let $m$ training examples, $n$ features

| Gradient Descent | Normal Equation |
|---|---|
| ⇒ Need to choose '$\alpha$' | ⇒ No need to choose '$\alpha$' |
| ⇒ Needs many iterations | ⇒ Don't need to iterate |
| ⇒ works well even when $n$ is large | ⇒ Need to compute ** $(X^TX)^{-1}$ ⇒ Slow if $n$ is very large |
| If $n \approx 10^6$ or larger | $n = 100, 1000, 10{,}000$ ⇒ might be slow (fast / reasonable) |

** If $X \Rightarrow \mathbb{R}^{m \times n+1}$ then $X^T \Rightarrow \mathbb{R}^{n+1 \times m}$

Set, $X^TX = A \Rightarrow \mathbb{R}^{n+1 \times n+1}$ $O(n^3)$ ⇒ time complexity of inverting a matrix

$(n+1 \times m) \times (m \times n+1)$ — same

Square matrix

∴, for large value of $n$ inverting a matrix is computationally expensive.

---

What if $(X^TX)$ is non-invertable? (i.e. singular matrix / degenerate matrix)

Octave: `pinv(X'*X)*X'*y`

↓ pseudo inverse

If $X^TX$ is non-invertable

⇒ Redundant features exist (i.e linearly dependent)

Eg) $x_1 = \text{size (feet}^2\text{)}$; $x_2 = \text{size (m}^2\text{)}$