

# CS4261 Algorithmic Mechanism Design

→ Players  $N = \{1, 2, \dots, n\}$

Game → Actions

→ Preferences over outcomes  
 $\text{BR}_i(\vec{p}_{-i}) = \{q_j \in \Delta(A_i) : u_i(q_j) \geq u_i(q_k) \forall k \in N \setminus \{i\}\}$   
 general framework for strategic interaction.

NE

Normal form game → set of players  $N = \{1, 2, \dots, n\}$

action profile  $\vec{a} \in A_1 \times A_2 \times \dots \times A_n$

utility of each  $\vec{a}$  for each player  $u_i(\vec{a})$ .

2, 1	1, 2
1, 2	2, 1

Socially optimal: maximize the total benefit

envy free: no one prefers another bundle more than his own

Socially optimal: maximise  $\sum_i u_i(o)$

Pareto optimal:  $\# o' \text{ s.t. } (u_i(o') \geq u_i(o) \forall i \in N)$

everybody won't be worse-off with swapping and  $(u_i(o') > u_i(o) \exists i \in N)$

someone gets strictly better-off with swapping

Dominant strategy: A best option for a player, regardless of what other players choose

(weak) Domination:  $\vec{p} \in \Delta(A_i)$  dominates  $\vec{q} \in \Delta(A_i)$ :  $\forall \vec{p}_{-i} \in \Delta(A_{-i})$ :

Best response set (strong) Domination: strict inequality for all.  $u_i(\vec{p}_{-i}, \vec{p}) \geq u_i(\vec{p}_{-i}, \vec{q})$  for all  $\vec{p}_{-i} \in \Delta(A_{-i})$

$\text{BR}_i(\vec{a}_{-i}) := \{b \in A_i \mid b \in \text{argmax } u_i(\vec{a}_{-i}, b)\}$

↑  
the set of options that yield the best outcome for me, given what everyone else is going to play.

Nash equilibrium:  $\forall i \in N, a_i \in \text{BR}_i(\vec{a}_{-i})$

i.e. it is in everyone's best response set.

$A > B$  (dominates)

because  $5 > 2$

4 > 3.

Mixed strategies

- Player utility: expected value (we assume players are risk-neutral)

- Mixed Nash equilibrium:  $\forall i \in N$ :

↓ always exists!  $\forall \vec{q}_i \in \Delta(A_i), u_i(\vec{p}) \geq u_i(\vec{p}_{-i}, \vec{q}_i)$  support of a distribution:

It is never better (in terms of utility/EV) to switch to a different mixed strategy.

1, 5	4, 4
4, 3	3, 3

intersections are Nash equilibria.

set of options taken with nonzero probability.

- Best response

similarly defined.

Nash equilibrium

Theorem: If action  $a \in A_i$  is strictly dominated by some  $\vec{p} \in \Delta(A_i)$  then  $a$  is never played in a Nash eqn. with any positive probability.

← iterated removal of dominated strategies

A mixed strategy can dominate another strategy too!

mixed > top row?

(2)

Zero-sum game:  $\rightarrow$  2-player game  
 $\rightarrow \forall a_i \in A_1, \forall b_j \in A_2 : u_1(a_i, b_j) = -u_2(a_i, b_j)$

Mixed Nash eqm is poly-time computable via simplex.

Duality of linear optimization (simplex) problem:

<u>Primal</u> minimize $\vec{c}^T \vec{x}$ s.t. $A\vec{x} \geq \vec{b}$ and $x_i \geq 0 \forall i \in N$	<u>Dual</u> maximize $\vec{b}^T \vec{y}$ s.t. $A^T \vec{y} \leq \vec{c}$ $y_j \geq 0 \forall j \in M$
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Theorems: If  $\vec{x}^*$  and  $\vec{y}^*$  are

the optimal solutions, then:

① Optimality:  $\vec{c}^T \vec{x}^* = \vec{b}^T \vec{y}^*$

② Complementary Slackness:

If  $x_i^* > 0$  then  $(A^T \vec{y})_i = c_i$

If  $y_j^* > 0$  then  $(A \vec{x})_j = b_j$

Given  $A$ ,  $\vec{b}$ ,  $\vec{c}$ , the optimal for both problems are the same.  
matrix      matrix

von Neumann Minimax thm: For any payoff  $A$ ,

$$\max_{\vec{p} \in \Delta(A)} \min_{\vec{q} \in \Delta(A_2)} \vec{p}^T A \vec{q}^T =: v_+ = v_- := \min_{\vec{q} \in \Delta(A_2)} \max_{\vec{p} \in \Delta(A)} \vec{p}^T A \vec{q}^T$$

get expected payoff for strategy

maximin      minimax

To prove: ① show that it is (at least) as good if player 2 uses a pure strategy,

$$\max_{\vec{p} \in \Delta(A)} \min_{\vec{q} \in \Delta(A_2)} \vec{p}^T A \vec{q}^T = \max_{\vec{p} \in \Delta(A)} \min_j (\vec{p}^T A)_j$$

min over all mixed strategies      min over all pure strategies

② Use LP duality:

$$\begin{aligned} \max & v_+ \\ \text{s.t. } & v_+ \leq \sum_{i=1}^n a_{ij} x_i \quad \text{for all } j \in M \\ & \text{and } \sum_{i=1}^n x_i = 1 \end{aligned} \quad = \quad \begin{aligned} \min & v_- \\ \text{s.t. } & v_- \geq \sum_{j=1}^m a_{ij} y_j \quad \text{for all } i \in N \\ & \text{and } \sum_{j=1}^m y_j = 1 \end{aligned}$$

all pure strategies

Support of a Nash eqm: support of  $\vec{p}$ :  $\{a : p(a) > 0\}$ . Thm: If  $(\vec{p}, \vec{q})$  is a Nash eqm and

↑  
all those options  
that have tve  
contribution to  $\vec{p}$ .

$a \in \text{supp}(\vec{p})$  then:

$$u_1(a, \vec{q}) \geq u_1(a', \vec{q}) \quad \forall a' \in A_1$$

Solving Nash eqm for two players directly cannot be done with LP, but with this it can be done:

$$\begin{aligned} \text{find } \vec{p}, \vec{q} \text{ s.t. } & \sum_{a \in A_1} p(a) = 1, \quad \sum_{b \in A_2} q(b) = 1 \\ \forall \vec{p}' \in \Delta(A_1) : & u_1(\vec{p}, \vec{q}) \geq u_1(\vec{p}', \vec{q}) \\ \forall \vec{q}' \in \Delta(A_2) : & u_2(\vec{p}, \vec{q}) \geq u_2(\vec{p}, \vec{q}') \end{aligned}$$

(there are infinitely many constraints)

↑  
 $\forall B_1 \subseteq A_1, \forall B_2 \subseteq A_2$ : Find  $\vec{p}, \vec{q}$  s.t.  $\sum_{a \in A_1} p(a) = 1, \sum_{b \in A_2} q(b) = 1$

$\forall a \notin B_1, p(a) = 0; \forall a \in B_1, p(a) > 0$

$\forall b \notin B_2, q(b) = 0; \forall b \in B_2, q(b) > 0$

exponential time alg. by trying all subsets

$\forall b \in B_2 \forall b' \in A_2, u_2(\vec{p}, b) \geq u_2(\vec{p}, b')$

$\forall a \in B_1, \forall a' \in A_1, u_1(a, \vec{q}) \geq u_1(a', \vec{q})$

## Sperner's lemma

- Given any  $n$ -simplex (e.g. triangle, tetrahedron, ...), with corners coloured in distinct colours:
- Triangulate it in any way, where colours of vertices on each face must come from a colour at any of its corners.
  - Then there exists an odd number of simplices whose vertices use all  $(n+1)$  colours.

Proof for  $n=2$ :

$$\begin{aligned} Q &:= \text{num. of triangles with } \begin{matrix} \text{colours of vertices} \\ (G, B, B) \text{ or } (G, G, B) \end{matrix} \\ R &:= \text{num. of triangles with } (R, G, B) \\ X &:= \text{num. of edges with } (G, B) \text{ on boundary} \\ Y &:= \text{num. of edges with } (G, B) \text{ on interior} \end{aligned}$$

↑  
dimensions.

$$\therefore 2Q+R = \text{number of directed GB or BG edges} = 2Y+X$$

$\because X$  is odd,  $\therefore R$  is odd,

can be shown to be odd.

Brouwer fixed point thm: Given  $f: A \rightarrow B$  continuous and  $K$  is compact convex set then:

Nash theorem: A Nash equilibrium always exists.

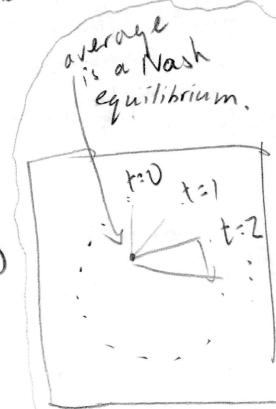
Regret Minimisation:  
 $n :=$  number of actions

$L_{\pi}^t :=$  expected loss of algorithm  $\pi$  at time  $t$   
 $L_{\pi}^t = \sum_{i=1}^t L_{\pi}^i$  = total loss of algorithm  $\pi$  up to time  $t$ .

Regret:  $L_{\pi}^t - L_{\text{best}}^t$   
 $\uparrow$   
 best action, not best algorithm!

Greedy algorithm: At time  $t$ , choose the action that minimises  $L_i^t$ .  
 (tie-break by lower index)

Regret of  $O(n)$   
 $L_{\text{greedy}}^t \in O(n)$   
 $L_{\text{best}}^t$



Randomised greedy alg.:

If there are ties for the best action, then choose uniform probability.

Multiplicative weight updates (MWU)

$$\left. \begin{aligned} \text{Initially: } &\{w_i^1 = 1\} \\ &p_i^1 = \frac{1}{n} \end{aligned} \right\} \text{when } \varepsilon = 0 \Rightarrow \text{pure random play} \\ \text{At t, } \left\{ \begin{aligned} w_i^t &= w_i^{t-1} e^{-\varepsilon L_i^t} \\ p_i^t &= \frac{w_i^t}{W_t}, W_t = \sum_i w_i^t \end{aligned} \right. \quad \left. \begin{aligned} \Leftrightarrow +\infty &\Rightarrow \text{randomised greedy.} \end{aligned} \right.$$

Multiplicative weight updates

$$W^{t+1} = \sum_{i=1}^n w_i^{t+1} \geq w_{\text{best}}^{t+1}$$

$$w_i^{t+1} = e^{-\varepsilon L_i^t}$$

$$\text{Formula: } \forall n \in [-1, 1] : e^x \leq \frac{1+x}{1-x}$$

$$\therefore W^{t+1} \leq \sum_{i=1}^n w_i^t (1 + (-\varepsilon L_i^t) + (-\varepsilon L_i^t)^2)$$

$$\left( \text{since } -1 \leq L_i^t \leq 1 \right) \leq (1 + \varepsilon^2) \left( \sum w_i^t \right) - \varepsilon \left( \sum w_i^t L_i^t \right)$$

$$= W_t (1 + \varepsilon^2 - \varepsilon \sum_{i=1}^n L_i^t p_i^t)$$

$$1 + \varepsilon^2 \leq e^{\varepsilon^2} \rightarrow \frac{1 + \varepsilon^2 - \varepsilon \sum L_i^t p_i^t}{W_t} \leq e^{\varepsilon^2 - \varepsilon L_{\pi}^t}$$

$$\frac{1 + \varepsilon^2 - \varepsilon \sum L_i^t p_i^t}{W_t} \leq e^{\varepsilon^2 - \varepsilon \left( \sum_{i=1}^t L_i^t p_i^t \right)}$$

$$= n^t e^{t \varepsilon^2 - \varepsilon L_{\pi}^t}$$

$$= n^t e^{t \varepsilon^2 - \varepsilon L_{\pi}^t}$$

$$\therefore \frac{e^{-\varepsilon L_{\pi}^t}}{e^{\varepsilon L_{\pi}^t}} \leq \frac{W_{t+1}}{W_t} \leq n^t e^{t \varepsilon^2 - \varepsilon L_{\pi}^t}$$

$$e^{\varepsilon L_{\pi}^t} \leq e^{\varepsilon L_{\pi}^t} \cdot n^t e^{\varepsilon^2 t}$$

## Multiplicative weight update & minimax them

If player 2 uses an online algorithm A with regret R, then

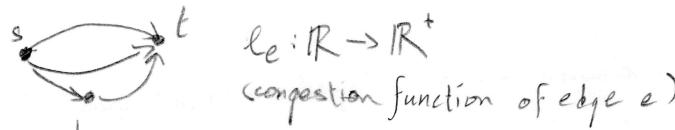
average loss is at most  $v_- + \frac{R}{T}$  after T rounds:

$$\text{Pf: } L_A^T \leq L_{\text{best}}^T + R \leq T v_- + R \Rightarrow \frac{L_A^T}{T} \leq v_- + \frac{R}{T}$$

there is some pure strategy  
that guarantees P2 a loss  
of at most  $v_-$  against any  $\vec{p}$   
at every round.

$\Rightarrow$  If both players use MWV to pick a strategy  
at every round, then their average strategies are  
a Nash eqm of the underlying minimax game

## Routing games



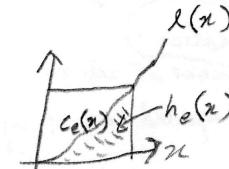
- atomic when edges must have integer flow

Equilibrium: switching to a different path never yields a better result.

Braess' Paradox: Adding an edge increases the social cost.

Price of Anarchy:  $\frac{\text{WorstNash}(G)}{\text{OPT}(G)}$

In non-atomic version, pure Nash eqm always exists!



Let  $c_e(x) := x \cdot l_e(x)$  (total social cost of congestion at e)  
Let  $c'_e(x) := \frac{d}{dx} c_e(x)$   
Lemma:  $\forall P, P' \in P_i, f_p^{*} > 0 \Rightarrow c'_p(f^*) \leq c'_p(f^{**})$

iff a flow is optimal. (i.e. marginal social cost is no more than any other path's)  
 $l_e^*(x) := c'_e(x) = l_e(x) + x \cdot l'_e(x); l_p^*(x) = \sum_{e \in P} l_e^*(x)$

Corollary: a flow is optimal for  $\langle G, r, l \rangle \Leftrightarrow$  it is a NE for  $\langle G, r, l^* \rangle$

Thm: If there exists  $\alpha > 1$  s.t.  $c_e(x) \leq \alpha h_e(x) \forall e \in E$ , then

$$h_e(x) := \int_x^\infty l_e(y) dy \quad \text{PoA} \leq \alpha$$

coalition value = 1 if sum of member weights  $\geq \frac{n}{2}$   
0 otherwise

## Cooperative games

Induced subgraph: value of a coalition is the sum of edge weights in the coalition.

Network flow: value of a coalition is the maxflow using those edges only.

Weighted voting games:  $(w_1, \dots, w_n; q)$   
↑ a cutoff  
each player (n players total)  
has a weight

Bankruptcy problem: split debt amongst creditors in some way.

$$N = \{1, 2, \dots, n\}$$

i.e. joining the big group is always better.

characteristic  $f^c: v: 2^N \rightarrow \mathbb{R}$  (value function) mapping from power set to  $\mathbb{R}$ )  
coalition structure (cs) = some partition of  $N$ ;  $\text{OPT}(G) = \max_{cs} \sum_{S \in cs} v(S)$

imputation:  $\forall S \subseteq N, \sum_{i \in S} x_i = v(S)$  super additive game:  $\forall S, T \subseteq N : v(S) + v(T) \leq v(S \cup T)$ .

simple game:  $v(S) \in \{0, 1\}$  pay each player convex game:  $S \subseteq T \subseteq N$  and  $i \in N \setminus T \Rightarrow v(S \cup \{i\}) - v(S) \leq v(T \cup \{i\}) - v(T)$

monotone:  $\forall S \subseteq T \subseteq N \Rightarrow v(S) \leq v(T)$  i.e. adding people to a group is not worse.

Core of a cooperative game:

An imputation  $\vec{x}$  is in the core if  $\sum_{i \in S} x_i = x(S) \geq v(S)$ ,  $\forall S \subseteq N$

(i.e. no subset of the coalition will want to break off.)

$$\Rightarrow v(S) \leq \sum_{i \in S} x_i \leq v(N) - v(N \setminus S)$$

amount that

$S$  can get on their own.

marginal utility  
of the coalition by  
adding  $S$  to them

some  $S$  elements in the coalition  
making a new coalition with those elements only. (5)

Proof that core is empty is NP-hard.

Simple game:  $\forall S \subseteq N, v(S) \in \{0, 1\}$

winning coalition: those with value 1

losing coalition: otherwise

veto player: a player that is a member of every winning coalition (can't win without them)

Thm: Let  $G = \langle N, v \rangle$  be a simple game, then  $(\text{Core}(G)) \neq \emptyset \Leftrightarrow G$  has veto players and  $v(N) = 1$ .

Lemma: Core of induced subgraph game is not empty  $\Leftrightarrow$  graph has no negative cut.

Shapley value:  $\frac{1}{n!} \sum_{\sigma \in \Pi(N)} m_i(\sigma)$

marginal contribution of  $i$  in  $\sigma$ .

Satisfier:

- Efficiency ( $\sum_{i \in N} \phi_i = v(N)$ ): all money are distributed

- Symmetry ( $\forall S \subseteq N \setminus \{i, j\}: v(S \cup \{i\}) = v(S \cup \{j\}) \Rightarrow \phi_i = \phi_j$ ): equal players are paid equally

- Dummy / Null player ( $\forall S \subseteq N \setminus \{i\}: v(S \cup \{i\}) = v(S) \Rightarrow \phi_i = 0$ ): those who don't contribute are not paid anything

- Additivity/Linearity ( $\phi_i(v_1) + \phi_i(v_2) = \phi_i(v_1 + v_2)$ ): combined game combines the payment

Thm: Shapley value is the

value  
function 1      value  
function 2

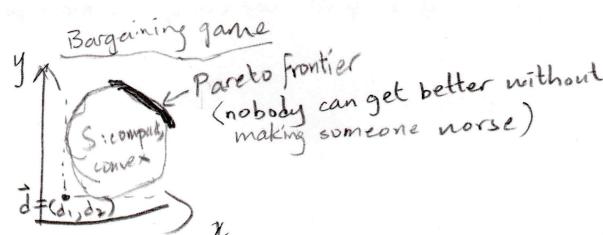
only division that  
satisfies all four properties

Nash bargaining solution

$$= \max_{(v_1, v_2) \in S} (v_1 - d_1)(v_2 - d_2)$$

$\vec{S}$  satisfies:

assuming  
they are  
in first  
quadrant  
of  $(v_1, v_2)$ .



- Efficiency: no outcome Pareto-dominates  $(f_1(S, \vec{d}), f_2(S, \vec{d}))$

- Symmetry: reflecting  $S$  and  $\vec{d}$  on  $y=x$  should reflect the chosen point

- Independence of Irrelevant Alternatives (IIA): Removing portions of  $S$  that do not contain the chosen point should not change the chosen point.

- Invariance under Equivalent Representations (IER): Translation and scaling on either axis should translate and scale the chosen point in the same way.

## Good markets

- Thick (lots of buyers & sellers, everyone is aware of their options)
- Timely (not too fast or too slow)
- Safe (people cannot be hurt by revealing preferences, fair outcomes, people are better off by participating)

## Unravelling

- Matching is done earlier & earlier (bad)

## Matching scenario

- Set of students  $S = \{s_1, \dots, s_n\}$
- Set of hospitals  $H = \{h_1, \dots, h_m\}$
- Each student ranks hospitals with a total ordering :  $\succ_s$
- Each hospital ranks students with a total ordering :  $\succ_h$

Outcome: A one-to-one matching  $M: S \rightarrow H$

Blocking pair of a matching  $M$ : A pair  $(s, h)$  where  $h \succ_s M(s)$  and  $s \succ_h M^{-1}(h)$  (i.e. both of them prefer each other to their assigned counterpart)

## Gale-Shapley Algorithm → polytime & returns a stable matching

- Start with all students unassigned
- While there are unassigned students:
  - Each unassigned student proposes to their favourite not-yet-proposed-to hospital
  - Each hospital looks at the list of students that proposed to it at this round and whoever is assigned to it already (if exists) picks the most preferred one. All others remain/become unassigned.

must always exist.

Matching with couples → stable matching might not exist (but in practice usually exists)

Stable if: No  $(s, h)$  prefers each other

No  $((c_1, c_2), (h_1, h_2))$  prefers each other.

Thm: Gale-Shapley assigns each student to their most preferred hospital in which some stable matching exists.  
 ⇒ It is better for students than hospitals  
 ⇒ Students cannot game the system, but hospitals can (to get a more preferred student)

## Allocation of Indivisible Goods

•  $\pi(i)$  : set of goods allocated to player  $i$  under  $\pi$

$$v_i(S) := \sum_{g \in S} v_{ig} \quad \text{value of good } g \text{ to player } i.$$

Assume that  
 $\forall i, j \in N, v_i(N) = v_j(N)$ .

### Desirable properties

• Optimality:  $\pi$  is optimal :=  $\pi \in \arg \max_{\pi'} \sum_i v_i(\pi'(i))$

• Pareto optimality: no allocation dominates  $\pi$ . (somebody will get strictly worse off in any other outcome)

• Envy-freeness: no player wants another's bundle :  $\forall i, j \in N, v_i(\pi(i)) \geq v_i(\pi(j))$

• Maximin share: if I get to partition the items, what is the maximum value (to me) of the worst bundle?

(it is independent of the goods given to other players). i.e.  $MMS_i := \max_{\pi} \min_{S \subseteq \pi} v_i(S)$

• Maximin share requirement: Each player gets at least their maximin share, i.e.  $\forall i \in N, v_i(\pi(i)) \geq MMS_i$ ,

### Approximate solutions:

• EF-1 : no player wants another's bundle with the best good removed :  $\forall i, j \in N, \exists g \in \pi(j) \text{ s.t. } v_i(\pi(i)) \geq v_j(\pi(j) \setminus \{g\})$

•  $\alpha$ -EF (for some  $0 < \alpha < 1$ ) :  $\forall i, j \in N, v_i(\pi(i)) \geq \alpha \cdot v_i(\pi(j))$

•  $\alpha$ -MMS (for some  $0 < \alpha < 1$ ) :  $\forall i \in N, v_i(\pi(i)) \geq \alpha \cdot MMS_i$

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## Theory for indivisible goods with additive valuations

- EF allocation does not always exist (consider a single good divided amongst two players)
  - EF-1 allocation always exists
  - MMS allocation does not always exist
  - $\frac{2}{3}$ -MMS allocation always exists
  - Deciding if an EF allocation exists is NP-complete (by reduction from PARTITION problem, where every item is valued the same by all players)

Algorithm for finding an EF-1 allocation in  $O(mn^3)$  time

- While there is an unallocated good  $g$ :  $\frac{\text{number of items}}{\text{number of players}}$ 
    - Give  $g$  to a player that nobody envies (which must always exist because the envy graph is a DAG)
    - Decycle the envy graph
  - End.

- For each cycle, swap the bundles amongst them.  
The cycle disappears, and other people that envy player  $j$  will now envy the player that  $j$ 's bundle was given to.  
So the number of edges decreases.  
Continue until there are no cycles left.

## Rent Division

$N := \{1, \dots, n\}$  players

$G_i := \{g_{i1}, \dots, g_{in}\}$  rooms

$v_{ij} :=$  player i's valuation of room j.  $\leftarrow$  total rent that needs to be paid

Assume that  $\forall i, j \in N$ ,  $\sum_k v_{ik} = \sum_k v_{jk} := R$

Output: a room allocation  $\sigma: N \rightarrow N$  and a rent division  $\vec{p}$  where  $\sum_i p_i = R$

EF outcome:  $\langle \sigma, \vec{p} \rangle$  s.t.  $V_{i\sigma(i)} - p_{\sigma(i)} \geq V_{ij} - p_j \quad \forall i, j \in N$ .  
 i.e. "I don't prefer your room for the price you ask."

### Thms for rent division:

- EF outcome always exists, and can be computed efficiently
  - In any EF outcome, room allocation (i.e.  $\sigma$ ) is optimal (1<sup>st</sup> welfare thm)
  - If outcome  $\langle \sigma, \vec{p} \rangle$  is EF, then so is  $\langle \sigma', \vec{p} \rangle$  for any optimal room allocation  $\sigma'$ . (2<sup>nd</sup> welfare thm)

## General algorithmic framework

- Compute a socially optimal allocation  
(max weighted matching) → Find an EF price vector → This price vector will work with any optimal allocation  
(linear programming) (2<sup>nd</sup> welfare thm)

## Ways to choose amongst EF outcomes

- **Equitability** : minimise the disparity between the highest and lowest utilities:  $\arg \min_{\vec{p} \in EF} \max_{i \in N} (u_i(\vec{p}) - u_j(\vec{p}))$
  - **Maximin** : maximise the minimum utility:  $\arg \max_{\vec{p} \in EF} \min_{i \in N} u_i(\vec{p})$

Thms:

- There is a unique maximum EF price vector, and this vector is also equitable (however, there might exist equitable price vectors that are not maximum)

## Single item auctions

- English auction: auctioneer sets a starting price, bidders take turns raising their bids, last bidder wins and pays his bid.
    - It is rational to bid iff  $p + \delta \leq v$ , and I should bid  $p + \delta$ . Winner will eventually pay second highest value or current price my valuation

• Japanese auction: auctioneer sets a starting price then keeps raising it until all but one bidder drops out, last bidder pays the current price.

- Dutch auction: auctioneer sets a high starting price and then starts lowering it until a bidder accepts the price.
  - Sealed-bid auction: all bidders simultaneously submit their bids, the higher bidder gets the item and pays
    - his bid (first-price auction), or
    - 2nd highest bid (second-price, or Vickrey, auction)
- (8)

Thm: In a Vickrey auction, truthful bidding is a dominant strategy (i.e. truthful bidding will never make a person worse off regardless of the actions of everyone else.)

Note: There are many NEs in a Vickrey auction.

e.g.  $\vec{v} = (50, 30, 70)$  (valuations)

possible NE:  $(50, 30, 70), (0, 0, 70), (70, 0, 0)$

↑  
third player  
wins and pays  
nothing      ↑  
first player  
wins and pays  
nothing.

### Multi-unit auctions (identical items)

- There are multiple, identical items
- Each bidder wants one item, and values it at  $v_i$
- How should the items be distributed, and how much should they pay?

### Multi-unit auctions (different items)

- There are multiple, different items.
- Each player wants one item, values item  $j$  at  $v_{ij}$ .
- How should the items be distributed, and how much should they pay?

### (General) Mechanism Design

- Players  $N = \{1, \dots, n\}$
- Outcomes  $O = \{0, \dots, o_m\}$
- Each player has a utility function  $u_i : O \rightarrow \mathbb{R}$
- Centre chooses an outcome to maximise some function (e.g.  $\sum_i u_i(o^*)$ )

Incentive Compatibility: If everyone else reports their true valuations, I should report truthfully too. (i.e. reporting true valuations is a NE)

Dominant Strategy: I should report truthfully regardless of everyone else. (i.e. reporting true valuations is a (weakly) dominant strategy.)

Revelation Principle: Given any mechanism  $M$ , there exists a mechanism  $M'$  whose inputs are users' valuations, and whose outputs are exactly like those of  $M$ . (i.e. there is always an incentive-compatible mechanism)

Problems: computational burden is pushed to the center  
the direct mechanism might have additional bad equilibria.

### Vickrey-Clarke-Groves Mechanisms

1. Choose an outcome that maximises  $\sum_i v_i(o^*)$  (i.e. socially optimal outcome)

2. To determine the payment that player  $j$  must make:

pretend  $j$  does not exist, and choose  $o_{-j}^*$  that maximises  $\sum_i v_i(o_{-j}^*)$   
 $j$  pays  $\sum_{i \neq j} v_i(o_{-j}^*) - \sum_{i \neq j} v_i(o^*)$  (i.e. the negative externality that player  $j$  imposes on others)

Thm: In a VCG mechanism, truthful reporting is a dominant strategy.

Proof:  $u_i(o^*) = v_i(o^*) - \left( \sum_{i \neq j} v_i(o^*) - \sum_{i \neq j} v_i(o_{-j}^*) \right)$

$$= \sum_i v_i(o^*) - \sum_{i \neq j} v_i(o_{-j}^*)$$

total social welfare  
(any other outcome  $o'$  must have lower total social welfare than  $o^*$  (which is socially optimal))

#### Assumptions:

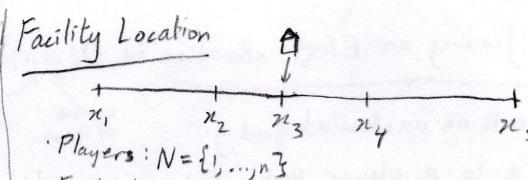
Choice set monotonicity:

$$O_{-i} \subseteq O$$

No negative externalities:

$$\forall o_{-i} \in O_{-i}, v_i(o_{-i}) \geq 0$$

Bidders must trust the auctioneer in a sealed-bid auction.



Measures:

- Total cost:  $\sum_i |f(\vec{x}) - x_i|$  (To minimise...)
- Max cost:  $\max_i |f(\vec{x}) - x_i|$

Thm: Choosing the median position has the minimum total cost. tiebreak towards larger player?

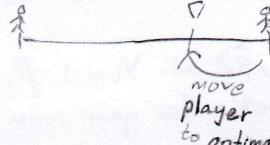
It is also strategyproof and group-strategyproof.

regardless of what others do, it is best to play truthfully

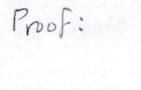
no subset of players can collude to make everybody in the subset strictly better off.

Thm: Any deterministic truthful mechanism has worst-case approximation of at least 2 to the maximum cost.

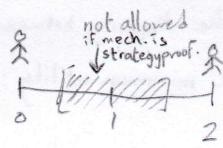
Proof by contradiction, with two players. i.e. we are using the max cost measure.



Then reason backwards: Any randomised truthful mechanism has worst-case expected approximation of at least  $\frac{3}{2}$  to the maximum cost.

Proof:  When let  $E[f] \leq \frac{1}{2}$ . Then the person at 1 has expected cost of  $\geq \frac{1}{2}$ .

Then if he lies and claims that he is at 2 instead, the mechanism has to pick a location either  $\leq \frac{1}{2}$  or  $\geq \frac{3}{2}$ .



Now, if instead we have one person at 0 and one person at 2 playing truthfully, due to the above reasoning, the mechanism has to pick a location either  $\leq \frac{1}{2}$  or  $\geq \frac{3}{2}$ , hence the maximum cost is  $\geq \frac{3}{2}$ .