

Date Submitted: 12/8/2019

Youtube Link: https://www.youtube.com/watch?v=Bq_x91CdNGs

Schematics/Images:

- Sensor (COM 7) and Collector (COM 8) Initialization on Tera Term - Task 3 on TI
15.4 Stack Project Zero:

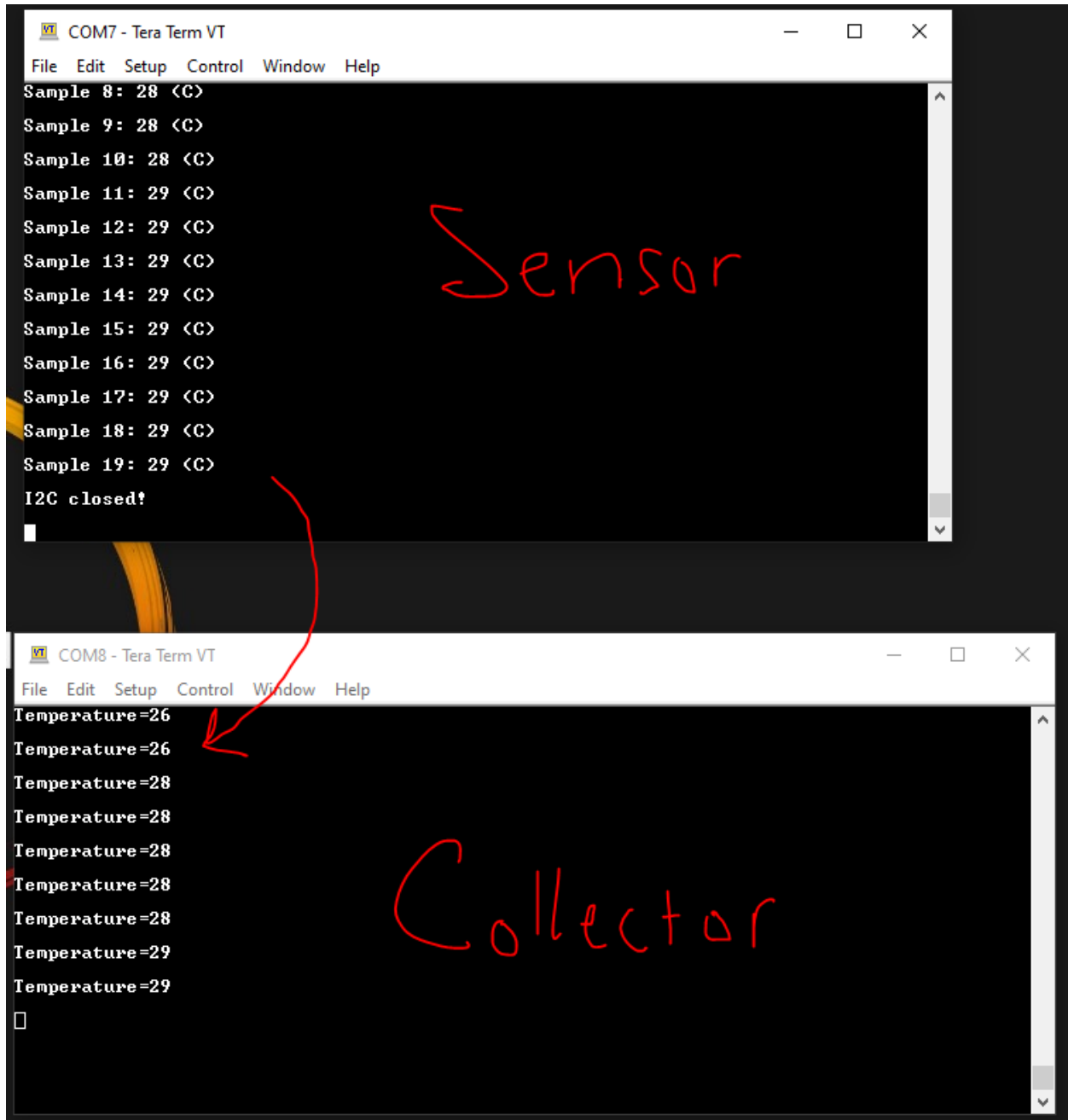
```
VT COM7 - Tera Term VT
File Edit Setup Control Window Help
LL-TI Sensor
State Changed: 1
Started: 0x1
Channel: 0
State Changed: 3
```

```
VT COM8 - Tera Term VT
File Edit Setup Control Window Help
z z ~-nPermitJoin-ON
TI Collector
Started
Channel: 0
PermitJoin-ON
Joined: 0x1
ConfigRsp: 0x1
Temperature=32
Temperature=32
Temperature=32
```

- Sensor Portable App Temperature Samples (x20) - Task 1 on Using Stack and Portable
App to Create a Remote Sensor section:

```
VT COM7 - Tera Term VT
File Edit Setup Control Window Help
Sample 8: 26 <C>
Sample 9: 26 <C>
Sample 10: 26 <C>
Sample 11: 26 <C>
Sample 12: 26 <C>
Sample 13: 26 <C>
Sample 14: 26 <C>
Sample 15: 26 <C>
Sample 16: 26 <C>
Sample 17: 27 <C>
Sample 18: 26 <C>
Sample 19: 26 <C>
```

- Using Stack to Send Sampled Temperature Values from Sensor to Collector - Task 3 on Using Stack and Portable App to Create a Remote Sensor section:



temperature.c (from sensor) :

```

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 */

/*
 * ===== i2ctmp116.c =====
 */
#include <stdint.h>
#include <stddef.h>
#include <unistd.h>
#include "smsgs.h"
#include "mac_util.h"
#include "api_mac.h"
#include "sensor.h"
extern Smsgs_tempSensorField_t tempSensor;

/* Driver Header files */
#include <ti/drivers/GPIO.h>
#include <ti/drivers/I2C.h>
#include <ti/display/Display.h>

/* Example/Board Header files */
#include "Board.h"

```

```

#define TASKSTACKSIZE      640

/*
 * ===== TMP Registers =====
 */
#define Si7021_TMP_REG      0xE3
#define Si7021_HUM_REG      0xE5

#define Si7021_ADDR         0x40;

static Display_Handle display;

/*
 * ===== mainThread =====
 */
void *mainThread(void *arg0)
{
    uint16_t      sample;
    uint16_t      temperature, temperaturef;
    uint8_t       txBuffer[1];
    uint8_t       rxBuffer[2];
    I2C_Handle     i2c;
    I2C_Params     i2cParams;
    I2C_Transaction i2cTransaction;

    /* Call driver init functions */
    Display_init();
    GPIO_init();
    I2C_init();

    /* Configure the LED and if applicable, the TMP116_EN pin */
    GPIO_setConfig(Board_GPIO_LED0, GPIO_CFG_OUT_STD | GPIO_CFG_OUT_LOW);
#ifdef Board_GPIO_TMP116_EN
    GPIO_setConfig(Board_GPIO_TMP116_EN, GPIO_CFG_OUT_STD | GPIO_CFG_OUT_HIGH);
    /* 1.5 ms reset time for the TMP116 */
    sleep(1);
#endif

    /* Open the HOST display for output */
    display = Display_open(Display_Type_UART, NULL);
    if (display == NULL) {
        while (1);
    }

    /* Turn on user LED */
    GPIO_write(Board_GPIO_LED0, Board_GPIO_LED_ON);
    Display_printf(display, 0, 0, "Starting the i2ctmp example.");

    /* Create I2C for usage */
    I2C_Params_init(&i2cParams);
    i2cParams.bitRate = I2C_400kHz;
    i2c = I2C_open(Board_I2C_TMP, &i2cParams);

```

```

if (i2c == NULL) {
    Display_printf(display, 0, 0, "Error Initializing I2C\n");
    while (1);
}
else {
    Display_printf(display, 0, 0, "I2C Initialized!\n");
}

/* Common I2C transaction setup */
i2cTransaction.writeBuf = txBuffer;
i2cTransaction.writeCount = 1;
i2cTransaction.readBuf = rxBuffer;
i2cTransaction.readCount = 2;

/* Try Si7021 */
txBuffer[0] = Si7021_TMP_REG;
i2cTransaction.slaveAddress = Si7021_ADDR;
if (!I2C_transfer(i2c, &i2cTransaction)) {
    /* Could not resolve a sensor, error */
    Display_printf(display, 0, 0, "Error. No TMP sensor found!");
    while(1);
}
else {
    Display_printf(display, 0, 0, "Detected Si7021 sensor.");
}

/* Take 20 samples and print them out onto the console */
for (sample = 0; sample < 20; sample++) {
    if (I2C_transfer(i2c, &i2cTransaction)) {
        /*
         * Extract degrees C from the received data;
         * see Si7021 datasheet
         */
        temperature = (rxBuffer[0] << 8) | (rxBuffer[1]);
        temperaturef = (((175.72 * temperature)/ 65536) - 46.85);

        Display_printf(display, 0, 0, "Sample %u: %d (C)",
                        sample, temperaturef);
    }
    else {
        Display_printf(display, 0, 0, "I2C Bus fault.");
    }

    tempSensor.objectTemp = temperaturef;
    tempSensor.ambienceTemp = temperaturef;
    Util_setEvent(&Sensor_events, EXT_SENSOR_READING_TIMEOUT_EVT);

    /* Sleep for 1 second */
    sleep(1);
}

I2C_close(i2c);
Display_printf(display, 0, 0, "I2C closed!");

return (NULL);

```

}
