

# EL 6483 Real-time Embedded system

HW 2 Due 4<sup>th</sup> Mar. 2016

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1.

1. GPIOD\_MODER: 0x 40020C00 ~ 0x 40020C20

2. The address computed from stm32f4xx.h

```
#define GPIOD_BASE (AHB1PERIPH_BASE + 0x0C00)
```

```
#define AHB1PERIPH_BASE (PERIPH_BASE + 0x00020000)
```

```
#define PERIPH_BASE ((uint32_t)0x40000000)
```

GPIOD\_ address should start at PERIPH\_BASE + 0X0020000 + 0x0C00 which is 0x40020C00

They are same as I expected in the first question.

```
/*
```

```
3. Modified in main.c following in the function init_LED_pins()
```

```
4. As two new function added, using on and BSRRL and BSRRH to set/reset GPIOD  
using -> and |=
```

```
Also now you know LED is controlled under GPIOD
```

```
*/
```

---

2. /\* Now you know the button press output to GPIOA \*/

---

3.

1. yes. While pressing the button I got an increment of one.

```
(gdb) x 0x40020010
```

```
0x40020010: 0x0000c040
```

```
(gdb) x 0x40020010
```

```
0x40020010: 0x0000c041
```

2.

3. disassemble

```
74 {
```

```
0x08000544 <+0>: push{r7} // store r7
```

```
0x08000546 <+2>: sub sp, #20 // stack pointer sub by 20
```

```
0x08000548 <+4>: add r7, sp, #0 // r7 change to sp
```

```
0x0800054a <+6>: str r0, [r7, #4] // store R0 in the address R7+4, in  
//this case R0 is the parameter i pass into the  
//function
```

```
75 int a = i + 12;
```

```
0x0800054c <+8>: ldr r3, [r7, #4] // load R0 to R3 (i)
```

```
0x0800054e <+10>: adds r3, #12 // R3 = R3 + 12 (a) and update flag
```

```
0x08000550 <+12>: str r3, [r7, #12] // store R3 after the R0's position
```

```
// till now, [r7, #4] is i and [r7, # 12] is a
```

```
76 GPIOD->BSRRL |= (1 << a);
```

```
0x08000552 <+14>: ldr r2, [pc, #40] ; (0x800057c <LED_0n+56>)
```

```
// load from address program counter + 40 to R2
```

```
0x08000554 <+16>: ldr r3, [pc, #36] ; (0x800057c <LED_0n+56>)
```

```
// load from address program counter + 36 to R3
```

```
0x08000556 <+18>: ldrhr3, [r3, #24]
```

```
// load from address R3 +24 higher 16bits to R3
```

```

    0x08000558 <+20>:uxthr3, r3
// expand 16bit R3 into full 32 bit unsigned
    0x0800055a <+22>:uxthr0, r3
// expand 16bit R3 into R0
    0x0800055c <+24>:movsr1, #1
// move 1 to R1 and update condition flag
    0x0800055e <+26>:ldr r3, [r7, #12]
// load from address R7 +12 to R3, which is a
    0x08000560 <+28>:lsl.w   r3, r1, r3
// left shift R1 by R3 bit and store the result into R3
    0x08000564 <+32>:uxthr3, r3
// expand R3
    0x08000566 <+34>:mov   r1, r0
// move R0 to R1

```

---

## Appendix: Code:

### *Assembly for LED\_On, LED\_Off, read\_button, max*

```

.section .text
.syntax unified
.global LED_Off, LED_On, read_button, max
.weak LED_On, LED_Off, read_button, max

```

LED\_On:

```

    PUSH {LR}
    LDR R1, = #0x40020c18
    LDR R2, [R1]
    MOV R3, R0
    ADD R4, R3, #12
    MOV R3, #1
    LSL R5, R3, R4
    ORR R4, R5, R2
    STR R4, [R1]
    POP {LR}
    BX LR

```

LED\_Off:

```

    PUSH {LR}
    LDR R1, = #0x40020c18
    LDR R2, [R1]
    MOV R3, R0
    ADD R4, R3, #28
    MOV R3, #1
    LSL R5, R3, R4
    ORR R4, R5, R2
    STR R4, [R1]
    POP {LR}
    BX LR

```

read\_button:

```

    PUSH {LR}
    LDR R1, = #0x40020010

```

```

LDR R2, [R1]
AND R3, R2, #1
MOV R0, R3
POP {LR}
BX LR

```

max:

```

PUSH {LR}
SUB R1, #1
LDR R3, [R0]
MOV R2, #0
MOV R5, R2
MOV R6, R0

```

MAX:

```

ADD R5, #1
ADD R6, #4
LDR R4, [R6]
CMP R4, R3
BGT UPDATE
CMP R5, R1

```

BEQ END

BNE MAX

UPDATE:

```

MOV R3, R4
MOV R2, R5
B MAX

```

END:

```

MOV R0, R3
MOV R1, R2
POP {LR}
BX LR

```

---

### *C Code:*

```

void init_LED_pins()
{

```

```

    RCC->AHB1ENR |= RCC_AHB1ENR_GPIODEN; // enable clock to GPIOD

```

```

    GPIOD->MODER &= ~(0x3 << (2*12)); // clear the 2 bits corresponding to pin 12

```

```

    GPIOD->MODER |= (1 << (2*12)); // set pin 12 to be general purpose output

```

// to enable the other pins (13,14,15), you will need to write to the appropriate bits of the ~MODER~ register.

```

    GPIOD->MODER &= ~(0x3 << (2*13)); // clear the 2 bits corresponding to pin 13

```

```

    GPIOD->MODER |= (1 << (2*13)); // set pin 12 to be general purpose output

```

```

    GPIOD->MODER &= ~(0x3 << (2*14)); // clear the 2 bits corresponding to pin 14

```

```

GPIO->MODER |= (1 << (2*14)); // set pin 12 to be general purpose output

GPIO->MODER &= ~(0x3 << (2*15)); // clear the 2 bits corresponding to pin 15
GPIO->MODER |= (1 << (2*15)); // set pin 12 to be general purpose output
}

void init_button()
{
    RCC->AHB1ENR |= RCC_AHB1ENR_GPIOAEN; // enable clock to GPIOA

    GPIOA->MODER &= ~(0x3 << (2*0)); // clear the 2 bits corresponding to pin 0
    // if the 2 bits corresponding to pin 0 are 00, then it is in input mode
}

uint32_t read_button(void)
{
    uint32_t key;

    if (GPIOA->IDR & 0x01)
        key = 1;
    else
        key = 0;

    return(key);
}

void LED_On(uint32_t i)
{
    int a = i + 12;
    GPIO->BSRRL |= (1 << a);
}

void LED_Off(uint32_t i)
{
    int a = i + 12;
    GPIO->BSRRH |= (1 << a);
}

int main(void)
{
    // initialize
    SystemInit();
    init_systick();
    init_LED_pins();
    init_button();
    int i;

    int arr[6] = {1,2,4,8,8,3};
    uint32_t n = 6;
    uint32_t index;

```

```
int y = max(arr, n, &index);
```

```
/*  
    LED_On(i);  
    LED_Off(i);  
*/  
while (1)  
{  
}  
}
```