

# Yohandi - Assignment 10

10)  $I = \frac{2}{3}MR^2$

$v_{com} = \omega R$

a.  $K_T + K_R = K$

$\frac{1}{2}mv_{com}^2 + \frac{1}{2}I\omega^2 = 20 J$

$\frac{1}{2}(M\omega^2R^2 + \frac{2}{3}M\omega^2R^2) = 20 J$

$M\omega^2R^2 = \frac{20 \cdot 6}{5} J$

$M\omega^2R^2 = 24 J$

$K_R = \frac{1}{2}I\omega^2 = \frac{1}{3}M\omega^2R^2 = \boxed{8 J}$

b.  $K_T = \frac{1}{2}mv_{com}^2 = 20 J - 8 J$

$mv_{com}^2 = 24 J$

$v_{com} = \sqrt{\frac{24}{M}} \text{ m/s}$

$= \sqrt{24 \cdot \frac{2R^2}{3I}} \text{ m/s}$

$= \boxed{2.74 \text{ m/s}}$

c.  $\Delta K = -\Delta U = -Mgh = -Mgx \sin \theta$

$= -\frac{2R^2}{3I} \cdot 98.1 \cdot \frac{1}{2} J$

$= -15.68 J$

$K_f = K_i + \Delta K = (20 - 15.68 J) \text{ J/s}$

$= \boxed{4.32 J}$

d.  $V_{com} = \omega R = \frac{5}{6}M\omega^2R^2 = 4.32 J$

$\omega^2R^2 = 1.62 \text{ m}^2/\text{s}^2$

$V_{com} = \omega R = \boxed{1.27 \text{ m/s}}$

12) at the top of the loop, the ball loses its energy potential (converted to kinetic energy)

$U_i = U_f + K_f$

$mgh = mg2R + \frac{1}{2}I\omega^2 + \frac{1}{2}mv^2$

$2mgh(h-2R) = \frac{2}{5}m\omega^2R^2 + \frac{1}{2}m\omega^2R^2$

$\frac{10g}{7} \frac{7R^2}{10} (h-2R) = \omega^2R^2 = v^2 \dots (1)$

note that the normal force is = 0 when the ball is almost "fall"

$\Sigma F = W$

$\frac{mv^2}{R} - 0 = mg$

$v^2 = gR \dots (2)$

(2)  $\rightarrow (1)$ :

$\frac{10g}{7} \frac{7R^2}{10} (h-2R) = gR$

$h = \frac{27}{10} R$

2)  $h = 32.4 \text{ cm} = 0.324 \text{ m}$

b)  $U_i = U_f + K_f$

$mgh = mgR + \frac{1}{2}I\omega^2 + \frac{1}{2}mv^2$

$2g(h-R) = \frac{2}{5}\omega^2R^2 + \omega^2R^2$

$2g(h-R) = \frac{7}{5}\omega^2R^2 = \frac{7}{5}v^2$

$v^2 = \frac{10}{7}g(h-R)$

$v = \sqrt{\frac{10g}{7}(h-R)} = \boxed{2.898 \text{ m/s}}$

Force component of the horizontal:

$F_c = \frac{mv^2}{R} = \frac{0.320 \cdot 10^{-3} (2.898)^2}{12 \cdot 10^{-2}} \text{ N}$

$F_c = \boxed{0.0224 \text{ N}}$

c)  $\leftarrow$  (to the left)

15) a)  $V_{com} = \omega R = \boxed{0.11 \omega}$

b)  $F_{net} = m \cdot a_{com}$

$-\mu mg = m \cdot a_{com}$

$a_{com} = -\mu \cdot g = -0.21 \cdot 98 \text{ m/s}^2 = \boxed{-2.058 \text{ m/s}^2}$

c)  $I\alpha = \tau_{net}$

$\frac{2}{5}MR^2\alpha = -\mu mgR$

$\alpha = -\frac{5\mu g}{2R} = \boxed{-46.77 \text{ rad/s}^2}$

d)  $\omega = \omega_0 + \alpha t \dots (1)$

$v = v_0 + at \dots (2)$

(2)

$\omega R = 8.5 - 2.058t$

$\omega = \frac{8.5 - 2.058t}{0.11} \text{ rad/s} \dots (3)$

(3)  $\rightarrow$  (1)

$\frac{8.5 - 2.058t}{0.11} = 0 + 46.77t$

$8.5 = (0.11 \cdot 46.77 + 2.058)t$

$t = \boxed{1.185}$

$$e) x = v_0 t + \frac{1}{2} a t^2$$

$$x = 8.5 \cdot 1.18 + \frac{1}{2} (-2.058) 1.18^2 \text{ m}$$

$$\boxed{x = 8.60 \text{ m}}$$

$$f) v = \omega R$$

$$v = (\omega_0 + \alpha t) R$$

$$v = \alpha t R$$

$$v = (46.77 \cdot 1.18) (0.1) \text{ m/s}$$

$$\boxed{v = 6.07 \text{ m/s}}$$

$$22) \vec{r} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 2 & -3 & 2 \\ F_x & 7 & -6 \end{vmatrix} \text{ Nm}$$

$$= 4\hat{i} + (-12 - 2F_x)\hat{j} + (14 + 3F_x)\hat{k} \text{ Nm}$$

$$\boxed{F_x = -5 \text{ N}}$$

$$31) a) \boxed{L = 0} \text{ (at the top } v_{\text{ball}} = 0)$$

$$b) L = m(\vec{r} \times \vec{v})$$

$$L = 0.4 \left( \left( 2, \frac{v^2}{4g} \right) \times \left( 0, -\frac{v}{\sqrt{2}} \right) \right)$$

$$\boxed{L = -16\sqrt{2} \text{ kg m}^2/\text{s}}$$

$$c) \vec{\tau} = \vec{r} \times \vec{F}$$

$$\vec{\tau} = \left( 2, \frac{v^2}{2g} \right) \times (0, -mg)$$

$$\boxed{\vec{\tau} = -7.84 \text{ Nm}}$$

$$d) \vec{\tau} = \vec{r} \times \vec{F}$$

$$\vec{\tau} = \left( 2, \frac{v^2}{4g} \right) \times (0, -mg)$$

$$\boxed{\vec{\tau} = -7.84 \text{ Nm}}$$

$$30) a) \bar{\tau}_{\text{avg}} = \frac{\Delta L}{\Delta t} = \frac{0.8 - 3}{1.5} \text{ Nm}$$

$$= -1.467 \text{ Nm}$$

$$b) \theta = \omega_0 t + \frac{1}{2} \alpha t^2$$

$$= \frac{L_i}{I} t + \frac{1}{2} \frac{\bar{\tau}}{I} t^2$$

$$\boxed{20.36 \text{ rad}}$$

$$c) \text{Work} = \vec{\tau} \cdot \theta = (-1.467)(20.36) \text{ J}$$

$$= \boxed{-29.86 \text{ J}}$$

$$d) P = \frac{W}{\Delta t} = \frac{29.86 \text{ J}}{1.5 \text{ s}} = \boxed{+19.91 \text{ watt}}$$

$$52) a) L_i = L_f$$

$$I_i \omega_i = I_f \omega_f$$

$$\omega_f = \frac{I_i}{I_f} \omega_i$$

$$= \left( \frac{\frac{1}{2} 4m R^2 + m R^2}{\frac{1}{2} 4m R^2 + \frac{1}{4} m R^2} \right) \cdot 0.320 \text{ rad/s}$$

$$= \boxed{0.4267 \text{ rad/s}}$$

$$b) \frac{K_f}{K_o} = \frac{\frac{1}{2} I_f \omega_f^2}{\frac{1}{2} I_i \omega_i^2} = \frac{I_i}{I_f} \cdot \frac{4}{3} = 1.333$$

c) the energy required for the cockroach to move from the edge to half the center of disc

$$61)$$

$$L_i = L_f$$

$$I_i \omega_i = I_f \omega_f$$

$$\omega_f = \frac{I_i}{I_f} \omega_i = \frac{(0.12)}{(0.12 + 0.2 \cdot 0.67)} \cdot 2.4 \text{ rad/s}$$

$$\boxed{\omega_f = 1.5 \text{ rad/s}}$$