# A first PDE solution in PETSC Finite differences on a structured grid

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## outline for today

#### book Chapter 2:

▶ finish up the tri.c example (only 2 slides)

#### book Chapter 3:

boundary-value problem for Poisson's equation:

$$-\nabla^2 u = f$$

- finite difference (FD) method
- ▶ FD method generates linear system Au = b

## large (merely tridiagonal) linear system

- ▶ look at c/ch2/tri.c; notice
  - PetscOptions...()
  - MatGetOwnershipRange(A, &Istart, &Iend)
  - generic row of A is

$$-1 \ 3 \ -1$$

- o "manufacture" exact solution: MatMult (A, xexact, b)
- for example, use Richardson as KSP:
  - \$ ./tri -ksp\_monitor -ksp\_type richardson \
     -pc\_type none
  - \$ ./tri -ksp\_monitor -ksp\_type richardson \
     -pc\_type jacobi
- performance = execution time, for now
  - \$ time ./tri -tri\_m 10000
  - \$ alias timer
  - \$ timer ./tri -tri\_m 10000

#### performance on $m = 2 \times 10^7$ unknowns

\$ timer mpiexec -n N ./tri -tri\_m 20000000 \
 -ksp\_rtol 1.0e-10 -ksp\_type KSP -pc\_type PC

<u>KSP</u>	<u>PC</u>	N=1 time (s)	N=4 time (s)
preonly	lu	10.74	
	cholesky	5.84	
richardson	jacobi	13.48	5.45
gmres	none	9.99	5.30
	jacobi	10.23	4.49
	ilu	4.77	
	bjacobi+ilu		2.99
cg	none	7.22	3.18
	jacobi	7.49	3.31
	icc	4.81	
	bjacobi+icc		2.87

Table 2.2: Times for tri.c to solve systems of dimension  $m=2\times 10^7$ . In this case the matrix is tridiagonal, symmetric, diagonally-dominant, and positive definite. All runs were on WORKSTATION (see page 41).

note: for N> 1 use

-pc\_type bjacobi -sub\_pc\_type PC

if you want PC=ilu, icc on each process



## Poisson equation on a square

- ▶ let S be the open unit square  $(0,1) \times (0,1)$
- recall *Laplacian* of u(x, y):

$$\nabla^2 u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}$$

boundary value problem:

$$-\nabla^2 u = f \quad \text{on } \mathcal{S}$$
$$u = 0 \quad \text{on } \partial \mathcal{S}$$

for example, if

$$f(x,y) = 2(1 - 6x^2)y^2(1 - y^2)$$
$$+ 2(1 - 6y^2)x^2(1 - x^2)$$
then  $u(x,y) = (x^2 - x^4)(y^4 - y^2)$ 

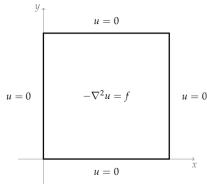


Figure 3.1: The Poisson equation on the unit square S, with homogeneous Dirichlet boundary conditions.

#### where does Poisson come from?

- model for: electrostatic potential, equilibrium distribution from random walks, various other physical phenomena
- for example, heat conduction in solids:
  - if k is the conductivity then Fourier's law says heat flux is

$$\mathbf{q} = -k\nabla u$$

if f describes a heat source then energy conservation says

$$c\rho \partial u/\partial t = -\nabla \cdot \mathbf{q} + f$$

 $\circ$  if k = 1, and in equilibrium (steady state) then get our Poisson equation

$$0 = \nabla^2 u + f$$

#### choice of grid = first step of an approximation

- ▶ put structured grid of m<sub>x</sub> by m<sub>y</sub> points on S
- ▶ spacing  $h_x = 1/(m_x 1)$ and  $h_y = 1/(m_y - 1)$
- grid coordinates are  $x_i = i h_x$ ,  $y_j = j h_y$
- ► the main notation of numerical differential equations: the unknown value of u(x, y) at node (x<sub>i</sub>, y<sub>j</sub>) will be approximated by the numbers u<sub>i,j</sub> which we actually compute:

$$u_{i,j} \approx u(x_i, y_j)$$

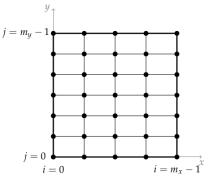


Figure 3.2: A grid on the unit square S, with  $m_x = 5$  and  $m_y = 7$ .

# finite difference approximation of partial derivatives

- our equation has second partial derivatives
- steps to the finite difference form of the Laplacian:

$$\frac{\partial u}{\partial x}(x,y) = \lim_{h \to 0} \frac{u(x+h,y) - u(x,y)}{h}$$

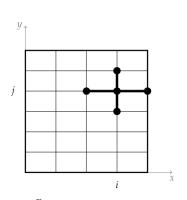
$$\frac{\partial u}{\partial x}(x_i,y_j) \approx \frac{u(x_i+h_x,y_j) - u(x_i,y_j)}{h_x}$$

$$\approx \frac{u_{i+1,j} - u_{i,j}}{h_x}$$

$$\frac{\partial^2 u}{\partial x^2}(x_i,y_j) \approx \frac{u_{i+1,j} - 2u_{i,j} + u_{i-1,j}}{h_x^2}$$

$$\nabla^2 u(x_i,y_j) \approx \frac{u_{i+1,j} - 2u_{i,j} + u_{i-1,j}}{h_x^2}$$
"stencil"  $\nearrow$ 

$$+ \frac{u_{i,j+1} - 2u_{i,j} + u_{i,j-1}}{h_v^2}$$



## FD scheme gives linear system

FD equations for our Poisson problem:

$$-\frac{u_{i+1,j}-2u_{i,j}+u_{i-1,j}}{h_X^2}-\frac{u_{i,j+1}-2u_{i,j}+u_{i,j-1}}{h_y^2}=f_{i,j},$$

$$u_{0,j}=0,\quad u_{m_x-1,j}=0,\quad u_{i,0}=0,\quad u_{i,m_y-1}=0$$

- first equation applies at all interior points
- boundary condition treated as trivial equations: "1 u = 0"
- ▶ is a linear system of  $L = m_x m_y$  equations in L unknowns

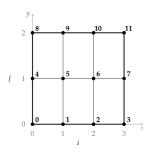
$$A\mathbf{u} = \mathbf{b}$$

where A is  $L \times L$  matrix and **u**, **b** are  $L \times 1$  column vectors



#### ordering of unknowns

- ► actually building linear system requires global ordering of unknowns: k = 0, 1, ..., L
- $m_x = 4$  and  $m_y = 3$  case has L = 12:



- o only k = 5, 6 eqns are *not* b.c.s
- (weak) diagonal dominance: a = |2b + 2c|
- but matrix is not symmetric
- surprisingly-large condition number for small example:  $\kappa(A) = 43.16$

