

"Active set" redirects here. For the band, see [The Active Set](#).

In mathematical [optimization](#), a problem is defined using an objective function to minimize or maximize, and a set of constraints

$$g_1(x) \geq 0, \dots, g_k(x) \geq 0$$

that define the [feasible region](#), that is, the set of all x to search for the optimal solution. Given a point x in the feasible region, a constraint

$$g_i(x) \geq 0$$

is called **active** at x if $g_i(x) = 0$ and **inactive** at x if $g_i(x) > 0$. Equality constraints are always active. The **active set** at x is made up of those constraints $g_i(x)$ that are active at the current point ([Nocedal & Wright 2006](#), p. 308).

The active set is particularly important in optimization theory as it determines which constraints will influence the final result of optimization. For example, in solving the [linear programming](#) problem, the active set gives the [hyperplanes](#) that intersect at the solution point. In [quadratic programming](#), as the solution is not necessarily on one of the edges of the bounding polygon, an estimation of the active set gives us a subset of inequalities to watch while searching the solution, which reduces the complexity of the search.

Active set methods

In general an active set algorithm has the following structure:

Find a feasible starting point

repeat until "optimal enough"

solve the equality problem defined by the active set (approximately)

compute the [Lagrange multipliers](#) of the active set

remove a subset of the constraints with negative Lagrange multipliers

search for infeasible constraints

end repeat

Methods that can be described as **active set methods** include:^[1]

- [Successive linear programming](#) (SLP)
- [Sequential quadratic programming](#) (SQP)
- [Sequential linear-quadratic programming](#) (SLQP)
- [Reduced gradient method](#) (RG)
- [Generalized reduced gradient method](#) (GRG)

References

1. [Nocedal & Wright 2006](#), pp. 467–480

Bibliography

- Murty, K. G. (1988). *Linear complementarity, linear and nonlinear programming* . Sigma Series in Applied Mathematics. **3**. Berlin: Heldermann Verlag. pp. xviii+629 pp. [ISBN 3-88538-403-5](#). [MR 0949214](#) .
- Nocedal, Jorge; Wright, Stephen J. (2006). *Numerical Optimization* (2nd ed.). Berlin, New York: Springer-Verlag. [ISBN 978-0-387-30303-1](#)..

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