

# **GNSS SDK**

# **Commands Manual**

**GNSS Module Series**

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# About the Document

## History

Revision	Date	Author	Description
1.0	2015-09-11	Hyman DING	Initial
1.1	2016-01-18	Connie ZHOU	Added the current supported SDK commands in Table 1.
1.2	2016-05-20	Simon HU	<ol style="list-style-type: none"><li>1. Added the following new commands: PQECEP, PQODO, PQPZ90, PQGLP, PQVEL.</li><li>2. Added L76 and L76-L in Table 1.</li><li>3. Added the Chapter 3: Appendix References.</li></ol>

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# 1 Introduction

Quectel GNSS modules support SDK commands which are defined and developed by Quectel. This document describes these SDK commands. The configuration parameters saved by SDK commands will still exist in flash even after upgrading the modules' firmware.

This document is applicable to Quectel L70/L76/L76-L/L80/L86 modules.

The current supported SDK commands are shown in the table below:

**Table 1: Current Supported SDK Commands**

SDK Commands	Description	L70	L80	L76	L76-L	L86
PQBAUD	Set NMEA Port Default Baudrate	Y	Y	Y	Y	Y
PQEPE	Enable/Disable PQEPE Sentence Output	Y	Y	Y	Y	Y
PQ1PPS	Set the Type and Pulse Width of 1PPS's Output	Y	Y	Y	Y	Y
PQFLP	Set the Module into FLP(Fitness Low Power) Mode	Y	Y	N	N	N
PQTXT	Enable/Disable GPTXT Sentence Output	N	Y	N	N	Y
PQECEF	Enable/Disable ECEFPOSVEL Sentence Output	N	N	Y	Y	N
PQODO	Start/Stop Odometer Reading	N	N	Y	Y	N
PQPZ90	Enable/Disable Switching from WGS84 to PZ-90.11	N	N	Y	Y	N
PQGLP	Set the Module into GLP(GNSS Low Power) Mode	N	N	Y	Y	N
PQVEL	Enable/Disable 3 Ways Velocity Sentence Output	N	N	Y	Y	N

## NOTES

1. Y means supported; N means not supported.
2. For more details about the usage of PQFLP and PQGLP commands, please refer to **document [1]**.

## 2 Quectel NMEA Packet Protocol

This chapter introduces the Quectel NMEA packet protocol which is a set of extension messages of the standard NMEA packet protocol. These messages are used to control and configure Quectel L70/L76/L76-L/L80/L86 modules.

The structure of Quectel NMEA packet is shown as below:

### 2.1. Quectel NMEA Packet Format

Preamble	TalkerID	PktType	DataField	*	CHK1	CHK2	CR	LF
----------	----------	---------	-----------	---	------	------	----	----

\*The maximum length of each packet is restricted to 255 bytes.

Packet Contents:

Preamble: One byte character.

‘\$’

TalkerID: Two bytes character string.

“PQ”

PktType: 1-10 bytes character string.

An identifier used to tell the decoder how to decode the packet.

DataField: The DataField has variable lengths depending on the packet type.

A command symbol ‘,’ must be inserted ahead of each data field to help the decoder process the DataField.

\* : 1 byte character.

The star symbol is used to mark the end of DataField.

CHK1,CHK2: Two bytes character string.

CHK1 and CHK2 are the check sum of the data between Preamble and ‘\*’.

CR,LF: Two bytes binary data.

The two bytes are used to identify the end of a packet.

## 2.2. PQBAUD Change NMEA Port Default Baudrate

### PQBAUD Change NMEA Port Default Baudrate

Write Command <b>\$PQBAUD,W,&lt;baudrate&gt;*Checksum&lt;CR&gt;&lt;LF&gt;</b>	Response <b>\$PQBAUD,W,OK*Checksum&lt;CR&gt;&lt;LF&gt;</b>  If error <b>\$PQBAUD,W,ERROR*Checksum&lt;CR&gt;&lt;LF&gt;</b>
Reference	

#### Parameter

<b>&lt;baudrate&gt;</b>	NMEA port baudrate. 9600 by default; could be set to 4800, 14400, 19200, 38400, 57600 and 115200
-------------------------	---

#### Example

```
$PQBAUD,W,115200*43 //Change NMEA port default baudrate to 115200
$PQBAUD,W,OK*40 //Set OK
```

#### NOTES

1. The command will be effective immediately after setting.
2. Parameter is automatically saved.
3. If you change the baudrate, then there is no response returned in the current baudrate.

## 2.3. PQEPE Enable/Disable PQEPE Sentence Output

The packet enables/disables output of the URC including EPE data, that is, estimated horizontal and vertical position errors.

### PQEPE Enable/Disable PQEPE Sentence Output

Write Command <b>\$PQEPE,W,&lt;mode&gt;,&lt;save&gt;*Checksum&lt;CR&gt;&lt;LF&gt;</b>	Response <b>\$PQEPE,W,OK*Checksum&lt;CR&gt;&lt;LF&gt;</b>  If error <b>\$PQEPE,W,ERROR*Checksum&lt;CR&gt;&lt;LF&gt;</b>
URC Message	<b>\$PQEPE,&lt;EPE_hori&gt;,&lt;EPE_vert&gt;*Checksum&lt;CR&gt;&lt;LF&gt;</b>



	Parameter
	<EPE_hori> Estimated horizontal position error
	<EPE_vert> Estimated vertical position error
	Example
	\$PQEPE,5.3050,3.2000*53
Reference	

## Parameter

<mode>	Operation
	0 Disable the URC including EPE data
	1 Enable the URC including EPE data
<save>	Save operation
	0 Parameter is not saved, ineffective after restart
	1 Parameter is saved in flash, effective after restart

## Example

```
$PQEPE,W,1,1*2A //Enable the URC including EPE data, and save parameter in flash
$PQEPE,W,OK*02 //Set OK
```

### NOTE

The command will be effective immediately after setting.

## 2.4. PQ1PPS Set the Type and Pulse Width of 1PPS's Output

### PQ1PPS Set the Type and Pulse Width of 1PPS's Output

Write Command	Response
\$PQ1PPS,W,<type>,<width>*Checksum<CR><LF>	\$PQ1PPS,W,OK*Checksum<CR><LF>
	If error
	\$PQ1PPS,W,ERROR*Checksum<CR><LF>
Reference	

## Parameter

<b>&lt;type&gt;</b>	The type of 1PPS's output 0 Disable 1PPS output 1 Send 1PPS after the first fix 2 Send 1PPS after 3D fix 3 Send 1PPS after 2D fix 4 Send 1PPS always
<b>&lt;width&gt;</b>	PPS pulse width in millisecond Range: 2-998

## Example

```
$PQ1PPS,W,4,100*1D //Set the type of 1PPS's output and PPS pulse width
$PQ1PPS,W,OK*30 //Set OK
$PQ1PPS,W,0,0*18 //Disable 1PPS output
$PQ1PPS,W,OK*30 //Set OK
```

## NOTES

1. The command will be effective immediately after setting.
2. Parameter is automatically saved.
3. If **<type>** is set as 0, **<width>** could be set as 0, 1, 2-998.

## 2.5. PQFLP Set the Module into FLP Mode

### PQFLP Set the Module into FLP Mode

Write Command \$PQFLP,W,<mode>,<save>*Checksum m<CR><LF>	Response \$PQFLP,W,OK*Checksum<CR><LF>  If error \$PQFLP,W,ERROR*Checksum<CR><LF>
Read Command \$PQFLP,R*Checksum<CR><LF>	Response \$PQFLP,R,<mode>*Checksum<CR><LF>
Reference	

## Parameter

<b>&lt;mode&gt;</b>	Module operation mode 0 Normal mode
---------------------	--

	1	FLP mode
<save>		Save operation
	0	Parameter is not saved, ineffective after restart
	1	Parameter is saved in flash, effective after restart

### Example

```
$PQFLP,W,1,1*20 //Change to FLP mode
$PQFLP,W,OK*08 //Set OK

$PQFLP,R*25 //Read mode
$PQFLP,R,1*38 //Read OK, FLP mode enabled
```

### NOTE

The command will be effective immediately after setting.

## 2.6. PQTXT Enable/Disable GPTXT Sentence Output

### PQTXT Enable/Disable GPTXT Sentence Output

Write Command	Response
\$PQTXT,W,<mode>,<save>*Checksum<CR><LF>	\$PQTXT,W,OK*Checksum<CR><LF>
m <CR><LF>	If error
	\$PQTXT,W,ERROR*Checksum<CR><LF>
URC Message	\$GPTXT,01,01,02,<status>*Checksum<CR><LF>
	Parameter
	<status> Status of antenna
	ANTSTATUS=OK: antenna is well connected
	ANTSTATUS=OPEN: antenna has been disconnected
	ANTSTATUS=SHORT: antenna is short-circuited
	Example
	\$GPTXT,01,01,02,ANTSTATUS=OK*3B
Reference	

## Parameter

<mode>	Operation
	0    Disable GPTXT sentence output 1    Enable GPTXT sentence output
<save>	Save operation
	0    Parameter is not saved, ineffective after restart 1    Parameter is saved in flash, effective after restart

## Example

```
$PQTXT,W,1,1*22      //Enable GPTXT sentence output and save parameter in flash
$PQTXT,W,OK*0A        //Set OK
```

### NOTE

The command will be effective immediately after setting.

## 2.7. PQECEF Enable/Disable ECEFPOSVEL Sentence Output

PQECEF    Enable/Disable ECEFPOSVEL Sentence Output	
Write Command \$PQECEF,W,<mode>,<save>*ChkSum<CR><LF>	Response \$PQECEF,W,OK*ChkSum<CR><LF>  If error \$PQECEF,W,ERROR*ChkSum<CR><LF>
Read Command \$PQECEF,R*ChkSum<CR><LF>	Response \$PQECEF,R,<mode>*ChkSum<CR><LF>
URC Message	\$ECEFPOSVEL,<time>,<x>,<y>,<z>,<v_x>,<v_y>,<v_z>*ChkSum<CR><LF>  Parameter <div> <div>&lt;time&gt;</div> <div>UTC from the internal real-time clock</div> </div> <div> <div>&lt;x&gt;</div> <div>the value of X axis in ECEF</div> </div> <div> <div>&lt;y&gt;</div> <div>the value of Y axis in ECEF</div> </div> <div> <div>&lt;z&gt;</div> <div>the value of Z axis in ECEF</div> </div> <div> <div>&lt;v_x&gt;</div> <div>velocity component of X axis in ECEF</div> </div> <div> <div>&lt;v_y&gt;</div> <div>velocity component of Y axis in ECEF</div> </div> <div> <div>&lt;v_z&gt;</div> <div>velocity component of Z axis in ECEF</div> </div>

	Example \$ECEFPOSVEL,052743.000,-1526672.867459,6191083.982 801,143008.780911,0,0,0*14
Reference	

## Parameter

<mode>	Operation 0 Disable ECEFPOSVEL sentence output 1 Enable ECEFPOSVEL sentence output
<save>	Save operation 0 Parameter is not saved, ineffective after restart 1 Parameter is saved in flash, effective after restart

## Example

```
$PQCECF,W,1,1*7F // Enable ECEFPOSVEL sentence output, and save parameter in flash
$PQCECF,W,OK*57 // Set OK
$PQCECF,R*7A // Read mode
$PQCECF,R,1*67 // Read OK, ECEFPOSVEL sentence output enabled
```

### NOTE

The command will be effective immediately after setting.

## 2.8. PQODO Start/Stop Odometer Reading

PQODO Start/Stop Odometer Reading	
Write Command \$PQODO,W,<mode>*ChkSum<CR><LF> F>	Response \$PQODO,W,OK*ChkSum<CR><LF>  If error \$PQODO,W,ERROR*ChkSum<CR><LF>
Read Command \$PQODO,R*ChkSum<CR><LF>	Response \$PQODO,R,<mode>*ChkSum<CR><LF>  If error \$PQODO,R,ERROR*ChkSum<CR><LF>
Query Command	Response

\$PQODO,Q*ChkSum<CR><LF>	\$PQODO,Q,<distance>*ChkSum<CR><LF>
	If error \$PQODO,Q,ERROR*ChkSum<CR><LF>
Reference	

## Parameter

<mode>	Start or stop odometer reading 0 Stop odometer reading and remember the distance value. 1 Start odometer reading and initialize the distance as 0.
<distance>	Current distance. Unit: meter.

## Example

```
$PQODO,W,1*23 // Start odometer reading
$PQODO,W,OK*16 // Set OK
$PQODO,R*3B // Read mode
$PQODO,R,1*26 // Read OK, odometer reading has already been started
$PQODO,Q*38 // Query the distance value
$PQODO,Q,123.45*0B // Current distance value returned
```

## NOTES

1. The command will be effective immediately after setting.
2. If you want to clear the distance value when the odometer reading function is on, you must stop the function first, and then re-start it.
3. The module automatically stops odometer reading after restart. **\$PQODO,W,1\*23** must be executed again to re-start odometer reading.

## 2.9. PQPZ90 Enable/Disable Switching from WGS84 to PZ-90.11

### PQPZ90 Enable/Disable Switching from WGS84 to PZ-90.11

Write Command	Response
\$PQPZ90,W,<mode>,<save>*ChkSum<CR><LF>	\$PQPZ90,W,OK*ChkSum<CR><LF>
	If error \$PQPZ90,W,ERROR*ChkSum<CR><LF>
Read Command	Response

\$PQPZ90,R*ChkSum<CR><LF>	\$PQPZ90,R,<mode>*ChkSum<CR><LF>
URC Message	\$GNDTM,P90,x,xx.xxxx,x,xx.xxxx,x,xxx,W84*hh<CR><LF> >  Parameter definition is available in Table 4.
Reference	Appendix 3.3

## Parameter

<mode>	Operation 0 Disable switching from WGS84 to PZ-90.11 1 Enable switching from WGS84 to PZ-90.11
<save>	Save operation 0 Parameter is not saved, ineffective after restart 1 Parameter is saved in flash, effective after restart

## Example

```
$PQPZ90,W,1,1*79 // Enable switching from WGS84 to PZ-90.11, and save parameter into flash
$PQPZ90,W,OK*51 // Set OK
$PQPZ90,R*7C // Read mode
$PQPZ90,R,0*60 // Read OK, switching from WGS84 to PZ-90.11 enabled
```

## NOTES

1. The command will be effective immediately after setting <save> to 0. However, when <save> is set to 1, it will be effective only after restart.
2. If switching from WGS84 to PZ-90.11 is enabled and effective, the coordinate values in RMC and GGA sentences will be switched to PZ-90.11 after fixing. Also, a DTM sentence will be displayed to identify the datum used.

## 2.10. PQGLP Set the Module into GLP Mode

### PQGLP Set the Module into GLP Mode

Write Command	Response
\$PQGLP,W,<mode>,<save>*ChkSum<CR><LF>	\$PQGLP,W,OK*ChkSum<CR><LF>
	If error \$PQGLP,W,ERROR*ChkSum<CR><LF>

Read Command \$PQGLP,R*ChkSum<CR><LF>	Response \$PQGLP,R,<mode>*ChkSum<CR><LF>
Reference	

## Parameter

<mode>	Module operation mode 0 Normal mode 1 GLP mode
<save>	Save operation 0 Parameter is not saved, ineffective after restart 1 Parameter is saved in flash, effective after restart

## Example

```
$PQGLP,W,1,1*21 // Change to GLP mode
$PQGLP,W,OK*09 // Set OK

$PQGLP,R*24 // Read mode
$PQGLP,R,1*39 // Read OK, GLP mode enabled
```

### NOTE

The command will be effective immediately after setting.

## 2.11. PQVEL Enable/Disable 3 Ways Velocity Sentence Output

PQVEL Enable/Disable 3 Ways Velocity Sentence Output	
Write Command \$PQVEL,W,<mode>,<save>*ChkSum <CR><LF>	Response \$PQVEL,W,OK*ChkSum<CR><LF>  If error \$PQVEL,W,ERROR*ChkSum<CR><LF>
Read Command \$PQVEL,R*ChkSum<CR><LF>	Response \$PQVEL,R,<mode>*ChkSum<CR><LF>
URC Message	\$PQVEL,<north_vel>,<east_vel>,<down_vel>*ChkSum<CR><LF>  Parameter



	<north_vel>	North velocity
	<east_vel>	East velocity
	<down_vel>	Down velocity
	Example	
	\$PQVEL,1.000000,2.000000,-0.000000*42	
Reference		

## Parameter

<mode>	Enable/disable 3 ways velocity sentence output
	0 Disable 1 Enable
<save>	Save operation
	0 Parameter is not saved, ineffective after restart 1 Parameter is saved in flash, effective after restart

## Example

```
$PQVEL,W,1,1*25 // Enable 3 ways velocity sentence output
$PQVEL,W,OK*0D // Set OK

$PQVEL,R*20 // Read mode
$PQVEL,R,1*3D // Read OK, 3 ways velocity sentence output enabled
```

### NOTE

The command will be effective immediately after setting.

## 3 Appendix References

### 3.1. Related Documents

Table 2: Related Documents

SN	Document Name	Remark
[1]	Quectel_GNSS_Low_Power_Mode_Application_Note	GNSS Low Power Mode Application Note

### 3.2. Terms and Abbreviations

Table 3: Terms and Abbreviations

Abbreviation	Description
1PPS	1 Pulse Per Second
ECEF	Earth-Centered, Earth-Fixed
EPE	Estimated Position Error
FLP	Fitness Low Power
GGA	Global Positioning System Fixed Data
GLL	Geographic Position – Latitude/Longitude
GLP	GNSS Low Power
GNSS	Global Navigation Satellite System
GPS	Global Positioning System
GSA	GNSS DOP and Active Satellites
GSV	GNSS Satellites in View

HDOP	Horizontal Dilution of Precision
NMEA	National Marine Electronics Association
ODO	Odometer
PDOP	Position Dilution of Precision
PZ90	Parametry Zemli 1990
RMC	Recommended Minimum Specific GNSS Data
URC	Unsolicited Result Code
VDOP	Vertical Dilution of Precision
VEL	Velocity
VTG	Course Over Ground and Ground Speed
ZDA	Time and Date

### 3.3. Datum Sentence Definition

The datum sentence definition for \$GNDTM,xxx,x,xx.xxxx,x,xx.xxxx,x,xxx,xxx\*hh<CR><LF> is illustrated below:

**Table 4: Datum Sentence Definition**

Field	Meaning
1	Local datum code (xxx): W84 – WGS84 W72 – WGS72 S85 – SGS85 P90 – PZ-90
2	Local datum sub code (x)
3	Latitude offset in minutes (xx.xxxx)
4	Latitude offset mark (N: +, S: -) (x)
5	Longitude offset in minutes (xx.xxxx)
6	Longitude offset mark (E: +, W: -) (x)

---

7	Altitude offset in meters.
<hr/>	
8	Datum (xxx):
	W84 – WGS84
	W72 – WGS72
	S85 – SGS85
9	P90 – PZ-90
	Checksum

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