#### Linear systems

Vec, Mat, KSP to solve linear systems in PETSc

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# preamble: partial differential equations (PDEs) coverage

- ▶ I have no chance of "covering" the field of PDEs
  - ▶ I will not try!
- PETSc is not a magic bullet for problems
- consider alternatives:
  - 1. FEM packages (FENICs, deal.II, libmesh, firedrake)
    - easier to use, easier for complex geometry
    - ▶ PETSc is often under the hood
  - solvers for classes of problems (e.g. clawpack for purely-hyperbolic systems)

#### PDEs done in this seminar

- ▶ the PDEs in this seminar are in three broad classes:
  - 1. linear elliptic or systems (e.g. Poisson equation, advection-diffusion, Stokes)
  - 2. nonlinear elliptic (e.g. p-Laplacian, obstacle)
  - time-dependent of various types (e.g. heat, shallow water, porous medium)
    - will focus on implicit time-stepping on these problems
- these classes are poorly-defined . . . my book is a grab-bag
- generally the case for my choices:

PDE problems generate large linear and nonlinear systems after discretization (e.g. finite difference or finite element)

# PDEs generate linear/nonlinear systems

- linear elliptic PDE generates linear system
  - ▶ for example: Poisson equation in Chapters 3, 9, and 11

$$-\nabla^2 u = f \longrightarrow A\mathbf{u} = \mathbf{b}$$

- linear elliptic PDE generates linear system
  - for example: p-Laplacian equation in Chapter 5

$$-\nabla \cdot \left( |\nabla u|^{p-2} \nabla u \right) = f \longrightarrow \mathbf{F}(\mathbf{u}) = 0$$



# linear systems from PDEs: big and sparse

One might say that if N is very large, it is probably an approximation to infinity. Trefethen & Bau, page 244

- discretized PDEs generate linear/nonlinear systems as large as we can handle
  - dimensions  $N=10^8$  (or more) are common
- but partial derivatives are local interactions
  - so matrix structure is sparse with lots of zeros
- job for today: solve small, fixed-size linear system
- job for next week: solve larger linear systems, and transition to PDE-generated systems

### recall how to get started with a PETSc example

check that environment variables are set to a valid PETSc installation:

```
$ echo $PETSC_DIR
$ echo $PETSC ARCH
```

compile and run a code:

```
$ cd c/ch2/
$ make vecmatksp
$ ./vecmatksp
```

\$ mpiexec -n 4 ./vecmatksp

#### PETSc object class 1: Vec

▶ to create, fill, and show a parallel Vec called b we do this:

```
Vec b;
int j[4] = \{0, 1, 2, 3\};
                                      # global indices
double v[4] = \{11.0, 7.0, 5.0, 3.0\}; # values
VecCreate(PETSC COMM WORLD,&b);
VecSetSizes(b,PETSC DECIDE,4);
VecSetFromOptions(b);
                                      # why needed?
VecSetValues(b,4,j,v,INSERT VALUES);
VecAssemblyBegin(b);
                                      # why needed?
VecAssemblyEnd(b);
VecView(b,PETSC_VIEWER_STDOUT_WORLD); # print @ stdout
VecDestroy(&b);
```

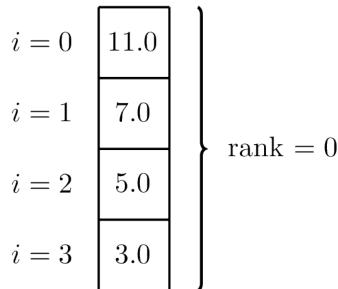
#### notice PETSc is object-oriented C . . . sort of

- C is not officially an object-oriented language
- but PETSc data types act that way
- we interact with Vec b only through function calls
  - internal representations are hidden
  - ▶ these functions are essentially "methods" of Vec
- ▶ however, "inheritance" and other C++ concepts are not in C
- in fact Vec is really a pointer to a struct ... but I will not look inside

# result from VecView(): serial

```
$ ./prog
Vec Object: 1 MPI processes
  type: seq
11.
7.
5.
3.
```

# a vector in serial: picture



### result from VecView(): parallel

- VecSetFromOptions() allows the type of the Vec to be set to different defaults at runtime
- thus we see this on 2 processes

```
$ mpiexec -n 2 ./prog
Vec Object: 2 MPI processes
  type: mpi
Process [0]
11.
7.
Process [1]
5.
3.
```

# a vector in parallel: picture

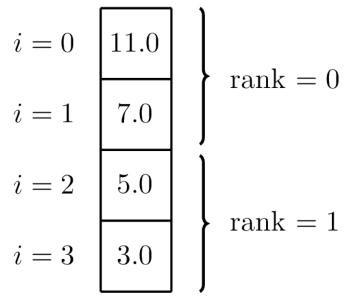


Figure 2:layout of Vec over two processes

# why VecAssemblyBegin()/End()?

recall:

```
VecAssemblyBegin(b);
VecAssemblyEnd(b);
```

- why is this needed?
- because VecSetValues() can be done in parallel
- entries of the Vec computed on one process will be moved "automatically" by this VecAssembly process to the process where they are owned

#### PETSc object class 2: Mat

▶ to create, show, and destroy a Mat called A we do this:

```
Mat
MatCreate(PETSC COMM WORLD,&A);
MatSetSizes(A,PETSC_DECIDE,PETSC_DECIDE,4,4);
MatSetFromOptions(A);
MatSetUp(A);
   CODE TO FILL ENTRIES 1
MatAssemblyBegin(A,MAT FINAL ASSEMBLY);
MatAssemblyEnd(A,MAT FINAL ASSEMBLY);
MatView(A,PETSC_VIEWER_STDOUT WORLD);
MatDestroy(&A);
```

#### PETSc object class 2: Mat

▶ to fill, here is one way:

```
int j[4] = {0, 1, 2, 3};  # column indices
i = 0;  # row index
v[0] = 1.0; v[1] = 2.0; v[2] = 3.0;
MatSetValues(A,1,&i,3,j,v,INSERT_VALUES);
i = 1;
v[0] = 2.0; v[1] = 1.0; v[2] = -2.0; v[3] = -3.0;
MatSetValues(A,1,&i,4,j,v,INSERT_VALUES);
...
```

ugly and tedious compared to Matlab's

$$A = [1.0 \ 2.0 \ 3.0 \ 0.0; \ldots]$$

 but PETSc grid/mesh support will automate such Mat entry-filling in PDE examples

# MatView() result

```
$ mpiexec -n 2 ./prog
Mat Object: 2 MPI processes
   type: mpiaij
row 0: (0, 1.) (1, 2.) (2, 3.)
row 1: (0, 2.) (1, 1.) (2, -2.) (3, -3.)
row 2: (0, -1.) (1, 1.) (2, 1.) (3, 0.)
row 3: (1, 1.) (2, 1.) (3, -1.)
```

▶ i.e. shown as sparse storage

# a matrix in parallel: picture of MPIAIJ

Figure 3:layout of Mat over two processes

#### matrix in parallel

- by default, parallel PETSc matrices (MPIAIJ) have each processor own a block of rows
- ▶ thus w = Av requires communication to put v on the right process, but then the result w is already there

# full code for solving linear system

- ▶ do
  - \$ cd c/ch2/
  - \$ make vecmatksp
  - \$ ./vecmatksp
  - \$ mpiexec -n 2 ./vecmatksp -vec\_view -mat\_view
- look at vecmatksp.c code
  - note all the error-checking clutter
  - clearly: need to explain "KSP"
  - which requires some attention to notation, definitions, and numerical linear algebra
  - next week