The Open VINO toolkit tutorial

Performance Optimization CV Winter Camp 2021

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What we need

- Microsoft Visual Studio 2015/2017
- CMake
- The OpenVINO toolkit (contains OpenCV)
- Open Model Zoo
- Segmentation model (e.g. DeepLab V3)

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```
cmake_minimum_required (VERSION 3.10)
project(blur_background_demo)
find_package(OpenCV REQUIRED)
add_definitions(-DUSE_OPENCV)
find_package(InferenceEngine 2.0 REQUIRED)
if(MSVC)
 add_definitions(-D_CRT_SECURE_NO_WARNINGS -DSCL_SECURE_NO_WARNINGS)
 add_compile_options(/wd4251 /wd4275 /wd4267 # disable some warnings
         /W3 # Specify the level of warnings to be generated by the compiler
         /EHsc) # Enable standard C++ stack unwinding, assume functions with extern "C" never throw
endif()
add_subdirectory(${OMZ_DEMO_DIR}/common/cpp/models models)
add_subdirectory(${OMZ_DEMO_DIR}/common/cpp/utils utils)
add_subdirectory(${OMZ_DEMO_DIR}/thirdparty/gflags gflags EXCLUDE_FROM_ALL)
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Set the OpenVINO's environment:
<path/to/openvino>/bin/setupvars.bat
OR
<path/to/openvino>/bin/setupvars.sh

Run Cmake:

cmake -B <path/for/build> -DOMZ_DEMO_ZOO <path/to/omz>

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Code: what we use

```
#include <iostream>
#include <string>
#include <opencv2/opencv.hpp>
#include <inference engine.hpp>
#include <models/segmentation model.h>
#include <utils/ocv common.hpp>
#include <utils/performance metrics.hpp>
```

Code: application parameters

```
int main(int argc, char *argv[])
     std::string input = argv[1];
     std::string backgroundPath = argv[2];
     std::string model path = argv[3];
```

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Code: open camera

```
int main(int argc, char *argv[])
   cv::VideoCapture cap;
   if (cap.open(std::stoi(input)))
       cap.set(cv::CAP PROP FRAME WIDTH, 1280);
       cap.set(cv::CAP PROP FRAME HEIGHT, 720);
       cap.set(cv::CAP_PROP_BUFFERSIZE, 1);
       cap.set(cv::CAP_PROP_AUTOFOCUS, true);
       cap.set(cv::CAP_PROP_FOURCC, cv::VideoWriter::fourcc('M','J','P','G'));
```

Code: prepare engine and model

```
int main(int argc, char *argv[])
  InferenceEngine::Core engine;
  ModelBase *model = new SegmentationModel(model path, true);
  InferenceEngine::CNNNetwork cnnNetwork =
     engine.ReadNetwork(model->getModelFileName());
```

Code: prepare engine and model

```
int main(int argc, char *argv[])
  model->prepareInputsOutputs(cnnNetwork);
   std::string inputName = model->getInputsNames()[0];
   std::string outputName = model->getOutputsNames()[0];
```

Code: prepare engine and model

```
int main(int argc, char *argv[])
  InferenceEngine::ExecutableNetwork execNetwork =
     engine.LoadNetwork(cnnNetwork, "GPU");
  InferenceEngine::InferRequest inferRequest =
     execNetwork.CreateInferRequest();
```

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```
while (cap.isOpened())
{
   auto startTime = std::chrono::steady_clock::now();
   cv::Mat frame;
   cap.read(frame);
   ...
}
```

```
while (cap.isOpened())
   InferenceEngine::Blob::Ptr imgBlob = wrapMat2Blob(frame);
   inferRequest.SetBlob(inputName, imgBlob);
   inferRequest.Infer();
   InferenceEngine::Blob::Ptr result = inferRequest.GetBlob(outputName);
```

```
while (cap.isOpened())
    InferenceResult inferenceResult;
    inferenceResult.outputsData.emplace(outputName,
        std::make shared<InferenceEngine::TBlob<float>>(
                *InferenceEngine::as<InferenceEngine::TBlob<float>>(result)));
    inferenceResult.internalModelData =
        std::shared_ptr<InternalImageModelData>(
                new InternalImageModelData(frame.size[1], frame.size[0]));
    std::unique ptr<ResultBase> segmentationResult = model->postprocess(inferenceResult);
```

```
while (cap.isOpened())
    cv::Mat outFrame;
    switch (type)
    case DELETE:
        outFrame = remove_background(frame, segmentationResult->asRef<SegmentationResult>());
        break;
    case BACKGROUND:
        outFrame = replace_background(frame, background,
                                   segmentationResult->asRef<SegmentationResult>());
        break;
```

```
while (cap.isOpened())
   metrics.update(startTime, outFrame, { 10, 22 }, cv::FONT_HERSHEY_COMPLEX,
   0.65);
   cv::imshow("Video", outFrame);
   int key = cv::waitKey(1);
   if (key == 27)
       break;
   if (key == 9)
       type++;
       if (type == NONE)
              type = 0;
```

```
cv::Mat replace_background(
      cv::Mat frame,
      cv::Mat background,
      SegmentationResult& segmentationResult)
   auto mask = segmentationResult.mask;
   cv::resize(background, background, frame.size());
```

```
cv::Mat replace_background(...)
  const int personLabel = 15;
  cv::Mat personMask = cv::Mat(mask.size(), mask.type(), 15);
  cv::compare(mask, personMask, cv::CMP_EQ);
```

```
cv::Mat replace_background(...)
{
    ...
    cv::Mat maskedFrame;
    cv::bitwise_or(frame, frame, maskedFrame, personMask);
    ...
}
```

```
cv::Mat replace_background(...)
   cv::Mat backgroundMask;
   cv::bitwise_not(personMask, backgroundMask);
   cv::Mat maskedBackground;
   cv::bitwise_or(background, background, maskedBackground,
   backgroundMask);
```

```
cv::Mat replace_background(...)
{
    ...
    cv::bitwise_or(maskedFrame, maskedBackground, frame);
    return frame;
}
```