Vector-Rotation to Euler Angles

Buck Baskin

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Some calculations were verified using Python.

1 Answer

$$R_{BA} = R_y(\alpha)R_x(\beta)R_y(\gamma)$$

- 1.1 Solving for α, β, γ
- **1.1.1** β
- 1.1.2
- **1.1.3** β
- 1.2 Conclusion