

# 操作系统实验报告

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# 实验：Tiny Shell 代码实现

## 1. 概述

### 1.1 实验任务

通过代码填空的方式实现一个简单的 linux shell，拥有执行前后台作业、查看作业信息、回收僵尸进程、暂停/恢复/终止作业等功能。

### 1.2 结果综述

1. 成功实现了一个 Tiny shell，通过了附带的 16 个 test 脚本测试，并具有一定鲁棒性，对于系统调用以及所有可能出错的函数都提供了 error handling，有能力应对 test 之外的其他苛刻情况。

2. 本实验所完成的 shell，输出并不遵循 shlab.pdf 中的要求——与 tshref 的输出一模一样，但也完成了相关工作。

## 2. 实验过程及结果

### 2.1 目的

The purpose of this assignment is to become more familiar with the concepts of process control and signalling。

### 2.2 实验内容要点

1. The prompt should be the string "tsh> "

这一点 tsh.c 中已经实现了，并且提供了开关 prompt 和 verbose 的一些 api。不过这些都是测试所使用的，和完成实验关系不大。

2. 分析 command line，如果输入的是内置指令，则立即执行，如果不是，则当成是一个可执行文件的路径，并 fork 一个子进程，执行该可执行文件

这一点在 tshref（实验所给的参考 shell 程序）中输入一个非法文件路径，会被当成一个未知指令，而不是一个非法的文件路径。而在我的 tinysql 中，这一点被实现了。

#### <1>parse()函数

tsh.c 中已经写好了一个 parse 函数，这个函数会忽略所有前导 space，将 command line 根据空格分割，构造 argv 参数列表，并将 argv 的最后一个元素置为 NULL（为了符合 execv 的参数要求）。parse()同时还提供了单引号的忽略功能。总体来说不是很鲁棒，但也够用了。需要注意的是该函数申请了一个静态 char 数组 array，用于临时存储 command line。因为在 parse()的实现里，argv 是指向 array，所以 array 必须是静态的，否则当 parse()结束之后，argv 不但会失去作用，而且会成为野指针。

<2>其次，在 eval 函数中实现小标题所提出的功能

使用 parse()分析 command line 得到相应信息：

- (1) 若是空指令或者非正常指令，则直接 return；
- (2) 若是 built in command，则调用 builtin\_cmd()，该函数的具体实现逻辑无需多讲，需要注意的是：在所有对 joblist 有写操作的语句两侧都要 mask 掉所有 signal 再恢复，防止 Races。
- (3) 若以上均不是，则将 argv 的第一个元素当做一个可执行文件，再 fork()出一个子程序（在 fork()前需要 mask 掉 sigchild 信号），再使用 execv()执行。同样，父进程中后续的 job 添加等语句也需要 mask 掉所有 signal。最后，根据 FG/BG 信息判断是否要执行 waitfg()。

<3>虽然实验中没有明文要求，但显然对于 BG、FG、ST 三种状态的相互转换的情况都要考虑到：

- (1) BG->FG：通过 fg 容易实现，解析参数，错误判断，安全地取出 job 和修改状态，通过 kill 发送 SIGCONT 信号（如果进程已经在 running，则默认不会对 SIGCONT 做出反应），调用 waitfg()。
- (2) FG->ST：在 sigchild handler 中通过解析子进程暂停状态实现，下文详细介绍。
- (3) ST->FG：通过 fg 容易实现，解析参数，错误判断，安全地取出 job 和修改状态，通过 kill 发送 SIGCONT 信号，调用 waitfg()。
- (4) ST->BG：通过 bg 容易实现，解析参数，错误判断，安全地取出 job 和修改状态，通过 kill 发送 SIGCONT 信号。
- (5) BG->ST：用户无法发出此类命令，因为 shell 不会向 background job 发送 SIGTSTP 信号。
- (6) FG->BG：用户无法发出此类命令，因为 shell 在有 foreground job running 时不会执行 bg 指令。但是由于标准输入流的缓冲和进程之间是独立并发运作的，所以实际上在 foreground job running 时输入的命令仍然会被存入缓冲区，并且在下一次 shell 的主循环执行时会被当做 command line 读入，这一特色对于各种批处理脚本（包括这次作业的 test 脚本）来说都是无碍甚至必要的，但是对于个别用户来说可能会造成困扰。我在 sigchild handler 的相应位置加入了一些代码（默认是被注释掉的，不启动该功能），使得每次 foreground job 结束时，都会先清空 stdin 缓冲，再读入新指令，以满足某些用户的特定需求。

<4>waitfg()的实现

在 shell 内定义全局变量 waiting，代表 shell 是否正在等待一个前台进程结束\暂停，并在 sigchild handler 中对于当前 foreground job 子进程的结束作特殊判断，以决定是否改变 waiting 的值。具体的实现遵照 pdf 的 hint，在 waitfg()通过 while 循环加上 sleep 的方式实现等待，暂不考虑性能优化。另外，在 while 循环前后将 SIGCHLD 信号的 mask 取消、恢复，可以增强 waitfg()的鲁棒性，避免死锁。

<5>execv 的参数构造

虽然最终的结果是不需要做额外的更改，但是思考是必要的。

```
int execv(const char *pathname, char *const argv[])
```

首先，execv()不返回（这无关紧要）。至于 execv()参数，需要 shell 事先准备好要传入这两个参数的变量，然后它们会被 fork()复制一份，最后传入 execv()。但这两个参数都是指针，于是有以下问题：

- (1) 如何保证指针使用的安全性

传入 execv()的指针指向的数据会被操作系统以特定方式（分别以'\0'和 NULL 为结尾）复制一份，并新申请相应的内存空间，且指针指向的内存是被复制的那一份所申请的新内存，所以不需要担心内存泄漏或者是野指针。

- (2) 如何保证指针取出的数据是正确的

同理，虽然 parse()返回的 argv 指向的是静态变量 array，且该变量会在 shell 下一次调用 parse()的时候被改变，但是 argv 在传入 execv()之后指向的已经不是 shell 进程 array 了，所以没有关系。

- (3) 在 fork()之后，子进程执行 execv()之前，主进程可能就执行了下一次 parse()，静态变量 array 的值可

能会被改变，从而 `evectv()` 复制时会得到错误的参数？

在 `fork()` 执行之后，主进程 `shell` 的静态变量 `array`，以及指向它的指针 `argv` 都会被子进程完全独立地复制一份，且指针的取值是根据进程重定位的。所以在 `fork()` 之后，即使 `shell` 第二次执行了 `parse()`，也只会改变 `shell` 本身的静态变量 `array`，不会影响子进程的 `array`。

3. `ctrl-c`(`ctrl-z`)会向 foreground job 及所有其衍生进程发送 `SIGINT`(`SIGTSTP`)信号，若没有前台进程，则没有影响。

该部分的实现逻辑也很繁复，使用 `signalmask` 保证对于 `joblist` 的安全存取就不再赘述，主要说两个重点：

#### <1>使用进程组实现 signal 的正确广播

这一点在 pdf 中也被反复提及。`Shell` 需要将 `SIGINT` 和 `SIGTSTP` 发送到 foreground job 及其所有衍生进程，能做到这一点的就是 `kill` 的进程组广播用法，以及 `fork()`“子进程和父进程同属一个进程组”的功能的结合。

在 `shell` 的实现中，每个 job 都要有不同的进程组 id，且要和 `shell` 进程的进程组 id 不同，原因有二：

(1) 防止发送给 foreground job 及其衍生进程的 signal 被广播给其他 job 或者 `shell` 本身。

(2) 发送给 `shell` 的 signal 被直接广播给 jobs。

发送操作自然是通过 `sigint` handler 和 `sigtstp` handler，就是简单的 `getjobpid()`、`kill()` 等操作。

需要注意的一点：

在 `eval()` 中 `fork()` 子进程后，调用 `setpgid()`，使 `shell` 设置其子进程的进程组 ID，然后使子进程设置其自己的进程组 ID。这些调用中有一个是冗余的，但这样做可以保证父、子进程在进一步操作之前，子进程都进入了该进程组。否则依赖于哪一个进程先执行，就产生一个竞态条件。

#### <2>使用 `waitpid()` 取得子进程信息

`waitpid()` 不但可以非阻塞地等待子进程结束\暂停，还能通过 `status` 参数获得子进程的结束信息。通过一些宏可以方便地解析 `status`，以实现在 `sigchild` handler 中根据子进程的结束\暂停原因，来对 `joblist` 做更改、输出反馈信息。具体实现见代码，在此不列举。

## 2.3 实验结果描述

```
终端
文件(F) 编辑(E) 查看(V) 搜索(S) 终端(T) 帮助(H)
[localhost:~/桌面/shelllab/shlab-handout]
# make test01
./sdriver.pl -t trace01.txt -s ./tsh -a "-p"
#
# trace01.txt - Properly terminate on EOF.
#
[localhost:~/桌面/shelllab/shlab-handout]
# make test02
./sdriver.pl -t trace02.txt -s ./tsh -a "-p"
#
# trace02.txt - Process builtin quit command.
#
[localhost:~/桌面/shelllab/shlab-handout]
# make test03
./sdriver.pl -t trace03.txt -s ./tsh -a "-p"
#
# trace03.txt - Run a foreground job.
#
tsh> quit
[localhost:~/桌面/shelllab/shlab-handout]
# make test04
./sdriver.pl -t trace04.txt -s ./tsh -a "-p"
#
# trace04.txt - Run a background job.
#
tsh> ./myspin 1 &
[1] (8478) ./myspin 1 &
[localhost:~/桌面/shelllab/shlab-handout]
#
```

```
终端
文件(F) 编辑(E) 查看(V) 搜索(S) 终端(T) 帮助(H)
[localhost:~/桌面/shelllab/shlab-handout]
# make test05
./sdriver.pl -t trace05.txt -s ./tsh -a "-p"
#
# trace05.txt - Process jobs builtin command.
#
tsh> ./myspin 2 &
[1] (8598) ./myspin 2 &
tsh> ./myspin 3 &
[2] (8600) ./myspin 3 &
tsh> jobs
[1] (8598) Running ./myspin 2 &
[2] (8600) Running ./myspin 3 &
[localhost:~/桌面/shelllab/shlab-handout]
# make test06
./sdriver.pl -t trace06.txt -s ./tsh -a "-p"
#
# trace06.txt - Forward SIGINT to foreground job.
#
tsh> ./myspin 4
Job [1] (8607) terminated by signal 2
[localhost:~/桌面/shelllab/shlab-handout]
# make test07
./sdriver.pl -t trace07.txt -s ./tsh -a "-p"
#
# trace07.txt - Forward SIGINT only to foreground job.
#
tsh> ./myspin 4 &
[1] (8614) ./myspin 4 &
tsh> ./myspin 5
Job [2] (8616) terminated by signal 2
tsh> jobs
[1] (8614) Running ./myspin 4 &
[localhost:~/桌面/shelllab/shlab-handout]
#
```

```
终端
文件(F) 编辑(E) 查看(V) 搜索(S) 终端(T) 帮助(H)
[localhost:~/桌面/shelllab/shlab-handout]
# make test08
./sdriver.pl -t trace08.txt -s ./tsh -a "-p"
#
# trace08.txt - Forward SIGTSTP only to foreground job.
#
tsh> ./myspin 4 &
[1] (9124) ./myspin 4 &
tsh> ./myspin 5
Job [2] (9126) stopped by signal 20
tsh> jobs
[1] (9124) Running ./myspin 4 &
[2] (9126) Stopped ./myspin 5
[localhost:~/桌面/shelllab/shlab-handout]
# make test09
./sdriver.pl -t trace09.txt -s ./tsh -a "-p"
#
# trace09.txt - Process bg builtin command
#
tsh> ./myspin 4 &
[1] (9133) ./myspin 4 &
tsh> ./myspin 5
Job [2] (9135) stopped by signal 20
tsh> jobs
[1] (9133) Running ./myspin 4 &
[2] (9135) Stopped ./myspin 5
tsh> bg %2
[2] (9135) ./myspin 5
tsh> jobs
[1] (9133) Running ./myspin 4 &
[2] (9135) Running ./myspin 5
[localhost:~/桌面/shelllab/shlab-handout]
#
```

```
终端
文件(F) 编辑(E) 查看(V) 搜索(S) 终端(T) 帮助(H)
[localhost:~/桌面/shelllab/shlab-handout]
# make test10
./sdriver.pl -t trace10.txt -s ./tsh -a "-p"
#
# trace10.txt - Process fg builtin command.
#
tsh> ./myspin 4 &
[1] (9210) ./myspin 4 &
tsh> fg %1
Job [1] (9210) stopped by signal 20
tsh> jobs
[1] (9210) Stopped ./myspin 4 &
tsh> fg %1
tsh> jobs
[localhost:~/桌面/shelllab/shlab-handout]
# make test11
./sdriver.pl -t trace11.txt -s ./tsh -a "-p"
#
# trace11.txt - Forward SIGINT to every process in foreground process group
#
tsh> ./mysplit 4
Job [1] (9220) terminated by signal 2
tsh> /bin/ps a
  PID TTY          STAT TIME  COMMAND
 1182 tty2        Ssl+   0:00 /usr/lib/gdm3/gdm-x-session --run-script env GNOME_SHELL_SESS
ION_MODE=ubuntu /usr/bin/gnome-session --session=ubuntu
 1184 tty2        Rl+    1:58 /usr/lib/xorg/Xorg vt2 -displayfd 3 -auth /run/user/0/gdm/Xau
thority -background none -noreset -keeptty -verbose 3
 1308 tty2        Sl+    0:00 /usr/lib/gnome-session/gnome-session-binary --session=ubuntu
 1627 tty2        Rl+    4:52 /usr/bin/gnome-shell
 1692 tty2        Sl     0:09 ibus-daemon --xim --panel disable
 1710 tty2        Sl     0:00 /usr/lib/ibus/ibus-dconf
 1711 tty2        Sl     0:02 /usr/lib/ibus/ibus-extension-gtk3
 1713 tty2        Sl     0:00 /usr/lib/ibus/ibus-x11 --kill-daemon
 1928 tty2        Sl+    0:00 /usr/lib/gnome-settings-daemon/gsd-power
 1930 tty2        Sl+    0:00 /usr/lib/gnome-settings-daemon/gsd-print-notifications
```

```
终端
文件(F) 编辑(E) 查看(V) 搜索(S) 终端(T) 帮助(H)
[localhost:~/桌面/shelllab/shlab-handout]
# make test12
./sdriver.pl -t trace12.txt -s ./tsh -a "-p"
#
# trace12.txt - Forward SIGTSTP to every process in foreground process group
#
tsh> ./mysplit 4
Job [1] (9449) stopped by signal 20
tsh> jobs
[1] (9449) Stopped ./mysplit 4
tsh> /bin/ps a
  PID TTY          STAT       TIME COMMAND
 1182 tty2      Ssl+      0:00 /usr/lib/gdm3/gdm-x-session --run-script env GNOME_SHELL_SESS
ION_MODE=ubuntu /usr/bin/gnome-session --session=ubuntu
 1184 tty2      Sl+       2:08 /usr/lib/xorg/Xorg vt2 -displayfd 3 -auth /run/user/0/gdm/Xau
thority -background none -noreset -keeptty -verbose 3
 1308 tty2      Sl+       0:00 /usr/lib/gnome-session/gnome-session-binary --session=ubuntu
 1627 tty2      Rl+       5:12 /usr/bin/gnome-shell
 1692 tty2      Sl        0:09 ibus-daemon --xim --panel disable
 1710 tty2      Sl        0:00 /usr/lib/ibus/ibus-dconf
 1711 tty2      Sl        0:02 /usr/lib/ibus/ibus-extension-gtk3
 1713 tty2      Sl        0:00 /usr/lib/ibus/ibus-x11 --kill-daemon
 1928 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-power
 1930 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-print-notifications
 1932 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-rfkill
 1933 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-screensaver-proxy
 1934 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-sharing
 1935 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-smartcard
 1946 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-sound
 1947 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-wacom
 1948 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-xsettings
 1968 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-a11y-settings
 1972 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-clipboard
 1974 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-color
 1976 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-datetime
 1978 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-housekeeping
```

```
终端
文件(F) 编辑(E) 查看(V) 搜索(S) 终端(T) 帮助(H)
[localhost:~/桌面/shelllab/shlab-handout]
# make test13
./sdriver.pl -t trace13.txt -s ./tsh -a "-p"
#
# trace13.txt - Restart every stopped process in process group
#
tsh> ./mysplit 4
Job [1] (9558) stopped by signal 20
tsh> jobs
[1] (9558) Stopped ./mysplit 4
tsh> /bin/ps a
  PID TTY          STAT       TIME COMMAND
 1182 tty2      Ssl+      0:00 /usr/lib/gdm3/gdm-x-session --run-script env GNOME_SHELL_SESS
ION_MODE=ubuntu /usr/bin/gnome-session --session=ubuntu
 1184 tty2      Sl+       2:12 /usr/lib/xorg/Xorg vt2 -displayfd 3 -auth /run/user/0/gdm/Xau
thority -background none -noreset -keeptty -verbose 3
 1308 tty2      Sl+       0:00 /usr/lib/gnome-session/gnome-session-binary --session=ubuntu
 1627 tty2      Sl+       5:17 /usr/bin/gnome-shell
 1692 tty2      Sl        0:10 ibus-daemon --xim --panel disable
 1710 tty2      Sl        0:00 /usr/lib/ibus/ibus-dconf
 1711 tty2      Sl        0:02 /usr/lib/ibus/ibus-extension-gtk3
 1713 tty2      Sl        0:00 /usr/lib/ibus/ibus-x11 --kill-daemon
 1928 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-power
 1930 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-print-notifications
 1932 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-rfkill
 1933 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-screensaver-proxy
 1934 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-sharing
 1935 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-smartcard
 1946 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-sound
 1947 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-wacom
 1948 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-xsettings
 1968 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-a11y-settings
 1972 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-clipboard
 1974 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-color
 1976 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-datetime
 1978 tty2      Sl+       0:00 /usr/lib/gnome-settings-daemon/gsd-housekeeping
```

```
终端
文件(F) 编辑(E) 查看(V) 搜索(S) 终端(T) 帮助(H)
9565 pts/0    R      0:00 /bin/ps a
[localhost:~/桌面/shelllab/shlab-handout]
# make test14
./sdriver.pl -t trace14.txt -s ./tsh -a "-p"
#
# trace14.txt - Simple error handling
#
tsh> ./bogus
No such file or directory
tsh> ./myspin 4 &
[1] (9647) ./myspin 4 &
tsh> fg
fg command requires PID or %jobid argument
tsh> bg
bg command requires PID or %jobid argument
tsh> fg a
fg: invalid pid number
tsh> bg a
bg: invalid pid number
tsh> fg 9999999
(9999999): No such process
tsh> bg 9999999
(9999999): No such process
tsh> fg %2
%2: No such job
tsh> fg %1
Job [1] (9647) stopped by signal 20
tsh> bg %2
%2: No such job
tsh> bg %1
[1] (9647) ./myspin 4 &
tsh> jobs
[1] (9647) Running ./myspin 4 &
[localhost:~/桌面/shelllab/shlab-handout]
#
```

```
终端
文件(F) 编辑(E) 查看(V) 搜索(S) 终端(T) 帮助(H)
[1] (9647) Running ./myspin 4 &
[localhost:~/桌面/shelllab/shlab-handout]
# make test15
./sdriver.pl -t trace15.txt -s ./tsh -a "-p"
#
# trace15.txt - Putting it all together
#
tsh> ./bogus
No such file or directory
tsh> ./myspin 10
Job [1] (9677) terminated by signal 2
tsh> ./myspin 3 &
[1] (9679) ./myspin 3 &
tsh> ./myspin 4 &
[2] (9681) ./myspin 4 &
tsh> jobs
[1] (9679) Running ./myspin 3 &
[2] (9681) Running ./myspin 4 &
tsh> fg %1
Job [1] (9679) stopped by signal 20
tsh> jobs
[1] (9679) Stopped ./myspin 3 &
[2] (9681) Running ./myspin 4 &
tsh> bg %3
%3: No such job
tsh> bg %1
[2] (9679) ./myspin 3 &
tsh> jobs
[1] (9679) Running ./myspin 3 &
[2] (9681) Running ./myspin 4 &
tsh> fg %1
tsh> quit
[localhost:~/桌面/shelllab/shlab-handout]
#
```



```
终端
文件(F) 编辑(E) 查看(V) 搜索(S) 终端(T) 帮助(H)
tsh> quit
[localhost:~/桌面/shelllab/shlab-handout]
# make test16
./sdriver.pl -t trace16.txt -s ./tsh -a "-p"
#
# trace16.txt - Tests whether the shell can handle SIGTSTP and SIGINT
#               signals that come from other processes instead of the terminal.
#
tsh> ./mystop 2
Job [1] (9710) stopped by signal 20
tsh> jobs
[1] (9710) Stopped ./mystop 2
tsh> ./myint 2
Job [2] (9713) terminated by signal 2
[localhost:~/桌面/shelllab/shlab-handout]
#
```

Test 脚本测试结果：16 个 test 测试结果均和 tshref 的结果相同（反馈信息的句式不一定完全相同）。

如同 shlab.pdf 所说，评判本次实验结果的标准不止是 test。我 tinyshell 代码中也添加有完善的注释（英文），且对于系统调用和其他函数的调用都做了 error handling。另外，对于这 16 个 test 所没有测试到的条件也都进行了实现和测试（例如子进程因为除 sigint、sigstp 的其他 signal 而结束、暂停、子进程意外结束），没有出 bug，证明 tinyshell 鲁棒性良好。

### 3. 总结体会与建议

操作系统课程的后半部分难度比较大，但是也更有意思一些。学到了很多，也在实验中体会到了计算机系统的趣味性，真的是很棒的体验。其实我并不是很常用 unix 系统，但由于这个实验我打开了大一装好但没打开几次的 Ubuntu 系统。

要说建议的话，希望老师注意身体，老师好像经常生病，一定要好好休息，这样才能给后面的同学带来更多这样好的课程体验。

### 4. 实验代码

```
1. /*
2.  * tsh - A tiny shell program with job control
3.  *
4.  * Baisiyu Bsyess
5.  */
6. #include <stdio.h>
7. #include <stdlib.h>
8. #include <unistd.h>
9. #include <string.h>
10. #include <ctype.h>
```

```

11. #include <signal.h>
12. #include <stdbool.h>
13. #include <sys/types.h>
14. #include <sys/wait.h>
15. #include <errno.h>
16.
17. /* Misc manifest constants */
18. #define MAXLINE    1024    /* max line size */
19. #define MAXARGS     128    /* max args on a command line */
20. #define MAXJOBS     16    /* max jobs at any point in time */
21. #define MAXJID      1<<16 /* max job ID */
22.
23. /* Job states */
24. #define UNDEF 0 /* undefined */
25. #define FG 1    /* running in foreground */
26. #define BG 2    /* running in background */
27. #define ST 3    /* stopped */
28.
29. /*
30.  * Jobs states: FG (foreground), BG (background), ST (stopped)
31.  * Job state transitions and enabling actions:
32.  *   FG -> ST : ctrl-z
33.  *   ST -> FG : fg command
34.  *   ST -> BG : bg command
35.  *   BG -> FG : fg command
36.  * At most 1 job can be in the FG state.
37.  */
38.
39. /* Global variables */
40. extern char **environ;    /* defined in libc */
41. char prompt[] = "tsh> "; /* command line prompt (DO NOT CHANGE) */
42. int verbose = 0;         /* if true, print additional output */
43. int nextjid = 1;         /* next job ID to allocate */
44. char sbuf[MAXLINE];      /* for composing sprintf messages */
45. bool waiting = false;    /* if shell is waiting for FG process */
46.
47. struct job_t {            /* The job struct */
48.     pid_t pid;            /* job PID */
49.     int jid;              /* job ID [1, 2, ...] */
50.     int state;            /* UNDEF, BG, FG, or ST */
51.     char cmdline[MAXLINE]; /* command line */
52. };
53. struct job_t jobs[MAXJOBS]; /* The job list */
54. /* End global variables */

```

```

55.
56.
57. /* Function prototypes */
58.
59. /* Here are the functions that you will implement */
60. void eval(char *cmdline);
61. int builtin_cmd(char **argv);
62. void do_bgfg(char **argv);
63. void waitfg(pid_t pid);
64.
65. void sigchld_handler(int sig);
66. void sigtstp_handler(int sig);
67. void sigint_handler(int sig);
68.
69. /* Here are helper routines that we've provided for you */
70. int parseline(const char *cmdline, char **argv);
71. void sigquit_handler(int sig);
72.
73. void clearjob(struct job_t *job);
74. void initjobs(struct job_t *jobs);
75. int maxjid(struct job_t *jobs);
76. int addjob(struct job_t *jobs, pid_t pid, int state, char *cmdline);
77. int deletejob(struct job_t *jobs, pid_t pid);
78. pid_t fgpid(struct job_t *jobs);
79. struct job_t *getjobpid(struct job_t *jobs, pid_t pid);
80. struct job_t *getjobjid(struct job_t *jobs, int jid);
81. int pid2jid(pid_t pid);
82. void listjobs(struct job_t *jobs);
83. int str2int(char *str); //parse a string to positive integer
84.
85. void usage(void);
86. void unix_error(char *msg);
87. void app_error(char *msg);
88. typedef void handler_t(int);
89. handler_t *Signal(int signum, handler_t *handler);
90.
91. /*
92.  * main - The shell's main routine
93.  */
94. int main(int argc, char **argv)
95. {
96.     char c;
97.     char cmdline[MAXLINE];
98.     int emit_prompt = 1; /* emit prompt (default) */

```

```

99.
100.  /* Redirect stderr to stdout (so that driver will get all output
101.   * on the pipe connected to stdout) */
102.  dup2(1, 2);
103.
104.  /* Parse the command line */
105.  while ((c = getopt(argc, argv, "hvp")) != EOF) {
106.      switch (c) {
107.          case 'h':          /* print help message */
108.              usage();
109.              break;
110.          case 'v':          /* emit additional diagnostic info */
111.              verbose = 1;
112.              break;
113.          case 'p':          /* don't print a prompt */
114.              emit_prompt = 0; /* handy for automatic testing */
115.              break;
116.          default:
117.              usage();
118.      }
119.  }
120.
121.  /* Install the signal handlers */
122.
123.  /* These are the ones you will need to implement */
124.  Signal(SIGINT, sigint_handler); /* ctrl-c */
125.  Signal(SIGTSTP, sigtstp_handler); /* ctrl-z */
126.  Signal(SIGCHLD, sigchld_handler); /* Terminated or stopped child */
127.
128.  /* This one provides a clean way to kill the shell */
129.  Signal(SIGQUIT, sigquit_handler);
130.
131.  /* Initialize the job list */
132.  initjobs(jobs);
133.
134.  /* Execute the shell's read/eval loop */
135.  while (1) {
136.
137.      /* Read command line */
138.      if (emit_prompt) {
139.          printf("%s", prompt);
140.          fflush(stdout);
141.      }
142.      if ((fgets(cmdline, MAXLINE, stdin) == NULL) && ferror(stdin))

```

```

143.     app_error("fgets error");
144.     if (feof(stdin)) { /* End of file (ctrl-d) */
145.         fflush(stdout);
146.         exit(0);
147.     }
148.
149.     /* Evaluate the command line */
150.     eval(cmdline);
151.     fflush(stdout);
152.     fflush(stdout);
153. }
154.
155.     exit(0); /* control never reaches here */
156. }
157.
158. /*
159.  * eval - Evaluate the command line that the user has just typed in
160.  *
161.  * If the user has requested a built-in command (quit, jobs, bg or fg)
162.  * then execute it immediately. Otherwise, fork a child process and
163.  * run the job in the context of the child. If the job is running in
164.  * the foreground, wait for it to terminate and then return. Note:
165.  * each child process must have a unique process group ID so that our
166.  * background children don't receive SIGINT (SIGTSTP) from the kernel
167.  * when we type ctrl-c (ctrl-z) at the keyboard.
168.  */
169. void eval(char *cmdline)
170. {
171.     char* argv[MAXLINE];
172.     //parse the command line
173.     int if_BG = parseline(cmdline, argv);
174.     //if its a blank or abnormal command
175.     if(argv[0] == NULL)
176.         return;
177.     //if its a build-in command
178.     if(builtin_cmd(argv))
179.         return;
180.     //if it wants to run something
181.     sigset_t mask_all, mask_one, prev_one;
182.     sigfillset(&mask_all);
183.     sigemptyset(&mask_one);
184.     sigaddset(&mask_one, SIGCHLD);
185.
186.     sigprocmask(SIG_BLOCK, &mask_one, &prev_one);

```

```

187.     pid_t child_pid = fork();
188.     if(child_pid==0)
189.     {//child progress
190.         setpgid(0, 0);//set child progress as the leader of the progress group
191.         sigprocmask(SIG_SETMASK, &prev_one, NULL);
192.         if(execv(argv[0], argv) == -1)
193.         {
194.             perror("");//execv error
195.             exit(1);
196.         }
197.     }
198.     else
199.     {//parent progress
200.         sigprocmask(SIG_BLOCK, &mask_all, NULL);
201.         setpgid(child_pid, child_pid);//set child progress as the leader of the progress
group, for sure
202.         if(if_BG)//new BG job
203.         {
204.             if(!addjob(jobs, child_pid, BG, cmdline))//if joblist is full
205.             {
206.                 kill(-child_pid, SIGKILL);
207.                 if(errno==ESRCH)
208.                 {
209.                     perror("kill failed");
210.                     exit(1);
211.                 }
212.             }
213.             printf("[%d] (%d) %s", nextjid==1?MAXJID:(nextjid-
1), child_pid, cmdline);//print the new bg job info
214.             fflush(stdout);
215.             sigprocmask(SIG_SETMASK, &prev_one, NULL);
216.
217.         }
218.         else//new FG job
219.         {
220.             if(!addjob(jobs, child_pid, FG, cmdline))//if joblist is full
221.             {
222.                 kill(-child_pid, SIGKILL);
223.                 if(errno==ESRCH)
224.                 {
225.                     perror("kill failed");
226.                     exit(1);
227.                 }
228.             }

```

```

229.         sigprocmask(SIG_SETMASK, &prev_one, NULL);
230.         waitfg(child_pid);
231.     }
232.     return;
233. }
234. return;//never reach here
235.
236. }
237.
238. /*
239.  * parseline - Parse the command line and build the argv array.
240.  *
241.  * Characters enclosed in single quotes are treated as a single
242.  * argument. Return true if the user has requested a BG job, false if
243.  * the user has requested a FG job.
244.  */
245. int parseline(const char *cmdline, char **argv)
246. {
247.     static char array[MAXLINE]; /* holds local copy of command line */
248.     char *buf = array;          /* pointer that traverses command line */
249.     char *delim;                 /* points to first space delimiter */
250.     int argc;                    /* number of args */
251.     int bg;                      /* background job? */
252.
253.     strcpy(buf, cmdline);
254.     buf[strlen(buf)-1] = ' '; /* replace trailing '\n' with space */
255.     while (*buf && (*buf == ' ')) /* ignore leading spaces */
256.         buf++;
257.
258.     /* Build the argv list */
259.     argc = 0;
260.     if (*buf == '\\') {
261.         buf++;
262.         delim = strchr(buf, '\\');
263.     }
264.     else {
265.         delim = strchr(buf, ' ');
266.     }
267.
268.     while (delim) {
269.         argv[argc++] = buf;
270.         *delim = '\\0';
271.         buf = delim + 1;
272.         while (*buf && (*buf == ' ')) /* ignore spaces */

```

```

273.         buf++;
274.
275.     if (*buf == '\\') {
276.         buf++;
277.         delim = strchr(buf, '\\');
278.     }
279.     else {
280.         delim = strchr(buf, ' ');
281.     }
282. }
283. argv[argc] = NULL;
284.
285. if (argc == 0) /* ignore blank line */
286. return 1;
287.
288. /* should the job run in the background? */
289. if ((bg = (*argv[argc-1] == '&')) != 0) {
290.     argv[--argc] = NULL;
291. }
292. return bg;
293. }
294.
295. /*
296.  * builtin_cmd - If the user has typed a built-in command then execute
297.  * it immediately.
298.  */
299. int builtin_cmd(char **argv)
300. {
301.     sigset_t mask_all, prev_one;
302.     sigfillset(&mask_all);
303.     if(!strcmp(argv[0], "jobs"))//the "jobs" command
304.     {
305.         listjobs(jobs);
306.         return 1;
307.     }
308.     else if(!strcmp(argv[0], "quit"))//the "quit" command
309.     {
310.         exit(0);
311.     }
312.     else if(!strcmp(argv[0], "bg")||!strcmp(argv[0], "fg"))//the "bg" or "fg" command
313.     {
314.         do_bgfg(argv);
315.         return 1;
316.     }

```



```

317.     return 0;    /* not a builtin command */
318. }
319.
320. /*
321.  * do_bgfg - Execute the builtin bg and fg commands
322.  */
323. void do_bgfg(char **argv)
324. {
325.     sigset_t mask_all, prev_one;
326.     if(!strcmp(argv[0], "bg"))//the "bg" command
327.     {
328.         if(argv[1]==NULL)//no argument
329.         {
330.             printf("bg command requires PID or %%jobid argument\n");
331.             fflush(stdout);
332.             return;
333.         }
334.         if(argv[1][0]=='%')//jid input
335.         {
336.             int jid;
337.             if((jid=str2int(argv[1]+1))==-1)//invalid argument
338.             {
339.                 printf("bg: invalid jid number\n");
340.                 fflush(stdout);
341.                 return;
342.             }
343.
344.             //do sigmask in case that signal handler may delete the job
345.             //just after we get the job
346.             sigprocmask(SIG_SETMASK, &mask_all, &prev_one);
347.             struct job_t *job = getjobjid(jobs, jid);
348.             if(job==NULL)
349.             {
350.                 printf("%%%d: No such job\n",jid);
351.                 fflush(stdout);
352.                 sigprocmask(SIG_SETMASK, &prev_one, NULL);
353.                 return;
354.             }
355.             job->state = BG;//set the job state
356.             printf("[%d] (%d) %s", nextjid==1?MAXJID:(nextjid-
1), job->pid, job->cmdline);//print the new bg job info
357.             fflush(stdout);
358.             sigprocmask(SIG_SETMASK, &prev_one, NULL);
359.

```

```

360.         kill(-(job->pid), SIGCONT); //send SIGCONT signal
361.         if(errno==ESRCH)
362.         {
363.             perror("kill failed");
364.             exit(1);
365.         }
366.
367.     }
368.     else //pid input
369.     {
370.         pid_t pid;
371.         if((pid=str2int(argv[1]))== -1) //invalid argument
372.         {
373.             printf("bg: invalid pid number\n");
374.             fflush(stdout);
375.             return;
376.         }
377.
378.         //do sigmask in case that signal handler may delete the job
379.         //just after we get the job
380.         sigprocmask(SIG_SETMASK, &mask_all, &prev_one);
381.         struct job_t *job = getjobpid(jobs, pid);
382.         if(job==NULL)
383.         {
384.             printf("(%d): No such process\n", pid);
385.             fflush(stdout);
386.             sigprocmask(SIG_SETMASK, &prev_one, NULL);
387.             return;
388.         }
389.         job->state = BG;
390.         printf("[%d] (%d) %s", nextjid==1?MAXJID:(nextjid-
1), job->pid, job->cmdline); //print the new bg job info
391.         fflush(stdout);
392.         sigprocmask(SIG_SETMASK, &prev_one, NULL);
393.
394.         kill(-(job->pid), SIGCONT);
395.         if(errno==ESRCH)
396.         {
397.             perror("kill failed");
398.             exit(1);
399.         }
400.     }
401.     return;
402.

```

```

403.     }
404.     else //the "fg" command
405.     {
406.         if(argv[1]==NULL)//no argument
407.         {
408.             printf("fg command requires PID or %%jobid argument\n");
409.             fflush(stdout);
410.             return;
411.         }
412.         if(argv[1][0]=='%')//jid input
413.         {
414.             int jid;
415.             if((jid=str2int(argv[1]+1))== -1)//invalid argument
416.             {
417.                 printf("fg: invalid jid number\n");
418.                 fflush(stdout);
419.                 return;
420.             }
421.
422.             //do sigmask in case that signal handler may delete the job
423.             //just after we get the job
424.             sigprocmask(SIG_SETMASK, &mask_all, &prev_one);
425.             struct job_t *job = getjobjid(jobs, jid);
426.             if(job==NULL)
427.             {
428.                 printf("%%%d: No such job\n",jid);
429.                 fflush(stdout);
430.                 sigprocmask(SIG_SETMASK, &prev_one, NULL);
431.                 return;
432.             }
433.             job->state = FG;
434.             sigprocmask(SIG_SETMASK, &prev_one, NULL);
435.
436.             kill(-(job->pid), SIGCONT);
437.             if(errno==ESRCH)
438.             {
439.                 perror("kill failed");
440.                 exit(1);
441.             }
442.             waitfg(job->pid);//wait for the foreground job's termination
443.         }
444.         else//pid input
445.         {
446.             pid_t pid;

```

```

447.         if((pid=str2int(argv[1]))== -1)//invalid argument
448.     {
449.         printf("fg: invalid pid number\n");
450.         fflush(stdout);
451.         return;
452.     }
453.
454.     //do sigmask in case that signal handler may delete the job
455.     //just after we get the job
456.     sigprocmask(SIG_SETMASK, &mask_all, &prev_one);
457.     struct job_t *job = getjobpid(jobs, pid);
458.     if(job==NULL)
459.     {
460.         printf("(%d): No such process\n",pid);
461.         fflush(stdout);
462.         sigprocmask(SIG_SETMASK, &prev_one, NULL);
463.         return;
464.     }
465.     job->state = FG;
466.     sigprocmask(SIG_SETMASK, &prev_one, NULL);
467.
468.     kill(-(job->pid), SIGCONT);
469.     if(errno==ESRCH)
470.     {
471.         perror("kill failed");
472.         exit(1);
473.     }
474.     waitfg(job->pid);//wait for the foreground job's termination
475. }
476. return;
477. }
478.
479.
480. return;
481. }
482.
483.
484. /*
485.  * waitfg - Block until process pid is no longer the foreground process
486.  */
487. void waitfg(pid_t pid)
488. {
489.     sigset_t no_mask, prev_one;
490.     sigemptyset(&no_mask);

```

```

491.     //set sigmask empty to prevent infinite waiting
492.     sigprocmask(SIG_SETMASK, &no_mask, &prev_one);
493.     //Global variable waiting, infer that if the shell is waiting for a fg job
494.     waiting = true;
495.     while(waiting && getjobpid(jobs,pid)->state==FG)
496.     {
497.         sleep(0.1);
498.     }
499.     sigprocmask(SIG_SETMASK, &prev_one, NULL);
500.     return;
501. }
502.
503. /*****
504.  * Signal handlers
505.  *****/
506.
507. /*
508.  * sigchld_handler - The kernel sends a SIGCHLD to the shell whenever
509.  *     a child job terminates (becomes a zombie), or stops because it
510.  *     received a SIGSTOP or SIGTSTP signal. The handler reaps all
511.  *     available zombie children, but doesn't wait for any other
512.  *     currently running children to terminate.
513.  */
514. void sigchld_handler(int sig)
515. {
516.     sigset_t mask_all, prev_all;
517.     pid_t pidfg, pid;
518.     int status = -1;
519.     sigfillset(&mask_all);
520.     if((pidfg=fgpid(jobs)) != 0)//if there is a foreground job running
521.     {
522.
523.         int res = waitpid(pidfg, &status, WNOHANG|WUNTRACED);
524.         if(res != 0)//if the terminated child is the fg job
525.         {
526.             if(WIFEXITED(status))//if the child is terminated by exit
527.             {
528.                 sigprocmask(SIG_BLOCK, &mask_all, &prev_all);
529.                 deletejob(jobs, pidfg);
530.                 waiting = false;//stop waiting for fg job
531.                 sigprocmask(SIG_SETMASK, &prev_all, NULL);
532.             }
533.
534.             else if(WIFSTOPPED(status))//if the child is stopped by a signal

```

```

535.         {
536.             sigprocmask(SIG_BLOCK, &mask_all, &prev_all);
537.             struct job_t *job = getjobpid(jobs, pidfg);
538.             job->state = ST;//set the job state
539.             waiting = false;//stop waiting for fg job
540.             printf("Job [%d] (%d) stopped by signal %d\n",job->jid,job->pid,WSTOPSIG(
                status));
541.             fflush(stdout);
542.             sigprocmask(SIG_SETMASK, &prev_all, NULL);
543.         }
544.
545.         else if(WIFSIGNALED(status))//if the child is terminated by a signal
546.         {
547.             sigprocmask(SIG_BLOCK, &mask_all, &prev_all);
548.             struct job_t *job = getjobpid(jobs, pidfg);
549.             waiting = false;//stop waiting for fg job
550.             printf("Job [%d] (%d) terminated by signal %d\n",job->jid,job->pid,WTERMS
                IG(status));
551.             fflush(stdout);
552.             deletejob(jobs, pidfg);//should deletejob AFTER printing it
553.             sigprocmask(SIG_SETMASK, &prev_all, NULL);
554.         }
555.         else//if the child is terminated otherwise
556.         {
557.             sigprocmask(SIG_BLOCK, &mask_all, &prev_all);
558.             struct job_t *job = getjobpid(jobs, pidfg);
559.             waiting = false;//stop waiting for fg job
560.             //printf("Job [%d] (%d) terminated abnormally\n",job->jid,job->pid);
561.             fflush(stdout);
562.             deletejob(jobs, pidfg);//should deletejob AFTER printing it
563.             sigprocmask(SIG_SETMASK, &prev_all, NULL);
564.         }
565.
566.         //In case that the user type a command when running a foreground job
567.         //Clean the stdin buffer after a foreground job's done
568.         //WARNING: This function is optional, you should use it only in one situation
569.         :
570.         //You would type commands using your human hands, and you want the shell
571.         //ignore your miss type when running a foreground job.
572.         /*
573.         int c;
574.         while ((c=getchar()) != '\n' && c != EOF);
575.         */
576.     }

```

```

576.
577.     }
578.
579.     while((pid = waitpid(-1, NULL, WNOHANG)) > 0)//reap the zombie child
580.     {
581.         sigprocmask(SIG_BLOCK, &mask_all, &prev_all);
582.         if(pid != pidfg)
583.             deletejob(jobs, pid);
584.         sigprocmask(SIG_SETMASK, &prev_all, NULL);
585.     }
586.     /* SIGTSTP default handler can send SIGCHLD, too. Can't check the error here.
587.     if (errno != ECHILD)
588.         perror("waitpid error:");
589.     */
590.     return;
591. }
592.
593. /*
594.  * sigint_handler - The kernel sends a SIGINT to the shell whenever the
595.  *   user types ctrl-c at the keyboard. Catch it and send it along
596.  *   to the foreground job.
597.  */
598. void sigint_handler(int sig)
599. {
600.     pid_t pid;
601.
602.     if((pid = fgpid(jobs))==0)//if there is no fg job
603.         return;
604.
605.     struct job_t *job = getjobpid(jobs, pid);
606.     kill(-pid, SIGINT);//send the SIGINT to the progress group
607.     if(errno==ESRCH)//error handling
608.     {
609.         perror("kill failed");
610.         exit(1);
611.     }
612.
613.     return;
614. }
615.
616. /*
617.  * sigtstp_handler - The kernel sends a SIGTSTP to the shell whenever
618.  *   the user types ctrl-z at the keyboard. Catch it and suspend the
619.  *   foreground job by sending it a SIGTSTP.

```

```

620. */
621. void sigtstp_handler(int sig)
622. {
623.     pid_t pid;
624.
625.     if((pid = fgpid(jobs))==0)//if there is no fg job
626.         return;
627.     kill(-pid, SIGTSTP);//send the SIGTSP to the progress group
628.     if(errno==ESRCH)
629.     {
630.         perror("kill failed");
631.         exit(1);
632.     }
633.
634.     return;
635. }
636.
637. /*****
638.  * End signal handlers
639.  *****/
640.
641. /*****
642.  * Helper routines that manipulate the job list
643.  *****/
644.
645. /* clearjob - Clear the entries in a job struct */
646. void clearjob(struct job_t *job) {
647.     job->pid = 0;
648.     job->jid = 0;
649.     job->state = UNDEF;
650.     job->cmdline[0] = '\0';
651. }
652.
653. /* initjobs - Initialize the job list */
654. void initjobs(struct job_t *jobs) {
655.     int i;
656.
657.     for (i = 0; i < MAXJOBS; i++)
658.         clearjob(&jobs[i]);
659. }
660.
661. /* maxjid - Returns largest allocated job ID */
662. int maxjid(struct job_t *jobs)
663. {

```



```

664.     int i, max=0;
665.
666.     for (i = 0; i < MAXJOBS; i++)
667.         if (jobs[i].jid > max)
668.             max = jobs[i].jid;
669.     return max;
670. }
671.
672. /* addjob - Add a job to the job list */
673. int addjob(struct job_t *jobs, pid_t pid, int state, char *cmdline)
674. {
675.     int i;
676.
677.     if (pid < 1)
678.         return 0;
679.
680.     for (i = 0; i < MAXJOBS; i++) {
681.         if (jobs[i].pid == 0) {
682.             jobs[i].pid = pid;
683.             jobs[i].state = state;
684.             jobs[i].jid = nextjid++;
685.             if (nextjid > MAXJOBS)
686.                 nextjid = 1;
687.             strcpy(jobs[i].cmdline, cmdline);
688.             if(verbose){
689.                 printf("Added job [%d] %d %s\n", jobs[i].jid, jobs[i].pid, jobs[i].cmdline);
690.             }
691.             return 1;
692.         }
693.     }
694.     printf("Tried to create too many jobs\n");
695.     return 0;
696. }
697.
698. /* deletejob - Delete a job whose PID=pid from the job list */
699. int deletejob(struct job_t *jobs, pid_t pid)
700. {
701.     int i;
702.
703.     if (pid < 1)
704.         return 0;
705.
706.     for (i = 0; i < MAXJOBS; i++) {

```

```

707.     if (jobs[i].pid == pid) {
708.         clearjob(&jobs[i]);
709.         nextjid = maxjid(jobs)+1;
710.         return 1;
711.     }
712. }
713. return 0;
714. }
715.
716. /* fgpid - Return PID of current foreground job, 0 if no such job */
717. pid_t fgpid(struct job_t *jobs) {
718.     int i;
719.
720.     for (i = 0; i < MAXJOBS; i++)
721.         if (jobs[i].state == FG)
722.             return jobs[i].pid;
723.     return 0;
724. }
725.
726. /* getjobpid - Find a job (by PID) on the job list */
727. struct job_t *getjobpid(struct job_t *jobs, pid_t pid) {
728.     int i;
729.
730.     if (pid < 1)
731.         return NULL;
732.     for (i = 0; i < MAXJOBS; i++)
733.         if (jobs[i].pid == pid)
734.             return &jobs[i];
735.     return NULL;
736. }
737.
738. /* getjobjid - Find a job (by JID) on the job list */
739. struct job_t *getjobjid(struct job_t *jobs, int jid)
740. {
741.     int i;
742.
743.     if (jid < 1)
744.         return NULL;
745.     for (i = 0; i < MAXJOBS; i++)
746.         if (jobs[i].jid == jid)
747.             return &jobs[i];
748.     return NULL;
749. }
750.

```

```

751. /* pid2jid - Map process ID to job ID */
752. int pid2jid(pid_t pid)
753. {
754.     int i;
755.
756.     if (pid < 1)
757.         return 0;
758.     for (i = 0; i < MAXJOBS; i++)
759.         if (jobs[i].pid == pid) {
760.             return jobs[i].jid;
761.         }
762.     return 0;
763. }
764.
765. /* listjobs - Print the job list */
766. void listjobs(struct job_t *jobs)
767. {
768.     int i;
769.
770.     for (i = 0; i < MAXJOBS; i++) {
771.         if (jobs[i].pid != 0) {
772.             printf("[%d] (%d) ", jobs[i].jid, jobs[i].pid);
773.             switch (jobs[i].state) {
774.                 case BG:
775.                     printf("Running ");
776.                     break;
777.                 case FG:
778.                     printf("Foreground ");
779.                     break;
780.                 case ST:
781.                     printf("Stopped ");
782.                     break;
783.                 default:
784.                     printf("listjobs: Internal error: job[%d].state=%d ",
785.                         i, jobs[i].state);
786.             }
787.             printf("%s", jobs[i].cmdline);
788.         }
789.     }
790. }
791. /*****
792.  * end job list helper routines
793.  *****/
794.

```

```

795.
796. /*****
797.  * Other helper routines
798.  *****/
799.
800. /*
801.  * usage - print a help message
802.  */
803. void usage(void)
804. {
805.     printf("Usage: shell [-hvp]\n");
806.     printf("  -h   print this message\n");
807.     printf("  -v   print additional diagnostic information\n");
808.     printf("  -p   do not emit a command prompt\n");
809.     exit(1);
810. }
811.
812. /*
813.  * unix_error - unix-style error routine
814.  */
815. void unix_error(char *msg)
816. {
817.     fprintf(stdout, "%s: %s\n", msg, strerror(errno));
818.     exit(1);
819. }
820.
821. /*
822.  * app_error - application-style error routine
823.  */
824. void app_error(char *msg)
825. {
826.     fprintf(stdout, "%s\n", msg);
827.     exit(1);
828. }
829.
830. /*
831.  * Signal - wrapper for the sigaction function
832.  */
833. handler_t *Signal(int signum, handler_t *handler)
834. {
835.     struct sigaction action, old_action;
836.
837.     action.sa_handler = handler;
838.     sigemptyset(&action.sa_mask); /* block sigs of type being handled */

```

```

839.     action.sa_flags = SA_RESTART; /* restart syscalls if possible */
840.
841.     if (sigaction(signum, &action, &old_action) < 0)
842.         unix_error("Signal error");
843.     return (old_action.sa_handler);
844. }
845.
846. /*
847.  * sigquit_handler - The driver program can gracefully terminate the
848.  *   child shell by sending it a SIGQUIT signal.
849.  */
850. void sigquit_handler(int sig)
851. {
852.     printf("Terminating after receipt of SIGQUIT signal\n");
853.     exit(1);
854. }
855.
856. //parse a string to positive integer, if fail then return -1
857. int str2int(char *str)
858. {
859.     int iter = 0;
860.     int res = 0;
861.     if(str[iter]=='\0')
862.         return -1;
863.     while(str[iter]!='\0')
864.     {
865.         if(str[iter]>'9' || str[iter]<'0')
866.             return -1;
867.         res = 10*res+str[iter]-'0';
868.         iter++;
869.     }
870.     return res;
871. }

```