Homework2

Problem 1 Solution

• First we get the function forLoopSum

```
function [outSum, computeTime] = forLoopSum(N)
    tic;
    outSum=0;
    for i = 1:N
        outSum = outSum + i^4;
    end
    computeTime = toc;
end
```

Then we get the function vectSum

```
function [outSum, computeTime] = vectSum(N)
    tic;
    outSum = sum((1:N).^4);
    computeTime = toc;
end
```

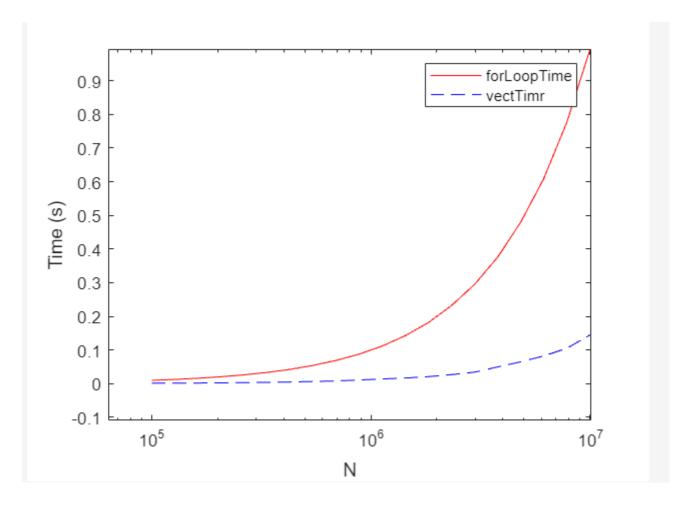
Then we get the plot

```
% give the list N
N = round(logspace(5,7,20));

forLoopTime = zeros(size(N));
vectTime = zeros(size(N));
outSum1 = zeros(size(N));
outSum2 = zeros(size(N));
flag=1;

for i = 1:length(N)
    [outSum1(i), forLoopTime(i)] = forLoopSum(N(i));
    [outSum2(i), vectTime(i)] = vectSum(N(i));
end

semilogx(N, forLoopTime, 'r-', N, vectTime, 'b--');
legend('forLoopTime', 'vectTimr');
disp(outSum1);
disp(outSum2);
```



- Conclusion
 - The efficiency of vectSum is better than forLoopSum
 - the result of the two method is the same

Problem 2 Solution

my_gcd

To make it more convenient, I choose mod instead of rem.

```
function out = my_gcd(a,b)
    while mod(a,b) ~= 0
        t=a;
        a=b;
        b=mod(t,b);
    end
    out = b;
end
```

my_lcm

In MATLAB's built-in lcm, it will raise a error while a=0 or b=0, So

```
function out = my_lcm(a,b)
  if a==0 || b==0
    out = NaN;
  else
    out = a*b/my_gcd(a,b);
  end
end
```

Problem 3 Solution

check

We first write a function to check if it is a perfect number

```
function out = check(N)
    cnt = 0;
    out = 0;
    for i = 1: round(N/2)
        if rem(N,i) == 0
            cnt = cnt + i;
        end
    end
    if cnt == N
        out = 1;
    end
end
```

perfectNumbers

Then we output the result

```
function out = perfectNumbers(N)
  out = [];
  for i = 2:N
     if check(i) == 1
        out(end+1) = i;
     end
  end
end
```

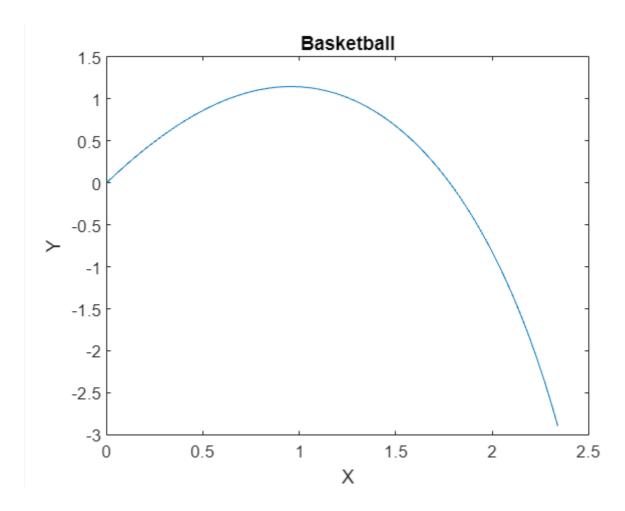
The output is:

Problem 4 Solution

Just get the function with the help of fomular

```
function [x,y] = basketball(g,c,x0,y0,vx0,vy0,tstep,tmax)
    t = 0:tstep:tmax;
    x = zeros(size(t));
    y = zeros(size(t)); % innitialization
    x(1) = x0;
    y(1) = y0;
    vx = vx0;
    vy = vy0;
    for i = 2:length(t)
        ax = -c * vx * sqrt(vx^2+vy^2);
        ay = -g -c * vy * sqrt(vx^2+vy^2);
        x(i) = x(i-1) + vx * tstep;
        y(i) = y(i-1) + vy * tstep;
        vx = vx + ax * tstep;
        vy = vy + ay * tstep;
    end
    plot(x,y);
    xlabel("X");
    ylabel("Y");
    title("Basketball");
end
```

The plot is:



Problem 5 Solution

Method a

It is not difficult so I show the function directly

```
function out = my_arctan(x,N)
  out = 0;
  for i = 1:10^N
     out = out + (-1)^(i+1)* x^(2*i-1) / (2*i-1);
  end
end
```

The result is:

```
>> pi = vpa(my_arctan(1,3) * 4 , 8)
pi =
3.1405927
>> pi = vpa(my_arctan(1,4) * 4 , 8)
pi =
3.1414927
\Rightarrow pi = vpa(my arctan(1,5) * 4 , 8)
pi =
3.1415827
>> pi = vpa(my_arctan(1,6) * 4 , 8)
pi =
3.1415917
>> pi = vpa(my_arctan(1,7) * 4 , 8)
pi =
3.1415926
```

Method b

Still easy

```
function out = my_pi(N)
  out = 0;
  for i = 1:10^N
     out = out + 1/(4*i-3)/(4*i-1);
  end
  out = out * 8;
end
```

The result is:

```
>> pi = vpa(my_pi(4),8)
pi =
3.1415427
>> pi = vpa(my_pi(5),8)
pi =
3.1415877
>> pi = vpa(my_pi(6),8)
pi =
3.1415922
>> pi = vpa(my_pi(7),8)
pi =
3.1415926
```

We find that we need fewer terms to reach the same level of accuracy that we got in (a)

Calculate π

Call the function we write in (a):

```
>> pi = (6*my_arctan(1/8,7)+2*my_arctan(1/57,7)+my_arctan(1/239,7))*4;
>> vpa(pi,8)
ans =
3.1415927
```

So we get the answer.

Problem 6 Solution

So silly

```
A=[1 2 3;4 5 6;7 8 9];

B = [A(:)]'

C = A(:,1:2)

D = A(1:2,:)

E = [A(1,1) @ A(1,2) @ A(1,3);

@ @ @ @ @;
```

```
A(2,1) 0 A(2,2) 0 A(2,3);

0 0 0 0 0;

A(3,1) 0 A(3,2) 0 A(3,3)]'

F = [A(3,3) 0 A(3,2) 0 A(3,1);

0 0 0 0 0;

A(2,3) 0 A(2,2) 0 A(2,1);

0 0 0 0 0;

A(1,3) 0 A(1,2) 0 A(1,1)]
```

The result:

B =

1 4 7 2 5 8 3 6 9

C =

1 2 4 5 7 8

D =

1 2 3 4 5 6

E =

F =

Problem 7 Solution

It seems that no need to explain too much

```
speed = [0.2, 0.3, 0.7, 1.3, 1.9, 255, 1.6, 1.1, 1.3, 255, 0.9, 0.7, 255, 0.4,
0.6];
time = [0, 100, 200, 300, 400, 500, 600, 700, 800, 900, 1000, 1100, 1200, 1300,
1400];

lessThan05 = numel(speed(speed<0.5))
lessTime = time(speed<0.5)
from350To1050 = speed(350<=time & time<=1050)
tt = logical(speed==255);
speed(tt) = NaN;

% flit the NaN
time = time(~isnan(speed));
speed = speed(~isnan(speed));
plot(time, speed);
xlabel("time");
ylabel("speed");</pre>
```

The result is:

lessThan05 =

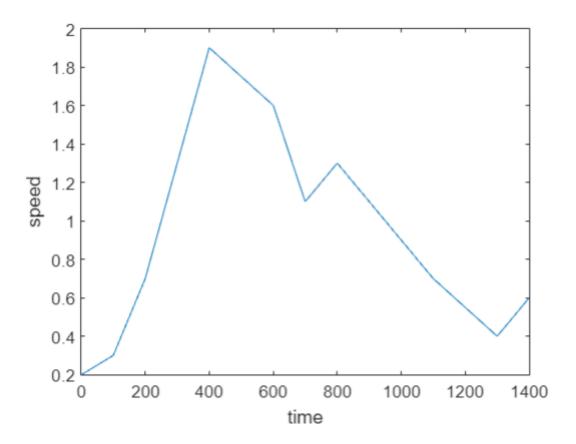
3

lessTime =

0 100 1300

from 350 To 1050 =

1.9000 255.0000 1.6000 1.1000 1.3000 255.0000 0.9000



I flit the erroneous measurements to make the plot more clear.

Problem 8 Solution

With the rule, we get:

```
use = [2,5,7,10,15]*100;
cost = zeros(1,5);

tt = use<=500;
cost(tt) = use(tt) * 2;

tt = use>500 & use<=1000;
cost(tt) = 1000 + (use(tt)-500) * 5;</pre>
```

```
tt = use>1000;
cost(tt) = 3500 + (use(tt)-1000) * 10;
cost = cost + 500;
useAndCost = [use' cost']
```

The result is:

useAndCost =

900
1500
2500
4000
9000

Problem 9 Solution

flipOddCol

```
function B = flipOddCol(A)

B = A;

B(:,1:2:end) = flipud(A(:,1:2:end));
end
```

An example:

A =

1 2 3 4 5 6 7 8 9

>> B = flipOddCol(A)

B =

7 2 9 4 5 6 1 8 3

diagEye

```
function B = diagEye(A)
    di = diag(A);
    di(:) = sum(di);
    B = diag(di);
end
```

An example:

A =

1 2 3 4 5 6

>> B = diagEye(A)

B =

6 0 0 6

colXchange

```
function B = colXchange(A)

B = A;

B(:,1:2:end-1) = A(:,2:2:end);

B(:,2:2:end) = A(:,1:2:end-1);
end
```

An example:

```
A =

1 2 3 4 5
6 7 8 9 10

>> B = colXchange(A)

B =

2 1 4 3 5
7 6 9 8 10
```

stripes

```
function B = stripes(n)
    B = zeros(n,n);
    B(2:2:end,:) = 1;
end
```

An example:

```
>> B = stripes(10)
B =
     0
            0
                   0
                         0
                                0
                                       0
                                              0
                                                     0
                                                           0
                                                                  0
     1
            1
                   1
                          1
                                1
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```

threshold

```
function B = threshold(A,lob,hib)

B = A;

B(A<lob) = lob;

B(A>hib) = hib;
end
```

An example:

Problem 10 Solution

palindrome

```
function res = palindrome(str)
    str = str(isletter(str));
    str = lower(str);
    strr = str(end:-1:1);
    res = all(str == strr);
end
```

Some examples:

```
>>> palindrome('Doc, note I dissent: a fast never prevents a fatness. I diet on cod')
ans =
     1
>>> palindrome('Never odd or even')
ans =
     1
>>> palindrome('A man a plan a canal Panama')
ans =
     1
>>> palindrome('I am Iron Man')
ans =
     0
```

longest palindrome

Are we not pure? "No, sir!" Panama's moody Noriega brags. "It is garbage!" Irony dooms a man—a prisoner up to new era.

check it:

```
str =
Are we not pure? "No, sir!" Panama s moody Noriega brags. "It is garbage!" Irony dooms a man—a prisoner up to new era.
>> palindrome(str)
ans =
1
```

So it is a palindrome.