

- Q1. • False  
• True  
• False

counter example:

$$A = \begin{bmatrix} 1 & 1 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

• True  
RHS:  $A^2 - AI + IA - I^2 = A^2 - I^2$   
• False  
LHS:  $A^2 + AB + BA + B^2 \neq A^2 + 2AB + B^2$

Q2. define  $S_i$  as the solution set of  $i$ -th linear system (i.e.  $S_i = \{x_i, y_i, z_i\}$ )

$$\rightarrow \left[ \begin{array}{ccc|c} 1 & -1 & 2 & 1 \\ 2 & 1 & 1 & 8 \\ 1 & 1 & 0 & 5 \end{array} \right] \xrightarrow{\substack{R_2 = R_2 - 2R_1 \\ R_3 = R_3 - R_1}} \left[ \begin{array}{ccc|c} 1 & -1 & 2 & 1 \\ 0 & 3 & -3 & 6 \\ 0 & 2 & -2 & 4 \end{array} \right] \dots$$

$$\xrightarrow{R_2 = \frac{1}{3}R_2} \left[ \begin{array}{ccc|c} 1 & -1 & 2 & 1 \\ 0 & 1 & -1 & 2 \\ 0 & 2 & -2 & 4 \end{array} \right] \xrightarrow{R_3 = R_3 - 2R_2} \left[ \begin{array}{ccc|c} 1 & -1 & 2 & 1 \\ 0 & 1 & -1 & 2 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$S_1 = \{3-t, 2+t, t \mid t \in \mathbb{R}\}$$

$$\rightarrow \left[ \begin{array}{ccc|c} 1 & 1 & 0 & 5 \\ 1 & 0 & 1 & 3 \\ 0 & 1 & -1 & 2 \end{array} \right] \xrightarrow{R_2 \leftrightarrow R_3} \left[ \begin{array}{ccc|c} 1 & 1 & 0 & 5 \\ 0 & 1 & -1 & 2 \\ 1 & 0 & 1 & 3 \end{array} \right] \dots$$

$$\xrightarrow{R_3 = R_3 - R_1 + R_2} \left[ \begin{array}{ccc|c} 1 & 1 & 0 & 5 \\ 0 & 1 & -1 & 2 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$$S_2 = \{3-t, 2+t, t \mid t \in \mathbb{R}\}$$

since  $S_1 = S_2$ , the linear systems are equivalent

Q3. 1)  $\left[ \begin{array}{cccc} 4 & 5 & 3 & 3 & 4 \\ 2 & 3 & 1 & 0 & 1 \\ 3 & 4 & 2 & 1 & 1 \end{array} \right]$

$$\left[ \begin{array}{cccc|c} 4 & 5 & 3 & 3 & 4 & -5 \\ 2 & 3 & 1 & 0 & 1 & -3 \\ 3 & 4 & 2 & 1 & 1 & -1 \end{array} \right]$$

2)  $\left[ \begin{array}{cccc|c} 4 & 5 & 3 & 3 & 4 & -5 \\ 2 & 3 & 1 & 0 & 1 & -3 \\ 3 & 4 & 2 & 1 & 1 & -1 \end{array} \right] \dots$

$$\xrightarrow{\substack{R_2 = 2R_2 \\ R_3 = 4R_3}} \left[ \begin{array}{cccc|c} 4 & 5 & 3 & 3 & 4 & -5 \\ 4 & 6 & 2 & 0 & 2 & -6 \\ 12 & 16 & 8 & 4 & 4 & -4 \end{array} \right] \dots$$

$$\xrightarrow{\substack{R_2 = R_2 - R_1 \\ R_3 = R_3 - 3R_1}} \left[ \begin{array}{cccc|c} 4 & 5 & 3 & 3 & 4 & -5 \\ 0 & 1 & -1 & -3 & -2 & -1 \\ 0 & 1 & -1 & -5 & -8 & 11 \end{array} \right] \dots$$

$$\xrightarrow{R_3 = R_3 - R_2} \left[ \begin{array}{cccc|c} 4 & 5 & 3 & 3 & 4 & -5 \\ 0 & 1 & -1 & -3 & -2 & -1 \\ 0 & 0 & 0 & -2 & -6 & 12 \end{array} \right] \dots$$

$$\xrightarrow{R_3 = -\frac{1}{2}R_3} \left[ \begin{array}{cccc|c} 4 & 5 & 3 & 3 & 4 & -5 \\ 0 & 1 & -1 & -3 & -2 & -1 \\ 0 & 0 & 0 & 1 & 3 & -6 \end{array} \right] \dots$$

$$\xrightarrow{\substack{R_1 = R_1 - 3R_3 \\ R_2 = R_2 + 3R_3}} \left[ \begin{array}{cccc|c} 4 & 5 & 3 & 0 & -5 & 13 \\ 0 & 1 & -1 & 0 & 7 & -19 \\ 0 & 0 & 0 & 1 & 3 & -6 \end{array} \right] \dots$$

$$\xrightarrow{R_1 = R_1 - 5R_2} \left[ \begin{array}{cccc|c} 4 & 0 & 8 & 0 & -40 & 108 \\ 0 & 1 & -1 & 0 & 7 & -19 \\ 0 & 0 & 0 & 1 & 3 & -6 \end{array} \right]$$

$$\xrightarrow{R_1 = \frac{1}{4}R_1} \left[ \begin{array}{cccc|c} 1 & 0 & 2 & 0 & -10 & 27 \\ 0 & 1 & -1 & 0 & 7 & -19 \\ 0 & 0 & 0 & 1 & 3 & -6 \end{array} \right]$$

$$x_1 = 27 - 2x_3 + 10x_5$$

$$x_2 = -19 + x_3 - 7x_5$$

$$x_4 = -6 - 3x_5$$

$x_3$  &  $x_5$  are free

Q4.  $\left[ \begin{array}{ccc|c} 3 & k & 1 & 0 \\ 0 & 4 & 1 & 0 \\ k & -5 & -1 & 0 \end{array} \right] \xrightarrow{R_3 = 3R_3} \left[ \begin{array}{ccc|c} 3 & k & 1 & 0 \\ 0 & 4 & 1 & 0 \\ 3k & -15 & -3 & 0 \end{array} \right] \dots$

$$\xrightarrow{R_3 = R_3 - kR_1} \left[ \begin{array}{ccc|c} 3 & k & 1 & 0 \\ 0 & 4 & 1 & 0 \\ 0 & -15-k^2-3 & -k & 0 \end{array} \right] \dots$$

$$\xrightarrow{R_3 = -4R_3} \left[ \begin{array}{ccc|c} 3 & k & 1 & 0 \\ 0 & 4 & 1 & 0 \\ 0 & 60+4k^2 & 12+4k & 0 \end{array} \right] \dots$$

$$\xrightarrow{R_3 = R_3 - (15+k^2)R_2} \left[ \begin{array}{ccc|c} 3 & k & 1 & 0 \\ 0 & 4 & 1 & 0 \\ 0 & 0 & -3+4k-k^2 & 0 \end{array} \right]$$

the system will have infinite solutions (other than the non-zero solution) if  $-3+4k-k^2=0$  (i.e.  $k=3$  or  $k=1$ )

Q5. Linear system:

$$\left[ \begin{array}{ccc|c} 1 & 4 & -2 & 1 \\ 1 & 7 & -6 & 6 \\ 0 & 3 & p & q \end{array} \right] \xrightarrow{R_2=R_2-R_1} \left[ \begin{array}{ccc|c} 1 & 4 & -2 & 1 \\ 0 & 3 & -4 & 5 \\ 0 & 3 & p & q \end{array} \right] \dots$$

$$\xrightarrow{R_3=R_3-R_2} \left[ \begin{array}{ccc|c} 1 & 4 & -2 & 1 \\ 0 & 3 & -4 & 5 \\ 0 & 0 & p+4 & q-5 \end{array} \right]$$

$$1) \begin{cases} p+4=0 \\ q-5 \neq 0 \end{cases} \Rightarrow \begin{cases} p=-4 \\ q \neq 5 \end{cases}$$

$$2) p+4 \neq 0 \Rightarrow p \neq -4$$

$$3) \begin{cases} p+4=0 \\ q-5=0 \end{cases} \Rightarrow \begin{cases} p=-4 \\ q=5 \end{cases}$$

Q8. system:

$$\left[ \begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 1 & 2 & a & 0 \\ 1 & 4 & a^2 & 0 \\ 1 & 2 & 1 & a-1 \end{array} \right] \xrightarrow{R_4=R_4-R_2} \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 1 & 2 & a & 0 \\ 1 & 4 & a^2 & 0 \\ 0 & 0 & 1-a & a-1 \end{array} \right]$$

the system will have at least one solution if and only if:

$$\begin{aligned} \rightarrow 1-a &= a-1 \\ \Rightarrow a &= 1 \end{aligned}$$

When  $a=1$ , system:

$$\left[ \begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 1 & 2 & 1 & 0 \\ 1 & 4 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \xrightarrow{\begin{matrix} R_2=R_2-R_1 \\ R_3=R_3-R_1 \end{matrix}} \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 3 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

the solution set:  $x_1 = -x_3$   
 $x_2 = 0$   
 $x_3$  is free

Q6. system:

$$\left[ \begin{array}{ccc|c} 1 & 0 & -1 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 1 & -1 \\ 1 & 2 & 4 & b \end{array} \right] \xrightarrow{R_4=R_4-R_1} \left[ \begin{array}{ccc|c} 1 & 0 & -1 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 2 & 5 & b-1 \end{array} \right] \dots$$

$$\xrightarrow{R_4=R_4-2R_3} \left[ \begin{array}{ccc|c} 1 & 0 & -1 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 1 & b-3 \end{array} \right] \dots$$

$$\xrightarrow{R_4=R_4-R_3} \left[ \begin{array}{ccc|c} 1 & 0 & -1 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & b-2 \end{array} \right]$$

the system will have infinitely many solutions if and only if:

$$\begin{aligned} \rightarrow b-2 &= 0 \\ \Rightarrow b &= 2 \end{aligned}$$

Q7. system:

$$\left[ \begin{array}{ccc|c} 1 & 1 & 1 & 2 \\ 1 & 2 & a & -1 \\ 2 & 3 & 0 & b \end{array} \right] \xrightarrow{R_3=R_3-R_2-R_1} \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 2 \\ 1 & 2 & a & -1 \\ 0 & 0 & -a-1 & b-1 \end{array} \right] \dots$$

$$\xrightarrow{R_2=R_2-R_1} \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 2 \\ 0 & 1 & a-1 & -3 \\ 0 & 0 & -a-1 & b-1 \end{array} \right]$$

$$1) \begin{cases} -a-1=0 \\ b-1 \neq 0 \end{cases} \Rightarrow \begin{cases} a=-1 \\ b \neq 1 \end{cases}$$

$$2) -a-1 \neq 0 \Rightarrow a \neq -1$$

$$3) \begin{cases} -a-1=0 \\ b-1=0 \end{cases} \Rightarrow \begin{cases} a=-1 \\ b=1 \end{cases}$$

$$Q9. A^k = \begin{cases} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, & k \text{ is even} \\ \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, & k \text{ is odd} \end{cases}$$

$$\text{proof: } A^2 = A \cdot A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\Rightarrow A^2 = I_3$$

$\rightarrow$  for  $k=2n$  ( $n$  is integer),

$$A^k = A^{2n} = (A^2)^n = I_3^n = I_3$$

$\rightarrow$  for  $k=2n+1$  ( $n$  is integer),

$$A^k = A^{2n+1} = (A^2)^n \cdot A = I_3^n \cdot A = A$$

hence, proved.



$$\begin{aligned} Q10. (a) (A^2 - B^2)^T &= (A^2)^T - (B^2)^T \\ &= (A^T)^2 - (B^T)^2 \\ &= A^2 - B^2 \text{ sym.} \end{aligned}$$

$$\begin{aligned} (b) ((A+B)(A-B))^T &= (A+B)^T (A-B)^T \\ &= (A^T + B^T)(A^T - B^T) \\ &= (A-B)(A+B) \text{ non-sym.} \end{aligned}$$

$$\begin{aligned} (c) (ABA)^T &= A^T B^T A^T \\ &= ABA \text{ sym.} \end{aligned}$$

$$\begin{aligned} (d) (ABAB)^T &= B^T A^T B^T A^T \\ &= BABA \text{ non-sym.} \end{aligned}$$

$$Q11, A = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \begin{bmatrix} 1 & \frac{1}{2} & 0 \end{bmatrix} = \begin{bmatrix} 1 & \frac{1}{2} & 0 \\ 2 & 1 & 0 \\ 3 & \frac{3}{2} & 0 \end{bmatrix}$$

$$A^2 = \begin{bmatrix} 2 & 1 & 0 \\ 4 & 2 & 0 \\ 6 & 3 & 0 \end{bmatrix} = 2A$$

$$A^3 = A^2 \cdot A = 2A \cdot A = 2A^2 = 2 \cdot 2A = 2^2 A$$

⋮

$$A^{11} = 2^{10} A = \begin{bmatrix} 1024 & 512 & 0 \\ 2048 & 1024 & 0 \\ 3072 & 1536 & 0 \end{bmatrix}$$

$$Q12. A^2 = A \cdot A = \begin{bmatrix} 1 & -2 & 2 \\ -2 & 1 & 2 \\ 2 & 2 & 1 \end{bmatrix} = \begin{bmatrix} 9 & 0 & 0 \\ 0 & 9 & 0 \\ 0 & 0 & 9 \end{bmatrix} = 9 I_3$$

$$A^8 = (A^2)^4 = 9^4 I_3$$

$$\rightarrow A^8 - 6400 I_3 = 16 I_3 = \begin{bmatrix} 16 & 0 & 0 \\ 0 & 16 & 0 \\ 0 & 0 & 16 \end{bmatrix}$$

$$\begin{aligned} Q13. (I-A)(I+A+A^2+\dots+A^{k-1}) \\ &= (I+A+A^2+\dots+A^{k-1}) - (A+A^2+A^3+\dots+A^k) \\ &= I - A^k \\ &= I \end{aligned}$$

$$Q14(a) A = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix}$$

$$AB = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = 0$$

we can see  $A \neq 0$  and  $B \neq 0$  but  $AB = 0$

$$(b) A = \begin{bmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{bmatrix} \quad B = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

$$\begin{aligned} AB - BA &= \begin{bmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} - \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \\ &= 0 \end{aligned}$$

we can see  $A \neq B$  but  $AB - BA = 0$

$$Q15(a) A = \begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix}$$

$$A^2 = \begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = 0$$

we can see  $A \neq 0$  but  $A^2 = 0$

$$(b) A = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}$$

$$A^2 = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} = A$$

we can see  $A \neq 0$  and  $A \neq I$  but  $A^2 = A$

$$Q16. A = \begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix} \quad B = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$(A-B)^2 = \begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ -1 & -1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = 0$$

we can see  $A \neq B$  but  $(A-B)^2 = 0$

$$Q17. A = \begin{bmatrix} A_{11} & A_{12} & \dots & A_{1N} \\ \vdots & \vdots & & \vdots \\ A_{N1} & A_{N2} & \dots & A_{NN} \end{bmatrix} \quad A^T = \begin{bmatrix} A_{11} & A_{21} & \dots & A_{N1} \\ \vdots & \vdots & & \vdots \\ A_{1N} & A_{2N} & \dots & A_{NN} \end{bmatrix}$$

note that  $A^T A = (0)_{N \times N}$

consider the main diagonal  $A^T A$ ,

$$A^T A_{ii} = \sum_{j=1}^N A_{ij}^2 = 0$$

since  $A_{ij}^2 \geq 0 \Rightarrow A_{ij} = 0$   
for every  $i=1, \dots, N$   
and every  $j=1, \dots, N$

$$\therefore A = (A_{ij})_{N \times N} = (0)_{N \times N} \\ = O_{N \times N}$$

$$Q18. (A+B)^2 = A^2 + AB + BA + B^2 = A^2 + B^2$$

$$\Rightarrow AB + BA = 0$$

$$\Rightarrow BA = -AB$$

$$AB(A+I) = ABA + AB$$

$$= A(-AB) + AB$$

$$= -A^2 B + AB$$

$$= -AB + AB$$

$$= 0$$

$$Q19. A = \begin{bmatrix} \frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & -\frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \end{bmatrix}$$

$$A^2 = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$A^3 = A^2 \cdot A = I_4 \cdot A$$

$$= \begin{bmatrix} \frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & -\frac{1}{2} & \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & -\frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \end{bmatrix}$$

$$\text{for } A^{2n} = (A^2)^n = (I_4)^n = I_4$$

$$\text{for } A^{2n+1} = A^{2n} \cdot A = I_4 \cdot A = A$$

$$Q20. \alpha = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix}, \quad \alpha^T = [\alpha_1 \ \alpha_2 \ \alpha_3]$$

$$\alpha \cdot \alpha^T = \begin{bmatrix} \alpha_1^2 & \alpha_1 \alpha_2 & \alpha_1 \alpha_3 \\ \alpha_2 \alpha_1 & \alpha_2^2 & \alpha_2 \alpha_3 \\ \alpha_3 \alpha_1 & \alpha_3 \alpha_2 & \alpha_3^2 \end{bmatrix}$$

$$\alpha^T \cdot \alpha = [\alpha_1^2 + \alpha_2^2 + \alpha_3^2]$$

$$= [1^2 + 1^2 + 1^2]$$

$$= [3]$$