

Error Analysis Assignment

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1 Significant figures

1.1 Determine the significant figures In this part, we are asked to determine the number of significant figures for the following numbers

numbers	number of significant figures
1.00101	6
1.0110×10^{-3}	5
0.0010011	5
3.140	4
1670.	4
1.68×10^4	3

1.2 Significant figures in calculations In this part, we are asked to express the results of the following calculations with the correct significant figures

calculations	results	results with correct significant figures
$3.1416 \times 0.28 / 2.34$	0.375917949 ...	0.38
$123.62 + 7.1 - 5.33$	125.39	125.4

2 Propagation of Uncertainty (Error)

In this part, we are asked to find the standard error σ_x in $x = f(u, v)$ as a function of the errors in σ_u and σ_v for the following functions:

- $x = u + v \Rightarrow \frac{\partial f}{\partial u} = 1, \frac{\partial f}{\partial v} = 1$

$$\sigma_x = \sqrt{\left(\frac{\partial f}{\partial u}\right)^2 \sigma_u^2 + \left(\frac{\partial f}{\partial v}\right)^2 \sigma_v^2} = \sqrt{1^2 \sigma_u^2 + 1^2 \sigma_v^2} = \sqrt{\sigma_u^2 + \sigma_v^2}$$

- $x = uv \Rightarrow \frac{\partial f}{\partial u} = v, \frac{\partial f}{\partial v} = u$

$$\sigma_x = \sqrt{\left(\frac{\partial f}{\partial u}\right)^2 \sigma_u^2 + \left(\frac{\partial f}{\partial v}\right)^2 \sigma_v^2} = \sqrt{v^2 \sigma_u^2 + u^2 \sigma_v^2} = x \sqrt{\left(\frac{\sigma_u}{u}\right)^2 + \left(\frac{\sigma_v}{v}\right)^2}$$

- $x = \frac{u}{v} \Rightarrow \frac{\partial f}{\partial u} = \frac{1}{v}, \frac{\partial f}{\partial v} = -\frac{u}{v^2}$

$$\sigma_x = \sqrt{\left(\frac{\partial f}{\partial u}\right)^2 \sigma_u^2 + \left(\frac{\partial f}{\partial v}\right)^2 \sigma_v^2} = \sqrt{\left(\frac{1}{v}\right)^2 \sigma_u^2 + \left(\frac{-u}{v^2}\right)^2 \sigma_v^2} = x \sqrt{\left(\frac{\sigma_u}{u}\right)^2 + \left(\frac{\sigma_v}{v}\right)^2}$$

- $x = uv^2 \Rightarrow \frac{\partial f}{\partial u} = v^2, \frac{\partial f}{\partial v} = 2uv$

$$\sigma_x = \sqrt{\left(\frac{\partial f}{\partial u}\right)^2 \sigma_u^2 + \left(\frac{\partial f}{\partial v}\right)^2 \sigma_v^2} = \sqrt{(v^2)^2 \sigma_u^2 + (2uv)^2 \sigma_v^2} = x \sqrt{\left(\frac{\sigma_u}{u}\right)^2 + \left(\frac{2\sigma_v}{v}\right)^2}$$

- $x = ue^{cv} \Rightarrow \frac{\partial f}{\partial u} = e^{cv}, \frac{\partial f}{\partial v} = cue^{cv}$

$$\sigma_x = \sqrt{\left(\frac{\partial f}{\partial u}\right)^2 \sigma_u^2 + \left(\frac{\partial f}{\partial v}\right)^2 \sigma_v^2} = \sqrt{(e^{cv})^2 \sigma_u^2 + (cue^{cv})^2 \sigma_v^2} = x \sqrt{\left(\frac{\sigma_u}{u}\right)^2 + (c\sigma_v)^2}$$

- $x = \frac{1}{u} \Rightarrow \frac{\partial f}{\partial u} = -\frac{1}{u^2}, \frac{\partial f}{\partial v} = 0$

$$\sigma_x = \sqrt{\left(\frac{\partial f}{\partial u}\right)^2 \sigma_u^2 + \left(\frac{\partial f}{\partial v}\right)^2 \sigma_v^2} = \sqrt{\left(-\frac{1}{u^2}\right)^2 \sigma_u^2} = x^2 \sigma_u$$

3 Snell's Law

According to Snell's law, the incident angle θ_1 of a ray traveling in a medium of index n_1 to the refraction angle θ_2 of the same light ray in the medium of refraction index n_2 relates with equation $n_1 \sin \theta_1 = n_2 \sin \theta_2$.

In this part, we are asked to find n_2 and its uncertainty from the following measurements:

$$\theta_1 = 22.0^\circ \pm 0.2^\circ$$

$$\theta_2 = 16.3^\circ \pm 0.2^\circ$$

$$n_1 = 1.000$$

$$n_2 = \frac{n_1 \sin \theta_1}{\sin \theta_2} = 1.3347 \dots = 1.33$$

$$\begin{aligned} \delta n_2 &= \sqrt{\left(\frac{\partial \sin \theta_1}{\partial \theta_1}\right)^2 \delta \theta_1^2 + \left(\frac{\partial \sin \theta_1}{\partial \theta_2}\right)^2 \delta \theta_2^2} = \sqrt{\left(\frac{\cos \theta_1}{\sin \theta_2}\right)^2 \delta \theta_1^2 + \left(-\frac{\sin \theta_1 \cos \theta_2}{\sin^2 \theta_2}\right)^2 \delta \theta_2^2} = \\ &\frac{n_2}{n_1} \sqrt{\left(\frac{\cos \theta_1}{\sin \theta_1}\right)^2 \delta \theta_1^2 + \left(\frac{\cos \theta_2}{\sin \theta_2}\right)^2 \delta \theta_2^2} = 0.019598 \dots = 0.02 \\ \Rightarrow n_2 &= 1.33 \pm 0.02 \end{aligned}$$

4 Simple Pendulum

To determine the acceleration of gravity, we can measure the oscillation period T of a pendulum with length L and use equation $g = \frac{4\pi^2 L}{T^2}$.

In this part, we are asked to determine the value and uncertainty of g from the following measurements:

$$T = 2.01 \pm 0.02 \text{ s}$$

$$L = 1.000 \pm 0.002 \text{ m}$$

$$g = \frac{4\pi^2 L}{T^2} = 9.7716 \dots \frac{\text{m}}{\text{s}^2} = 9.77 \frac{\text{m}}{\text{s}^2}$$

$$\begin{aligned} \delta g &= \sqrt{\left(\frac{\partial \frac{4\pi^2 L}{T^2}}{\partial T}\right)^2 \delta T^2 + \left(\frac{\partial \frac{4\pi^2 L}{T^2}}{\partial L}\right)^2 \delta L^2} = \sqrt{\left(-\frac{8\pi^2 L}{T^3}\right)^2 \delta T^2 + \left(\frac{4\pi^2}{T^2}\right)^2 \delta L^2} = \\ g \sqrt{\left(\frac{2}{T}\right)^2 \delta T^2 + \left(\frac{1}{L}\right)^2 \delta L^2} &= 0.19541 \dots \frac{\text{m}}{\text{s}^2} = 0.2 \frac{\text{m}}{\text{s}^2} \\ \Rightarrow g &= (9.77 \pm 0.2) \frac{\text{m}}{\text{s}^2} \end{aligned}$$

From the derived formula, the uncertainty of the gravity acceleration is dominated by the uncertainty measure of T (at least by its coefficient compared to the uncertainty measure of L). In order to improve the measurement, we have to reduce the uncertainty of T (δT).