4.1 Higher-order linear equations: first examples and preliminaries a lesson for MATH F302 Differential Equations

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for textbook: D. Zill, A First Course in Differential Equations with Modeling Applications, 11th ed.

outline

plan for these slides

- a bit of review of first-order linear equations (§2.3)
- a first look at how to solve constant-coefficient, second-order linear equations (from §4.3)
- a whole bunch of new language for higher-order linear equations
 - o basically, §4.1 is a lot of new words

first-order linear DEs: a review

recall first-order linear DEs:

$$a_1(x)y' + a_0(x)y = g(x)$$

one may divide by the leading coefficient:

$$y' + P(x)y = f(x)$$

- this requires leading coefficient $a_1(x)$ to not to be zero on the interval where we are solving
- special case 1 (easiest to solve): constant-coefficient and homogeneous

$$y'+by=0$$

- o homogeneous means the right-hand side is zero
- o constant-coefficient means b is constant
- the solution is ("by inspection"?)

$$y(x) = Ae^{-bx}$$

first-order linear review cont.

special case 2: homogeneous (but otherwise general)

$$y' + P(x)y = 0$$

- o now we need an integrating factor $\mu(x) = e^{Q(x)}$ where $Q(x) = \int P(x) dx$ is any antiderivative of P(x)
- multiplying by μ the equation becomes $(\mu(x)y(x))'=0$
- o thus

$$e^{Q(x)}y(x) = A$$

thus the solution is

$$y(x) = Ae^{-Q(x)}$$

homogeneous: a multiple of a solution is still a solution

first-order linear review cont.²

• general nonhomogeneous case: first-order linear

$$y' + P(x)y = f(x)$$

- o need same integrating factor; multiplying by $\mu = e^{Q(x)}$ yields $(\mu(x)y(x))' = \mu(x)f(x)$
- o integrate:

$$e^{Q(x)}y(x) = A + \int_a^x e^{Q(t)}f(t) dt$$

- where $Q(x) = \int P(x) dx$ is any antiderivative of P(x)
- written to emphasize right side has a free constant A
- thus the solution is

$$y(x) = Ae^{-Q(x)} + e^{-Q(x)} \int_{a}^{x} e^{Q(t)} f(t) dt$$

o solution is the homogeneous solution plus a particular solution

higher-order linear DEs: overview

for *n*th-order linear equations

$$a_n(x)y^{(n)} + a_{n-1}(x)y^{(n-1)} + \cdots + a_1(x)y' + a_0(x)y = g(x)$$

new versions of all four comments in red on the previous slides still apply

overview cont.

$$a_n(x)y^{(n)} + a_{n-1}(x)y^{(n-1)} + \cdots + a_1(x)y' + a_0(x)y \stackrel{*}{=} g(x)$$

1 if $a_n(x) \neq 0$ then we can divide by it:

$$y^{(n)} + b_{n-1}(x)y^{(n-1)} + \cdots + b_1(x)y' + b_0(x)y = f(x)$$

2 easiest case (§4.3) is homogeneous and constant coefficient

$$a_n y^{(n)} + a_{n-1} y^{(n-1)} + \dots + a_1 y' + a_0 y = 0$$

3 for the associated homogeneous equation to *,

$$a_n(x)y^{(n)} + a_{n-1}(x)y^{(n-1)} + \cdots + a_1(x)y' + a_0(x)y = 0$$

any multiple of, or sum of, solutions is again a solution

4 solutions of * are always solutions of the homogeneous equation plus a particular solution

solutions exist

Theorem

Consider the linear DE

$$a_n(x)y^{(n)} + a_{n-1}(x)y^{(n-1)} + \cdots + a_1(x)y' + a_0(x)y = g(x)$$

If the functions $a_j(x)$ and g(x) are continuous on some interval, and if $a_n(x) \neq 0$ on that interval, then solutions exist.

• Furthermore, if x_0 is in that interval then there is exactly one solution which satisfies the initial values

$$y(x_0) = y_0$$

 $y'(x_0) = y_1$
 \vdots
 $y^{(n-1)}(x_0) = y_{n-1}$

linear, homogeneous, constant-coefficient

- furthermore, linear DEs which are homogeneous and constant-coefficient always have exponential solutions
 - o you can always find at least one solution $y = e^{mx}$
 - o and multiples and sums of solutions are solutions
- example 1: solve, by trying $y(x) = e^{mx}$, the equation

$$y'' + 4y' - 5y = 0$$

fundamental set of solutions:

general solution:

example 2

• example 2: solve, by trying $y(x) = e^{mx}$, the equation

$$y''' + 3y'' - y' - 3y = 0$$

fundamental set of solutions:

general solution:

linear combination

- examples 1 and 2 are from §4.3 but they let me illustrate the language introduced in §4.1 ← read this section!
- · for example,

Theorem

If $y_1(x), y_2(x), \dots, y_n(x)$ solve a linear and homogeneous DE

$$a_n(x)y^{(n)} + a_{n-1}(x)y^{(n-1)} + \cdots + a_1(x)y' + a_0(x)y = 0$$

then any linear combination

$$y(x) = c_1y_1(x) + c_2y_2(x) + \cdots + c_ny_n(x)$$

is also a solution.

- idea: for linear and homogeneous DEs you can form a more general solution from any set of solutions
 - see examples 1 and 2

linear dependence and independence

• a set of functions $\{f_1(x), \ldots, f_n(x)\}$ is *linearly dependent* if you can combine with constants c_1, \ldots, c_n , some of which are not zero, and get the zero function:

$$c_1 f_1(x) + c_2 f_2(x) + \cdots + c_n f_n(x) = 0$$

- a set is linearly independent if it is not linearly dependent
- example:

$$f_1(x) = x^2 + x$$
, $f_2(x) = x^2 - x$, $f_3(x) = 5x$

are linearly dependent because

$$1 \cdot f_1(x) - 1 \cdot f_2(x) - \frac{2}{5} \cdot f_3(x) = 0$$

example 3

- recall from example 1 that $f_1(x)=e^x$ and $f_2(x)=e^{-5x}$ are solutions to y''+4y'-5y=0
- example 3: Find a solution of the initial value problem

$$y'' + 4y' - 5y = 0$$
, $y(0) = 2$, $y'(0) = -3$

• this calculation works because $\{f_1(x), f_2(x)\} = \{e^x, e^{-5x}\}$ is a linearly-independent set

checking linear independence

- generally it would require linear algebra thinking to check whether a set of functions is linearly independent
- but there is a determinant to save you from thinking!
- definition. given functions $f_1(x), \ldots, f_n(x)$ the *Wronskian* is the deteriminant where the rows are derivatives:

$$W(f_1, \dots, f_n) = \det \left(\begin{bmatrix} f_1 & f_2 & \dots & f_n \\ f'_1 & f'_2 & \dots & f'_n \\ \vdots & \vdots & & \vdots \\ f_1^{(n)} & f_2^{(n)} & \dots & f_n^{(n)} \end{bmatrix} \right)$$

• example 4: find the Wronskian of $\{e^{-3x}, e^{-x}, e^x\}$

theorem

Theorem

Suppose $\{y_1(x), y_2(x), \dots, y_n(x)\}$ are solutions of a homogeneous linear nth-order differential equation on some interval. Then

- The set of solutions is linearly-independent if and only if the Wronskian $W(y_1, ..., y_n)$ is nonzero on the interval.
- If the Wronskian $W(y_1, ..., y_n)$ is nonzero at some point on the interval then it is nonzero on the whole interval.

fundamental set

definition. a set of n linearly-independent solutions $\{y_1(x), y_2(x), \dots, y_n(x)\}$ of the homogeneous linear nth-order differential equation

$$a_n(x)y^{(n)} + a_{n-1}(x)y^{(n-1)} + \cdots + a_1(x)y' + a_0(x)y = 0$$

is a fundamental set of solutions

 once you have a fundamental set then the general solution of the above DE is

$$y(x) = c_1y_1(x) + c_2y_2(x) + \cdots + c_ny_n(x)$$

 if you have fewer than n solutions, or they are not linearly independent, then the linear combination is a solution, but not fully general

exercise 25 in §4.1

• exercise #25: Verify that the functions form a fundamental set of solutions on the interval. Form the general solution.

$$y'' - 2y' + 5y = 0,$$
 $\{e^x \cos 2x, e^x \sin 2x\},$ $(-\infty, \infty)$

exercise 27 in §4.1

• exercise #27: Verify that the functions form a fundamental set of solutions on the interval. Form the general solution.

$$x^2y'' - 6xy' + 12y = 0,$$
 $\{x^3, x^4\},$ $(0, \infty)$

expectations

- just watching this video is not enough!
 - o see "found online" videos at

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bueler.github.io/math302/week6.html
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- read section 4.1 in the textbook
 - know the meaning/definitions of:

homogeneous nonhomogeneous associated homogeneous equation linear combination superposition linearly dependent linearly independent Wronskian fundamental set of solutions general solution particular solution complementary function

- we will soon focus more on nonhomogeneous equations (§4.4), but the homogeneous case is central for a while (§4.3 and then §4.2)
- but during this course I will not ask questions about "boundary conditions" and "boundary value problems"
- there is quite a bit of new language in §4.1!
- do the WebAssign exercises for section 4.1