

CS 450: Assignment 04

Setup

- Copy `src/app/Assign03.cpp` and name it **`src/app/Assign04.cpp`**
- Replace "Assign03" in the application name and window title with "**Assign04**"
- Replace the name "Assign03RenderEngine" with "**Assign04RenderEngine**"
- Make a copy of the `vulkanshaders/Assign03` folder and name it **`vulkanshaders/Assign04`**
- Modify **`CMakeLists.txt`** by adding the following line to the end of the file:
 - o `CREATE_VULKAN_EXECUTABLE(Assign04)`
- Make sure the program configures, compiles, and runs as-is

Assign04.cpp

- Add the following includes:
 - o **`#include "VKUniform.hpp"`**
- Add the following to the **`SceneData`** struct:
 - o A `glm::vec3` to hold the camera position (e.g., `eye`)
 - *Default value:* (0,0,1)
 - o A `glm::vec3` to hold the camera's look-at point (e.g., `lookAt`)
 - *Default value:* (0,0,0)
 - **NOTE: This is NOT the direction the camera is facing! This is the point the camera is focusing on!**
 - o A `glm::vec2` to hold the last mouse position (e.g., `mousePos`)
 - o A `glm::mat4` to hold the current view matrix
 - *Default value:* identity matrix (`glm::mat4(1.0f)`)
 - o A `glm::mat4` to hold the current projection matrix
 - *Default value:* identity matrix (`glm::mat4(1.0f)`)
- Create a struct to hold vertex shader UBO *host* data: **`UBOVertex`**
 - o Add one field for the view matrix: **`alignas(16) glm::mat4 viewMat`**
 - o Add one field for the projection matrix: **`alignas(16) glm::mat4 projMat`**
- Add the following function for generating a transformation to rotate around an arbitrary point and axis: **`glm::mat4 makeLocalRotate(glm::vec3 offset, glm::vec3 axis, float angle)`**
 - o Generate a composite transformation to perform the following IN ORDER:
 - Translate by **NEGATIVE** offset
 - Rotate *angle* around *axis* (**REMEMBER TO CONVERT *angle* to RADIANS!!!!**)
 - Translate by offset
 - o Return the composite transformation

- Add a mouse cursor movement callback: **static void mouse_position_callback(GLFWwindow* window, double xpos, double ypos)**
 - Get RELATIVE mouse motion
 - Subtract mouse position (xpos, ypos) from previous mouse position (sceneData.mousePos) → glm::vec2 relMouse
 - Use glfwGetFramebufferSize() to acquire the current framebuffer size
 - **As long as the framebuffer has width and height greater than zero:**
 - Divide relMouse.x by current framebuffer width and relMouse.y by current framebuffer height to get scaled relative mouse motion
 - Make sure you do not do integer division!
 - Use relative mouse motion to rotate camera (use makeLocalRotate to get the appropriate matrix transformations):
 - RELATIVE X MOTION → rotate around GLOBAL Y axis
 - *Point to rotate:* sceneData.lookAt
 - *Offset to rotate around:* sceneData.eye
 - *Angle (degrees):* 30.0f * relative X mouse motion
 - *Axis:* glm::vec3(0,1,0)
 - RELATIVE Y MOTION → rotate around LOCAL X axis
 - *Point to rotate:* sceneData.lookAt
 - *Offset to rotate around:* sceneData.eye
 - *Angle (degrees):* 30.0f * relative Y mouse motion
 - *Axis:* cross product of camera direction and GLOBAL Y axis → LOCAL "X" axis
 - *Camera direction:* sceneData.lookAt – sceneData.eye
 - NOTE: Both sceneData.eye and sceneData.lookAt are glm::vec3 values; in order to multiply by a glm::mat4, you will need to convert to and from glm::vec4:
 - *glm::vec3 to glm::vec4 (as point):*
glm::vec4 lookAtV = glm::vec4(sceneData.lookAt, 1.0);
 - *glm::vec4 to glm::vec3:*
sceneData.lookAt = glm::vec3(lookAtV);
 - Either way, store new current mouse position (xpos, ypos) in sceneData.mousePos

- **Add keys to your GLFW key callback function:**
 - **NOTE: For both camera direction and local X axis, NORMALIZE vectors before factoring in speed!**
 - If the action is either GLFW_PRESS or GLFW_REPEAT, add checks for the following keys:
 - GLFW_KEY_W
 - Move FORWARD in current camera direction
 - *Points to change:* sceneData.lookAt, sceneData.eye
 - *Camera direction:* sceneData.lookAt - sceneData.eye
 - *Speed:* 0.1
 - GLFW_KEY_S
 - Move BACKWARD in current camera direction
 - *Points to change:* sceneData.lookAt, sceneData.eye
 - *Camera direction:* sceneData.lookAt - sceneData.eye
 - *Speed:* 0.1
 - GLFW_KEY_D
 - Move RIGHT in LOCAL X direction (i.e., positive)
 - *Points to change:* sceneData.lookAt, sceneData.eye
 - *Movement axis:* cross product of camera direction and GLOBAL Y axis
 - *Speed:* 0.1
 - GLFW_KEY_A
 - Move LEFT in LOCAL X direction (i.e., negative)
 - *Points to change:* sceneData.lookAt, sceneData.eye
 - *Movement axis:* cross product of camera direction and GLOBAL Y axis
 - *Speed:* 0.1
- **Modify Assign04RenderEngine:**
 - Add the following protected instance variables:
 - **UBOVertex hostUBOVert**
 - Holds HOST vertex shader UBO data
 - **UBOData deviceUBOVert**
 - Holds DEVICE vertex shader UBO data
 - **vk::DescriptorPool descriptorPool**
 - Memory manager for descriptor sets
 - **vector<vk::DescriptorSet> descriptorSets**
 - List of descriptor sets
 -

- Please note that the following are already defined in VulkanRenderEngine:
 - **VulkanInitData vkInitData**
 - Initial setup data, like the device and physical device
 - **const int MAX_FRAMES_IN_FLIGHT**
 - Maximum number of frames-in-flight
 - **unsigned int currentImage**
 - Current image (about to be) in flight
 - **VulkanPipelineData pipelineData**, which contains:
 - **vector<vk::DescriptorSetLayout> descriptorSetLayouts**
 - This is set during *VulkanRenderEngine's initialize()*, through a call to *createVulkanPipelineData()* and finally *getDescriptorSetLayouts()*
- Add to: **initialize()**; after the successful call to VulkanRenderEngine::initialize(params), do the following:
 - **We will be creating a SEPARATE SET of items for each frame-in-flight.**
 - **UBOData struct → already contains lists**
 - **List of descriptor sets**
 - **Create deviceUBOVert (instance variable) using the function createVulkanUniformBufferData()**
 - Use the device and physicalDevice from vkInitData
 - Size should be sizeof(UBOVertex)
 - Frames-in-flight should be MAX_FRAMES_IN_FLIGHT
 - **Create the descriptor pool (instance variable):**
 - Create a **vector of vk::DescriptorPoolSize** objects and add one:
 - Type is vk::DescriptorType::eUniformBuffer
 - Descriptor count is (UBO count * frames-in-flight)
 - For now: 1*MAX_FRAMES_IN_FLIGHT
 - Create the **vk::DescriptorPoolCreateInfo**
 - Use setPoolSizes(poolSizes) to set the pool sizes
 - Use setMaxSets(MAX_FRAMES_IN_FLIGHT)
 - Create the actual **descriptorPool** using **vkInitData.device.createDescriptorPool(poolCreateInfo)**
 - **Create the descriptor sets (instance variable):**
 - Create a local **vector of vk::DescriptorSetLayout** objects and add one per frame-in-flight:
 - Only ONE DescriptorSetLayout object was needed during pipeline creation (same for all frames)
 - Thus, getDescriptorSetLayouts() returns a list of ONE DescriptorSetLayout

- Now, however, we are creating SEPARATE DescriptorSet objects (one for each frame) that all use the same layout
 - Therefore, add the first element of `pipelineData.descriptorSetLayouts` to this local list of `DescriptorSetLayouts`, once for each frame-in-flight
 - Create a **`vk::DescriptorSetAllocateInfo`** object
 - Use `setDescriptorPool(descriptorPool)`
 - Use `setDescriptorSetCount(MAX_FRAMES_IN_FLIGHT)`
 - Use `setSetLayouts(localLayoutList)`
 - Create the actual **descriptorSets** using **`vkInitData.device.allocateDescriptorSets(allocInfo)`**
- For each frame-in-flight *index*:
 - Create a **vector of `vk::WriteDescriptorSet` objects** → **writes**
 - Create a **`vk::DescriptorBufferInfo` object** → **bufferVertexInfo**
 - Use `setBuffer(deviceUBOVert.bufferData[index].buffer)`
 - Use `setOffset(0)`
 - Use `setRange(sizeof(UBOVertex))`
 - Create a **`vk::WriteDescriptorSet` object** → **descVertWrites**
 - Use `setDstSet(descriptorSets[index])`
 - Use `setDstBinding(0)`
 - Use `setDstArrayElement(0)`
 - Use `setDescriptorType(vk::DescriptorType::eUniformBuffer)`
 - Use `setDescriptorCount(1)`
 - Use `setBufferInfo(bufferVertInfo)`
 - Add **descVertWrites** to **writes**
 - Update the descriptor sets with **`vkInitData.device.updateDescriptorSets(writes, {})`**
- Add to: **`~Assign04RenderEngine()`**:
 - Destroy the descriptor pool:
 - **`vkInitData.device.destroyDescriptorPool(descriptorPool)`**;
 - Clean up the UBO device data:
 - **`cleanupVulkanUniformBufferData(vkInitData.device, deviceUBOVert)`**;
- Override: **`vector<vk::DescriptorSetLayout> getDescriptorSetLayouts()`**
 - Create a **vector of `vk::DescriptorSetLayoutBinding` objects** → **allBindings**:
 - One **`vk::DescriptorSetLayoutBinding`** for the vertex shader UBO:
 - `binding = 0`
 - `descriptorType = vk::DescriptorType::eUniformBuffer`
 - `descriptorCount = 1`
 - `stageFlags = vk::ShaderStageFlagBits::eVertex`
 - `pImmutableSamplers = nullptr`

- Create a `vk::DescriptorSetLayout` using
`vkInitData.device.createDescriptorSetLayout(`
`vk::DescriptorSetLayoutCreateInfo({}, allBindings));`
 - Return a vector only containing the one `vk::DescriptorSetLayout`
- Create a new method: **`virtual void updateUniformBuffers(SceneData *sceneData, vk::CommandBuffer &commandBuffer)`**
 - Copy view matrix and projection matrix from `sceneData` into appropriate fields of `hostUBOVert`
 - Invert Y for the projection matrix:
 - `hostUBOVert.projMat[1][1] *= -1;`
 - Copy UBO host data into the CORRECT device UBO data:
 - `memcpy(deviceUBOVert.mapped[this->currentImage], &hostUBOVert, sizeof(hostUBOVert));`
 - Bind the CORRECT descriptor sets:
 - `commandBuffer.bindDescriptorSets(vk::PipelineBindPoint::eGraphics, pipelineData.pipelineLayout, 0, descriptorSets[currentImage], {});`
- Add to: **`recordCommandBuffer()`**
 - RIGHT before the call to `renderScene()`, call:
 - `updateUniformBuffers(sceneData, commandBuffer);`
- In the main function:
 - Get the initial position of the mouse AFTER the GLFW window is created:
 - `double mx, my;`
 - `glfwGetCursorPos(window, &mx, &my);`
 - `sceneData.mousePos = glm::vec2(mx, my);`
 - Call `glfwSetCursorPosCallback()` to appropriately set the mouse cursor motion function
 - Hide the cursor:
 - `glfwSetInputMode(window, GLFW_CURSOR, GLFW_CURSOR_DISABLED);`
 - INSIDE the drawing loop, BEFORE the call to `renderEngine->drawFrame(&sceneData):`
 - Set the value of `sceneData.viewMat` using `glm::lookAt()`
 - Parameters “eye” and “center” should come from `sceneData.eye` and `sceneData.lookAt`
 - Parameter “up” should be `glm::vec3(0,1,0)` (y axis)
 - Calculate the **aspect ratio** as the framebuffer width divided by height
 - NOTE: If either width or height are zero, set aspect ratio to 1.0. **Do NOT divide by zero!**
 - **Make sure to do FLOATING-POINT DIVISION!**

- Set the value of **sceneData.projMat** using **glm::perspective()**
 - *FOV*: 90.0f degrees (IN RADIANS!)
 - *Aspect*: aspect ratio calculated before
 - *Near plane*: 0.01f
 - *Far plane*: 50.0f

shader.vert

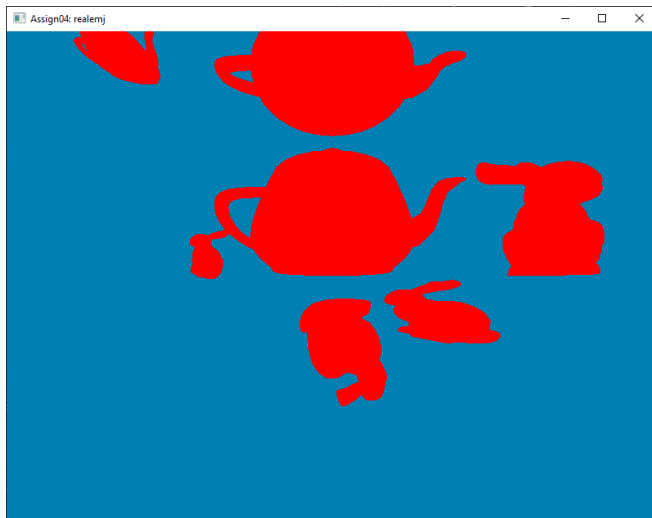
- Add the appropriate UBO struct
- Make sure that `gl_Position` receives the input vertex position multiplied by the model, view, and projection matrices
 - REMEMBER: RIGHT-TO-LEFT multiplication order!

Screenshot (5%)

You should be able to rotate your view with the mouse and move forward/strafe left/backward/strafe right with the WASD keys. Remember that movement with the keys should be RELATIVE to your current view.

For the screenshot, you will load **bunnyteatime.glb** and take a screenshot when the application first loads: **Assign04.png**.

Copy the image to the **screenshots/** folder.



Grading

Your OVERALL assignment grade is weighted as follows:

- 95% - Programming
- 5% - Screenshots