First Meeting(24/1)

Briefly discuss the plan of the independent project. And fix the python version issue that I could not get the simulation running.

Second Meeting(12/2)

We went through the code structure and discussed the multi-agent planner implementation plan. Professor suggested a rule-based lifelong planner system as a backup approach.

Third Meeting(6/3)

I presented a proposal to use CBS as the multi-agent path planner algorithm and some initial design ideas. Discussed feasibility of the algorithm.

Forth Meeting(11/4)

Demo the WIP algorithm. Discussed bug fixes plan and future improvements plan.

Final Meeting(4/8)

Final demo of the algorithm. I presented the final performance result as well as the performance comparison with other algorithms.