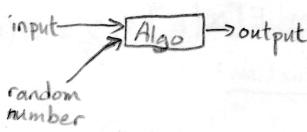


CS5330 Randomized Algorithms

Deterministic Algo: for every input, algo gives correct output quickly input → Algo → output

Randomized Algo: for every input, for most choices of randomness,
the algo gives correct output quickly
(i.e. occasionally it may run slowly or give the wrong answer)



Running time measurement → expected runtime
→ high probability bound on runtime

$$\text{Fact: } 1 - n \leq e^{-n}$$

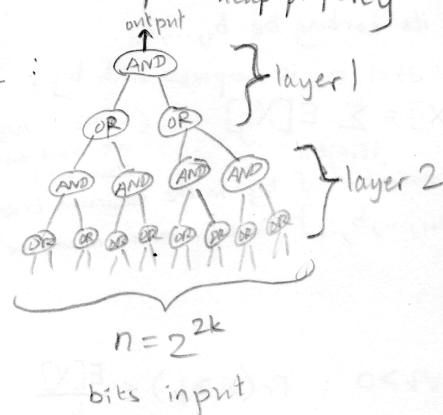
Treap (with randomized priorities) building \cong randomized quicksort

elements of $\langle x, y \rangle$

random

where X satisfies BST property: $\text{left} < X < \text{right}$
and Y satisfies heap property: $y > \text{left}$ and $y > \text{right}$

AND/OR tree:



$$f: \{0,1\}^{16} \rightarrow \{0,1\}$$

randomised algo: from root, query random subtree,
if the answer from that subtree is
insufficient then query the other subtree

Karger min cut:

(multigraph) While there are more than two vertices, pick a random edge and identify the two endpoints. Output the number of edges remaining.

$P(\text{answer is correct}) \geq \frac{2}{n(n-1)}$

Proof via properties: ① the min cut never decreases

② if the multigraph has n vertices

and min-cut size k , then it has at least $\frac{nk}{2}$ edges

Cor: there cannot be more than $\frac{n(n-1)}{2}$ distinct min cuts.

Probability space

- (Countable) sample space Ω (i.e. a set of countably many elements)
- probability measure $\Pr: \Omega \rightarrow [0,1]$

Event: any subspace of the sample space Ω

$$\Pr(E) = \sum_{w \in E} \Pr(w)$$

union bound: $\Pr(E_1 \cup E_2) \leq \Pr(E_1) + \Pr(E_2)$

Independent: $\Pr(E \cap F) = \Pr(E) \cdot \Pr(F)$

Freivald's algorithm: Given $n \times n$ matrices A, B, C , does $AB = C$?

Algorithm: pick random $r \in \{0,1\}^n$ and check that $A(Br) = Cr$

$O(n^2)$ time, and $AB \neq C \Rightarrow \Pr(ABr \neq Cr) \geq \frac{1}{2}$

Proof: there must be an entry d_{ij} in $D = AB - C$ that is nonzero. so we can just repeat $\lceil \log_2 \frac{1}{\delta} \rceil$ times

to d_{ij} . assuming everything else has been fixed, at least one of $\begin{cases} r_j = 1 \\ r_j = 0 \end{cases}$ will imply that $Dr \neq 0$.

Random variable: a function $X: \Omega \rightarrow \mathbb{R}$.

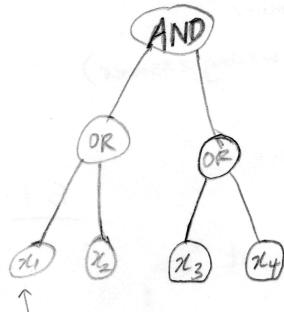
Expectation: $E[X] = \sum_i i \cdot \Pr(X=i)$ (could be unbounded, in which case $E[X]=\infty$)

Linearity of expectation: $E\left[\sum_i X_i\right] = \sum_i E[X_i]$

Variance: $\text{Var}[X] = E[(X - E[X])^2] = E[X^2] - E[X]^2$

Conditional expectation: $E[X|E] = \sum_x x \cdot \Pr(X=x|E)$

AND-OR tree evaluation:



E_{k-1} := expected running time

Indicator random variables: $X(w) := \begin{cases} 1 & \text{if } w \in E \\ 0 & \text{otherwise} \end{cases}$

Randomized quicksort analysis: Let the input be a_1, \dots, a_n and its sorting be b_1, \dots, b_n .

Let X_{ij} be the indicator ran. var. that b_i is compared with b_j .

Then: expected # of comparisons: $E[X] = \sum_{1 \leq i < j \leq n} E[X_{ij}]$ (since every element is compared at most once with each other)

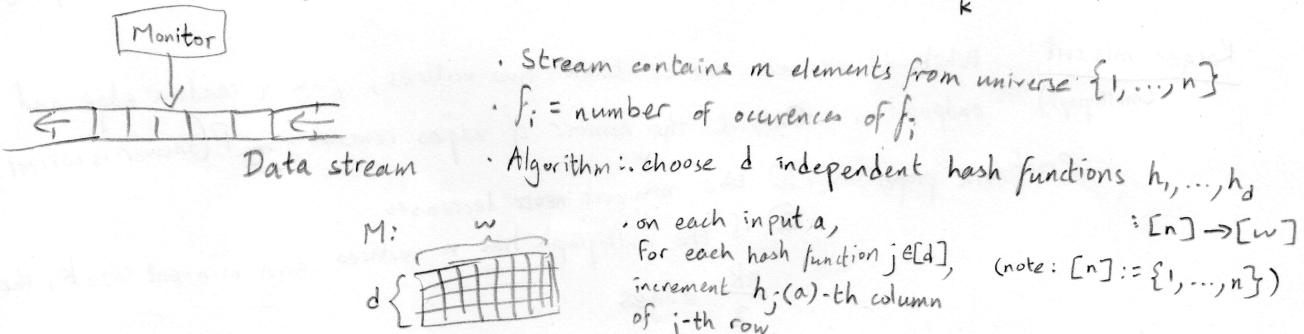
Observe: ① $X_{ij}=1$ if b_i is an ancestor of b_j in the recursion tree or vice versa
② $X_{ij}=0$ if any of $\{b_{i+1}, \dots, b_{j-1}\}$ is a common ancestor of $b_i \neq b_j$ in the recursion tree

Hence $\Pr(X_{ij}=1) = \frac{2}{j-i+1}$

Hence $E[X] \in O(n \log n)$

Markov's inequality: If X is a non-negative ran. var. then $\forall k > 0$: $\Pr(X \geq k) \leq \frac{E[X]}{k}$

Count-min sketch:



Thm: If $d = \log(\frac{1}{\delta})$ and $w = \frac{2}{\epsilon}$, then $\forall i \in [n]$, $f_i \leq \hat{f}_i \leq f_i + \epsilon m$ with probability $\geq 1 - \delta$.

Space needed: $O\left(\frac{1}{\epsilon} \log m \log\left(\frac{1}{\delta}\right)\right) + \text{cost of storing hash functions}$ at least $1 - \delta$.

Chebyshov's inequality: If X is a ran. var. then $\forall k > 0$: $\Pr(|X - E[X]| \geq k) \leq \frac{\text{Var}[X]}{k^2}$

Facts about variance: $\text{Var}[X] = E[(X - E[X])^2] = E[X^2] - E[X]^2$

If X and Y are independent: $E[XY] = E[X] \cdot E[Y]$

Binomial: $E[X] = np$

$\text{Var}[X] = np(1-p)$

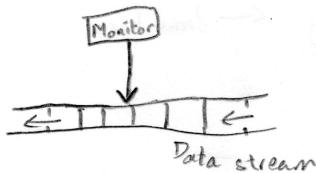
Bernoulli: $E[X] = p$

$\text{Var}[X] = p(1-p)$

$\text{Var}[X+Y] = \text{Var}[X] + \text{Var}[Y]$

Not necessarily independent: $\text{Var}\left[\sum_i X_i\right] = \sum_i \text{Var}[X_i] + 2 \cdot \sum_{i < j} \text{Cov}(X_i, X_j)$

where $\text{Cov}(X, Y) = E[X \cdot Y] - E[X] \cdot E[Y]$

Count sketch:

- Given $i \in [n]$, want to estimate f_i .
- Alg: choose a hash function $h: [n] \rightarrow [w]$, and n random signs $\sigma_1, \dots, \sigma_n \in \{-1, 1\}$
- on encountering a , update $C[h(a)] \leftarrow C[h(a)] + \sigma_a$
- given a query i , output $\hat{f}_i = \sigma_i \cdot C[h(i)]$
- Thm: If $w = \frac{3}{\epsilon^2}$ then $\forall i \in [n]$, $|\hat{f}_i - f_i| \leq \epsilon \sqrt{\sum_i f_i^2}$ with probability at least $\frac{2}{3}$.

Median finding:

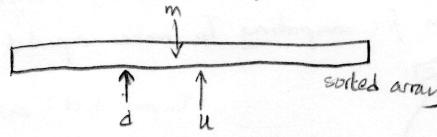
- Median: the $\lceil \frac{n}{2} \rceil$ 'th element in the sorted order

Best deterministic algorithm must make at least $2n$ comparisons

- Randomised algorithm taking $1.5n + o(n)$ comparisons!

Lazy median:

- Idea:



want to pick d and u

s.t. $d < m < u$ and there are n^c elements between d and u for $c < 1$.

it takes $\frac{3n}{2} + o(n)$ to determine the set of elements between d and u

the n^c elements can be sorted normally with $o(n)$ comparisons

- Algorithm:
- Pick $\lceil n^{\frac{3}{4}} \rceil$ elements in S at random with replacement into set R

Let d be the $\lfloor \frac{1}{2}n^{\frac{3}{4}} - \sqrt{n} \rfloor$ smallest element of R

Let u be the $\lfloor \frac{1}{2}n^{\frac{3}{4}} + \sqrt{n} \rfloor$ smallest element of R

By comparing every element in S to d and u , compute $C = \{x \in S \mid d \leq x \leq u\}$

$$\text{Pr}(\mathcal{E}_1) : |\{r \in R \mid r \leq m\}| < \frac{1}{2}n^{\frac{3}{4}} - \sqrt{n}$$

$$\text{Pr}(\mathcal{E}_2) : |\{r \in R \mid r \geq m\}| < \frac{1}{2}n^{\frac{3}{4}} - \sqrt{n}$$

$$\text{and } l_d = |\{x \in S \mid x < d\}|$$

$$\text{and } l_u = |\{x \in S \mid x > u\}|$$

If $l_d > \frac{n}{2}$ or $l_u > \frac{n}{2}$ then FAIL

If $|C| > 4n^{\frac{3}{4}}$ then FAIL

Sort C and output the $(\lfloor \frac{n}{2} \rfloor - l_d + 1)$ 'th element in the sorted order.

Proof: \mathcal{E}_1 and \mathcal{E}_2 : $E[|\{r \in R \mid r \leq m\}|] = \frac{1}{2}n^{\frac{3}{4}}$ (since each element in R has $\frac{1}{2}$ probability of being $\leq m$)

$$\therefore \text{By Chebyshev, } \Pr(\mathcal{E}_1) \leq \frac{n^{\frac{3}{4}}/4}{n} = O(n^{-\frac{1}{4}})$$

\mathcal{E}_3 : Suppose $> 2n^{\frac{3}{4}}$ elements of C are smaller than m

Then, $< \frac{1}{2}n - 2n^{\frac{3}{4}}$ elements are smaller than d

But R has $\frac{1}{2}n^{\frac{3}{4}} - \sqrt{n}$ elements smaller than d

Similar argument using Chebyshev... $\Pr(\mathcal{E}_3) = O(n^{-\frac{1}{4}})$

Since $O(n^{-\frac{1}{4}}) \in o(1)$, can repeat the algorithm until it does not fail.

Las Vegas algorithm: always gives the correct solution, but runtime may vary ← focus here

Monte Carlo algorithm: solution might be incorrect, but running time fixed.

Minimax lemma: $\min_i \max_j C(i, j) \geq \max_j \min_i C(i, j)$

Minimax lemma for mixed strategy: Row player fixes prob p_i for row i , Col player fixes prob q_j for col j

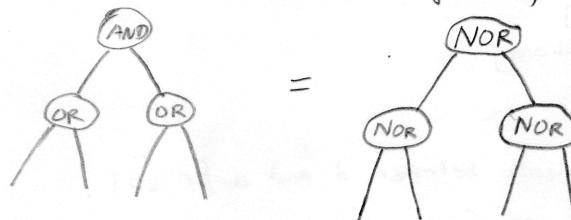
$$\min_{p_1, \dots} \max_j \sum_i p_i \cdot C(i, j) \geq \max_{q_1, \dots} \min_i \sum_j q_j \cdot C(i, j)$$

Von Neumann's minimax thm: this is equality ——————

Yao's minimax principle: To show that the expected cost for any randomised algorithm is $\geq T$, it suffices to show that one distribution Q over inputs has that:

For any deterministic algorithm A, $E_{x \sim Q} [\text{cost of running A on } x] \geq T$

AND-OR tree minimum: any randomized algorithm for computing T_k makes expected at least $n^{0.694}$ queries ($n=2^{2k}$)



• Input dist: each leaf independently set to 1 with prob $p = \frac{3-\sqrt{5}}{2}$

• every node in the NOR tree is 1 with prob p , since $(1-p)^2 = p$
 $T(h) = T(h-1) + (1-p)T(h-1) \geq 1.618 \cdot T(h-1)$
 $\therefore T(2k) \geq 1.618^{2k} = n^{0.694}$

Hoeffding bound: Let X_1, \dots, X_n be independent rand.vars, and assume that $X_i \in [a_i, b_i]$ for every i , and $\mu_i = E[X_i]$. Then for any $t > 0$, $\Pr\left(\left|\sum_i (X_i - \mu_i)\right| \geq t\right) \leq 2 \exp\left(-\frac{2t^2}{\sum_i (b_i - a_i)^2}\right)$

Chernoff bound: Let X_1, \dots, X_n be independent Bernoulli rand. vars.

Let $\mu_i = E[X_i] = \Pr(X_i = 1)$ and $\mu = \sum_i \mu_i$.

Then for any $\delta \in (0, 1)$, $\Pr\left(\left|\sum_i X_i - \mu\right| \geq \delta\mu\right) \leq 2 \exp\left(-\frac{\mu\delta^2}{3}\right)$

Chernoff is better when variables are skewed (i.e. $E[X_i] \ll \frac{1}{2}$)

G(n, p): random graph on n vertices that connects each pair of distinct vertices with probability p .

Thm: let $G \sim G(n, \frac{d}{n-1})$ where $d \geq C \log n$ for some $C > 0$. Then, with probability 99%, every vertex

Proof: use Chernoff bound to show that $\Pr(|\deg(X_i) - d| > 0.1d)$

$$\leq 2 \exp\left(-d \cdot \frac{(0.1)^2}{3}\right) \leq 2 \exp\left(-\frac{C \log n}{300}\right) \leq \frac{1}{100}$$

of G has $0.9d \leq \deg \leq 1.1d$

then use union bound.

Thm: n balls thrown randomly into n bins. With probability $\geq 99\%$, $\max_i X_i \leq 7 + \log n$

Proof using Chernoff bound (large deviations) followed by union bound.

$X_i :=$ number of balls in bin i

Count sketch with median: hash functions $h_1, \dots, h_d : [n] \rightarrow [w]$

• signs $s_1, \dots, s_d : [n] \rightarrow \{-1, +1\}$

• on each $a \in [n]$: for each $j \in [d]$, $c[j, h_j(a)] \leftarrow c[j, h_j(a)] + s_j(a)$

$f_i = \text{median}(s_1(i) \cdot c[1, h_1(i)], \dots, s_d(i) \cdot c[d, h_d(i)])$

each row has at most $\frac{1}{3}$ chance of being bad, i.e. $\|\hat{f}_j - f_j\|_2 \geq \epsilon \|f_j\|_2$

$$E[X_j] \leq \frac{d}{3}$$

$$\Pr\left(\sum_j X_j \geq \frac{d}{2}\right) \leq \Pr\left(\left|\sum_j X_j - E[\sum_j X_j]\right| \geq \frac{d}{2}\right) \leq 2 \exp\left(-\frac{2(\frac{d}{2})^2}{d}\right)$$

$$= 2e^{-d/18}$$

So set $w = O(\frac{1}{\epsilon^2})$ and

$$d = O(\log \frac{1}{\epsilon})$$

then $\forall i \in [n]$, $|\hat{f}_i - f_i| \leq \epsilon \sqrt{\sum_j f_j^2}$

with prob at least $1-\delta$.

(space complexity: $O(\epsilon^{-2} \log m \log \frac{1}{\delta})$ + cost for hash functions & signs)

So $d = \Theta(\log \frac{1}{\delta})$ to make error prob δ .

Discrepancy: n subsets $S_1, \dots, S_n \subseteq \{1, \dots, m\}$.

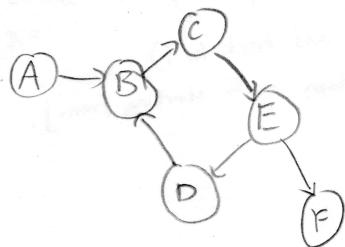
want a vector $x \in \{-1, 1\}^m$ s.t. $\forall i \in [n]$, $\left| \sum_{j \in S_i} x_j \right| \leq D$ \leftarrow called the discrepancy

(i.e. a vector that roughly equally partitions all sets)

Algorithm: choose x randomly. Then $\Pr \left(\max_i \left| \sum_{j \in S_i} x_j \right| > \sqrt{2m \ln n} \right) < 1$

(since, for each S_i , by Hoeffding, $\left| \sum_{j \in S_i} x_j \right| > \sqrt{2m \ln n}$ with probability $< \frac{1}{n}$)

Packet routing:



(see slides).

Hash functions should be: $h: U \rightarrow [n]$

• Pseudorandom

• Compactly representable $\leadsto H$: family of hash functions

• Efficiently computable $h \in H$ be uniformly chosen

number of bits to represent h is $\log_2 |H|$.

E.g. $H = \{h\}$ where $h(x) = x \bmod n$: not pseudorandom if x can be arbitrary

$H = \{h_a : a=1, \dots, n\}$ where $h_a(x) = ax \bmod n$: not pseudorandom if n divides a

Collision: $i, j \in U$ where $i \neq j$ and $h(i) = h(j)$

k -Universal: For all distinct i_1, \dots, i_k , $\Pr_{h \in H} [h(i_1) = \dots = h(i_k)] \leq \frac{1}{n^{k-1}}$
("universal" usually means 2-universal)

Strong k -universal: For all distinct $i_1, \dots, i_k \in U$ and all $y_1, \dots, y_k \in [n]$, $\Pr_{h \in H} [h(i_1) = y_1, \dots, h(i_k) = y_k] = \frac{1}{n^k}$

Strong k -universal $\Rightarrow k$ -universal

Strong k -universal \Rightarrow strong $(k-1)$ -universal

Consequences: if h is drawn from a 2-universal family, the expected number of collisions amongst s items is $O(\frac{s^2}{n})$

Stochastic processes: X_0, X_1, X_2, \dots X_t : state of process at time t

initial state

Markov chain: state X_t is only dependent on state X_{t-1} .

$(X_t \text{ is independent of } X_1, \dots, X_{t-2}, \text{ conditioned on the value of } X_{t-1})$

Transition matrix: $P_{i,j} = \Pr [X_t = j | X_{t-1} = i]$

from i to j

$$P = \begin{pmatrix} P_{0,0} & P_{0,1} & \dots & P_{0,j} & \dots \\ P_{1,0} & P_{1,1} & \dots & P_{1,j} & \dots \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ P_{i,0} & P_{i,1} & \dots & P_{i,j} & \dots \\ \vdots & \vdots & \ddots & \vdots & \vdots \end{pmatrix}$$

Stationary distribution: $\pi = (\pi_1, \dots, \pi_n)$ where $\pi P = \pi$

every finite state Markov chain has a stationary distribution

we usually use π_i to find $h_{i,j}$.

Irreducible: For any two states i and j , both $i \rightarrow j$ and $j \rightarrow i$ (where $i \rightarrow j$: $P_{i,j}^t > 0$ for some $t \geq 0$)

* Every finite state irreducible Markov chain has exactly one stationary distribution: $\pi_i = \frac{1}{h_{i,i}}$ (i.e. can get from i to j in t steps)

Hitting time: $h_{i,j}$: expected time to reach state j from state i . $h_{i,j} = E[\min\{t \geq 0, X_t = j\} | X_0 = i]$

Aperiodic: $\forall i$, $\gcd(\{t : P_{i,i}^t > 0\}) = 1$ Equiv aperiodic: $\forall i, \exists t_0 > 0$ s.t. $\forall t \geq t_0, P_{i,i}^t > 0$.

Thm: Given a finite state irreducible aperiodic Markov chain with stationary distribution π , for any state i ,

$$\lim_{t \rightarrow \infty} \Pr[X_t = i] = \pi_i; \quad (\text{i.e. the distribution converges to the stationary distribution})$$

Time reversible: There exists a distribution π s.t. $\forall i, j : \pi_i P_{ij} = \pi_j P_{ji}$

(i.e. the edge probability backward is the same as forward, it is like running the Markov chain backwards)

If a Markov chain is time-reversible, then π is a stationary distribution (since $(\pi P)_{ij} = \sum_i \pi_i P_{ij} = \sum_i \pi_j P_{ji} = \pi_j \sum_i P_{ji} = \pi_j$)

Commute time between two vertices i and j : $C_{ij} = h_{ij} + h_{ji}$ (time to go from i to j and back to i)

Cover time: max over all vertices j of the expected time to visit all vertices in a random walk starting from j .

Random walk: $P_{ij} = \frac{1}{\deg(i)}$ for each neighbour j of i .

stationary distribution: $\pi_i = \frac{\deg(i)}{2|E|}, h_i = \frac{2|E|}{\deg(i)}$

• If $G = K_n$, then $h_{ij} = n$ and cover time = $O(n \log n)$ (coupon collector problem)

• If G is the path of length n , then the cover time is $O(n^2)$

disjoint path of length $\frac{n}{2}$ ending in v , then $h_{v,u} = O(n^2), h_{u,v} = O(n^3)$, cover time = $O(n^3)$

• Thm: $C(G) \leq 2|E|(n-1)$ \uparrow cover time \Rightarrow can be shown by considering Markov chain on edges: if i is adjacent to j then $C_{ij} \leq 2|E|$

Markov chain Monte Carlo: for sampling something from a desired distribution.

- Design a Markov chain whose stationary distribution π is the desired distribution
- Make sure that each step can be executed efficiently, and convergence to π is "fast".

Metropolis-Hastings step: to make an arbitrary Markov chain on state space Ω with transition matrix Q have a desired stationary distribution π .

Algorithm:

① Pick Y by taking a step from X_t using Q

$$\textcircled{2} \quad \alpha := \frac{1}{2} \min \left\{ 1, \frac{\pi(Y) \cdot Q_{X_t, Y}}{\pi(X_t) \cdot Q_{Y, X_t}} \right\}$$

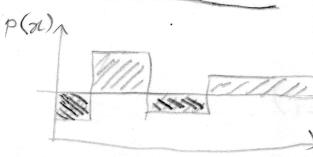
③ With probability α , $X_{t+1} \leftarrow Y$, else $X_{t+1} \leftarrow X_t$

can be shown that $\pi_i P_{ij} = \frac{\pi_j Q_{j,i}}{2} = \pi_j P_{j,i}$ (transit stay the same)

so the new stationary distribution is π .

Rapid mixing \Leftrightarrow approximate counting:

Total variation (TV) distance between distributions D_1, D_2 : $\|D_1 - D_2\| := \max_{A \subseteq \Omega} \left(\Pr_{x \sim D_1} [x \in A] - \Pr_{x \sim D_2} [x \in A] \right)$ (something like the L_∞ norm... over subsets)



Mixing time: (depends on ϵ (how well we need it mixed)): $d(t) := \max_{x \in \Omega} \|P^t(x) - \pi\|$ where π is the stationary distribution.

• rapidly mixing: $t_{\min}(\epsilon) \in \text{poly}(\text{problem size}, \epsilon)$

$$t_{\text{mix}}(\epsilon) = \min \{ t \mid d(t) \leq \epsilon \}$$

Coupling between distributions D_1, D_2 : (X, Y) where $X \sim D_1$ and $Y \sim D_2$. (X and Y are generally not independent)

Coupling lemma: $\|D_1 - D_2\| \leq \Pr[X \neq Y]$ where (X, Y) is a coupling between D_1, D_2 .

Coupling of Markov chains: same transition matrix, but possibly different starting states

Markov chain coupling lemma: If (X_t, Y_t) is a coupling of a Markov chain, and T is such that for every $x, y \in \Omega$, $\Pr[X_T \neq Y_T | X_0 = x, Y_0 = y] \leq \varepsilon$, then $t_{\text{mix}}(\varepsilon) \leq T$.

- E.g. card shuffling:
 - states: permutations of $\{1, \dots, n\}$
 - transition: moving a uniformly random card to the top
 - chains couple once all cards have moved to the top at least once
 - $\Pr[\exists C : C \text{ not moved to top in } T \text{ steps}] \leq n \cdot (1 - \frac{1}{n})^T \leq n \cdot e^{-\frac{T}{n}}$
 - When $T \in O(n \ln \frac{n}{\varepsilon})$, we have $\Pr[X_T \neq Y_T] \leq \varepsilon$ union bound
- E.g. lazy walk on a cycle:
 - stay at current node with probability $\frac{1}{2}$, move anticlockwise with probability $\frac{1}{4}$, move clockwise with probability $\frac{1}{4}$.
 - coupling of (X_t, Y_t) : with probability $\frac{1}{2}$, move X_t one step in a random direction, otherwise, move Y_t one step in a random direction
 - $d_t := X_t - Y_t \pmod{n}$ increases or decreases by 1 with probability $\frac{1}{2}$ each, so $d_t \equiv 0 \pmod{n}$ within $O(n^2)$ steps in expectation.
 - By Markov ineq: when $T \geq \frac{n^2}{\varepsilon}$, $\Pr[X_T \neq Y_T] = \Pr[\text{coupling time} \geq T] \leq \frac{\mathbb{E}[\text{coupling time}]}{T} = \varepsilon$
- E.g. random spanning trees:
 - consider random rooted arborescences instead
 - directed tree where all edges point away from root
 - with probability $\frac{1}{2}$, keep current arborescence, otherwise, pick a random edge from some vertex to the current root, and re-root the tree at the new root.
 - takes $O(n^6)$ time for roots to agree
 - after roots agree, takes another $O(n^3)$ to visit all vertices (and then entire arborescence will agree)
 - by Markov ineq: mixing time is $O(\frac{n^6}{\varepsilon})$

Fully polynomial randomised approximation scheme (FPRAS): given input x and parameters $\varepsilon, \delta \in (0, 1)$, the algorithm outputs an approximation \hat{V} such that $\Pr[|\hat{V} - V(x)| > \varepsilon \cdot V(x)] < \delta$, and the algorithm runs in $\text{poly}(|x|, \frac{1}{\varepsilon}, \log(\frac{1}{\delta}))$.

- (note: $V(x)$ is the true answer, so it means \hat{V} is a $(1 \pm \varepsilon)$ -multiplicative approximation of $V(x)$.)
- FPRAS For size estimation:
 - suppose $S \subseteq \Omega$, and we can efficiently generate uniform samples from Ω , and efficiently check if a sample is in S .
 - then there is an FPRAS for computing $\mu = \frac{|S|}{|\Omega|}$ that makes $\frac{3 \ln(\frac{2}{\delta})}{\varepsilon^2 \mu}$ samples from Ω .

Fully polynomial almost uniform sampler (FPAUS): (for sampling almost uniformly from Ω , usually as part of an FPRAS)

given input x and parameter $\varepsilon > 0$, output distribution $W(x)$ satisfies

$$\|W(x) - U(x)\| \leq \varepsilon$$
output distribution uniform distribution

and the algorithm runs in $\text{poly}(|x|, \frac{1}{\varepsilon})$.

E.g. k -colourings: Finding an approximation for the number of k -colourings in a given graph G_i .

G_i has n vertices and m edges = e_1, \dots, e_m

- Let G_i be the graph with all n vertices and edges $\{e_1, \dots, e_i\}$
- Let C_i be the number of k -colourings for G_i . (C_m is what we want, and $C_0 = k^n$)
- $C_m = \frac{C_m}{C_{m-1}} \times \frac{C_{m-1}}{C_{m-2}} \times \dots \times \frac{C_1}{C_0} \times C_0$
- want to approximate each $\frac{C_i}{C_{i-1}}$ up to multiplicative approximation $(1 \pm \frac{\epsilon}{2m})$ with

then by union bound, we can approximate $\frac{C_m}{C_0}$ up to multiplicative probability $\frac{\delta}{m}$,

approximation $(1 \pm \epsilon)$, so we have an FPRAS for C_m .

How to approximate $\frac{C_i}{C_{i-1}}$? Two sources of error:

- our sampler for C_{i-1} is only approximately uniform when we are sampling a finite amount of times
- can be shown that $\frac{C_i}{C_{i-1}} \geq \frac{3}{4}$ when $k > 2\Delta$

use FPAUS on G_{i-1} to produce a colouring A s.t. $|\Pr[A \text{ colours } G_i] - \frac{C_i}{C_{i-1}}| \leq \frac{\epsilon}{8m}$

if we sample r colourings from FPAUS on G_{i-1} , let Z_i be how many colour G_i ,

$$r \frac{C_i}{C_{i-1}} \left(1 - \frac{\epsilon}{6m}\right) \leq r \cdot \left(\frac{C_i}{C_{i-1}} - \frac{\epsilon}{8m}\right) \leq E[Z_i] \leq r \cdot \left(\frac{C_i}{C_{i-1}} + \frac{\epsilon}{8m}\right) \leq r \frac{C_i}{C_{i-1}} \left(1 + \frac{\epsilon}{6m}\right)$$

since $E[Z_i] \geq \frac{r}{2}$, by Chernoff bound, with $r = \frac{m^2}{\epsilon^2} \log(\frac{m}{\delta})$ samples, with probability $1 - \frac{\delta}{m}$, can get a $(1 \pm \frac{\epsilon}{6m})$ -multiplicative approximation of Z_i .

combining the two sources of error, we have a $(1 \pm \frac{\epsilon}{6m})^2 \subseteq (1 \pm \frac{\epsilon}{2m})$ -multiplicative approximation of $\frac{C_i}{C_{i-1}}$.

Conditional expectation: $E[X|Y]$ is a random variable $f(Y)$ where $f(y) = E[X|Y=y]$

$$\begin{aligned} \text{Lemma: } E[E[X|Y]] &= E[X] \\ E[E[X|Y,Z]|Z] &= E[X|Z] \end{aligned}$$

Martingale: Z_0, \dots, Z_n is a martingale w.r.t. X_0, \dots, X_n if for all $i \geq 0$:

- Z_i is a function of X_0, \dots, X_i
- $E[|Z_i|] < \infty$
- $E[Z_{i+1}|X_0, \dots, X_i] = Z_i$

Azuma-Hoeffding bound (like Hoeffding bound, but for martingales): If Z_0, \dots, Z_n is a martingale s.t. $B_k \leq Z_k - Z_{k-1} \leq B_k + c_k$ where B_k could depend on Z_0, \dots, Z_{k-1} .

then for all $t \geq 1$ and any $\lambda > 0$, $\Pr[|Z_t - Z_0| \geq \lambda] \leq 2 \exp\left(-\frac{2\lambda^2}{\sum_{k=1}^t c_k^2}\right)$

Dob martingale: want to find an approximation for $Z = f(X_1, \dots, X_n)$

$$\text{for any } i \geq 0, Z_i = E[f(X_1, \dots, X_n)|X_1, \dots, X_i]$$

then Z_0, \dots, Z_n forms a martingale w.r.t. X_1, \dots, X_n and $Z_n = Z$

E.g.: pattern matching: suppose X_1, \dots, X_n are random chars from an alphabet of size S , and we want to find $Z := \text{number of occurrences of a particular substring } B \text{ of size } k$

let $Z_i = E[Z|X_1, \dots, X_i]$, so $Z_n = Z$ and $Z_0 = E[Z] = (n-k+1) \cdot S^{-k}$

Note that $|Z_{k+1} - Z_k| \leq k$ (one char can contribute at most k occurrences of B)

By Azuma-Hoeffding, $\Pr[|Z - E[Z]| \geq \epsilon] \leq 2 \exp\left(-\frac{\epsilon^2}{2nk^2}\right)$

E.g. m balls, n bins, let X_i be the bin the i^{th} ball lands in (9)

want to find $Z := \text{number of empty bins}$

let $Z_i = E[Z | X_1, \dots, X_i]$ (Doob martingale)

note that $|Z_{k+1} - Z_k| \leq 1$, $Z_n = Z$, $Z_0 = E[Z]$

By Azuma-Hoeffding, $\Pr[|Z - E[Z]| \geq \varepsilon] \leq 2 \exp\left(-\frac{\varepsilon^2}{2m}\right)$
(note: we don't actually need to know $E[Z]$)

c-Lipschitz: $f(X_1, \dots, X_n)$ is c-Lipschitz if for all i and all possible values x_1, \dots, x_n and y_i :
 $|f(x_1, \dots, x_{i-1}, x_i, x_{i+1}, \dots, x_n) - f(x_1, \dots, x_{i-1}, y_i, x_{i+1}, \dots, x_n)| \leq c$
(i.e. each coordinate doesn't contribute too much to the final result)

If f is c-Lipschitz and X_1, \dots, X_n are independent, then $|Z_k - Z_{k-1}| \leq c$ for the Doob martingale
McDiarmid's inequality (special case of Doob + Azuma-Hoeffding): Z_0, \dots, Z_n .

If f is a function on n variables and is c-Lipschitz, and
 X_1, \dots, X_n are independent random variables,

then $\Pr[|f(X_1, \dots, X_n) - E[f(X_1, \dots, X_n)]| \geq \lambda] \leq 2 \exp\left(-\frac{2\lambda^2}{nc^2}\right)$