

Style Transfer with



BOSTON UNIVERSITY
MACHINE INTELLIGENCE
COMMUNITY

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Last Time

- → Learned the concepts of TensorFlow 1.2
- → Built and evaluated simple graphs
- → "Trained" a linear model

https://github.com/bumic/TF-Workshops/tree/master/Workshop%201



Today's Plan

- → Begin project: implementation of neural style transfer in TensorFlow (will last 3 workshops)
- → Concepts: convolutional neural networks, VGG-19 architecture, neural style transfer
- → Implementations: structure of a neural network implementation, skeleton code for NST



What You Need For Today

- → A computer & text editor
- → Installations of Python 2 or 3, TensorFlow, numpy, scipy, and Pillow
- → These can all be installed via pip install

```
>> pip install numpy
```

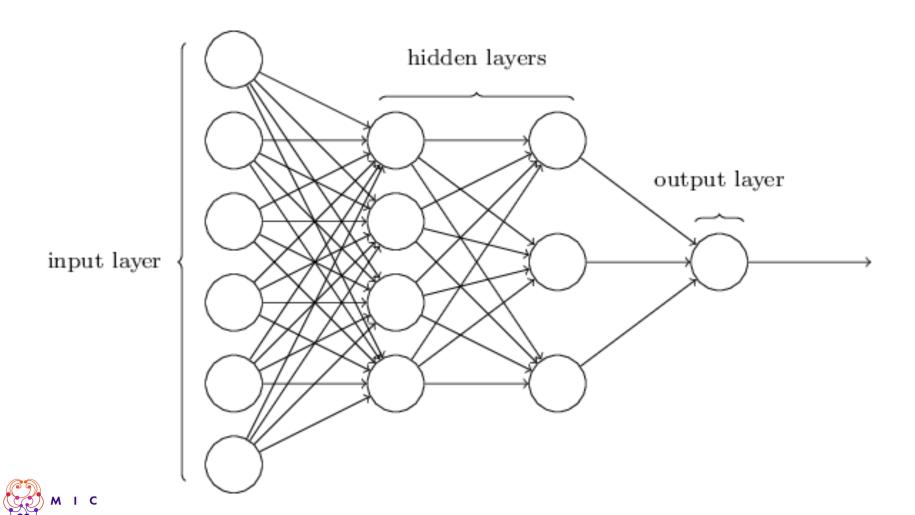
- >> pip install scipy
- >> pip install Pillow



A Brief Overview of Neural Networks

- → Multilayer perceptrons: the "plain vanilla" of machine learning
- → In a fully connected network, each **neuron** (a tensor in TensorFlow) in the next layer is connected to all neurons in the previous layer, and **feeds forward** information to "activate" the next neuron
- → What is this information?





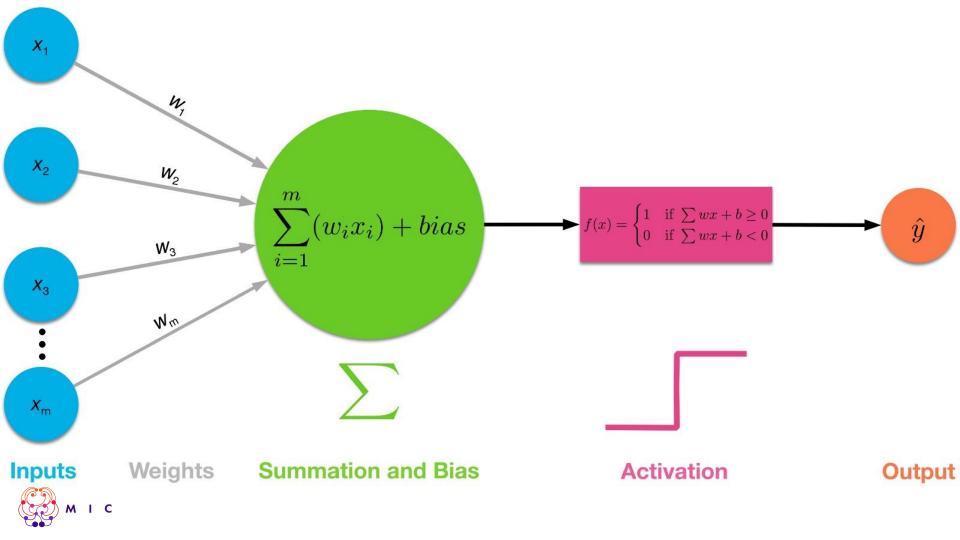
Neural Networks: Connections

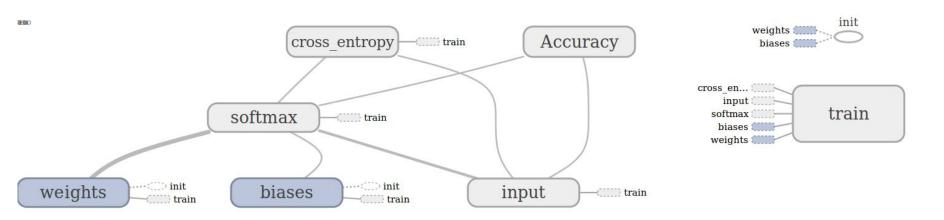
- → Weights: how "important" that neuron is
- → Bias: how high the weighted sum needs to be for neuron to be meaningfully active
- → Initialized randomly, then through training they are adjusted toward the correct value

$$Y = \sum (weight * input) + bias$$

$$linear_model = W * x + b$$





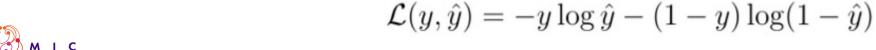




Neural Networks: Loss functions

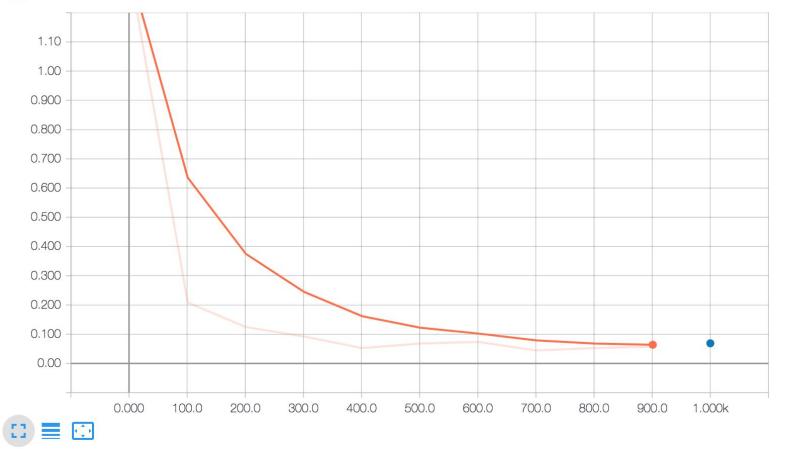
- → Loss functions add a cost to the network's output, i.e. penalizing the network for performing poorly
 - Difference between output and desired output
 - We want to minimize this. There are many loss functions...

MSE =
$$\frac{1}{n} \sum_{i=1}^{n} (y_i - \tilde{y}_i)^2$$





loss





Neural Networks: Training

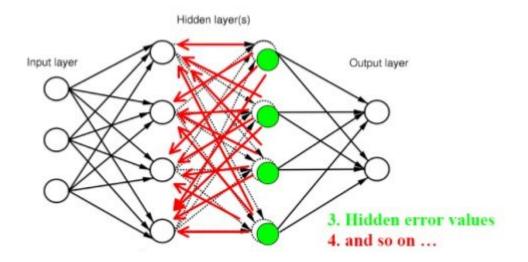
- → Training a network means minimizing this cost function more and more with each step.
- → Gradient descent is called an optimizer: it allows us to adjust weights and biases by telling them to increase or decrease to minimize the cost function
- → There are many other optimizers...

$$\mathbf{a}_{n+1} = \mathbf{a}_n - \gamma
abla F(\mathbf{a}_n)$$

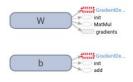


$$heta_{t+1} = heta_t - rac{\eta}{\sqrt{\hat{v}_t} + \epsilon} \hat{m}_t$$

Visual: Backpropagation

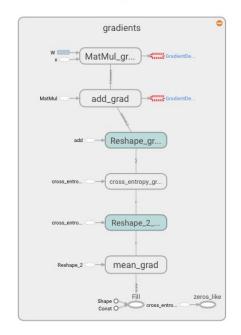


















"Neural networks" are a sad misnomer. They're neither neural nor even networks. They're chains of differentiable, parameterized geometric functions, trained with gradient descent (with gradients obtained via the chain rule). A small set of highschool-level ideas put together

11:58 AM - 12 Jan 2018







François Chollet @fchollet | 81,895 followers

Activity Map Analyse Visualise Alert

There's a point to be made that a neural network for food classification that can classify Tide pods as "not food" has already reached superhuman capabilities

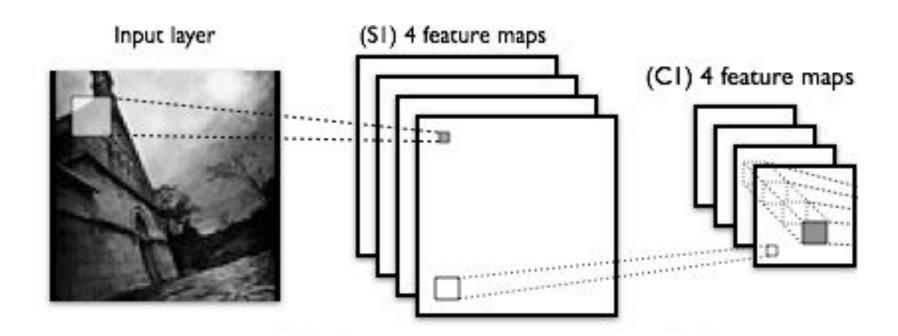
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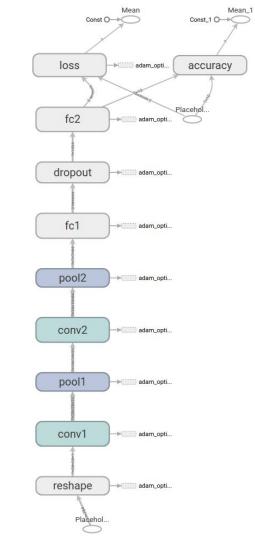
Convolutional Neural Networks

- → Neural networks with convolutional layers: use convolutions instead of matrix multiplications to produce output in hidden layers
- → Each convolution layer takes an input image and produces a set of feature maps by filtering
 - ◆ Each filter is "convolved" across the width and height of the input volume, producing a 2-dimensional activation map of that filter.







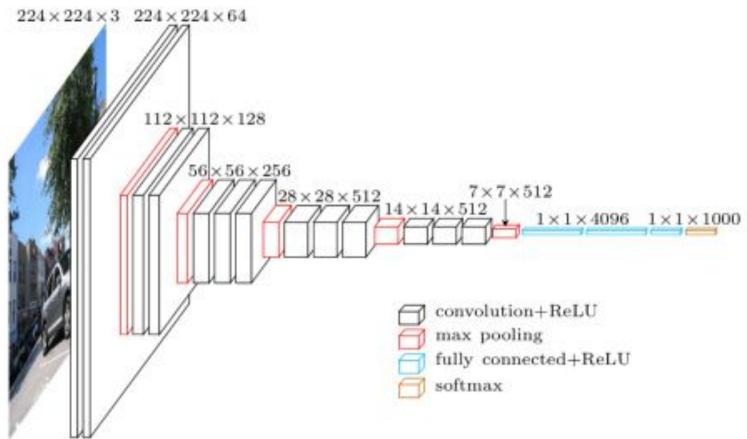




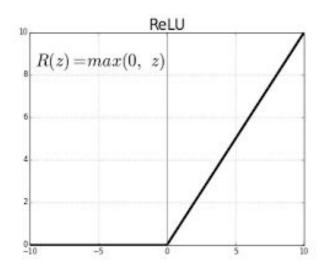
VGG-19

- → A specific version of VGGNet with 19 weight layers
- → VGGNet is a convolutional neural network originally used for image classification
 - uses 3×3 convolutional layers stacked on top of each other
 - reducing volume size is handled by max pooling
 - Two fully-connected layers, each with 4,096 nodes are followed by a softmax classifier.
- → Original VGGNet paper:









Softmax

$$\sigma(x_j) = \frac{e^{x_j}}{\sum_i e^{x_i}}$$

Max pooling

Single depth slice

×	1	1	2	4
	5	6	7	8
	3	2	1	0
	1	2	3	4

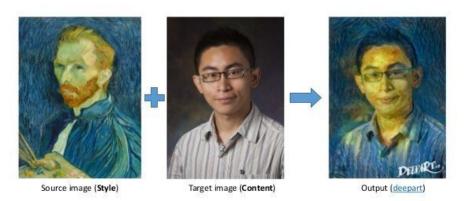
max pool with 2x2 filters and stride 2



V

What is Neural Style Transfer?

- → Representations of style and content can be isolated and manipulated separately from a convolutional NN!
- → Contains three main components:
 - Content image, style image, pastiche







Content image:
Picture we want to transfer style onto



Style image: Artwork whose style we want to transfer



Pastiche:
Final stylized image
(Initialized to random/white noise)



Content image: loss and reconstruction

- ullet Content Loss Mean Squared Error between feature maps for a given convolutional layer $oldsymbol{l}$
 - o P_{ij}^l : Feature map of **original image**
 - \circ F_{ij}^l : Feature map of image content to be generated
- Gradient descent is used to minimize the content loss.

$$L_{content}(\overrightarrow{p},\overrightarrow{x},l) = \frac{1}{2} \sum_{ij} (F_{ij}^l - P_{ij}^l)^2$$
 Original Generated image image



Style image: loss function

Style Loss

- o Gram Matrix: inner product between two vectorised features maps i and j
- o Computes correlations between different features

$$G_{ij}^l = \sum_k F_{ik}^l F_{jk}^l$$

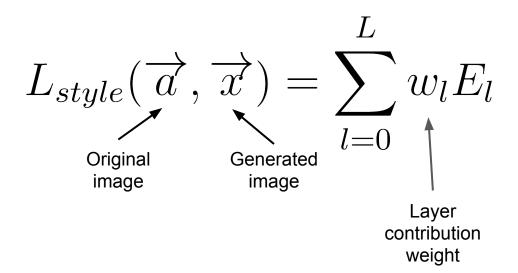
 Minimize mean-squared distance between entries of Gram matrix of style image and generated image

$$E_l = \frac{1}{4N_l^2 M_l^2} \sum_{i,j} (G_{ij}^l - A_{ij}^l)^2$$



Style image: reconstruction

- Total Style Loss across multiple layers
 - Weighted sum of styles losses across all layers of the convolutional network





Total Loss Function for NST

- Total Loss Jointly minimize error of a white noise image from
 - \circ Content representation of content image $ec{p}$
 - \circ Style representation of **style image** $ec{a}$

$$L_{total}(\overrightarrow{p}, \overrightarrow{a}, \overrightarrow{x}) = \alpha L_{content}(\overrightarrow{p}, \overrightarrow{x}) + \beta L_{style}(\overrightarrow{a}, \overrightarrow{x})$$

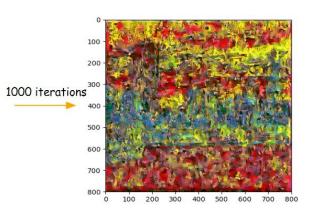
 \bullet α,β : weighting factors for content and style reconstruction respectively

$$\mathbf{x}^* = \operatorname*{argmin}_{\mathbf{x}} \left(lpha \mathcal{L}_{ ext{content}}(\mathbf{c}, \mathbf{x}) + eta \mathcal{L}_{ ext{style}}(\mathbf{s}, \mathbf{x}) \right)$$

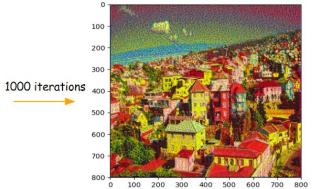


















Implementation of Neural Style Transfer

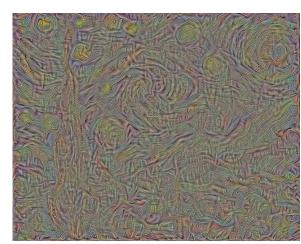
→ The implementation of neural style we will be using is located here:

https://goo.gl/M1pBRx

→ Let's go to it and play around!



Implementation of Neural Style Transfer



Iteration 10



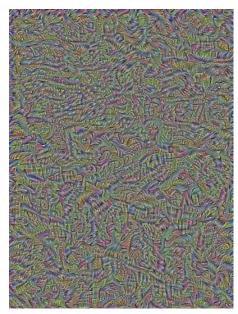
Iteration 300



Iteration 990



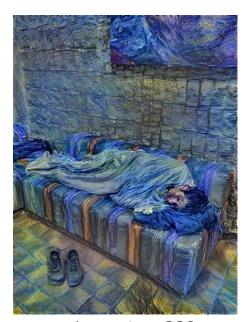
Implementation of Neural Style Transfer



Iteration 10



Iteration 300



Iteration 990



Let's (finally) start building it!

- → Go to https://github.com/anishathalye/neural-style
- → This is the NST implementation we will be rebuilding.
- → Download the file at the bottom:

→ This is our pretrained VGGNet that we will be using in our implementation. (pre-training a convnet is time-consuming!)



The Pre-trained Network

- → This network was trained on ImageNet (it can presumably classify images)
- → Open the file in MATLAB
- → If you don't have MATLAB, that's ok Python to come!



Implementing a Neural Network

- → *Architecting*: constructing the architecture of the neural network
- → *Preprocessing*: preprocessing the data so that it is in a form we can train on
- → *Training*: getting those perfect weights
- → *Testing/generating*: using the trained network to generate a result

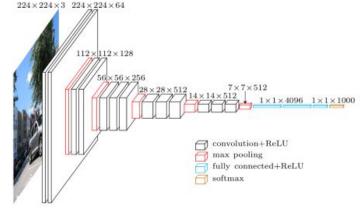


Implementation: Architecture

→ Open a new file. This will be our initialization of the architecture of the network.

→ First, we will initialize a dictionary of keys to refer back to the weight layers of our network, based on the .mat

file.





Upcoming Events with BUMIC

- → Impact of AI discussion group: 4/4/18
- → Next TensorFlow session: 4/11/18 @ 7pm
 - Continuing NST: Finishing architecture and training the network







