

Sequential quadratic programming (SQP) is an [iterative method](#) for [constrained nonlinear optimization](#). SQP methods are used on [mathematical](#) problems for which the [objective function](#) and the constraints are twice [continuously differentiable](#).

SQP methods solve a sequence of optimization subproblems, each of which optimizes a quadratic model of the objective subject to a linearization of the constraints. If the problem is unconstrained, then the method reduces to [Newton's method](#) for finding a point where the gradient of the objective vanishes. If the problem has only equality constraints, then the method is equivalent to applying [Newton's method](#) to the first-order optimality conditions, or [Karush–Kuhn–Tucker conditions](#), of the problem.

Algorithm basics

Consider a [nonlinear programming](#) problem of the form:

$$\begin{array}{ll} \min_x & f(x) \\ \text{s.t.} & b(x) \geq 0 \\ & c(x) = 0. \end{array}$$

The Lagrangian for this problem is^[1]

$$\mathcal{L}(x, \lambda, \sigma) = f(x) - \lambda^T b(x) - \sigma^T c(x),$$

where λ and σ are [Lagrange multipliers](#). At an iterate x_k , a basic sequential quadratic programming algorithm defines an appropriate search direction d_k as a solution to the [quadratic programming](#) subproblem

$$\begin{array}{ll} \min_d & f(x_k) + \nabla f(x_k)^T d + \frac{1}{2} d^T \nabla_{xx}^2 \mathcal{L}(x_k, \lambda_k, \sigma_k) d \\ \text{s.t.} & b(x_k) + \nabla b(x_k)^T d \geq 0 \\ & c(x_k) + \nabla c(x_k)^T d = 0. \end{array}$$

Note that the term $f(x_k)$ in the expression above may be left out for the minimization problem, since it is constant.

Alternative approaches

- [Sequential linear programming](#)
- [Sequential linear-quadratic programming](#)
- [Augmented Lagrangian method](#)

Implementations

SQP methods have been implemented such well known numerical environments as [MATLAB](#) and [GNU Octave](#). There also exist numerous software libraries, including open source

- [SciPy](#) (de facto standard for scientific Python) has `scipy.optimize.minimize(method='SLSQP')` solver
- [NLOpt](#) (C/C++ implementation, numerous interfaces including Python, R, MATLAB/Octave) and proprietary/commercial ones
- [LabVIEW](#)
- [KNITRO](#)^[2] (C, C++, C#, Java, Python, Fortran)
- [NPSOL](#) (Fortran)
- [SNOPT](#) (Fortran)
- [NLPQL](#) (Fortran)
- [SuanShu](#) (Java)

See also

- [Josephy-Newton algorithm](#)
- [Newton's method](#)
- [Secant method](#)

Notes

1. Jorge Nocedal and Stephen J. Wright (2006). *Numerical Optimization* . Springer. ISBN 0-387-30303-0.
2. [KNITRO User Guide: Algorithms](#)

References

- Bonnans, J. Frédéric; Gilbert, J. Charles; [Lemaréchal, Claude](#); Sagastizábal, Claudia A. (2006). *Numerical optimization: Theoretical and practical aspects* . Universitext (Second revised ed. of translation of 1997 French ed.). Berlin: Springer-Verlag. pp. xiv+490. doi:[10.1007/978-3-540-35447-5](#) . ISBN 3-540-35445-X. MR 2265882 .
- Jorge Nocedal and Stephen J. Wright (2006). *Numerical Optimization* . Springer. ISBN 0-387-30303-0.

External links

- [Sequential Quadratic Programming at NEOS guide](#)

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