

Johns Hopkins
Engineering for Professionals
605.767 Applied Computer Graphics

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Module 12C

Force Physics



Physics Topics

- Particle Physics
- Motion Evaluation
- Forces
 - Gravity
 - Springs
 - Rigid Body Dynamics
- Other Physics



Newton's Laws of Motion

1. An object continues with a constant velocity unless a force acts upon it
2. A force acting on an object produces acceleration that is proportional to the object's mass



Particle Physics

- Not to be confused with particle systems or physics used in particle systems
- Assumptions using infinitely small particles
 - Simplifies many calculations
 - Useful for sampling and solving more-complex problems

- **Basic components**

- \mathbf{p} - position in world space

- \mathbf{v} - velocity, change in position over time $v = \frac{p' - p}{t' - t}$

- \mathbf{a} - acceleration, change in velocity over time $a = \frac{v' - v}{t' - t}$

- Therefore, acceleration is the second derivative of the position with respect to time

- $a = \frac{dv}{dt} = \frac{d}{dt} \frac{dp}{dt} = \frac{d^2p}{dt^2}$



Particle Physics (cont.)

- **Momentum** - mass times velocity
- **Force** - mass times acceleration $f = ma$
 - Useful variant:
 - $a = \frac{1}{m}f$
- Updating values
 - Update position:
 - $p' = p + vt + \frac{1}{2}at^2$
 - Update velocity:
 - $v' = v + at$
 - velocity usually has a dampening factor (d), thus making the update function:
 - $v' = vd + at$



Evaluating Motion

- Update object state
 - \mathbf{X}_i - current state of object (position, velocity, etc.)
 - t_i - current time
 - h - change in time
 - $\mathbf{F}(t, \mathbf{X}_i)$ - update function
- **Euler's Method**
 - Simplest form, but often unstable
 - $\mathbf{X}_{i+1} = \mathbf{X}_i + h\mathbf{F}(t, \mathbf{X}_i)$
 - derived from $(\mathbf{X}_{i+1} - \mathbf{X}_i)/h = \mathbf{F}(t, \mathbf{X}_i)$
 - $t_{i+1} = t_i + h$



Evaluating Motion (cont.)

- Midpoint Method - Runge-Kutta (second-order)

- $\mathbf{A}_1 = \mathbf{F}(t, \mathbf{X}_i)$
- $\mathbf{A}_2 = \mathbf{F}(t + h/2, \mathbf{X}_i + h\mathbf{A}_1/2)$
- $\mathbf{X}_{i+1} = \mathbf{X}_i + h\mathbf{A}_2$
- $t_{i+1} = t_i + h$

- **Runge-Kutta** (fourth-order)

- $\mathbf{A}_1 = \mathbf{F}(t, \mathbf{X}_i)$
- $\mathbf{A}_2 = \mathbf{F}(t + h/2, \mathbf{X}_i + h\mathbf{A}_1/2)$
- $\mathbf{A}_3 = \mathbf{F}(t + h/2, \mathbf{X}_i + h\mathbf{A}_2/2)$
- $\mathbf{A}_4 = \mathbf{F}(t + h, \mathbf{X}_i + h\mathbf{A}_3)$
- $\mathbf{X}_{i+1} = \mathbf{X}_i + (h/6)(\mathbf{A}_1 + 2\mathbf{A}_2 + 2\mathbf{A}_3 + \mathbf{A}_4)$
- $t_{i+1} = t_i + h$



Force of Gravity

- General formula

- $f = G \frac{m_1 m_2}{r^2}$

- G - gravitational constant
- m_i - mass of each object
- r - distance between the objects' centers
- Earth's average gravitation at sea level
 - $f = gm$
 - where $g \approx 10 \frac{\text{m}}{\text{s}^2}$
 - games often use a reduced gravitational factor producing a “bouncy” effect



Spring Force

- Hook's Law
 - Force exerted by a spring depends on the distance the spring is extended
 - Formula
 - $f_{\text{spring}} = -k(|\mathbf{d}| - l_i)\mathbf{d}$
 - k - spring constant
 - \mathbf{d} - vector from one end of the spring to the other
 - $|\mathbf{d}|$ - norm of \mathbf{d}
 - l_i - current length of the spring
 - Observations
 - If ($l_i == |\mathbf{d}|$), the spring is at rest — no force is exerted
 - If ($l_i < |\mathbf{d}|$), the spring pushes outward on the two connected objects
 - If ($l_i > |\mathbf{d}|$), the spring draws the two connected objects inward



Spring Force (cont.)

- **Limit of elasticity**
 - There are practical limits to the amount a spring can stretch and contract
 - Too much contraction
 - The spring coils touch — **connected objects cannot be any closer together**
 - l_i - current spring length cannot be less than zero
 - Too much extension
 - The spring loses its elasticity
 - Unlikely you will need this level of detail
- Rarely do applications use spring objects (coils)
 - Spring force usually referred to as ***spring-like*** forces



Spring Force Applications

- Tethered Objects
 - **Camera attached to character**
 - Third-person view
- One-dimensional Array
 - Hair
 - **Rope**
- Two-dimensional Array
 - **Cloth**
 - Water Surface
- Mimic Buoyancy
- **Stiff Springs**
 - Can mimic connected joints (bones) in rigid hierarchies
 - Useful for procedural animations

