Johns Hopkins
Engineering for Professionals

605.767 Applied Computer Graphics

Brian Russin

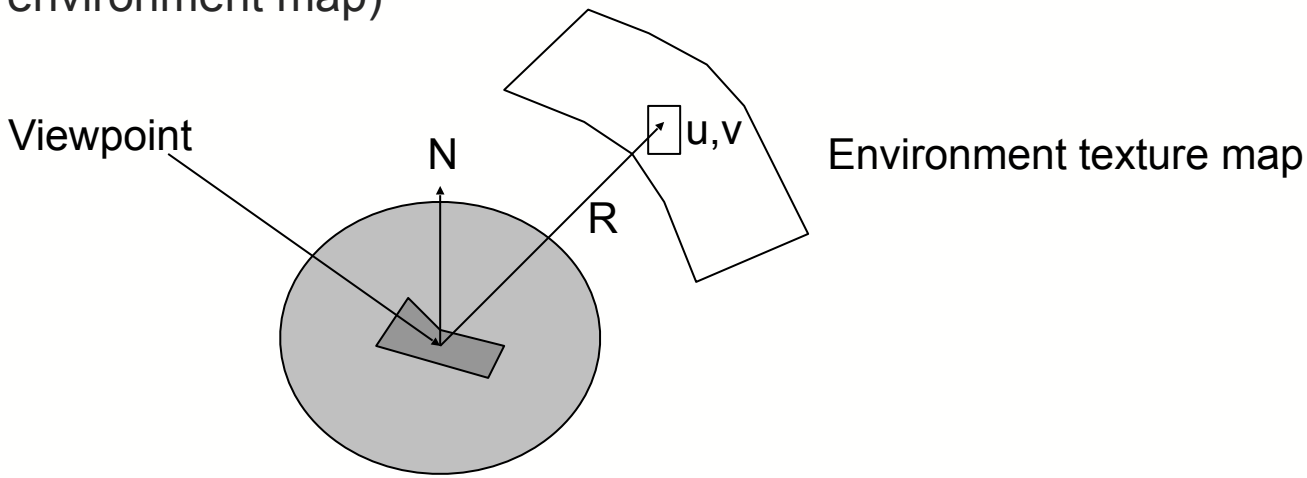
Module 9F
Environment Maps

Environment Mapping

SolidWorks 2000 (from NVIDIA web site)

Environment Mapping

- Environment mapping refers to the process of reflecting the surrounding environment in a shiny object
  - Texture mapping technique where the pattern mapped onto an object depends on the view vector
  - Simplification of ray tracing where only the reflected ray is traced
    - Process is terminated once it intersects texture
- Reflect the view ray from the object surface
  - Intersect this ray with a sphere containing the image of the environment to be reflected (called an environment map)



Steps in Environment Mapping

- Generate or load a 2D image of the environment
  - Environment maps are usually prefiltered
- For each pixel containing a reflective object, compute its normal
- Compute the reflection vector from the view vector and the normal

  $R = 2(N \cdot V)N - V$
- Use the reflection vector to index into the environment map
- Use texel data from the environment map to color the pixel
- Several projection functions are available
  - Blinn and Newell's method
  - Sphere map
    - Improves on Blinn and Newell
    - Used in many early OpenGL demos
  - Cubic environment mapping
  - Other environment mapping methods

Flat Surfaces

- Note on Environment Mapping
  - Large flat surfaces do not work as well
    - Reflected rays do not vary as much as off curved surfaces
    - Small part of environment map is mapped onto a relatively large surface
      - Individual texels of environment map become visible

Blinn and Newell's Method

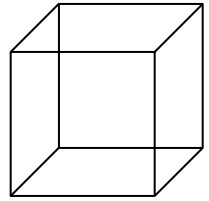
- Use the reflected view vector to index into latitude, longitude environment map
  - Rather than a globe viewed from the outside it is like a map of constellations in the sky
  - Single equirectangular texture map can be created from real world environments using photography techniques
    - 360-degree camera
- Conversion of the reflected ray $r=(r_x, r_y, r_z)$ into latitude-longitude
  - Latitude varies from 0 to π radians
    - $Lat = \arccos(-r_z)$
  - Longitude varies from 0 to 2*π radians
    - $Lng = \text{atan2}(r_y, r_x)$
- Problems
  - Non-uniform density – more texels near the poles
  - Singularities
    - Poles
    - Issues where left and right edges meet

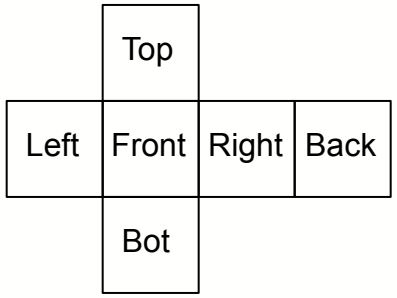
Spherical Environment Mapping

- 1st Environment mapping technique supported in hardware
- OpenGL Programming Guide gives a method for creating an environment map
  - Take a photograph of a large silvered sphere in a surrounding environment
  - Camera located infinite distance away, lens with infinite focal length
  - Scan the photograph
  - Alternatively: use an extremely wide angle (fish-eye) lens
- With OpenGL use GL_SPHERE_MAP texgen mode
- Disadvantage – valid only for a single view direction
  - Can map other views but can get artifacts where parts of the sphere map become magnified
- Good Resources
  - Section 10.4.2 (8.4.2 in 3rd Edition)
  - http://www.debevec.org/ReflectionMapping/
  - http://www.ozone3d.net/tutorials/glsl_texturing_p04.php#part_41

Cubic Environment Mapping

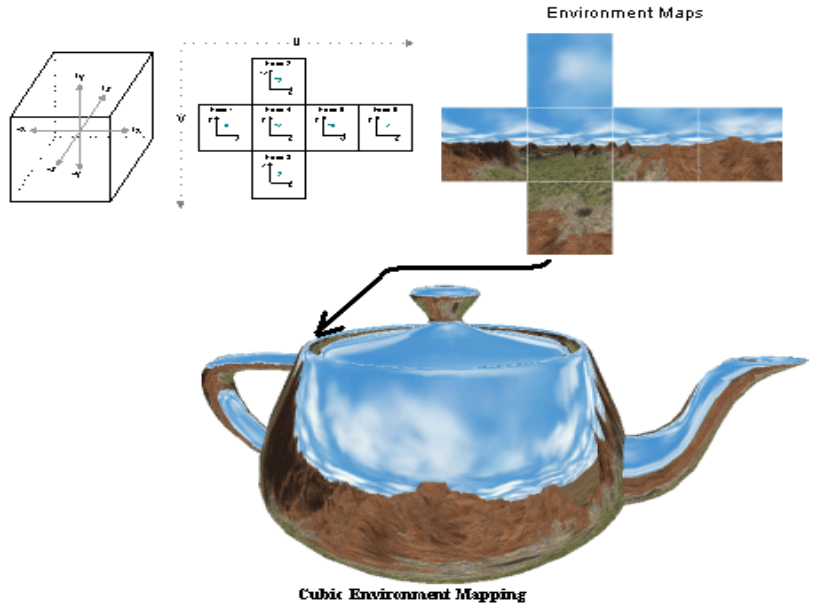
- Many graphics accelerators offer cubic environment mapping support
  - Support in OpenGL and other graphics APIs
- Environment map is 6 maps that form the faces of a cube
  - View point is fixed at the center, 6 views are rendered
  - View independent
- For a single reflection vector (normalized)
  - Find the face it intersects (which map)
    - Reflection vector with the largest magnitude selects the face
      - E.g. (-0.2, 0.5, -0.84) selects the -z face
  - Map the components of the reflected vector into (u,v)
    - Example of intersection with negative z axis:
      - $u = r_x + 0.5$
      - $v = -r_z + 0.5$





Cubic Environment Mapping

- Advantages
  - Environment maps can be rendered in real-time
    - Place camera at center of cube
    - Project the scene onto the 6 faces of a cube
  - More uniform sampling than spherical methods
    - Spherical methods have more texels near poles than equator



http://www.ocworkbench.com/hardware/ati/radeon/radeonp3.htm [link inactive]

Using Cube Maps with GLSL

- Sampler function: samplerCube
- Texture access function: textureCube
  - Provide the cubeMap and the reflection vector
- OpenGL setup

```
glEnable(GL_TEXTURE_CUBE_MAP);
glGenTextures(1, &cubemap_texture);
glBindTexture(GL_TEXTURE_CUBE_MAP, cubemap_texture);
glTexParameteri(GL_TEXTURE_CUBE_MAP, GL_TEXTURE_WRAP_S, GL_REPEAT);
glTexParameteri(GL_TEXTURE_CUBE_MAP, GL_TEXTURE_WRAP_T, GL_REPEAT);
glTexParameteri(GL_TEXTURE_CUBE_MAP, GL_TEXTURE_WRAP_R, GL_REPEAT);
glTexParameteri(GL_TEXTURE_CUBE_MAP, GL_TEXTURE_MAG_FILTER, GL_LINEAR);
glTexImage2D(GL_TEXTURE_CUBE_MAP_POSITIVE_X, 0, GL_RGBA, 256,
                        256,0, GL_RGBA, GL_UNSIGNED_BYTE, image1);
glTexImage2D(GL_TEXTURE_CUBE_MAP_NEGATIVE_X, 0, GL_RGBA, 256,
                        256,0, GL_RGBA, GL_UNSIGNED_BYTE, image2);
glTexImage2D(GL_TEXTURE_CUBE_MAP_POSITIVE_Y, 0, GL_RGBA, 256,
                        256,0, GL_RGBA, GL_UNSIGNED_BYTE, image3);
glTexImage2D(GL_TEXTURE_CUBE_MAP_NEGATIVE_Y, 0, GL_RGBA, 256,
                        256,0, GL_RGBA, GL_UNSIGNED_BYTE, image4);
glTexImage2D(GL_TEXTURE_CUBE_MAP_POSITIVE_Z, 0, GL_RGBA, 256,
                        256,0, GL_RGBA, GL_UNSIGNED_BYTE, image5);
glTexImage2D(GL_TEXTURE_CUBE_MAP_NEGATIVE_Z, 0, GL_RGBA, 256,
                        256,0, GL_RGBA, GL_UNSIGNED_BYTE, image6);
```

Cube Maps

- Downloadable cube maps:
  - https://www.cleanpng.com/free/cube-mapping.html
- Dynamic cube map generation
  - Can generate cube maps for your scene by drawing all objects except reflecting object with camera placed in center of reflecting object
    - Single pass to render all 6 different views
      - Possible in Direct X Shader Model 4 and some OpenGL extensions
      - https://registry.khronos.org/OpenGL/extensions/ARB/ARB_geometry_shader4.txt
      - http://stackoverflow.com/questions/462721/rendering-to-cube-map
- Tutorial
  - http://www.ozone3d.net/tutorials/glsl_texturing_p05.php#part_51

Other Environment Mapping

- Dual Parabaloid Mapping
  - Similar to spherical mapping but uses parabaloid
  - More uniform texel sampling than other methods
- Octahedral Mapping
  - Similar to cube mapping
  - Projects onto octahedron
  - Can easily be unfolded to fit in one image file

Bump Environment Mapping

- Combination of bump mapping and environment mapping
- Perturbs environment mapping coordinates by the normal differentials found in the bump map
  - Effect is to perturb the reflection vector
- Requires 2 additional maps: bump map and an environment map

http://developer.nvidia.com/view.asp?IO=ogl_dynamic_bumpreflection [link inactive]