

Ben Ridenbaugh

5-1. a.  $V_R = 1 + 0j$   $V_L = 0 + 1j$

b.  $V = (1 + 0j) + (0 + 1j) = 1 + 1j$

$|V| = \sqrt{1^2 + 1^2} = \sqrt{2}$

$\theta = \tan^{-1}(1) = 45^\circ$

$V = \sqrt{2} \angle 45^\circ$

c.

5-16 a.  $Z_1 = 10 + 25j$   $Z_2 = 5 + 15j$

$Z = (10 + 25j) + (5 + 15j) = 15 + 40j$

b.  $|Z| = \sqrt{(15)^2 + (40)^2} = 42.72$

$\theta = \tan^{-1}(40/15) = 69.44^\circ$

$Z = 42.72 \angle 69.44^\circ$

5-19. a.  $Z_1 = 100 \Omega + 0j$   $Z_2 = 0 + 5.65j$   $Z_3 = 0 + 7073.55j$

$Z_2 + Z_3 = (0 + 5.65j) + (0 + 7073.55j)$

$= 0 + 7079.21j$

7 Polar:  $7079.21 \angle \text{DNE?}$

b.  $Z_1 + Z_2 + Z_3 = 100 + 7079.21j$

$|Z_1 + Z_2 + Z_3| = 7079.91$   $\theta = \tan^{-1}(7079.21/100) = 89.19^\circ$

c.  $\frac{Z_2 + Z_3}{Z_1 + Z_2 + Z_3} = \frac{0 + 7079.21j}{100 + 7079.21j} = 0 + 1j$

$\angle \text{DNE?}$

d. conjugate:  $0 - 1j$

$ZZ^* = 0$

5-24. a.  $Z_R = 120 + 0j$   $Z_L = 0 + 120\sqrt{3}j$   $Z_C = 0 + \frac{1}{50\sqrt{3}}j$

$120 \angle 0^\circ$

$120\sqrt{3} \angle \text{DNE}$

$\frac{1}{50\sqrt{3}} \angle \text{DNE}$

b.  $Z = 0 + \frac{1}{50\sqrt{3}}j + \frac{120 + 0j + 0 + 120\sqrt{3}j}{120 + 0j + 0 + 120\sqrt{3}j} = \frac{1}{50\sqrt{3}}j + \frac{24941.53}{120 + 120\sqrt{3}j}$

$= \frac{1}{50\sqrt{3}}j + 207.84 + 360j = 207.84 + 360.03j$

$|Z| = 415.71$

$\theta = \tan^{-1}(360.03/207.84) = 60^\circ$

$415.71 \angle 60^\circ$

$$C. \text{ conjugate: } 207.84 - 360.03j$$

$$ZZ^* = (415.71 \angle 60^\circ)(415.71 \angle -60^\circ)$$

$$= 172819.07$$

$$S-31. a. Z_R = 1000 + 0j \quad Z_L = 0 - 1000j$$

$$1000 \angle 0^\circ \quad 1000 \angle DNE$$

$$b. I_1 = \frac{0 - 1000j}{1000 - 1000j}$$

$$= 0 + 1j$$

$$1 \angle DNE$$

$$I_2 = \frac{1000 + 0j}{1000 - 1000j}$$

$$= 1 + 0j$$

$$1 \angle 0^\circ$$

$$c. I = 0 + 1j + 1 + 0j = 1 + 1j$$

$$S-38 \quad Z_1 = \frac{(10 - 0j)(20 - 20j)}{30 - 30j} = 0 + 6.66j$$

$$6.66 \angle DNE$$

$$Z_2 = \frac{(10 - 0j)(20 - 10j)}{30 - 30j} = 6.66 + 3.33j$$

$$7.45 \angle 26.56^\circ$$

$$Z_3 = \frac{(0 - 20j)(20 - 10j)}{30 - 30j} = 0 + 20j$$

$$20 \angle DNE$$