 Sensor Detection Error
3. Cam1 Sensor Range Error

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4. Cam2 Sensor Detection Error
5. Cam2 Sensor Range Error
6. Coarse Sun Sensor Error

- **Switch on CubeSense** by selecting *PowOn* in the drop-down menu next to *CubeSense Power Selection* in the *ADCS Power Control* box (*ADCS 3-Axis* tab) and transmit the command by clicking on the green arrow.
- Ensure that the **lens caps** of **both cameras** are **on**.
- Navigate to the *ADCS Config* tab and read the ADCS configuration. Scroll down to Cam1 and Cam2 sensor configuration (there are nine values in total per sensor) and make a note of all these values.
- Navigate to the *Adcs 3-Axis* → *Configuration* → Set *Cam1 Sensor Configuration* block and copy **all** the Cam1 values as you noted in the ADCS configuration block. Change the ***Cam1 detection threshold* to 150**. Set the ***Cam1 sensor exposure time*** to 35 if Cam1 is a Nadir sensor, or to 100 if Cam1 is a Sun sensor. Click on the green arrow to send these commands.
- Navigate to *Adcs 3-Axis* → *Configuration* → *Set Cam2 Sensor Configuration* block and copy **all** the Cam2 values as you noted in the ADCS configuration block. Change the ***Cam2 detection threshold* to 150**. Set the *Cam2* ***sensor exposure time*** to 35 if Cam2 is a Nadir sensor, or to 100 is Cam2 is a Sun sensor. Click on the green arrow to send these commands.
- Navigate back to the *ADCS* tab and verify the following values:

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **Adcs 3-Axis → ADCS State → Current ADCS State** | | | |
| **ADCS Run Mode** | AdcsEnabled | ✓ | ✓ |
| **Attitude Estimation Mode** | EstNone | ✓ | ✓ |
| **Control Mode** | ConNone | ✓ | ✓ |
| **CubeSense Enabled** | Checked | ✓ | ✓ |
| **Sun is Above Local Horizon*** | Checked | ✓ | ✓ |
| **All other checkboxes**** | Unchecked | ✓ | ✓ |
| **Adcs 3-Axis → ADCS Power → CubeSense Current Measurements** | | | |
| **CubeSense 3V3 current** | 35 ± 7 mA | 34.9 mA ✓ | 31.5 mA |
| **Cam1 SRAM current** | < 2 mA | 0 mA ✓ | 0 mA |
| **Cam2 SRAM current** | < 2 mA | 0 mA ✓ | 0 mA |
| **Adcs 3-Axis → Raw Sensor Measurements → Raw Cam1 Sensor** | | | |

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| | | | |
|---|---|---|---|
| **Cam1 centroid X** | 0 | ✓ | ✓ |
| **Cam1 centroid Y** | 0 | ✓ | ✓ |
| **Capture Status*** | CaptureSuccessOwn | ✓ | ✓ |
| **Detection Result** | DetectTooFewEdges or DetectSunNotFound | ✓ | ✓ |
| **Adcs 3-Axis → Raw Sensor Measurements → Raw Cam2 Sensor** | | | |
| **Cam2 centroid X** | 0 | ✓ | ✓ |
| **Cam2 centroid Y** | 0 | ✓ | ✓ |
| **Capture Status*** | CaptureSuccessOwn | ✓ | ✓ |
| **Detection Result** | DetectTooFewEdges or DetectSunNotFound | ✓ | ✓ |

* If ***Sun is Above Local Horizon*** is **not** checked the *CubeADCS* expects to be in the eclipse part of its orbit according to the Unix time (or when ***Capture Status*** reads ***CaptureStartup***). This means the CubeACP will **not** sample the raw CubeSense outputs. If this happens change the *CubeACP*'s Unix time to "move" the satellite out of eclipse. This is done at *CubeACP* → *Standard* → *Satellite State* → *Current Unix Time*. (Normal flight software is used for Health Check).

** Except for the aforementioned error flags.

- Take **off** the **Cam1 camera**'s **lens cap**.
- Verify the following from the *Adcs 3-Axis* → *Raw Sensor Measurements* → *Raw Cam1* box by testing the sensor with a light source (a dark environment will prevent false detections). If Cam1 is a **Nadir** sensor then a **large** light source should be used (e.g. a desk lamp), or if Cam1 is a **Sun** sensor then a **small** light source should be used (e.g. narrow beam flash light). Vary the distance between the light source and the sensor until consistent measurements are observed (normally ±150mm). If difficulties are experienced with the Nadir sensor then the light source can be covered with white paper/cloth to create a more uniform light source. Finally, if no results are obtained for the Nadir or Sun sensors the exposure value can be adjusted.

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **Adcs 3-Axis → Raw Sensor Measurements → Raw Cam1 Sensor** | | | |
| **Detection Result** | DetectSuccess | ✓ | |
| **Capture Status*** | CaptureSuccessOwn | ✓ | |
| **Centroid Y** when placing the light close to the camera boresight | Close to zero | ✓ | |

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| | | | |
|---|---|---|---|
| **Centroid Y** when moving the light **up**** | Increasing | ✓ | |
| **Centroid Y** when moving the light **down**** | Decreasing | ✓ | |
| **Centroid X** when placing the light close to the camera boresight | Close to zero | ✓ | |
| **Centroid X** when moving the light to your **right**** | Increasing | ✓ | |
| **Centroid X** when moving the light to your **left**** | Decreasing | ✓ | |

* If ***Sun is Above Local Horizon*** is **not** checked the *CubeADCS* expects to be in the eclipse part of its orbit according to the Unix time (or when ***Capture Status*** reads ***CaptureStartup***). This means the CubeACP will **not** sample the raw CubeSense outputs. If this happens change the *CubeACP*'s Unix time to "move" the satellite out of eclipse. This is done at *CubeACP* → *Standard* → *Satellite State* → *Current Unix Time*. (Normal flight software is used for Health Check).

** When looking at the lens from the front with the camera pins below the lens. Refer to the Appendix A at the end of this document for more detail on the CubeADCS' axes.

- While keeping the light in the field of view of the sun sensor, navigate to *Adcs 3-Axis* → *Save Image* block and Select *Cam1* in the drop-down menu next to *Camera Select*. The *Image size* drop-down menu can be any value, but not selecting *Size0* will reduce the downloading time by lowering the image quality (*Size3* recommended). Capture the image by sending the command by clicking on the green arrow. The camera will capture an image after a delay of 3 seconds. Continue to hold the light in front of the camera for this duration.
- Navigate to *Adcs 3-Axis* → *Status of Image Capture and Save Operation* box. Refresh the box. The *Percentage Complete* will increase slowly, which indicates the process of the image being saved to the SD card from CubeSense's memory.
- Once the *Percentage Complete* reaches 100%, navigate to the *File download* tab.
- Click on the refresh icon in the *Remote File System* block.

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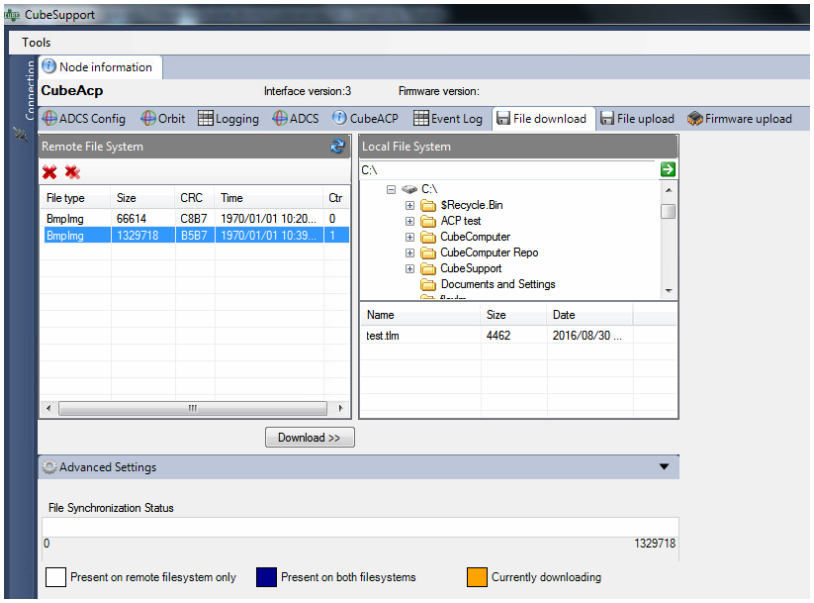


**Figure 9 – *File download* tab**

- Click on the *Bmp.Img* file at the end of the list. Once the file is selected the File Synchronization total size will change to the file size.
- Select a destination path in the Local File System and click the download button. A pop-up menu will appear where a location and file name can be specified, after which the download will start and the *File Synchronization Status* load bar will progress.

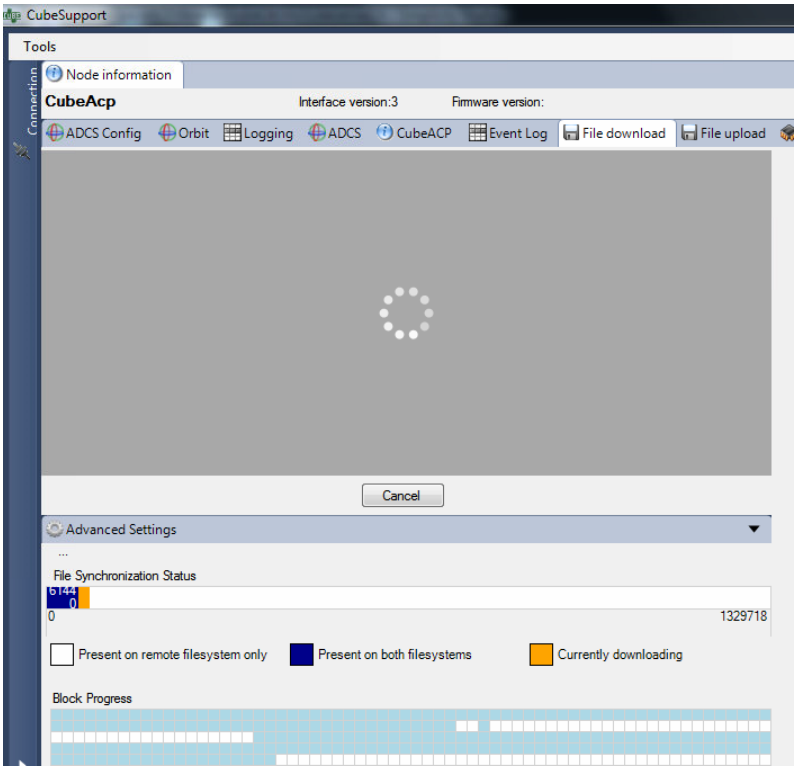


**Figure 10 – Downloading a file**

Signature of tester(s): H Wessels E C Groenewald

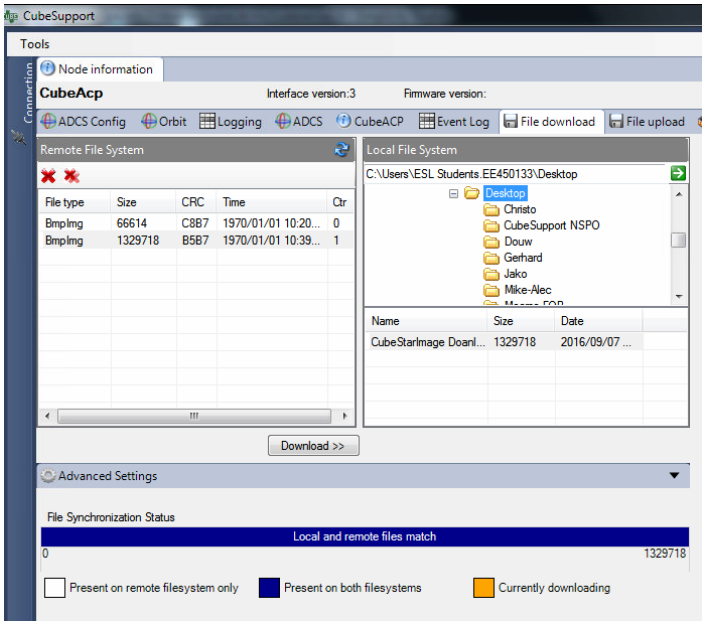


**Figure 11 – File download complete**

- Verify that the light source is clearly visible in the image (large and round for a Nadir sensor, or a small spot for Sun sensor).
- Put the **Cam1** camera's **lens cap** back **on**.
- Take **off** the **Cam2** camera's **lens cap**.
- Navigate back to the *ADCS* tab.
- Verify the following from the *Adcs 3-Axis → Raw Sensor Measurements → Raw Cam2* box by testing the sensor with a light source (a dark environment will prevent false detections). If Cam1 is a **Nadir** sensor then a **large** light source should be used (e.g. a desk lamp), or if Cam1 is a **Sun** sensor then a **small** light source should be used (e.g. narrow beam flash light). Vary the distance between the light source and the sensor until consistent measurements are observed (normally ±150mm). If difficulties are experienced with the Nadir sensor then the light source can be covered with white paper/cloth to create a more uniform light source. Finally, if no results are obtained for the Nadir or Sun sensors the exposure value can be adjusted.

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **ADCS 3-Axis → Raw Sensor Measurements → Raw Cam2 Sensor** | | | |
| **Detection Result** | DetectSuccess | ✓ | |
| **Capture Status*** | CaptureSuccessOwn | ✓ | |
| **Centroid Y** when placing the light close to the camera boresight | Close to zero | ✓ | |

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| | | | |
|---|---|---|---|
| **Centroid Y** when moving the light **up**** | Increasing | ✓ | |
| **Centroid Y** when moving the light **down**** | Decreasing | ✓ | |
| **Centroid X** when placing the light close to the camera boresight | Close to zero | ✓ | |
| **Centroid X** when moving the light to your **right**** | Increasing | ✓ | |
| **Centroid X** when moving the light to your **left**** | Decreasing | ✓ | |

* If ***Sun is Above Local Horizon*** is **not** checked the *CubeADCS* expects to be in the eclipse part of its orbit according to the Unix time (or when ***Capture Status*** reads ***CaptureStartup***). This means the CubeACP will **not** sample the raw CubeSense outputs. If this happens change the *CubeACP*'s Unix time to "move" the satellite out of eclipse. This is done at *CubeACP* → *Standard* → *Satellite State* → *Current Unix Time*. (Normal flight software is used for Health Check).

** When looking at the lens from the front with the camera pins below the lens. Refer to the Appendix A at the end of this document for more detail on the CubeADCS' axes.

- Follow the previous steps again to download a Cam2 camera image by selecting *Cam2* in the drop-down list. Remember to keep the light source in the field of view of the camera for the 3 seconds of image capture.
- Verify that the light source is clearly visible in the image (large and round for a Nadir sensor, or a small spot for Sun sensor).
- Put the **Cam2** sensor's **lens cap** back **on**.
- Switch **off CubeSense** in the *ADCS Power Control* box.

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# 5. CubeControl

## 5.1 CubeControl Signal MCU

Follow the instructions below to perform the CubeControl Signal MCU health check:

- Switch **on CubeControl Signal MCU** by selecting *PowOn* in the drop-down menu next to *CubeControl Signal Power Selection* in the *ADCS Power Control* box and transmit the command by clicking on the green arrow.
- Verify the following under the *ADCS* tab:

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **ADCS 3-Axis → ADCS state → Current ADCS State** | | | |
| **ADCS Run Mode** | AdcsEnabled | ✓ | ✓ |
| **Attitude Estimation Mode** | EstNone | ✓ | ✓ |
| **Control Mode** | ConNone | ✓ | ✓ |
| **CubeControl Signal Enabled** | Checked | ✓ | ✓ |
| **All other checkboxes*** | Unchecked | ✓ | ✓ |
| **ADCS 3-Axis → ADCS Power → CubeControl Current Measurements** | | | |
| **CubeControl 3V3 Current** | 30 ± 10 mA | 29.29 mA ✓ | 29.30 mA |
| **CubeControl 5V Current** | 5 ± 4 mA | 3.42 mA ✓ | 3.42 mA |
| **CubeControl Vbat Current** | < 4 mA | 0.98 mA ✓ | 0.98 mA |
| **ADCS 3-Axis → ADCS Power → ADCS Temperatures** | | | |
| **Magnetometer Temperature** | Near room temp | 24.5 °C ✓ | 24.8 °C ✓ |
| **MCU Temperature** | Near room temp | 27 °C ✓ | 28 °C ✓ |
| **ADCS 3-Axis → Raw Sensor Measurements → Raw Css1 to Css6** | | | |
| **CSS1** | 8 ± 5 | ✓ | |
| **CSS2** | 8 ± 5 | ✓ | |
| **CSS3** | 8 ± 5 | ✓ | |
| **CSS4** | 8 ± 5 | ✓ | |
| **CSS5** | 8 ± 5 | ✓ | |
| **CSS6** | 8 ± 5 | ✓ | |
| **ADCS 3-Axis → Raw Sensor Measurements → Raw Css7 to Css10** | | | |
| **CSS7** | 8 ± 5 | ✓ | |
| **CSS8** | 8 ± 5 | ✓ | |

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| | | | |
|---|---|---|---|
| **CSS9** | 8 ± 5 | ✓ | |
| **CSS10** | 8 ± 5 | ✓ | |

* Except for the aforementioned error flags and *Sun is Above Local Horizon*.

- Expose the coarse sun sensors to a bright light, one by one.
- Verify the following:

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **ADCS 3-Axis → Raw Sensor Measurements → Raw Css1 to Css10** | | | |
| Raw measurements when **exposed** to light | > 50 (each channel) | ✓ | |

- Go to *ADCS 3-Axis → ADCS state → Current ADCS State* and ensure that the *Magnetometer Range Error* is **not** checked. If it is checked the magnetometer is unable to measure a sufficient/overpowering magnetic field. This can be solved by placing the magnetometers away from motors, power supplies, large ferromagnetic objects, *etc.* or ensuring no contact to an anti-static mat.
- Familiarise the **axes** of the magnetometer, as shown at the end of this document in Appendix A.
- Navigate to *Adcs 3-Axis - Raw Sensor Measurements* and verify the operation of the magnetometers by using the *Raw Magnetometer*. Choose an axis on the magnetometer and point it in the positive direction of the magnetic field lines (north) to align the axis with the magnetic vector. Now rotate the magnetometer around this axis. The chosen axis must remain positive while the other two axes will both go negative and positive though the rotation. Repeat this for all three axes to verify polarities.

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **ADCS 3-Axis → Raw Sensor Measurements** | | | |
| **Raw Magnetometer shows varying values in X, Y and Z directions correctly** | ✓ | ✓ | ✓ |

- Navigate to *Adcs 3-Axis – Adcs Measurements → Magnetic Field vector*. Rotate the magnetometer and verify that the magnetic field vector displays both positive and negative in X, Y, and Z directions correctly. Fill the following table accordingly:

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|

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| ADCS 3-Axis → Adcs Measurements → Magnetic Field Vector | | | |
|---|---|---|---|
| **Magnetic Field can measure both positive and negative in X, Y and Z directions** | ✓ | ✓ | ✓ |

Test the magnetorquer rods and coil by following the procedure below:

- Navigate to the *Adcs 3-Axis-Actuator-Commands* → *Set Magnetorquer Output* box. Command the magnetorquer coil (X-axis) to maximum positive direction by setting the slider bar all the way to the right next to *Command X Magnetorquer* and send the command by clicking on the green arrow.
- Confirm the current measurement and the direction of magnetic field in the table below. The direction can be confirmed by placing a compass directly in line with the magnetorquer and observing the field direction or using an external magnetometer. Note that the magnetorquer pulses on for a maximum of 0.8 seconds and then switches off.
- Change the command to maximum negative and confirm the current and direction again.
- Command the magnetorquer to 0 to turn off the magnetorquer.
- Repeat these steps for the Y and Z magnetorquer rods and record the required values below.

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **ADCS 3-Axis - ADCS Power → ADCS Misc/CubeControl Current Measurements** | | | |
| **(X) Magnetorquer Current** | 120 ± 20 mA | 133.7 mA ✓ | 133.5 mA |
| **X Magnetorquer direction of magnetic field with max positive command** | +X | ✓ | ✓ |
| **X Magnetorquer direction of magnetic field with max negative command** | -X | ✓ | ✓ |
| **(Y) Magnetorquer Current** | 65 ± 10 mA | 66.6 mA ✓ | 65.7 mA |
| **Y Magnetorquer direction of magnetic field with max positive command** | +Y | ✓ | ✓ |
| **Y Magnetorquer direction of magnetic field with max negative command** | -Y | ✓ | ✓ |

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| | | | |
|---|---|---|---|
| **(Z) Magnetorquer Current** | 65 ± 10 mA | 65.7 mA ✓ | 65.7 mA |
| **Z Magnetorquer direction of magnetic field with max positive command** | +Z | ✓ | ✓ |
| **Z Magnetorquer direction of magnetic field with max negative command** | -Z | ✓ | ✓ |

- Ensure that all the magnetorquers are set to 0 (turned off) before continuing the test.

## 5.2 CubeControl Motor and Signal MCU

Follow the instructions below to perform the CubeControl MCU health check:

- Switch **on** CubeControl's **Motor MCU** by selecting *PowOn* in the drop-down menu next to *CubeControl Signal Power Selection* in the *ADCS Power Control* box and transmit the command by clicking on the green arrow. (*CubeControl Signal Power Selection* must remain enabled).
- Verify the following:

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **ADCS 3-Axis → ADCS state → Current ADCS State** | | | |
| **ADCS Run Mode** | AdcsEnabled | ✓ | ✓ |
| **Attitude Estimation Mode** | EstNone | ✓ | ✓ |
| **Control Mode** | ConNone | ✓ | ✓ |
| **CubeControl Signal Enabled** | Checked | ✓ | ✓ |
| **CubeControl Motor Enabled** | Checked | ✓ | ✓ |
| **All other checkboxes*** | Unchecked | ✓ | ✓ |
| **ADCS 3-Axis → ADCS Power → CubeControl Current Measurements** | | | |
| **CubeControl 3V3 Current** | 65 ± 15 mA | 60.5 mA ✓ | 60.5 mA |
| **CubeControl 5V Current** | 5 ± 4 mA | 3.42 mA ✓ | 3.42 mA |
| **CubeControl Vbat Current** | < 4 mA | 0.98 mA ✓ | 0.98 mA |
| **ADCS 3-Axis → ADCS Power → ADCS Temperatures** | | | |
| **Magnetometer Temperature** | Near room temp | 24.8 °C ✓ | 26.8 °C ✓ |
| **MCU Temperature** | Near room temp | 27 °C ✓ | 29 °C ✓ |
| **Adcs 3-Axis → ADCS Power → Rate sensor temperatures** | | | |
| **X-Rate Sensor Temperature** | Near room temp | 21 °C ✓ | 23 °C ✓ |

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| | | | |
|---|---|---|---|
| **Y-Rate Sensor Temperature** | Near room temp | 25 °C ✓ | 27 °C ✓ |
| **Z-Rate Sensor Temperature** | Near room temp | 21 °C ✓ | 24 °C ✓ |

* Except for the aforementioned error flags and *Sun is Above Local Horizon*.

- Rotate the magnetometer and confirm that the values in the *Raw Magnetometer* box change. Ensure that the X, Y and Z axes display both positive and negative values.

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **ADCS 3-Axis → Raw Sensor Measurements** | | | |
| **Raw Max X, Mag Y and Mag Z measurements can measure both positive and negative** | ✓ | ✓ | ✓ |

- Switch **off** CubeControl's **Signal MCU** by selecting *PowOff* in the drop-down menu next to *CubeControl Signal Power Selection* in the *ADCS Power Control* box and transmit the command by clicking on the green arrow.
- Only the CubeControl Motor MCU should now be on.

## 5.3 CubeControl Motor MCU

- Verify the following:

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **ADCS 3-Axis → ADCS state → Current ADCS State** | | | |
| **ADCS Run Mode** | AdcsEnabled | ✓ | ✓ |
| **Attitude Estimation Mode** | EstNone | ✓ | ✓ |
| **Control Mode** | ConNone | ✓ | ✓ |
| **CubeControl Motor Enabled** | Checked | ✓ | ✓ |
| **All other checkboxes*** | Unchecked | ✓ | ✓ |
| **ADCS 3-Axis → ADCS Power → Rate sensor temperatures** | | | |
| **X-Rate Sensor Temperature** | Near room temp | 18 °C ✓ | 23 °C ✓ |
| **Y-Rate Sensor Temperature** | Near room temp | 23 °C ✓ | 27 °C ✓ |
| **Z-Rate Sensor Temperature** | Near room temp + 10°C | 19 °C ✓ | 24 °C ✓ |
| **ADCS 3-Axis - ADCS Measurements → Rate Sensor Rates** | | | |

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| | | | |
|---|---|---|---|
| **X-rate can be positive or negative (tilt the unit)** | ✓ | ✓ | ✓ |
| **Y-rate can be positive or negative (tilt the unit)** | ✓ | ✓ | ✓ |
| **Z-rate can be positive or negative (tilt the unit)** | ✓ | ✓ | ✓ |

* Except for the aforementioned error flags and *Sun is Above Local Horizon*.

- Rotate the magnetometer and confirm that the values in the *Raw Magnetometer* box change. Ensure that the X, Y and Z axes display both positive and negative values.

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **ADCS 3-Axis → Raw Sensor Measurements** | | | |
| **Raw Magnetometer shows varying values in X, Y and Z directions correctly** | ✓ | ✓ | ✓ |

Test the magnetorquer rods and coil by following the procedure below:

- Navigate to the *Adcs 3-Axis-Actuator-Commands → Set Magnetorquer Output* box. Command the magnetorquer coil (X-axis) to maximum positive direction by setting the slider bar all the way to the right next to *Command X Magnetorquer* and send the command by clicking on the green arrow.
- Confirm the current measurement and the direction of magnetic field in the table below. The direction can be confirmed by placing a compass directly in line with the magnetorquer and observing the field direction or using an external magnetometer. Note that the magnetorquer pulses on for a maximum of 0.8 seconds and then switches off.
- Change the command to maximum negative and confirm the current and direction again.
- Command the magnetorquer to 0 to turn off the magnetorquer.
- Repeat these steps for the Y and Z magnetorquer rods and record the required values below.

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **ADCS 3-Axis → ADCS Power → ADCS Misc/CubeControl Current Measurements** | | | |
| **(X) Magnetorquer Current** | 120 ± 20 mA | 132.5 mA ✓ | 131.8 mA |

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| | | | |
|---|---|---|---|
| **X Magnetorquer direction of magnetic field with max positive command** | +X | ✓ | |
| **X Magnetorquer direction of magnetic field with max negative command** | -X | ✓ | |
| **(Y) Magnetorquer Current** | 65 ± 10 mA | 66 mA ✓ | 65.4 mA |
| **Y Magnetorquer direction of magnetic field with max positive command** | +Y | ✓ | |
| **Y Magnetorquer direction of magnetic field with max negative command** | -Y | ✓ | |
| **(Z) Magnetorquer Current** | 65 ± 10 mA | 65.6mA ✓ | 64.9 mA |
| **Z Magnetorquer direction of magnetic field with max positive command** | +Z | ✓ | |
| **Z Magnetorquer direction of magnetic field with max negative command** | -Z | ✓ | |

- Ensure that all the magnetorquers are set to 0 power (turned off) before continuing the test.

## 5.4 CubeControl Motor Health check

This section is only applicable to the Y-Momentum ADCS where the y-momentum wheel is mounted on CubeControl.

- Switch **on Motor Power** by selecting *PowOn* in the drop-down menu next to *Motor Power Selection* in the *ADCS Power Control* box and transmit the command by clicking on the green arrow. (CubeControl Motor MCU must remain powered on)
- Verify the following:

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **ADCS 3-Axis → ADCS state → Current ADCS State** | | | |
| **ADCS Run Mode** | AdcsEnabled | ✓ | ✓ |
| **Attitude Estimation Mode** | EstNone | ✓ | ✓ |
| **Control Mode** | ConNone | ✓ | ✓ |
| **CubeControl Motor Enabled** | Checked | ✓ | ✓ |

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| | | | |
|---|---|---|---|
| **Motor Driver Enabled** | Checked | ✓ | ✓ |
| **All other checkboxes*** | Unchecked | ✓ | ✓ |

* Except for the aforementioned error flags and *Sun is Above Local Horizon*.

- Navigate to *Adcs 3-Axis – Actuator commands*, and in the *Set Wheel Speed* box, set the *Commanded Y speed* to 4000rpm (the axis of the wheel can later be changed in the *ADCS Config* tab).
- Verify the following after 20 seconds:

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **ADCS 3-Axis → ADCS Measurements → Wheel Speed** | | | |
| **Y Wheel Speed** | 4000 ± 10 rpm | ✓ | ✓ |
| **ADCS 3-Axis → ADCS Power → Wheel Currents** | | | |
| **Wheel2Current** | 15 ± 9 mA | 16.16 mA ✓ | 15.18 mA |

- Command the wheel speed to -2000 RPM.
- Verify the following after 20 seconds:

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **ADCS 3-Axis → ADCS Measurements → Wheel Speed** | | | |
| **Y Wheel Speed** | -2000 ± 10 rpm | ✓ | ✓ |
| **ADCS 3-Axis → ADCS Power → Wheel Currents** | | | |
| **Wheel2Current** | 9 ± 9 mA | 10.5 mA ✓ | 10.04 mA |

- Command the wheel speed to 0 RPM
- Verify the following after 20 seconds:

| Test / Task | Expected Result | Observed Result | User Observed Results |
|---|---|---|---|
| **ADCS 3-Axis → ADCS Measurements → Wheel Speed** | | | |
| **Y Wheel Speed** | 0 | ✓ | ✓ |
| **ADCS 3-Axis → ADCS Power → Wheel Currents** | | | |
| **Wheel2Current** | 7 ± 9 mA | 3.79 mA ✓ | 3.79 mA |

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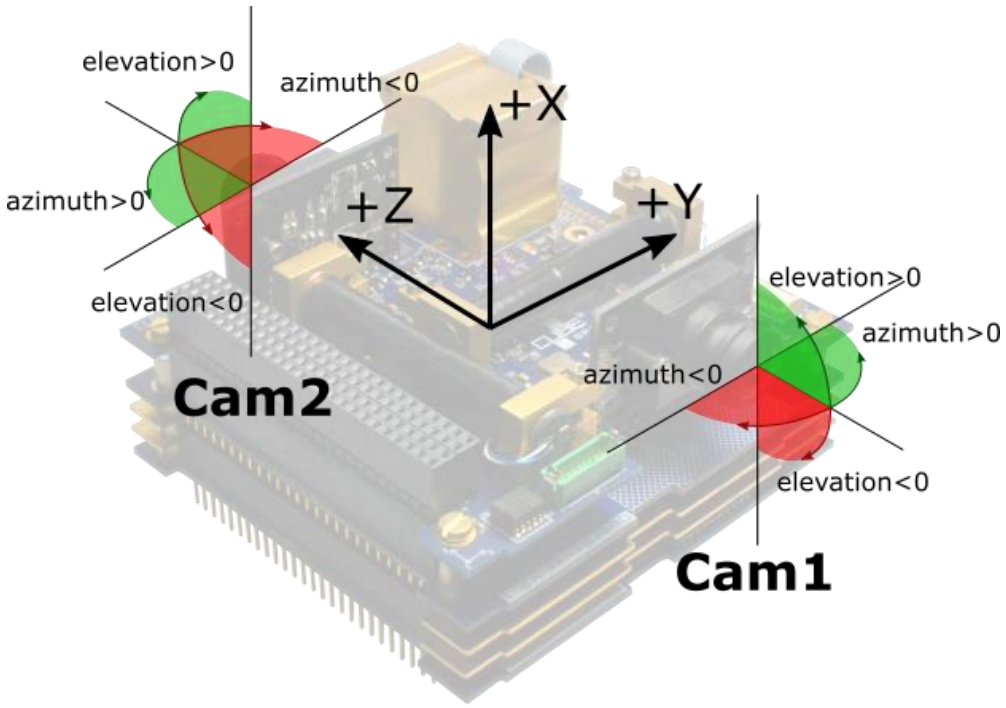
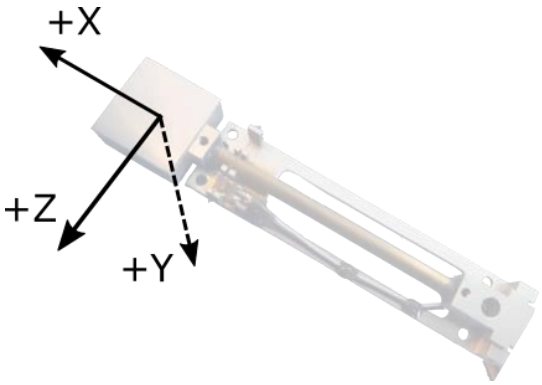
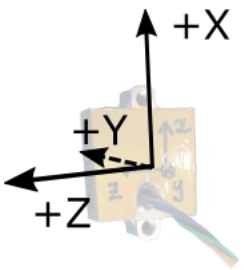
# 6. Appendix A: CubeADCS Axes




**CubeADCS and CubeSense Cameras**




**Main Magnetometer**




**Redundant Magnetometer**

Signature of tester(s): H Wessels & C Groenewald

# 7. Document Version History

| Version | Responsible person(s) | Pages | Date | Description of change |
|---|---|---|---|---|
| 3.0 | MK | ALL | 20/03/2017 | V3 First draft |
| 3.02 | CJG | ALL | 15/05/2017 | Added client column |
| 3.03 | CJG | 29-31 | 06/06/2017 | Updated the CubeStar Health Check. |
| 3.04 | CJG | 8,<br>17,<br>18-19 | 15/06/2017 | Changed wait time for ACP boot to 10s.<br>Updated magnetometer test description.<br>Removed unnecessary current measurements. |
| 3.05 | CJG | 9 | 22/06/2017 | Updated the firmware version |
| 3.06 | CJG | All | 18/07/2017 | Updated and added bootloader section. |
| 3.07 | CJG | ALL | 03/08/2017 | Added y-Momentum ADCS Wheel Test |
| 3.08 | HW | 7 | 19/01/2018 | Improved readability |
| 3.09 | CJG | 12 | 15/02/2018 | Updated the ACP Image |
| 3.10 | HW | CubeSense | 26/02/2018 | Changed naming of Nadir/Sun to Cam1/Cam2, and improved readability. |
| 3.11 | HW | CubeControl | 27/02/2018 | Improved magnetometer checks, measurement tolerances, and various small things. |
| 3.12 | HW | CubeSense | 07/03/2018 | Added rough check for CubeSense camera boresight verification |
| 3.13 | HW | CubeSense<br>CubeStar<br>CubeADCS Axes | 03/04/2018 | Improved CubeSense download readability<br>Updated CubeStar Health Check<br>Improved CubeADCS Axes Appendix |
| 3.14 | HW | CubeStar<br>CubeSense | 06/04/2018 | Updated CubeStar Detection timing range<br>Updated eclipse solution description |
| 3.15 | HW | CubeControl<br>All | 19/04/2018 | Fixed Momentum wheel tests<br>Combined 3-Axis and Y-Mom Documents |