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## **Summary: Why Finite Difference Methods Work**

Chapter 2 of the textbook (R. J. LeVeque, 2007) starts with the ODE BVP example

$$u''(x) = f(x),$$
  $u(0) = \alpha,$   $u(1) = \beta.$ 

It constructs a practical finite difference (FD) numerical method on this example. Then it explains why the numerical solution will converge to the exact solution as we refine the grid  $(m \to \infty \text{ and } h \to 0)$ . We will use the same basic "consistency + stability  $\implies$  convergence" strategy on all problems, the Lax equivalence theorem. This summary puts the whole strategy on one page, for linear DEs, with details suppressed.

To use this as a worksheet: Fill in the extra space, or the reverse side, with your details!

**Stage 1. Apply scheme to DE.** Choose the grid/mesh, including number of unknowns m and spacing h. Apply your FD *discretization* or *scheme*; it creates a *family* of matrices  $\{A^h\}$ :

**Stage 2. Solve the scheme.** Numerical solution of the system of (linear) algebraic equations:

$$A^h U^h = F^h \qquad \Longrightarrow \qquad U^h = (A^h)^{-1} F^h$$

**Stage 3. LTE and error equation.** Let  $\hat{U}_j^h = u(x_j)$  be the grid values of the exact solution u(x) of your DE. (You may not know u(x)!) Define the *local truncation error* (LTE) as the residual from the scheme, when it is applied to the exact solution:

$$\tau^h = A^h \hat{U}^h - F^h = O(h^p)$$

Taylor's theorem generates the *order of accuracy* p, and if p > 0 then the scheme is *consistent*. Defining the *numerical error*  $E^h = U^h - \hat{U}^h$ , get:

$$E^h U^h = -\tau^h \qquad \Longrightarrow \qquad E^h = -(A^h)^{-1} \tau^h$$

**Stage 4. Apply stability to show convergence.** Show *stability*: there is C > 0 so that  $||(A^h)^{-1}|| \le C$  for all h > 0. (Stability may be difficult to show!) Because  $||\tau^h|| = O(h^p)$ , get *convergence* at rate p:

$$||E^h|| = ||-(A^h)^{-1}\tau^h|| \le ||(A^h)^{-1}|| ||\tau^h|| \le CO(h^p) = O(h^p)$$