NetworkVisualization-PyTorch

December 12, 2024

[]: #COMMENT IF NOT USING COLAB VM

```
# This mounts your Google Drive to the Colab VM.
     from google.colab import drive
     drive.mount('/content/drive')
     # TODO: Enter the foldername in your Drive where you have saved the unzipped
     # assignment folder, e.g. 'DeepLearning/assignments/assignment5/'
     FOLDERNAME = 'cs6353/assignments/assignment5/'
     assert FOLDERNAME is not None, "[!] Enter the foldername."
     # Now that we've mounted your Drive, this ensures that
     # the Python interpreter of the Colab VM can load
     # python files from within it.
     import sys
     sys.path.append('/content/drive/My Drive/{}'.format(FOLDERNAME))
     # This downloads the CIFAR-10 dataset to your Drive
     # if it doesn't already exist.
     %cd /content/drive/My\ Drive/$FOLDERNAME/cs6353/datasets/
     !bash get datasets.sh
     %cd /content/drive/My\ Drive/$FOLDERNAME
[4]: # #UNCOMMENT IF USING CADE
     # import os
     # ##### Request a GPU #####
     # ## This function locates an available gpu for usage. In addition, this_
     ⇔function reserves a specificed
     # ## memory space exclusively for your account. The memory reservation prevents
     ⇔the decrement in computational
     # ## speed when other users try to allocate memory on the same gpu in the
     ⇔shared systems, i.e., CADE machines.
     # ## Note: If you use your own system which has a GPU with less than 4GB of
     →memory, remember to change the
     # ## specified mimimum memory.
     # def define_gpu_to_use(minimum_memory_mb = 3500):
         thres_memory = 600 #
```

```
#
      qpu_to_use = None
#
      try:
#
          os.environ['CUDA_VISIBLE_DEVICES']
#
          print('GPU already assigned before: ' + str(os.
 ⇔environ['CUDA_VISIBLE_DEVICES']))
#
          return
#
      except:
#
          pass
#
      for i in range(16):
#
          free\_memory = !nvidia-smi --query-qpu=memory.free -i $i_{\sqcup}
    -format=csv, nounits, noheader
#
          if free memory[0] == 'No devices were found':
#
               break
#
          free memory = int(free memory[0])
#
          if free_memory>minimum_memory_mb-thres_memory:
#
               gpu\_to\_use = i
#
              break
#
      if qpu_to_use is None:
#
          print('Could not find any GPU available with the required free memory_
      ' + str(minimum_memory_mb) \
                 + 'MB. Please use a different system for this assignment.')
#
#
      else:
#
          os.environ['CUDA VISIBLE DEVICES'] = str(qpu to use)
          print('Chosen GPU: ' + str(qpu to use))
#
# ## Request a gpu and reserve the memory space
# define_qpu_to_use(4000)
```

1 Network Visualization (PyTorch)

In this notebook we will explore the use of *image gradients* for generating new images.

When training a model, we define a loss function which measures our current unhappiness with the model's performance; we then use backpropagation to compute the gradient of the loss with respect to the model parameters, and perform gradient descent on the model parameters to minimize the loss.

Here we will do something slightly different. We will start from a convolutional neural network model which has been pretrained to perform image classification on the ImageNet dataset. We will use this model to define a loss function which quantifies our current unhappiness with our image, then use backpropagation to compute the gradient of this loss with respect to the pixels of the image. We will then keep the model fixed, and perform gradient descent on the image to synthesize a new image which minimizes the loss.

In this notebook we will explore three techniques for image generation:

- 1. **Saliency Maps**: Saliency maps are a quick way to tell which part of the image influenced the classification decision made by the network.
- 2. **Fooling Images**: We can perturb an input image so that it appears the same to humans, but will be misclassified by the pretrained network.
- 3. Class Visualization: We can synthesize an image to maximize the classification score of a particular class; this can give us some sense of what the network is looking for when it classifies images of that class.

This notebook uses **PyTorch**;

```
[5]: import torch
import torchvision
import torchvision.transforms as T
import random
import numpy as np
from scipy.ndimage import gaussian_filter1d
import matplotlib.pyplot as plt
from cs6353.image_utils import SQUEEZENET_MEAN, SQUEEZENET_STD
from PIL import Image

//matplotlib inline
plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'
```

1.0.1 Helper Functions

Our pretrained model was trained on images that had been preprocessed by subtracting the percolor mean and dividing by the per-color standard deviation. We define a few helper functions for performing and undoing this preprocessing. You don't need to do anything in this cell.

```
[6]: def preprocess(img, size=224):
         transform = T.Compose([
             T.Resize(size),
             T.ToTensor(),
             T.Normalize(mean=SQUEEZENET_MEAN.tolist(),
                         std=SQUEEZENET_STD.tolist()),
             T.Lambda(lambda x: x[None]),
         ])
         return transform(img)
     def deprocess(img, should_rescale=True):
         transform = T.Compose([
             T.Lambda(lambda x: x[0]),
             T.Normalize(mean=[0, 0, 0], std=(1.0 / SQUEEZENET_STD).tolist()),
             T.Normalize(mean=(-SQUEEZENET MEAN).tolist(), std=[1, 1, 1]),
             T.Lambda(rescale) if should_rescale else T.Lambda(lambda x: x),
             T. ToPILImage(),
```

```
l)
return transform(img)

def rescale(x):
    low, high = x.min(), x.max()
    x_rescaled = (x - low) / (high - low)
    return x_rescaled

def blur_image(X, sigma=1):
    X_np = X.cpu().clone().numpy()
    X_np = gaussian_filter1d(X_np, sigma, axis=2)
    X_np = gaussian_filter1d(X_np, sigma, axis=3)
    X.copy_(torch.Tensor(X_np).type_as(X))
    return X
```

2 Pretrained Model

For all of our image generation experiments, we will start with a convolutional neural network which was pretrained to perform image classification on ImageNet. We can use any model here, but for the purposes of this assignment we will use SqueezeNet [1], which achieves accuracies comparable to AlexNet but with a significantly reduced parameter count and computational complexity.

Using SqueezeNet rather than AlexNet or VGG or ResNet means that we can easily perform all image generation experiments on CPU.

[1] Iandola et al, "SqueezeNet: AlexNet-level accuracy with 50x fewer parameters and < 0.5MB model size", arXiv 2016

```
[7]: # Download and load the pretrained SqueezeNet model.

model = torchvision.models.squeezenet1_1(pretrained=True)

# We don't want to train the model, so tell PyTorch not to compute gradients

# with respect to model parameters.

for param in model.parameters():
    param.requires_grad = False

# you may see warning regarding initialization deprecated, that's fine, please

→continue to next steps
```

/usr/local/lib/python3.10/dist-packages/torchvision/models/_utils.py:208: UserWarning: The parameter 'pretrained' is deprecated since 0.13 and may be removed in the future, please use 'weights' instead.

```
warnings.warn(
```

/usr/local/lib/python3.10/dist-packages/torchvision/models/_utils.py:223: UserWarning: Arguments other than a weight enum or `None` for 'weights' are deprecated since 0.13 and may be removed in the future. The current behavior is equivalent to passing `weights=SqueezeNet1_1_Weights.IMAGENET1K_V1`. You can also use `weights=SqueezeNet1_1_Weights.DEFAULT` to get the most up-to-date

```
weights.
  warnings.warn(msg)
Downloading: "https://download.pytorch.org/models/squeezenet1_1-b8a52dc0.pth" to
/root/.cache/torch/hub/checkpoints/squeezenet1_1-b8a52dc0.pth
100%| | 4.73M/4.73M [00:00<00:00, 26.3MB/s]</pre>
```

2.1 Load some ImageNet images

We have provided a few example images from the validation set of the ImageNet ILSVRC 2012 Classification dataset. To download these images, descend into cs6353/datasets/ and run get_imagenet_val.sh.

Since they come from the validation set, our pretrained model did not see these images during training.

Run the following cell to visualize some of these images, along with their ground-truth labels.

```
[8]: from cs6353.data_utils import load_imagenet_val
X, y, class_names = load_imagenet_val(num=5)

plt.figure(figsize=(12, 6))
for i in range(5):
    plt.subplot(1, 5, i + 1)
    plt.imshow(X[i])
    plt.title(class_names[y[i]])
    plt.axis('off')
plt.gcf().tight_layout()
```



3 Saliency Maps

Using this pretrained model, we will compute class saliency maps as described in Section 3.1 of [2].

A saliency map tells us the degree to which each pixel in the image affects the classification score for that image. To compute it, we compute the gradient of the unnormalized score corresponding to the correct class (which is a scalar) with respect to the pixels of the image. If the image has shape (3, H, W) then this gradient will also have shape (3, H, W); for each pixel in the image, this gradient tells us the amount by which the classification score will change if the pixel changes by a small amount. To compute the saliency map, we take the absolute value of this gradient, then

take the maximum value over the 3 input channels; the final saliency map thus has shape (H, W) and all entries are nonnegative.

[2] Karen Simonyan, Andrea Vedaldi, and Andrew Zisserman. "Deep Inside Convolutional Networks: Visualising Image Classification Models and Saliency Maps", ICLR Workshop 2014.

3.0.1 Hint: PyTorch gather method

Recall in Assignment 1 you needed to select one element from each row of a matrix; if s is an numpy array of shape (N, C) and y is a numpy array of shape (N,) containing integers 0 <= y[i] < C, then s[np.arange(N), y] is a numpy array of shape (N,) which selects one element from each element in s using the indices in y.

In PyTorch you can perform the same operation using the gather() method. If s is a PyTorch Tensor of shape (N, C) and y is a PyTorch Tensor of shape (N,) containing longs in the range 0 <= y[i] < C, then

```
s.gather(1, y.view(-1, 1)).squeeze()
```

will be a PyTorch Tensor of shape (N,) containing one entry from each row of s, selected according to the indices in y.

run the following cell to see an example.

You can also read the documentation for the gather method and the squeeze method.

```
[9]: # Example of using gather to select one entry from each row in PyTorch
    def gather_example():
        N, C = 4, 5
         s = torch.randn(N, C)
        y = torch.LongTensor([1, 2, 1, 3])
        print(s)
        print(y)
        print(s.gather(1, y.view(-1, 1)).squeeze())
    gather_example()
    tensor([[-0.4704, 0.4622, 0.4585, 0.7762, 0.0918],
            [-0.6684, -1.2903, 0.8677, -0.3519, -0.8512],
            [0.2262, -1.2637, 0.6996, 0.0696, 0.5859],
            [-0.7096, -0.1254, 1.3071,
                                        1.1746, 0.2500]])
    tensor([1, 2, 1, 3])
    tensor([ 0.4622, 0.8677, -1.2637, 1.1746])
```

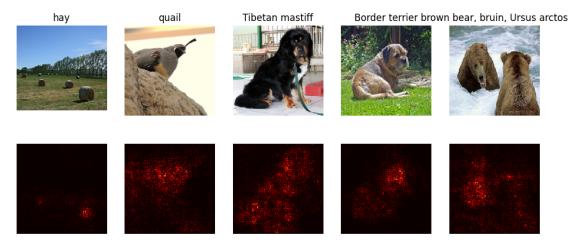
```
[13]: def compute_saliency_maps(X, y, model):
    """
    Compute a class saliency map using the model for images X and labels y.

Input:
    - X: Input images; Tensor of shape (N, 3, H, W)
    - y: Labels for X; LongTensor of shape (N,)
    - model: A pretrained CNN that will be used to compute the saliency map.
```

```
Returns:
  - saliency: A Tensor of shape (N, H, W) giving the saliency maps for the \Box
\hookrightarrow input
  images.
  11 11 11
  # Make sure the model is in "test" mode
  model.eval()
  # Make input tensor require gradient
  X.requires_grad_()
  saliency = None
# TODO: Implement this function. Perform a forward and backward pass<sub>\cup</sub>
→through #
  # the model to compute the gradient of the correct class score with respect
  # to each input image. You first want to compute the loss over the correct | |
  # scores (we'll combine losses across a batch by summing), and then compute_
  # the gradients with a backward pass.
                                                                   ш
# Forward pass: Compute scores for all classes
  scores = model(X)
  # Select the correct class scores
  correct_scores = scores.gather(1, y.view(-1, 1)).squeeze()
  # Backward pass: Compute gradients of correct class scores with respect to \Box
\hookrightarrow inputs
  correct_scores.sum().backward()
  # Compute saliency as the maximum absolute value of the gradients along the
⇔color channels
  saliency, _ = torch.max(X.grad.abs(), dim=1)
END OF YOUR CODE
  #
→ #
```

Once you have completed the implementation in the cell above, run the following to visualize some class saliency maps on our example images from the ImageNet validation set:

```
[14]: def show_saliency_maps(X, y):
          # Convert X and y from numpy arrays to Torch Tensors
          X_tensor = torch.cat([preprocess(Image.fromarray(x)) for x in X], dim=0)
          y_tensor = torch.LongTensor(y)
          # Compute saliency maps for images in X
          saliency = compute_saliency_maps(X_tensor, y_tensor, model)
          # Convert the saliency map from Torch Tensor to numpy array and show images
          # and saliency maps together.
          saliency = saliency.numpy()
          N = X.shape[0]
          for i in range(N):
              plt.subplot(2, N, i + 1)
              plt.imshow(X[i])
              plt.axis('off')
              plt.title(class_names[y[i]])
              plt.subplot(2, N, N + i + 1)
              plt.imshow(saliency[i], cmap=plt.cm.hot)
              plt.axis('off')
              plt.gcf().set_size_inches(12, 5)
          plt.show()
      show_saliency_maps(X, y)
```



4 INLINE QUESTION

A friend of yours suggests that in order to find an image that maximizes the correct score, we can perform gradient ascent on the input image, but instead of the gradient we can actually use the saliency map in each step to update the image. Is this assertion true? Why or why not?

Answer:

No, the assertion is not true. The saliency map only provides the absolute magnitude of the gradient, highlighting which pixels influence the output the most, but it lacks directional information. Gradient ascent, however, requires both magnitude and direction to correctly adjust the input image towards maximizing the target score. Using only the saliency map would result in incorrect or inefficient updates, as it doesn't guide the image adjustments in the correct direction.

5 Fooling Images

We can also use image gradients to generate "fooling images" as discussed in [3]. Given an image and a target class, we can perform gradient **ascent** over the image to maximize the target class, stopping when the network classifies the image as the target class. Implement the following function to generate fooling images.

[3] Szegedy et al, "Intriguing properties of neural networks", ICLR 2014

```
[15]: def make_fooling_image(X, target_y, model):
         Generate a fooling image that is close to X, but that the model classifies
         as target_y.
         Inputs:
         - X: Input image; Tensor of shape (1, 3, 224, 224)
         - target_y: An integer in the range [0, 1000)
         - model: A pretrained CNN
         - X_fooling: An image that is close to X, but that is classifed as target_y
         by the model.
         # Initialize our fooling image to the input image, and make it require_
       \hookrightarrow gradient
         X_fooling = X.clone()
         X_fooling = X_fooling.requires_grad_()
         learning_rate = 1
       # TODO: Generate a fooling image X fooling that the model will classify as \Box
         # the class target y. You should perform gradient ascent on the score of L
       \hookrightarrow the #
```

```
# target class, stopping when the model is fooled.
→ #
  # When computing an update step, first normalize the gradient:
      dX = learning_rate * g / ||g||_2
                                                                          ш
→ #
  # You should write a training loop.
→ #
  # HINT: For most examples, you should be able to generate a fooling image
  # in fewer than 100 iterations of gradient ascent.
  # You can print your progress over iterations to check your algorithm.
# Initialize our fooling image to the input image, and make it require
\hookrightarrow gradient
  X_fooling = X.clone()
  X_fooling = X_fooling.requires_grad_()
  learning_rate = 1
  max_iterations = 100
  for i in range(max_iterations):
      # Forward pass: Compute scores for the current fooling image
      scores = model(X_fooling)
      # Check if the model is fooled
      if scores.argmax(dim=1).item() == target_y:
          print(f"Model fooled after {i} iterations.")
          break
      # Compute the gradient of the score for the target class with respect_
⇔to the image
      target_score = scores[0, target_y]
      target_score.backward()
      # Normalize the gradient
      grad = X_fooling.grad
      dX = learning_rate * grad / grad.norm()
```

Run the following cell to generate a fooling image. You should ideally see at first glance no major difference between the original and fooling images, and the network should now make an incorrect prediction on the fooling one. However you should see a bit of random noise if you look at the 10x magnified difference between the original and fooling images. Feel free to change the idx variable to explore other images.

```
idx = 0
target_y = 6

X_tensor = torch.cat([preprocess(Image.fromarray(x)) for x in X], dim=0)
X_fooling = make_fooling_image(X_tensor[idx:idx+1], target_y, model)

scores = model(X_fooling)
assert target_y == scores.data.max(1)[1][0].item(), 'The model is not fooled!'
```

Model fooled after 9 iterations.

After generating a fooling image, run the following cell to visualize the original image, the fooling image, as well as the difference between them.

```
[17]: X_fooling_np = deprocess(X_fooling.clone())
X_fooling_np = np.asarray(X_fooling_np).astype(np.uint8)

plt.subplot(1, 4, 1)
plt.imshow(X[idx])
plt.title(class_names[y[idx]])
plt.axis('off')

plt.subplot(1, 4, 2)
plt.imshow(X_fooling_np)
plt.title(class_names[target_y])
plt.axis('off')
```

```
plt.subplot(1, 4, 3)
X_pre = preprocess(Image.fromarray(X[idx]))
diff = np.asarray(deprocess(X_fooling - X_pre, should_rescale=False))
plt.imshow(diff)
plt.title('Difference')
plt.axis('off')

plt.subplot(1, 4, 4)
diff = np.asarray(deprocess(10 * (X_fooling - X_pre), should_rescale=False))
plt.imshow(diff)
plt.title('Magnified difference (10x)')
plt.axis('off')

plt.gcf().set_size_inches(12, 5)
plt.show()
```



6 Class visualization

By starting with a random noise image and performing gradient ascent on a target class, we can generate an image that the network will recognize as the target class. This idea was first presented in [2]; [3] extended this idea by suggesting several regularization techniques that can improve the quality of the generated image.

Concretely, let I be an image and let y be a target class. Let $s_y(I)$ be the score that a convolutional network assigns to the image I for class y; note that these are raw unnormalized scores, not class probabilities. We wish to generate an image I^* that achieves a high score for the class y by solving the problem

$$I^* = \arg\max_I (s_y(I) - R(I))$$

where R is a (possibly implicit) regularizer (note the sign of R(I) in the argmax: we want to minimize this regularization term). We can solve this optimization problem using gradient ascent, computing gradients with respect to the generated image. We will use (explicit) L2 regularization of the form

$$R(I) = \lambda ||I||_2^2$$

and implicit regularization as suggested by [3] by periodically blurring the generated image. We can solve this problem using gradient ascent on the generated image.

In the cell below, complete the implementation of the create_class_visualization function.

- [2] Karen Simonyan, Andrea Vedaldi, and Andrew Zisserman. "Deep Inside Convolutional Networks: Visualising Image Classification Models and Saliency Maps", ICLR Workshop 2014.
- [3] Yosinski et al, "Understanding Neural Networks Through Deep Visualization", ICML 2015 Deep Learning Workshop

```
[18]: def jitter(X, ox, oy):
          11 11 11
          Helper function to randomly jitter an image.
          Inputs
          - X: PyTorch Tensor of shape (N, C, H, W)
          - ox, oy: Integers giving number of pixels to jitter along W and H axes
          Returns: A new PyTorch Tensor of shape (N, C, H, W)
          11 11 11
          if ox != 0:
              left = X[:, :, :, :-ox]
              right = X[:, :, -ox:]
              X = torch.cat([right, left], dim=3)
          if oy != 0:
              top = X[:, :, :-oy]
              bottom = X[:, :, -oy:]
              X = torch.cat([bottom, top], dim=2)
          return X
```

```
[19]: def create_class_visualization(target_y, model, dtype, **kwargs):
    """
    Generate an image to maximize the score of target_y under a pretrained_
    →model.

Inputs:
    - target_y: Integer in the range [0, 1000) giving the index of the class
    - model: A pretrained CNN that will be used to generate the image
    - dtype: Torch datatype to use for computations

Keyword arguments:
    - l2_reg: Strength of L2 regularization on the image
    - learning_rate: How big of a step to take
    - num_iterations: How many iterations to use
    - blur_every: How often to blur the image as an implicit regularizer
```

```
- max_jitter: How much to gjitter the image as an implicit regularizer
  - show_every: How often to show the intermediate result
  model.type(dtype)
  12_reg = kwargs.pop('12_reg', 1e-3)
  learning_rate = kwargs.pop('learning_rate', 25)
  num_iterations = kwargs.pop('num_iterations', 100)
  blur_every = kwargs.pop('blur_every', 10)
  max_jitter = kwargs.pop('max_jitter', 16)
  show_every = kwargs.pop('show_every', 25)
  # Randomly initialize the image as a PyTorch Tensor, and make it requires \Box
\hookrightarrow gradient.
  img = torch.randn(1, 3, 224, 224).mul_(1.0).type(dtype).requires_grad_()
  for t in range(num_iterations):
      # Randomly jitter the image a bit; this gives slightly nicer results
     ox, oy = random.randint(0, max_jitter), random.randint(0, max_jitter)
     img.data.copy_(jitter(img.data, ox, oy))
      # TODO: Use the model to compute the gradient of the score for the
      # class target_y with respect to the pixels of the image, and make a
      # gradient step on the image using the learning rate. Don't forget the #
      # L2 regularization term!
      # Be very careful about the signs of elements in your code.
      # Forward pass: Compute scores and the target class score
     scores = model(img)
     target_score = scores[0, target_y]
      # Compute the gradient of the target class score with respect to the
\hookrightarrow image
     target_score.backward()
      # Normalize the gradient and update the image
     grad = img.grad
      img.data += learning_rate * grad / (grad.norm() + 1e-8)
      # Add L2 regularization term
     img.data -= 12_reg * img.data
      # Zero out gradients for the next iteration
      img.grad.zero_()
```

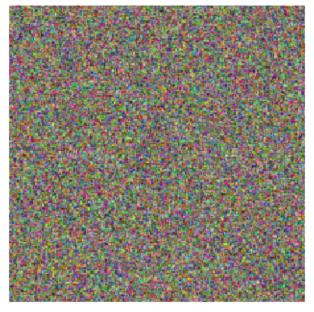
```
END OF YOUR CODE
      # Undo the random jitter
      img.data.copy_(jitter(img.data, -ox, -oy))
      # As regularizer, clamp and periodically blur the image
      for c in range(3):
         lo = float(-SQUEEZENET MEAN[c] / SQUEEZENET STD[c])
         hi = float((1.0 - SQUEEZENET_MEAN[c]) / SQUEEZENET_STD[c])
         img.data[:, c].clamp (min=lo, max=hi)
      if t % blur_every == 0:
         blur_image(img.data, sigma=0.5)
      # Periodically show the image
      if t == 0 or (t + 1) % show_every == 0 or t == num_iterations - 1:
         plt.imshow(deprocess(img.data.clone().cpu()))
         class_name = class_names[target_y]
         plt.title('%s\nIteration %d / %d' % (class_name, t + 1,__
→num_iterations))
         plt.gcf().set_size_inches(4, 4)
         plt.axis('off')
         plt.show()
  return deprocess(img.data.cpu())
```

Once you have completed the implementation in the cell above, run the following cell to generate an image of a Tarantula:

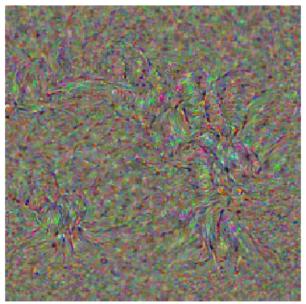
```
[20]: dtype = torch.FloatTensor
  # dtype = torch.cuda.FloatTensor # Uncomment this to use GPU
model.type(dtype)

target_y = 76 # Tarantula
  # target_y = 78 # Tick
  # target_y = 187 # Yorkshire Terrier
  # target_y = 683 # Oboe
  # target_y = 366 # Gorilla
  # target_y = 604 # Hourglass
out = create_class_visualization(target_y, model, dtype)
```

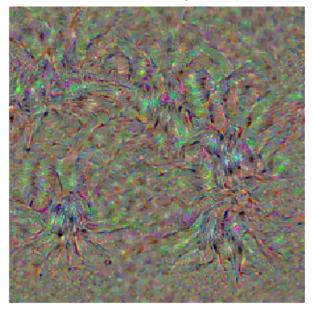
tarantula Iteration 1 / 100



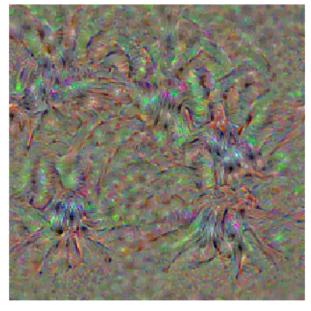
tarantula Iteration 25 / 100



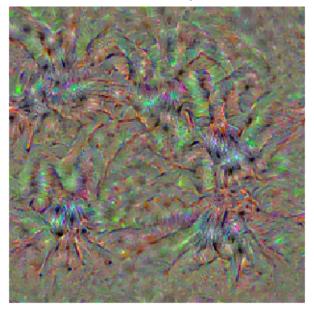
tarantula Iteration 50 / 100



tarantula Iteration 75 / 100



tarantula Iteration 100 / 100

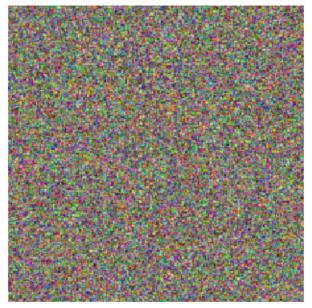


Try out your class visualization on other classes! You should also feel free to play with various hyperparameters to try and improve the quality of the generated image, but this is not required.

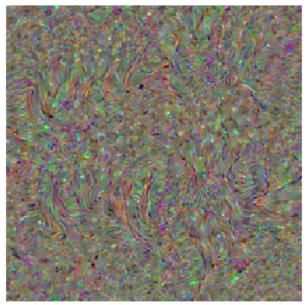
```
[21]: # target_y = 78 # Tick
    target_y = 187 # Yorkshire Terrier
# target_y = 683 # Oboe
# target_y = 366 # Gorilla
# target_y = 604 # Hourglass
    target_y = np.random.randint(1000)
    print(class_names[target_y])
X = create_class_visualization(target_y, model, dtype)
```

sea anemone, anemone

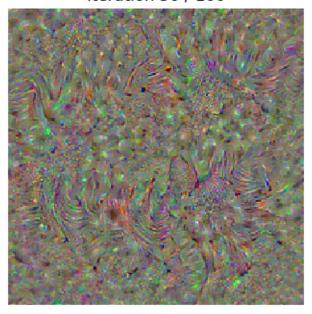
sea anemone, anemone Iteration 1 / 100



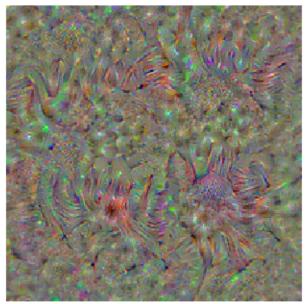
sea anemone, anemone Iteration 25 / 100



sea anemone, anemone Iteration 50 / 100



sea anemone, anemone Iteration 75 / 100



sea anemone, anemone Iteration 100 / 100

