# **Project Summary**

This project demonstrates the development and evaluation of an Automatic Number Plate Recognition (ANPR) system for Indian vehicles. The system follows a two-stage pipeline: **simulated license plate detection** using ground truth annotations from the dataset, followed by **character recognition** using the EasyOCR library. The **"Indian Vehicle Dataset" from Kaggle** was used, which provided both images and crucial XML annotations containing bounding boxes and the ground truth license plate numbers.

The primary challenge was the performance of the out-of-the-box OCR engine on real-world images. Despite simulating perfect detection, the OCR component achieved an **Exact Match Accuracy of ~22%** and a **Character Error Rate (CER) of ~33%**. This underperformance is attributed to factors like diverse fonts, variable lighting, image quality issues (blur, low resolution), and complex plate angles present in the dataset. Attempts to improve performance with generic, aggressive preprocessing steps proved detrimental, highlighting the sensitivity of OCR models and the need for empirically tuned solutions.

The project concludes that while EasyOCR provides a functional baseline, a production-ready ANPR system requires a more specialized approach. Key next steps include fine-tuning a dedicated object detection model like **YOLOv8** for precise plate localization and implementing sophisticated, domain-specific **image preprocessing and post-processing validation rules** to handle the unique challenges of Indian license plates.

# **Number Plate Recognition Project Report**

This document details an Automatic Number Plate Recognition (ANPR) system developed as a small project, demonstrating key concepts in computer vision and machine learning. It covers the project's pipeline, the dataset used, the models and libraries employed, a discussion of challenges encountered and system performance, and proposed next steps for improvement.

# 1. Project Overview and Pipeline

The goal of this project is to build an ANPR system capable of detecting and recognizing alphanumeric characters from Indian vehicle license plates in images. A typical ANPR system operates in two main stages:

#### A. License Plate Detection

This stage involves identifying and localizing the license plate region within an input image or video frame. The output of this stage is a bounding box (coordinates) that isolates the license plate.

### B. Character Recognition (Optical Character Recognition - OCR)

Once the license plate is detected and cropped, this stage focuses on interpreting the alphanumeric characters present on the plate and converting them into a machine-readable text string.

### **Overall Pipeline:**

- 1. Image Loading: Load the input image.
- 2. License Plate Detection (Simulated): In this demonstration, we leverage the ground truth bounding box annotations from the dataset to perfectly isolate the license plate. This simulates an ideal detection step, allowing us to focus on the OCR's performance.
- 3. **License Plate Cropping:** Using the precise bounding box coordinates, the license plate region is cropped from the original image.
- 4. Character Recognition (OCR): The cropped license plate image is fed into an OCR engine to extract the alphanumeric characters.
- 5. **Post-processing (OCR Output):** The raw text output from the OCR engine is cleaned and formatted (e.g., converted to uppercase, removal of non-alphanumeric characters, and heuristic corrections for common OCR errors).
- 6. **Evaluation & Visualization:** The recognized text is compared against the known ground truth, and results are displayed visually on the image and quantitatively as performance metrics.

#### 2. Dataset Used: Indian Vehicle Dataset

For this project, we utilized the "Indian Vehicle Dataset" available on Kaggle. This dataset is particularly suitable because it focuses on Indian license plates and, critically, includes XML annotation files alongside the images.

- Dataset Source: <u>Kaggle: Indian Vehicle Dataset</u>
- Structure: The dataset is organized into three main directories:
  - google-images/: Contains images scraped from Google, often providing diverse angles and lighting.
  - State-wise\_OLX/: Contains sub-folders for various Indian states (e.g., DL, MH, UP, KA), each containing images from that specific state, likely from OLX website scraping.
  - o video\_images/: Contains frames captured from mobile devices on highways,

representing various daylight conditions.

- **Annotations:** Crucially, for each image (.jpg, .png), there's a corresponding .xml file (in PASCAL VOC format). These XML files provide:
  - Bounding Box Coordinates: xmin, ymin, xmax, ymax for the license plate region.
  - License Number: The actual alphanumeric characters of the license plate (stored under the <name> tag).

The presence of these detailed XML annotations is invaluable for evaluating the OCR component, as it provides precise ground truth for comparison.

### 3. ML Models and Libraries

#### A. Core Models:

- License Plate Detection (Conceptual / Simulated):
  - YOLOv8 (You Only Look Once): While we did not fully train a YOLOv8 model from scratch or fine-tune it on this dataset for license plate detection, YOLOv8 (specifically yolov8n.pt for its speed) was initially considered. In a production system, a YOLOv8 model would be fine-tuned on a custom dataset annotated specifically for 'license\_plate' objects. For this project, the detection step is simulated by directly using the ground truth bounding box coordinates from the dataset's XML annotations. This allows us to focus on the performance of the OCR module with perfectly cropped plates.

## • Character Recognition (OCR):

EasyOCR: This is a robust, ready-to-use open-source OCR library. It supports multiple languages, including English (which Indian plates use). EasyOCR was chosen for its ease of integration and good out-of-the-box performance, reducing the need for complex custom OCR model training within the scope of this small project.

## B. Supporting Libraries:

- opencv-python-headless (OpenCV): Essential for all image processing tasks, including reading images, cropping, drawing bounding boxes and text, and various preprocessing steps (like grayscale conversion, blurring, adaptive thresholding, and deskewing).
- matplotlib: Used for visualizing the processed images and displaying performance plots.
- numpy: Fundamental library for numerical operations, especially handling image data as arrays.
- Levenshtein: Utilized for calculating the Levenshtein distance (edit distance)

- between strings, which is crucial for determining the Character Error Rate (CER).
- **ultralytics:** Provides the YOLO class for easily loading and performing inference with YOLOv8 models.
- **google.colab:** For mounting Google Drive and managing files in the Colab environment.
- xml.etree.ElementTree: Python's built-in library for parsing XML annotation files.

# 4. Challenges Encountered & Why Underperformance Occurred

During the development and testing of this project, several challenges arose, primarily impacting the performance of the character recognition (OCR) stage.

### A. Initial Preprocessing Degradation (A Key Learning Point)

- The Problem: An early attempt to "improve" OCR performance involved applying aggressive image preprocessing steps (like adaptive thresholding, scaling, and deskewing using fixed parameters) directly to the cropped license plate images before feeding them to EasyOCR.
- The Result: Counter-intuitively, these steps significantly degraded performance, reducing Exact Match Accuracy from an initial "okayish" ~18-22% down to a mere 2%.
- The Lesson: This was a critical learning experience. It highlighted that:
  - **Fixed preprocessing is not a universal solution:** What works for one set of images or one OCR engine might be detrimental to another.
  - EasyOCR's Internal Optimizations: EasyOCR's pre-trained models are likely designed to handle a certain range of image variations internally, or they expect input closer to the raw cropped image. My aggressive external transformations interfered with its learned features, effectively corrupting the input for its models.
  - Parameter Sensitivity: Parameters for operations like blurring, thresholding, and deskewing are highly sensitive and require careful empirical tuning specific to the dataset and target OCR.

# B. Inherent Challenges of Real-World License Plates (Even at Best Performance)

Even after reverting to the better-performing, simpler preprocessing, the system's Exact Match Accuracy remained in the ~22% range, and the CER around ~33%. This "underperformance" (relative to a production-ready system) stems from fundamental difficulties in ANPR:

- 1. **Image Quality Variability:** The dataset, sourced from web scraping and mobile captures, contains images with:
  - o Varying Resolution & Blur: Many plates are low-resolution or

- motion-blurred, making characters difficult to discern.
- Compression Artifacts: Web images often suffer from JPEG compression, which degrades character edges.

## 2. Challenging Environmental Conditions:

- Inconsistent Lighting: Images are taken under diverse lighting conditions (daylight, shadows, glare, reflections). This can cause uneven illumination on the plate, making some characters too dark or too bright.
- Angles and Skew: License plates are rarely perfectly frontal. Plates captured at sharp angles or with perspective distortion make character recognition harder, even if cropped perfectly.

## 3. Diversity of Indian License Plates:

- Font Variations: Indian license plates utilize a wide array of fonts, sizes, and character styles. A general OCR model like EasyOCR, while robust, may not be optimally trained for all these specific variations.
- Physical Deterioration: Plates can be dirty, scratched, partially obscured, or have faded paint, impacting character visibility.
- Regional Formats: While standardizing, some regional differences or old plates exist.

# 4. OCR Model Generality:

 EasyOCR is a general-purpose OCR. It is not specifically fine-tuned on thousands of Indian license plate images to learn their unique characteristics and common error patterns. This means it might confuse visually similar characters (e.g., 'O' vs 'O', 'I' vs '1', 'S' vs '5', 'M' vs 'H') more frequently.

### 5. Evaluation Metrics

For a project of this nature, both detection and recognition components require distinct evaluation metrics.

## A. Character Recognition (OCR) Evaluation:

Since we used ground truth license plate numbers from the XML annotations, we were able to quantify OCR performance directly.

# • Exact Match Accuracy:

- Definition: The percentage of license plates where the entire recognized text string precisely matches the ground truth string.
- Why it's important: For ANPR, an exact match is often required for downstream applications (e.g., database lookup, tolling). A single incorrect character can invalidate the entire plate.
- Observed Performance (Current Best): ~22%

#### • Character Error Rate (CER):

- Definition: Calculated as (Levenshtein Distance between GT and Recognized)
  / (Length of Ground Truth String). Levenshtein distance measures the minimum number of single-character edits (insertions, deletions, substitutions) required to change one word into the other.
- Why it's important: CER provides a more granular view of OCR errors. Even if an exact match is not achieved, a low CER indicates that most characters were recognized correctly, which might be acceptable for some applications (e.g., fuzzy matching, or if minor errors can be corrected by contextual post-processing).
- Observed Performance (Current Best): ~33%

#### **B. License Plate Detection Evaluation (Theoretical):**

In this demonstration, we *simulated* perfect detection by using the ground truth bounding boxes directly. For a real-world system where a detection model (like YOLO) is trained, the following metrics would be crucial:

### • Intersection over Union (IoU):

- Definition: Measures the overlap between the predicted bounding box and the actual ground truth bounding box. A value of 1.0 means perfect overlap, 0.0 means no overlap.
- Why it's important: Used to determine if a detection is considered a "True Positive" (i.e., if its IoU with a ground truth box exceeds a certain threshold, e.g., 0.5 or 0.75).

#### • Precision:

- Definition: (True Positives) / (True Positives + False Positives). Out of all the bounding boxes the model *predicted*, how many were actually correct detections?
- Why it's important: Avoids detecting many irrelevant objects.

#### Recall:

- Definition: (True Positives) / (True Positives + False Negatives). Out of all the actual license plates in the image, how many did the model correctly detect?
- Why it's important: Ensures the model doesn't miss too many actual plates.

#### • F1-Score:

 Definition: The harmonic mean of Precision and Recall. It provides a single score that balances both metrics.

# • Mean Average Precision (mAP):

 Definition: The standard metric for object detection. It involves calculating Average Precision (AP) for each class (here, 'license\_plate') and then averaging these APs across different IoU thresholds.  Why it's important: Provides a comprehensive measure of a detector's performance, considering both localization accuracy and classification accuracy.

# 6. Future Work and Next Steps for Improvement

To evolve this demonstration into a robust, high-performance ANPR system capable of handling the real-world challenges, the following critical next steps would be undertaken:

## 1. Dedicated License Plate Detection Model Training:

- Data Preparation: Convert the XML annotations from the "Indian Vehicle Dataset" into a format compatible with YOLOv8 training (e.g., .txt files with class\_id x\_center y\_center width height).
- Model Fine-tuning: Fine-tune a pre-trained YOLOv8 model (e.g., yolov8m.pt or yolov8x.pt for higher accuracy) on this annotated dataset. This would teach the model to specifically identify and precisely localize license plates, replacing our current ground-truth simulation. This is the most crucial step for improving the overall pipeline.

## 2. Advanced Image Preprocessing (Carefully Tuned):

- Adaptive Binarization: Re-evaluate and carefully tune adaptive thresholding techniques (like cv2.adaptiveThreshold or Otsu's binarization) on the *cropped license plate* to optimally separate characters from the background.
- Robust Deskewing: Implement a more robust deskewing algorithm that can handle various plate orientations and is less sensitive to noise, ensuring characters are perfectly horizontal for OCR.
- Noise Reduction: Experiment with different noise reduction filters (e.g., non-local means denoising) to preserve character integrity.
- Contrast Enhancement: Fine-tune CLAHE parameters or explore other contrast enhancement methods.
- Empirical Tuning: Crucially, any preprocessing steps would be added and tuned empirically by observing their effect on a diverse validation set and iterating.

# 3. Sophisticated OCR Post-processing and Validation:

- Pattern-Based Correction: Develop a rule-based system using regular expressions that leverages the known structure of Indian license plates (e.g., XX YY ZZ NNNN or XX YY NNNN). This system can correct common OCR errors (like 'O' vs 'O', 'I' vs '1', 'B' vs '8') by checking if the recognized string fits a valid pattern, and suggesting the closest valid string if it doesn't.
- o State/District Code Validation: Integrate lookup tables for valid state and

- district codes (e.g., MH, DL, UP, O1, O2) to further validate and correct the initial characters.
- Character Confidence: If EasyOCR provides character-level confidence scores, use these to prioritize corrections (e.g., correct low-confidence characters first).

### 4. Exploring Alternative OCR Solutions:

 If EasyOCR's performance remains insufficient even after robust preprocessing and post-processing, consider other powerful OCR libraries like PaddleOCR or even training a custom Convolutional Recurrent Neural Network (CRNN) model specifically for Indian license plate characters.

### 5. Data Augmentation:

 If a custom detection or OCR model is trained, extensive data augmentation (rotation, translation, scaling, brightness changes, blurring, adding noise) would be applied during training. This trains the model to be invariant to the very challenges observed (angles, lighting, blur).

By systematically addressing these areas, the ANPR system can be significantly improved to meet the demands of real-world applications, delivering high accuracy and robustness across diverse conditions.