Bahram Behzadian

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Research Interests Reinforcement learning, robotics.

Education

University of New Hampshire

Ph.D. candidate in Computer Science, 2019-Present

Advisor: Marek Petrik

University of New Hampshire

MSc. in Computer Science, 2015-2019

Master's thesis: Feature Selection by Singular Value Decomposition for Reinforcement Learning

Thesis advisor: Marek Petrik

TAMPERE UNIVERSITY OF TECHNOLOGY, FINLAND MSc. in Machine Automation, 2010-2013

Master's thesis: Robot Localization with Weak Maps

Thesis advisor: Wolfram Burgard

AZAD UNIVERSITY OF MASHHAD, IRAN BSc. in Mechanical Engineering, 2002-2007

Final project: HVAC design for 16,000 sq. ft cold storage warehouse

Research Experience REINFORCEMENT LEARNING AND ROBUSTNESS LAB

Research Assistant
University of New Hampshire, Durham, NH, USA

2015–Present

Projects: Optimizing the ambiguity sets for robust Markov decision processes, efficient algorithms for S-rectangular robust MDPs, and feature construction from high-dimensional raw-input observation for linear value function approximation for reinforcement learning.

AUTONOMOUS INTELLIGENT SYSTEMS LAB

Research Assistant

2012-2014

University of Freiburg, Freiburg, Germany

Project: Mobile robot localization and navigation on hand-drawn maps.

Conference Publications Behzadian, B., Petrik, M., Ho, C. P. Ho. "Fast Algorithms for L_{∞} constrained S-rectangular Robust MDPs" In Neural Information Processing Systems (NeurIPS), 2021.

Behzadian, B., Russel, R. H., Petrik, M., Ho, C. P. "Optimizing Percentile Criterion using Robust MDPs" In *International Conference on Artificial Intelligence and Statistics (AISTATS)*, 2021.

Behzadian, B., Gharatappeh, S., Petrik, M. "Fast Feature Selection for Linear Value Function Approximation" In *International Conference on Automated Planning and Scheduling*, (ICAPS), 2019.

Behzadian, B., Agarwal, P., Burgard, W., Tipaldi, G. D. "Monte Carlo localization in hand-drawn maps" In *International Conference on Intelligent Robots and Systems (IROS)*, 2015.

Boniardi, F., Behzadian, B., Burgard, W., Tipaldi, G. D. "Robot navigation in hand-drawn sketched maps." In *European Conference on Mobile Robotics*, (ECMR), 2015.

Symposiums & Workshops

Russel, R. H., Behzadian, B., Petrik, M. "Optimizing Norm-bounded Weighted Ambiguity Sets for Robust MDPs" In Neural Information Processing Systems (NeurIPS) Safety and Robustness in Decision-making Workshop, 2019.

Behzadian, B., Petrik, M., "Feature Selection by Singular Value Decomposition for Reinforcement Learning" In *International Conference on Machine Learning (ICML) Prediction and Generative Modeling Workshop*, 2018.

Behzadian, B., Petrik, M. "Low-rank Feature Selection for Reinforcement Learning" In *International Symposium on Artificial Intelligence and Mathematics*, (ISAIM), 2018.

Additional Employment ENVIO, INC.

AI Engineer Intern

Summer 2018

Dover, NH, USA

Worked on solving a vehicle routing problem designed for intermodal trucking

PERGAS POLYMER CO.

PLC Programmer / Automation Engineer

2008-2009

Tehran, Iran

Provided technical support in the troubleshooting of electrical and PLC control systems and machinery

TADBIR SANAT CONSULTING ENGINEERS

HVAC System Designer

2007-2008

Tehran, Iran

Performed calculations in mechanical systems design, selection, sizing of equipment, and interconnected HVAC, hydronic, steam, and plumbing systems

Teaching Experience University of New Hampshire

Teaching Assistant

Reinforcement Learning
Assembly Language Programming and Machine Organization
Fall 2021
Intro to Computer Science I
Intro to Computer Science II
Fom Problems to Algorithms to Programs
Fall 2017
From Programs to Computer Science
Spring and Fall 2017

Scholarships /Awards

CEPS Graduate Fellowship

2015

College of Engineering and Physical Sciences, University of New Hampshire

A prestigious award that is based on the strength of academic record and the potential for success in graduate school.

Thesis and Dissertation Fellowship

2012

Office of International Affairs, Tampere University of Technology

Technical

Programming Languages: Python; C/C++; R; Matlab.

Skills Tools: Git; LaTeX; Linux; TLA+.