

Ben Ridenbaugh

HW 9

8-28. $y(x) = \frac{-P}{128EI} (7L^2x - 16x^3)$

a. $y'(x) = \theta(x) = \frac{-P}{128EI} (7L^2 - 48x^2)$

b. $\theta(x) = 0$ when...

$$7L^2 - 48x^2 = 0$$

$$x = \pm \sqrt{\frac{7}{48}} L^2$$

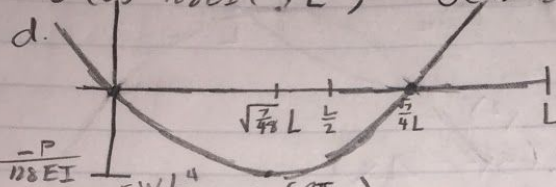
c. $y(0) = 0$

$$\theta(0) = \frac{-P}{128EI} (7L^2)$$

$$y\left(\frac{L}{4}\right) = \frac{-P}{128EI} \left(\frac{7}{4}L^3 - \frac{1}{4}L^3\right) = \frac{-P}{128EI} \left(\frac{3}{2}L^3\right)$$

$$\theta\left(\frac{L}{4}\right) = \frac{-P}{128EI} (7L^2 - 3L^2) = \frac{-P}{128EI} (4L^2)$$

$$y(x) = 0 \text{ when } x = 0, \sqrt{\frac{7}{16}} L^2$$

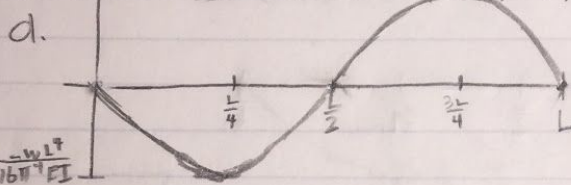


8-30. $y(x) = \frac{-WL^4}{16\pi^4 EI} \sin\left(\frac{2\pi}{L}x\right)$

a. $y'(x) = \theta(x) = \frac{-2WL^3}{16\pi^3 EI} \cos\left(\frac{2\pi}{L}x\right)$

b. $y(x) = 0$ when $x = 0, \frac{L}{2}, L, \frac{3L}{2}, \dots$

c. $\theta(x) = 0$ when $x = \frac{L}{4}, \frac{3L}{4}, \frac{5L}{4}, \dots$



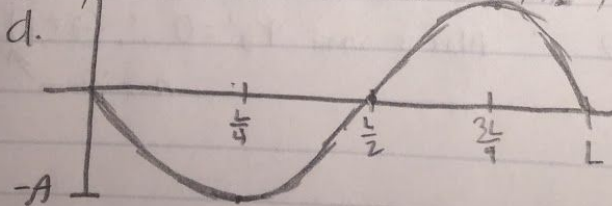
Flipped because of negative constant

8-33. $y(x) = -A \sin\left(\frac{2\pi}{L}x\right)$

a. $y'(x) = \theta(x) = -A\left(\frac{2\pi}{L}\right) \cos\left(\frac{2\pi}{L}x\right)$

b. $\theta(x) = 0$ when $x = \frac{L}{4}, \frac{3L}{4}, \frac{5L}{4}, \dots$

c. $y(x) = 0$ when $x = 0, \frac{L}{2}, L, \frac{3L}{2}, \dots$



8-35. $y(x) = \frac{-w}{48EI} (2x^4 - 5x^3L + 3x^2L^2)$
 a. $y'(x) = \theta(x) = \frac{-w}{48EI} (8x^3 - 15x^2L + 6xL^2)$
 $x(8x^2 - 15xL + 6L^2) = 0$
 $\therefore x = 0, .58L, 1.3L$ $\sqrt{\frac{15L \pm \sqrt{(-15L)^2 - 4(8)(6L^2)}}{2(8)}}$
 $\frac{15L \pm \sqrt{33}L}{16}$

b. $\theta(0) = 0$ $\theta(L) = \frac{-w}{48EI} (2L^4 - 5L^4 + 3L^4) = 0$

c.



8-36. $y(x) = \frac{-M}{4EIL} (x^3 - Lx^2)$

a. $y'(x) = \theta(x) = \frac{-M}{4EIL} (3x^2 - 2Lx)$

b. $\theta(x) = \frac{-M}{4EIL} (3x^2 - 2Lx) = 0$

$\therefore x = 0, \frac{2}{3}L$

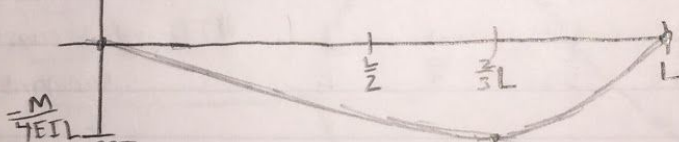
c. $y(0) = 0$

$y(L) = 0$

$\theta(0) = 0$

$\theta(L) = \frac{-M}{4EIL} (L^2)$

d.



8.37. $\sigma_\theta = \frac{32T}{\pi d^3} \sin \theta \cos \theta$

$\tau_\theta = \frac{16T}{\pi d^3} (\cos^2 \theta - \sin^2 \theta)$

a. $\sigma_\theta = \frac{32T}{\pi d^3} \sin \theta \cos \theta \Rightarrow \frac{16T}{\pi d^3} \sin 2\theta$

$\sigma_\theta' = \frac{32T}{\pi d^3} \cos 2\theta$

Max is when $\sigma_\theta' = 0 \therefore \theta = \frac{\pi}{4}$

b. $\tau_\theta = \frac{16T}{\pi d^3} (\cos^2 \theta - \sin^2 \theta) \Rightarrow \frac{16T}{\pi d^3} \cos 2\theta$

$\tau_\theta' = -\frac{32T}{\pi d^3} \sin 2\theta$

Max is when $\tau_\theta' = 0 \therefore \theta = \frac{\pi}{2}$

minimum

$2 \sin \theta \cos \theta = \sin 2\theta$
 $\cos^2 \theta - \sin^2 \theta = \cos 2\theta$