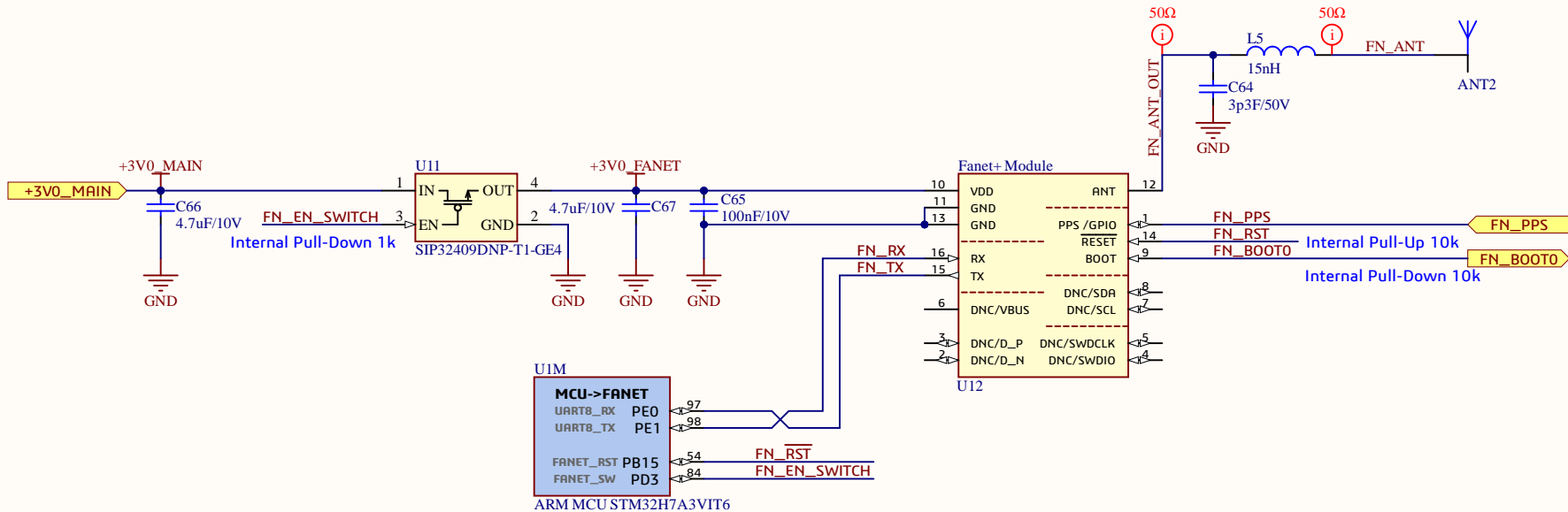


Table 8. Typical Current Consumption <sup>(1)</sup>				
INPUT VOLTAGE V <sub>PVDD</sub> (V)	MODE	PWM FREQUENCY f <sub>PWM</sub> (kHz)	I <sub>PVDD</sub> +I <sub>AVDD</sub> (mA)	INPUT CURRENT I <sub>AVDD</sub> (mA)
7.2	Idle and Mute	384	14.5	4.1
	Sleep	—	9.0	1.32
	Shutdown	—	0.039	0.077
12	Idle and Mute	384	17.4	4.1
	Sleep	—	9.0	1.32
	Shutdown	—	0.045	0.077
15	Idle and Mute	384	19.4	4.1
	Sleep	—	9.1	1.32
	Shutdown	—	0.049	0.077
19	Idle and Mute	384	22.4	4.1
	Sleep	—	9.3	1.32
	Shutdown	—	0.054	0.077
24	Idle and Mute	384	26.2	4.1
	Sleep	—	9.4	1.32
	Shutdown	—	0.061	0.077

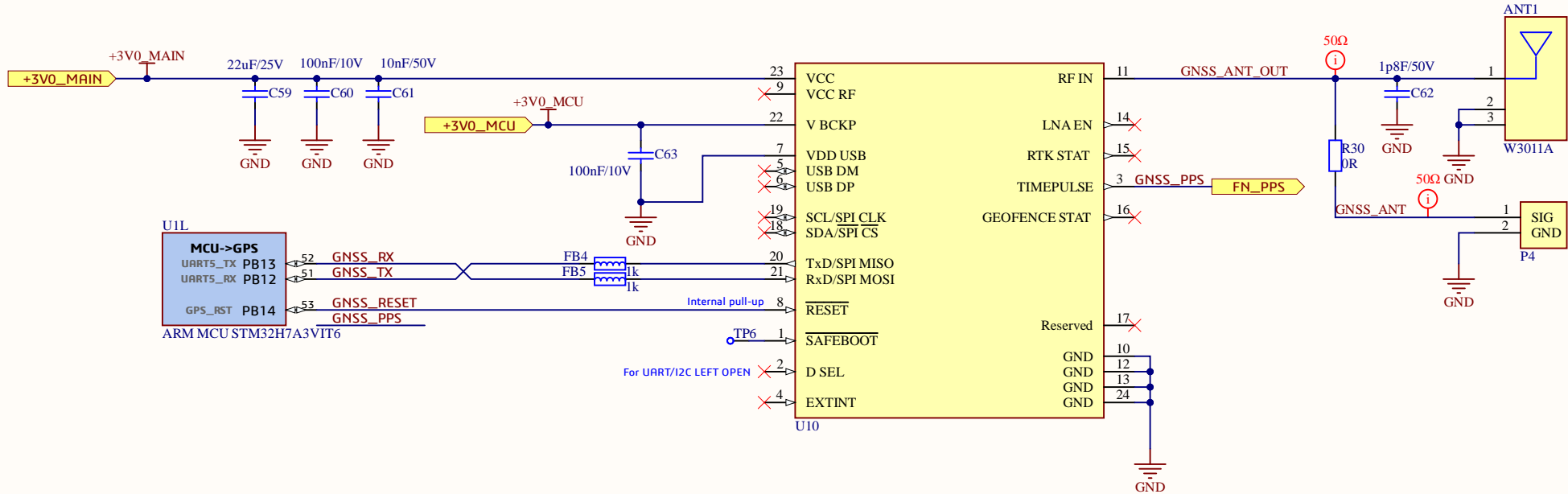
(1) T<sub>A</sub> = 25°C, PVDD pin tied to AVDD pin, V<sub>DVDD</sub> = 3.3 V, R<sub>LOAD</sub> = 4Ω, f<sub>IN</sub> = Idle, f<sub>S</sub> = 48 kHz, Gain = 20.7 dBV

**Checked**



Title		
Size A4	Number	Revision
Date: File:	4. 13. 2021 J:\Altium projekt\robota\...\Fanet.SchDoc	Sheet of Drawn By:

Checked



Title		
Size	Number	Revision
A4		
Date:	4.13.2021	Sheet of
File:	J:\Altium projekty_robota\...\GNSS.SchDoc	Drawn By:

Checked

A

B

C

D

IC- tento co je na display bck TPS61165 alebo tento TPS61169

IC od najlacnejšieho boost

<https://www.ti.com/power-management/led-drivers/products.html?pq=pcos&familyid=480#p1129=Boost;Boost%20Controller&p1299=1;1&sor=1130;asc>

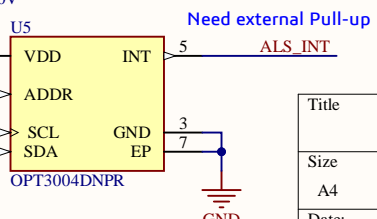
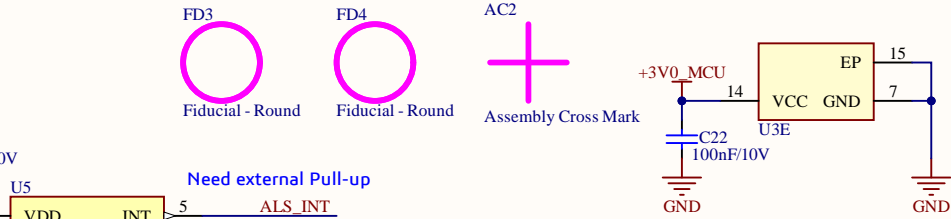
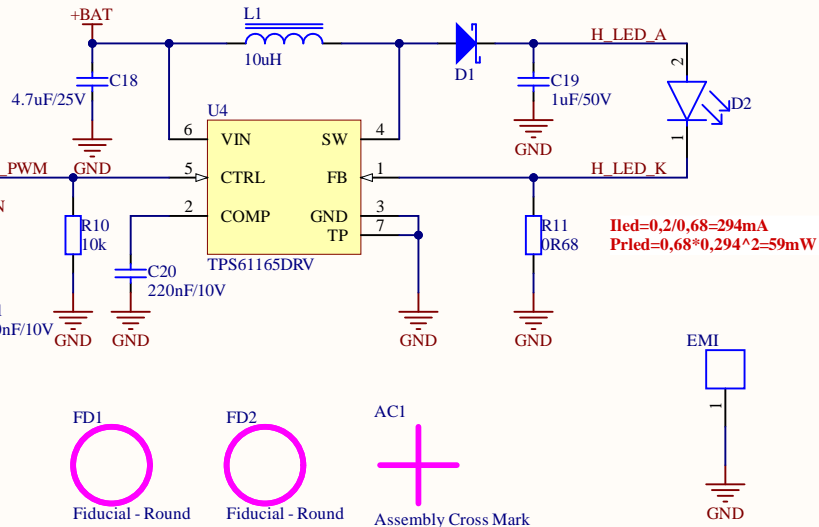
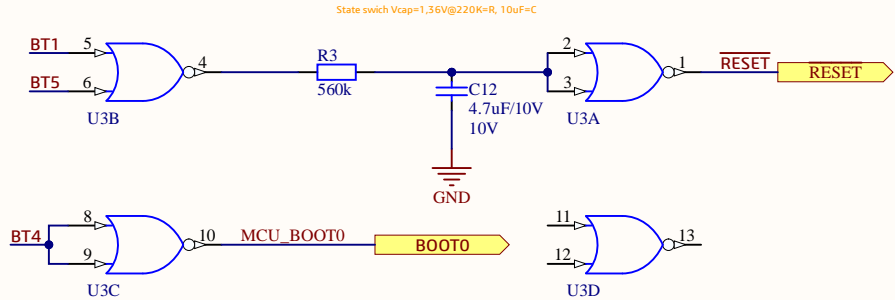
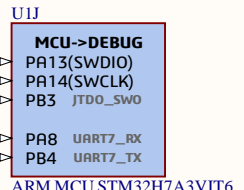
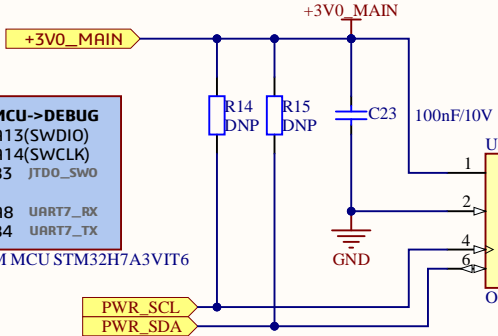
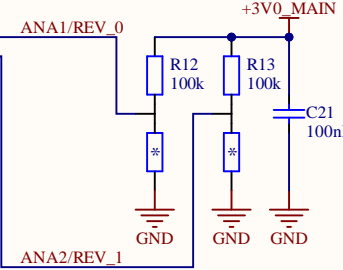
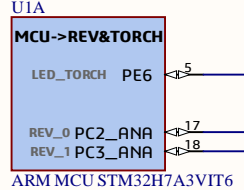
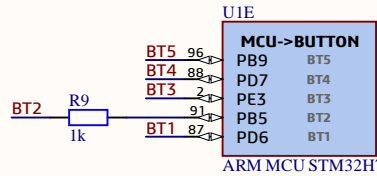
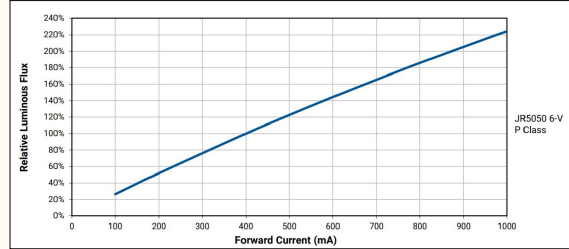
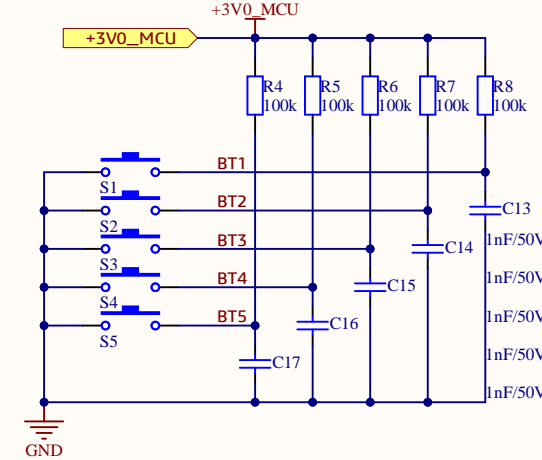
LEDs: na výber z viacerých stupňov teplôt

[https://www.mouser.sk/Optoelectronics/LED-Lighting/LED-Emitters/High-Power-LEDs-White/\\_/N-8usfjZ1yzvvqx?P=1z0rxi7Z1z0yr4hZ1yxucpoZ1z0z7ptZ1z0wtwpZ1y7gjcjZ1z0wuhfZ1z0wt8jZ1z0wuf8Z1yhzp&Ns=Pricing%7c0](https://www.mouser.sk/Optoelectronics/LED-Lighting/LED-Emitters/High-Power-LEDs-White/_/N-8usfjZ1yzvvqx?P=1z0rxi7Z1z0yr4hZ1yxucpoZ1z0z7ptZ1z0wtwpZ1y7gjcjZ1z0wuhfZ1z0wt8jZ1z0wuf8Z1yhzp&Ns=Pricing%7c0)

Skus nahradiť cievkou touto aj pre BCK aj pre Torch:

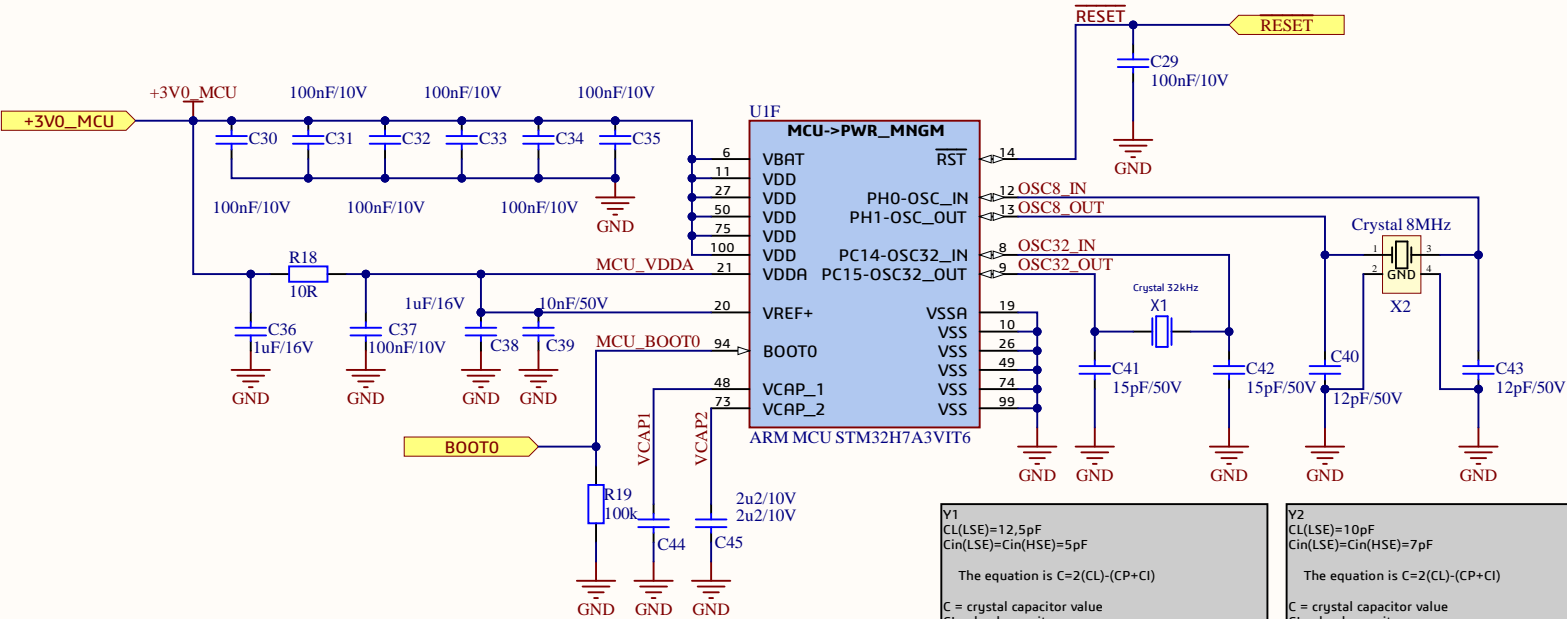
<https://www.mouser.sk/ProductDetail/Murata-Electronics/DFE322512F-100M%3dP2?q=AAQIKX63v8RsOU770VFHkQ%3D%3D>

<https://www.mouser.sk/ProductDetail/TDK/TFM322512ALMA100MTAA?q=BJlw7L4Cy7%252BbfpLKVm%252BmtA%3D%3D>



Title		
Size	Number	Revision
A4		
Date:	4.13.2021	Sheet of
File:	J:\Altium projekty_robota\Main_schema	Doc

Checked

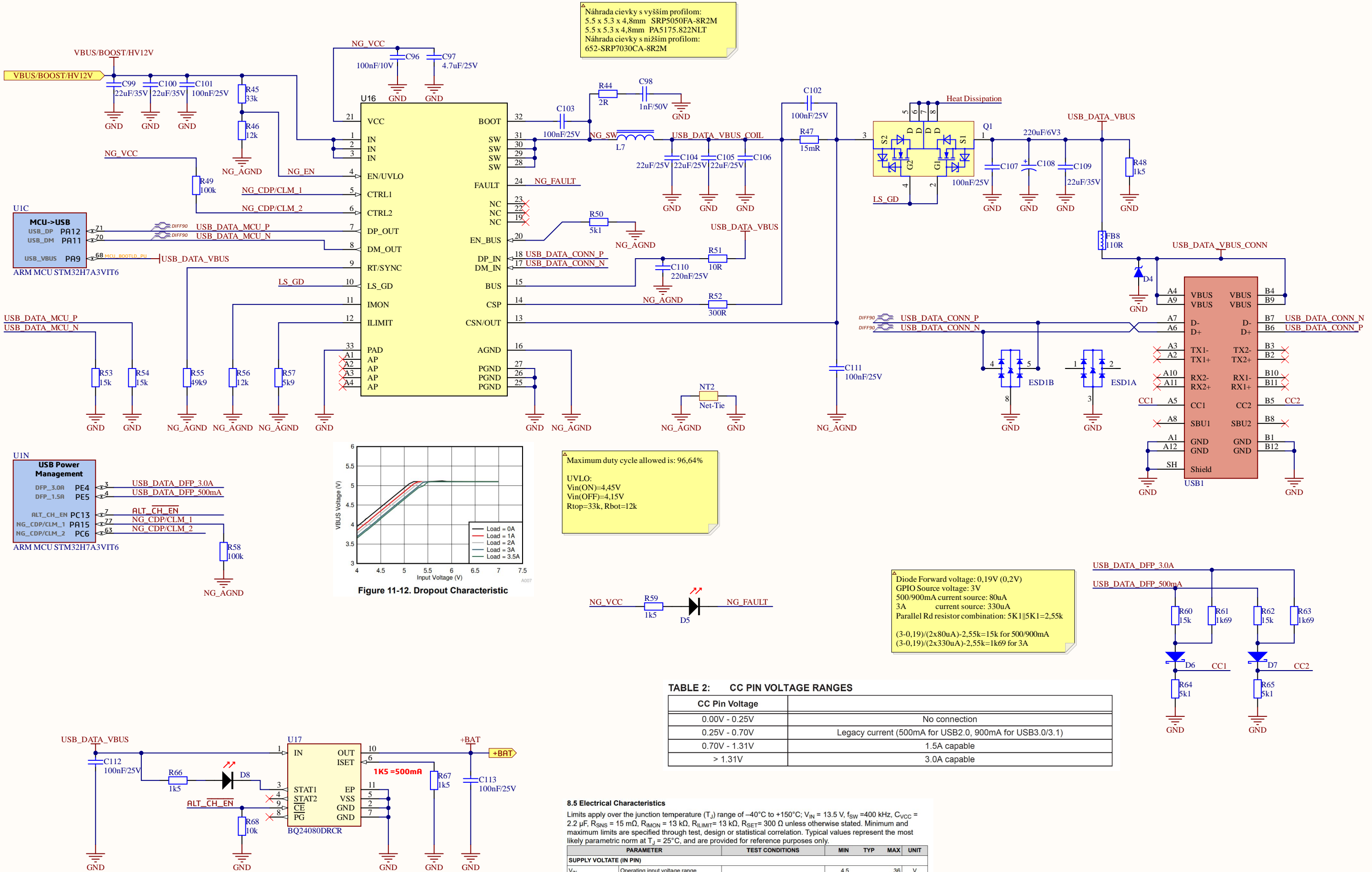


Y1  
CL(LSE)=12,5pF  
Cin(LSE)=Cin(HSE)=5pF  
The equation is  $C=2(CL)-(CP+CI)$   
C = crystal capacitor value  
CL = load capacitance  
CP = parasitic capacitance (wires, socket, traces)  
CI = input capacitance (mcu itself)  
LSE  $C=2*12,5-(3pF+5pF)=17pF \rightarrow 18pF/15pF$

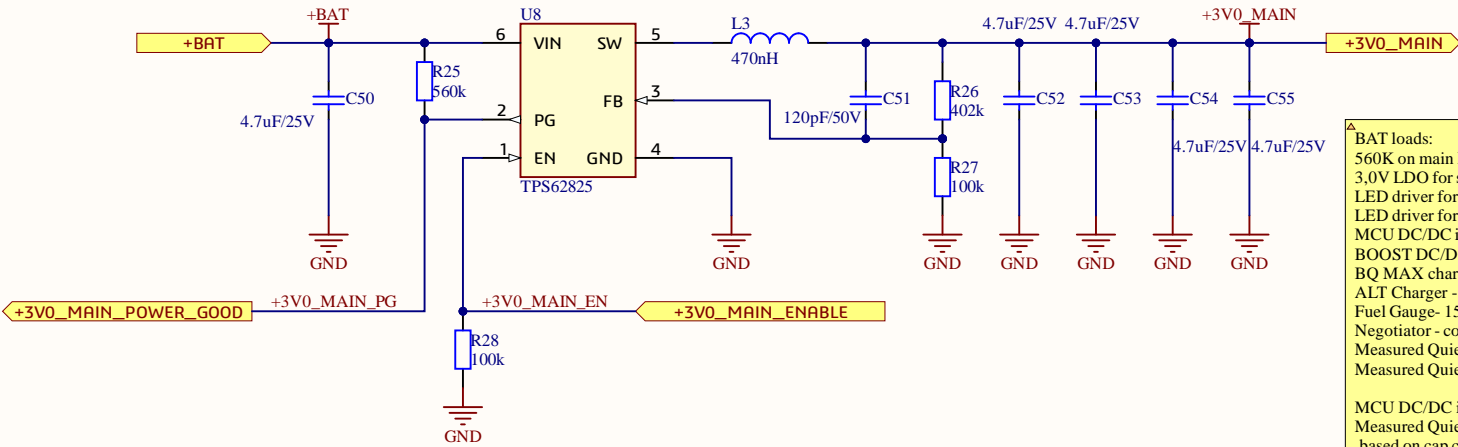
Y2  
CL(LSE)=10pF  
Cin(LSE)=Cin(HSE)=7pF  
The equation is  $C=2(CL)-(CP+CI)$   
C = crystal capacitor value  
CL = load capacitance  
CP = parasitic capacitance (wires, socket, traces)  
CI = input capacitance (mcu itself)  
LSE  $C=2*10pF-(3pF+5pF)=17pF \rightarrow 12pF/12pF$

Title		
Size	Number	Revision
A4		
Date:	4.13.2021	Sheet of
File:	J:\Altium projekt_robota\...\MCU_PWR_Sch.Dwg	Drawn By:

Checked

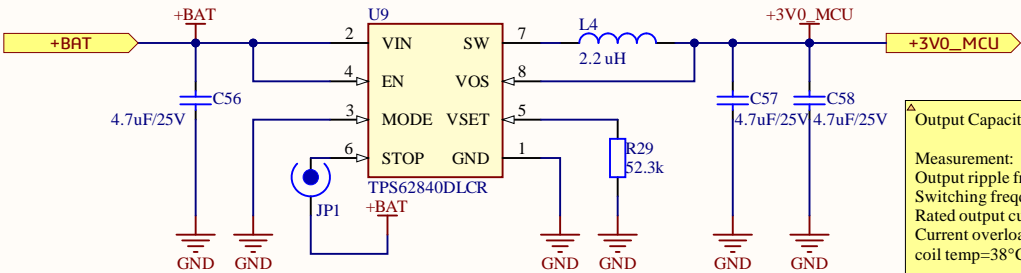






Output Capacitance Min: 22uF  
Measurement:  
Output ripple from 8,2mV to 14mV  
Switching frequency: from 1,3MHz to 602kHz  
Rated output current 2A  
Current overload up to 2,5A @66kHz, ACripple=50mV, coil temp=29°C, IC temp=31°C

BAT loads:  
560K on main DC/DC for PG output (7,1uA)  
3,0V LDO for sensors OFF, disabled (1uA)  
LED driver for Display Disabled (1uA)  
LED driver for Torch Disabled (1uA)  
MCU DC/DC in stop mode (100uA-120uA)  
BOOST DC/DC for AMP Disabled (1-3uA)  
BQ MAX charger - (BATFET EN - 32-60uA) BATFET DIS 12-23uA !!!  
ALT Charger - DIS state 2-5uA  
Fuel Gauge- 15-30uA  
Negotiator - connected trough BQ Max CH - 700-990uA  
Measured Quiescent current without NG- 270uA  
Measured Quiescent current with NG - 1145uA  
  
MCU DC/DC in RUN mode - without GNSS V\_BCKP  
Measured Quiescent current without NG- 680uA to peak 1366uA f= 1Hz  
based on cap charging  
Average current =830uA  
  
MCU DC/DC in RUN mode - GNSS V\_BCKP from 3V0\_MCU  
Measured Quiescent current without NG- 693uA to peak 1347uA f= 1Hz  
Average current =838uA  
GNSS V\_BCKP current consumption from DS =15uA

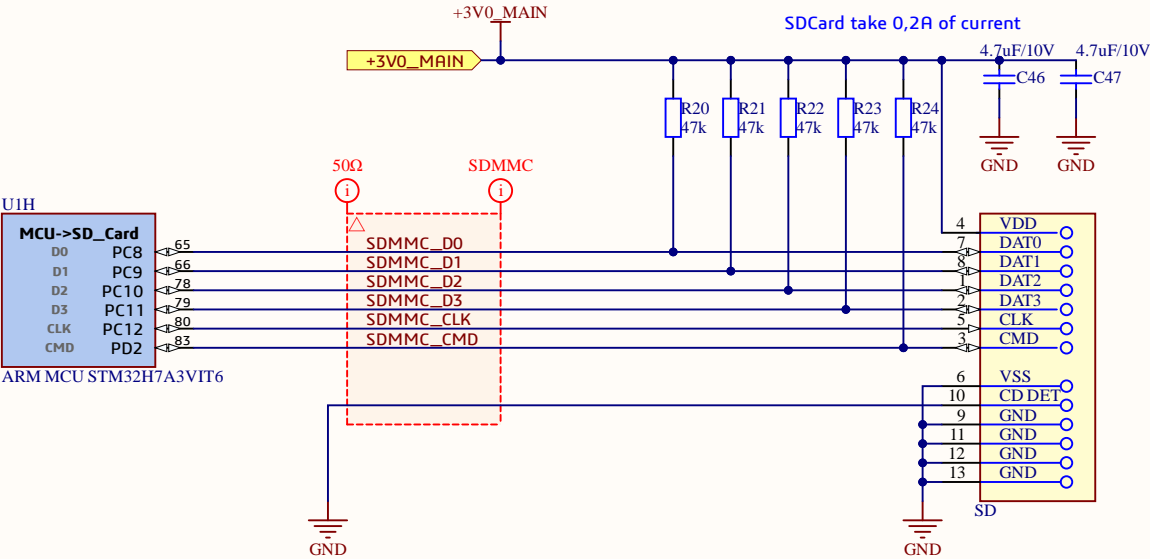


Output Capacitance Min: 10uF  
Measurement:  
Output ripple from 4,08mV to 10,8mV  
Switching frequency: from 1,71MHz to 855kHz  
Rated output current 750mA  
Current overload up to 1A @205kHz, ACripple=24mV, coil temp=38°C, IC temp=43°C

MODE - Direct to GND  
-automatic PWM and power-save mode operation  
STOP - Solder JP1  
-temporarily stop the switching of the regulator.

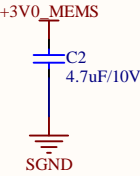
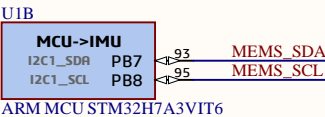
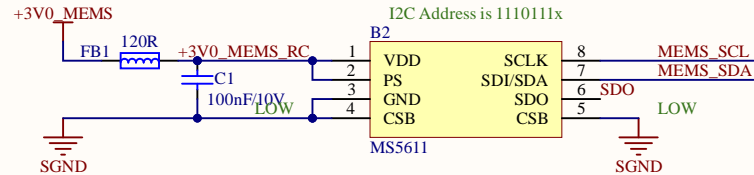


Checked



Title		
Size	Number	Revision
A4		
Date:	4.13.2021	Sheet of
File:	J:\Altium projkety_robota\...\SD_Card.SchDoc	Drawn By:

Checked



Cable  
WR-FFC Flat Flexible Cable FFC / FPC Jumper  
Cables WR-FFC 0.5mm Type 1 06P 100mm length  
687606100002

Connector  
1. FFC & FPC Connectors WR-FPC SMT Horiz  
0.50mm Dual.Cont. 687106182122  
2. FFC & FPC Connectors WR-FPC 0.5mm SMT ZIF  
6Pin Hrztl Top Cont 68710614022

Alternativa od Molex:  
Conn:5034800640  
Flex:150200053

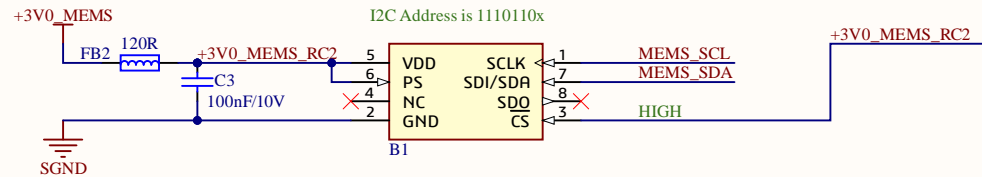


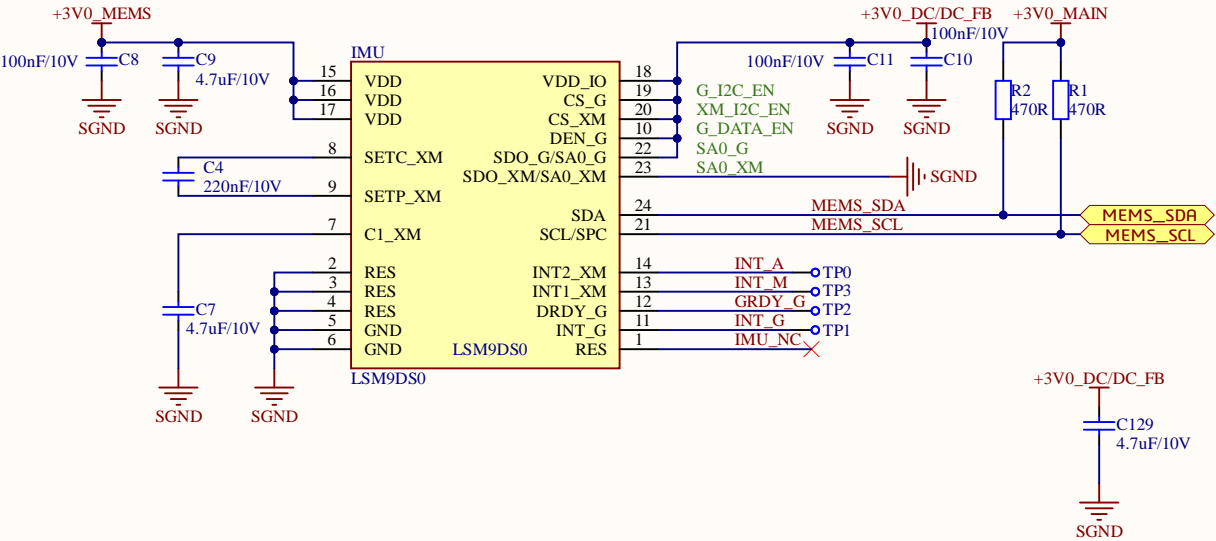
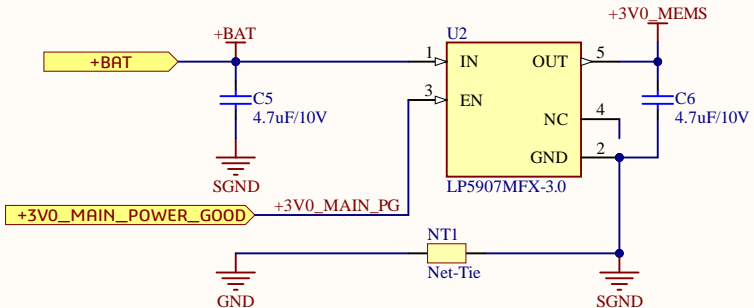
Table 15. Linear acceleration and magnetic sensor SAD+read/write patterns

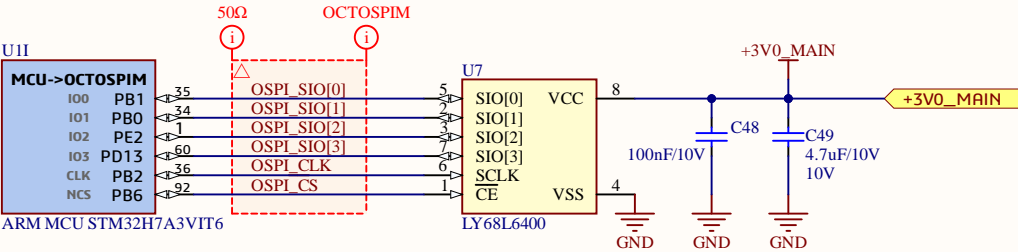
Command	SDO_XM/SA0_XM pin	SAD[6:2]	SAD[1:0]	R/W	SAD+R/W
Read	0	00111	10	1	00111101 (3D)
Write	0	00111	10	0	00111100 (3C)
Read	1	00111	01	1	00111011 (3B)
Write	1	00111	01	0	00111010 (3A)

Angular rate sensor address:

Table 16. Angular rate SAD+read/write patterns

Command	SAD[6:1]	SAD[0] = SDO_G/SA0_G pin	R/W	SAD+R/W
Read	110101	0	1	11010101 (D5h)
Write	110101	0	0	11010100 (D4h)
Read	110101	1	1	11010111 (D7h)
Write	110101	1	0	11010110 (D6h)





Lyontek Inc. LY68L6400SLIT v púzdre sop8 150mil \_ WSON nekupis...  
[https://lcsc.com/product-detail/RAM\\_Lyontek-Inc-LY68L6400SLIT\\_C261881.html](https://lcsc.com/product-detail/RAM_Lyontek-Inc-LY68L6400SLIT_C261881.html)

Alternativa  
Vilsion Tech VTI7064MSME  
[https://lcsc.com/product-detail/RAM\\_VTI7064MSME\\_C139966.html](https://lcsc.com/product-detail/RAM_VTI7064MSME_C139966.html)

Title		
Size	Number	Revision
A4		
Date:	4.13.2021	Sheet of
File:	J:\Altium projekty_robota\...\SRAM_QPI_SchDoc	By:

