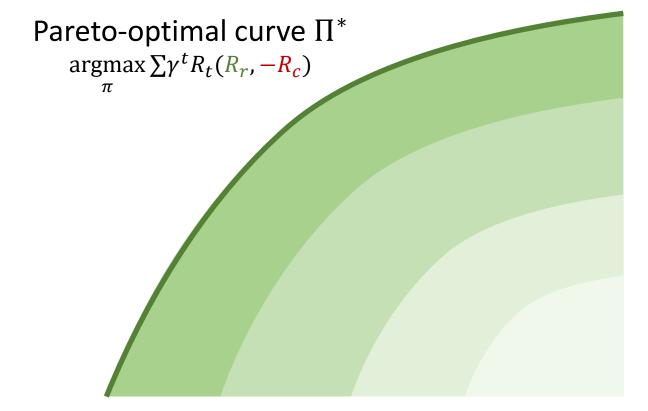
## Task Completion $G_r$



Risk  $G_c$