## Bernadette K. Bucher

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**Research Interests:** Active Perception, Learning, Exploration, and Sampling; Robotic Manipulation and Navigation; Representation Learning; Exploration-Exploitation Tradeoffs

### **Education**

#### University of Pennsylvania

Ph.D. Computer Science

August 2018 - present<sup>†</sup>

Advisors: Dr. Kostas Daniilidis and Dr. Nikolai Matni

M.S.E. Robotics

August 2018 - December 2020

Fully funded through fellowships, department, and advisors

#### Georgia Institute of Technology

August 2016 - August 2018

15 graduate credits, School of Computer Science Fully funded by Lockheed Martin Corporation

#### The University of Alabama

M.A. Economics M.A. Mathematics, *Thesis Advisor:* Dr. Kabe Moen B.S. Mathematics and Economics January 2012 - May 2014 August 2012 - May 2014 August 2010 - May 2014

Fully funded through academic scholarships

### **Publications**

Georgios Georgakis\*, **Bernadette Bucher**\*, Karl Schmeckpeper, Siddharth Singh, Kostas Daniilidis. *Learning to Map for Active Semantic Goal Navigation*. ICLR, 2022.

Frederik Ebert\*, Yanlai Yang\*, Karl Schmeckpeper, **Bernadette Bucher**, Georgios Georgakis, Kostas Daniilidis, Chelsea Finn, Sergey Levine. *Bridge Data: Boosting Generalization of Robotic Skills with Cross-Domain Datasets*. RSS, 2022.

Georgios Georgakis, **Bernadette Bucher**, Anton Arapin, Karl Schmeckpeper, Nikolai Matni, Kostas Daniilidis. *Uncertainty-driven Planner for Exploration and Navigation*. ICRA, 2022.

Bernadette Bucher\*, Karl Schmeckpeper\*, Nikolai Matni, Kostas Daniilidis. *An Adversarial Objective for Scalable Exploration*. IROS, 2021.

Sudeep Dasari, Frederik Ebert, Stephen Tian, Suraj Nair, **Bernadette Bucher**, Karl Schmeckpeper, Siddharth Singh, Sergey Levine, Chelsea Finn. *RoboNet: Large-Scale Multi-Robot Learning*. CoRL, 2019.

## **Refereed Workshop Papers**

Frederik Ebert\*, Yanlai Yang\*, Karl Schmeckpeper, **Bernadette Bucher**, Georgios Georgakis, Kostas Daniilidis, Chelsea Finn, Sergey Levine. *Bridge Data: Boosting Generalization of Robotic Skills with Cross-Domain Datasets*. NeurIPS Workshop on Deep Reinforcement Learning, 2021.

<sup>&</sup>lt;sup>†</sup>On maternity leave during Fall 2020 and Summer 2022 semesters.

<sup>\*</sup>Denotes equal contribution.

**Bernadette Bucher**\*, Karl Schmeckpeper\*, Nikolai Matni, Kostas Daniilidis. *Action for Better Prediction*. RSS Workshop on Visual Learning and Reasoning for Robotic Manipulation, 2020.

**Bernadette Bucher**\*, Siddharth Singh\*, Clélia de Mulatier, Kostas Daniilidis, Vijay Balasubramanian. *Curiosity Increases Equality in Competitive Resource Allocation*. ICLR Workshop on Bridging AI and Cognitive Science, 2020.

Sudeep Dasari, Frederik Ebert, Stephen Tian, Suraj Nair, **Bernadette Bucher**, Karl Schmeckpeper, Siddharth Singh, Sergey Levine, Chelsea Finn. *RoboNet: Large-Scale Multi-Robot Learning*. NeurlPS Workshop on Deep Reinforcement Learning, 2019.

**Bernadette Bucher**, Anton Arapin, Ramanan Sekar, Feifei Duan, Marc Badger, Kostas Daniilidis, Oleh Rybkin. *Perception-Driven Curiosity with Bayesian Surprise*. RSS Workshop on Combining Learning and Reasoning Towards Human-Level Robot Intelligence, 2019.

Kenneth Chaney\*, **Bernadette Bucher**\*, Evangelos Chatzipantazis, Jianbo Shi, Kostas Daniilidis. *Unsupervised Monocular Depth and Latent Structure*. CVPR Workshop on 3D Scene Understanding for Vision, Graphics, and Robotics, 2019.

## **Preprints**

Kendall J. Queen, Karl Schmeckpeper, **Bernadette Bucher**, Siddharth Singh, Kostas Daniilidis, Nikolai Matni. *Event-Based Lane Detection for Autonomous Ground Vehicles*. Submitted, 2021.

Sadat Shaik\*, **Bernadette Bucher**\*, Nephele Agrafiotis, Stephen Phillips, Kostas Daniilidis, William Schmenner. *Learning Portrait Style Representations*. arXiv Preprint, 2020.

## **Industry Experience**

**Robotics Research Intern** (June 2021 - December 2021, Remote) *Seattle Robotics Lab* NVIDIA Research, NVIDIA Corporation

• Developed novel algorithms for precision placing under the supervision of Dr. Dieter Fox.

 $\textbf{Senior Software Engineer} \; (\textbf{September 2016 - August 2019}, \; \textbf{King of Prussia}, \; \textbf{PA}) \\ \textit{Warfighter Solutions}$ 

Rotary and Mission Systems, Lockheed Martin Corporation

- Engineering team author for \$200+ million winning government proposal.
- Architecture team lead for internal research effort of 2 to 12 people. Executed demos for customer engagements. Transitioned technology to affiliated business capture efforts.
- Author and demo lead for multiple RFI responses to various government customers.
- Designed and developed suite of configurable digital signal processing algorithms for real-time software defined radio platforms in C++ and CUDA.
- Supported integration of algorithm software suite for different applications and waveforms across multiple programs including government contracts and internal research efforts.
- Led and supported multiple physical layer development and RF integration processes from algorithm simulation through hardware integration.
- Interviewed 50+ engineering candidates to support division staffing.

**Software Engineer** (January 2015 - September 2016, Gaithersburg, MD & King of Prussia, PA) *GEOINT Visualization Services* 

Space Systems Company, Lockheed Martin Corporation

- Designed, developed, and maintained full stack web-based mapping software.
- POC for users developing with our API to build plugins for our applications.
- Led 3 to 8 person software engineering team in planning complete sprints, ran daily scrum meetings, and wrote new stories during periods as an Agile Scrum Master.

**Systems Integration and Test Engineer** (September 2014 - January 2015, Gaithersburg, MD) *Integrated Exploitation Capabilities* 

Information Systems and Global Solutions, Lockheed Martin Corporation

- Evaluated image processing algorithms for technology assessment of existing software.
- Developed and maintained C++ and Java based software products on an Agile team.

## **Selected Presentations**

- Sampling Policies and State Representations in Robotic Manipulation and Navigation Pipelines. Invited speaker. Siemens Healthineers, Research Seminar, November 2022.
- *Uncertainty-based Mapping and Navigation*. Invited speaker. University of Utah, Robotics Seminar, April 2022.
- Adversarial Curiosity. Invited speaker. Honda Research Institute, Curious Minded Machines Winter Seminar Series, December 2020.
- Improving Predictive Models with Curiosity. Invited speaker. University of Pennsylvania, GRASP Student Seminar Series, April 2020.
- Perception-Driven Representations for Autonomous Robotics. Invited speaker. Massachusetts Institute of Technology, CSAIL, Robotics Seminar, November 2019.
- Perception-Driven Curiosity with Bayesian Surprise. Invited speaker. Honda Research Institute, Curious Minded Machines Workshop, August 2019.
- Geometric Deep Learning. Invited speaker. University of Alabama, Department of Mathematics, Applied Mathematics Seminar, April 2019.
- Error Correcting Codes. Invited speaker. Lockheed Martin Corporation, Rotary and Mission Systems, Warfighter Solutions Lunch and Learn Series, September 2017.
- Digital Demodulation. Invited speaker. Lockheed Martin Corporation, Rotary and Mission Systems, Warfighter Solutions Lunch and Learn Series, March 2017.
- Mathematics Careers in Digital Signals Processing. Invited speaker. Villanova University, Department of Mathematics, Association of Women in Mathematics, February 2017.
- Modeling Illicit Drug Use: How Does Methamphetamine Use Spread Through Urban and Rural Populations? Poster presentation. Joint Mathematics Meetings, January 2014.
- The Navier-Stokes Equations: A Survey of Progress and Problems. Invited speaker. University of Alabama, Department of Mathematics, Mathematics Seminar, November 2013.
- Infectious Disease Modeling and the Spread of Methamphetamine Use. Invited speaker. University of Alabama, Department of Mathematics, Pi Mu Epsilon, October 2013.

# **Selected Honors and Awards**

Haidas and Chryssikou Fellowship	2020-2021
Rising Stars Executive Mentoring Program, Lockheed Martin Corporation	2018-2019
Special Recognition Award, Lockheed Martin Corporation	2017
New Business Capture Award, Lockheed Martin Corporation	2017
2 Spot Awards, Lockheed Martin Corporation	2016-2017
10+ Peer Awards, Lockheed Martin Corporation	2015-2018
Outstanding Presenter Award, Joint Mathematics Meetings	2014
Double Major with Distinction Award	2014
Faculty Excellence Award in Economics	2013
Analytic Excellence in Business Award	2013
Special Achievement Award in Economics	2012
University of Alabama Presidential Scholarship	2010-2014
University of Alabama Engineering Scholarship	2010-2012

# **Selected Teaching and Service**

Reviewer for RSS Workshops, ICRA, IROS, RA-L and JMLR	May 2020 - present
Head Teaching Assistant Automata, Computability and Complexity (CIS 262) Dr. Jean Gallier, University of Pennsylvania	January 2020 - May 2020
Team Mentor, George Washington Carver High School FIRST Tech Challenge	August 2019 - February 2020
Teaching Assistant Advanced Topics in Machine Perception (CIS 680) Dr. Jianbo Shi, University of Pennsylvania	August 2019 - December 2019
Mentor, Research and Engineering Apprenticeship Program  Army Engineering Outreach Program	June 2019 - August 2019
Volunteer, Girls Lead in Science and Technology Coding Camp	August 2019
Volunteer Robot Design Judge FIRST LEGO League	February 2019
Volunteer Teacher, Lockheed Martin Corporation Representative Cool Careers in Cybersecurity for Girls Workshop	December 2014
Lab Instructor, Mathematics Technology Learning Center The University of Alabama	January 2013 - May 2014

# Selected Research and Leadership Experience

GRASP Lab Student Advisory Committee, University of Pennsylvania	2020-2021
Vice President, Pi Mu Epsilon, University of Alabama Chapter	2013-2014
REU in Modeling and Industrial Applied Mathematics, NC State University	2013
REU in Algorithmic Combinatorics on Words, UNC at Greensboro	2012
Coxswain, University of Alabama NCAA Division I Women's Rowing Team	2010-2013