Ph.D. Student



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Bumjin Park

My research focuses on understanding Al's **mind** through rigorous and precise analysis based on scientific assumptions about the "brain" of Al, neural representations. Just as **epistemology** has long sought to interpret human cognition, I explore the fundamental principles that shape both human and artificial intelligence.

I work on Cognitive Science, Mechanistic Interpretability, Explainable AI, Large Language Models, Multi-Agent Systems, and Communication, leveraging mathematics and programming to drive my research.

My long-term goal is to uncover the **General Principles of Mind** that underlie both human and Al intelligence and to advance philosophical and scientific research that enables their efficient utilization.

Education •

Ph.D. in Artificial Intelligence

09/2023 - Present

Korea Advanced Institute of Science and Technology (KAIST), AI Graduate School

- Proposal: Integrating Cognitive Architectures into Large Language Models [Drive]

M.S. in Artificial Intelligence (4.17/4.3)

09/2021 - 08/2023

Korea Advanced Institute of Science and Technology (KAIST), AI Graduate School

- Thesis: Partitioned Channel Gradient for Reliable Saliency Map in Image Classification [Drive]

B.S. in Mathematics (Double Major in Software Engineering) (4.39/4.5) Chung-Ang University, Korea

03/2018 - 08/2020

Publication

IJCAI Memorizing Documents with Guidance in Large Language Models [IJCAI]

Bumjin Park, Jaesik Choi

International Joint Conference on Artificial Intelligence, 2024

ICPRAI Identifying the Source of Generation for Large Language Models [Springer Nature]

Bumjin Park, Jaesik Choi

Pattern Recognition and Artificial Intelligence, 2024

Applied Sci. Message Action Adapter Framework in Multi-Agent Reinforcement [Appl. Sci.]

Learning

Bumjin Park, Jaesik Choi *Applied Sciences*, 2025

Applied Sci. Cooperative Multi-Robot Task Allocation with Reinforcement Learning [Appl. Sci.]

properties many model task anodation with remote enter Learning

Bumjin Park, Cheongwoong Kang, Jaesik Choi

Applied Sciences, 2022

Sensors Scheduling PID Attitude and Position Control Frequencies for [Sensors]

Time-Optimal Quadrotor Waypoint Tracking under Unknown External

Disturbances

Cheongwoong Kang, Bumjin Park, Jaesik Choi

Sensors, 2021

ICCAS Generating Multi-Agent Patrol Areas by Reinforcement Learning [IEEE] Bumjin Park, Cheongwoong Kang, and Jaesik Choi 2021 21st International Conference on Control, Automation and Systems (ICCAS), IEEE UnderReview AlchemyNet: Learning Material Composition Distributions for Property [Drive] Prediction Bumjin Park, Jihyun Jun, Jungeun Lee, Hyungjin Bae, Jinmo Kim, Sangkeun Han, Jaesik Choi Pattern Recognition Letters UnderReview Deontological Keyword Bias: The Impact of Modal Verbs on Normative [Drive] **Judgments of Language Models** Bumjin Park*, Jinsil Lee*, Jaesik Choi (* equally contributed) ACL 2025

Project •

ADD (Agency for Defense Development) - Unmanned Swarm CPS Research Lab 10/2021 - Present

Multi-agent swarm intelligence interacting with physical and simulated environments (Cyber-Physical System).

Skills:

- Multi-agent reinforcement learning for patrol and communication.
- Simulation-to-reality (Sim-to-Real) transfer using domain adaptation.
- ROS-based communication between physical and simulated environments (Gazebo and Webots) for both UAVs (DJI) and UGVs (Husarion Rosbot). [Youtube Demo]

Achievements:

- Publications: Journal (2) / Conference (1) / Domestic Journal (1) / Domestic Conference (4)
- Patent Applications (2), Registered Patent (1)
- Software Registrations (2)
- KTL Certified Evaluations (2)

Kolmar - AlchemyNet & Domain Knowledge (Phase 2)

11/2024 - Present

Phase 2 of cosmetic Al leveraging domain knowledge for AlchemyNet.

- Publications: Journal (Under Review: 1) / Conference (Under Review: 1)
- Web Application (1)

Kolmar - Al for Cosmetic Composition (Phase 1)

08/2023 - 03/2024

Development of **AlchemyNet** (inspired by the concept of an alchemist) to encode formulation compositions and predict multiple properties, including viscosity, pH, density, and hardness.

Global AI Frontier LAB

08/2024 - Present

Interpretation of bias representation in Large Language Models based on mechanistic Interpretability.

Minor Projects - Short Term Projects

X-Ray Object Detection and Saliency

08/2024

This study applies XAI techniques, such as attribution maps, to enhance the interpretability of X-ray object detection models. By analyzing decision-making in overlapping object scenarios, it improves model transparency and aids multi-object detection.

| 정보과학회 | 대형언어모델 생성 텍스트의 원천 문서 추적 박범진, 최재식 정보과학회지 특집원고, 2024 | [Drive] |
|-------|---|---------|
| KSC | 대형 언어 모델의 문장 표현의 설명가능적 해석 박범진, 최재식 한국정보과학회 (KSC), 2024 | [Drive] |
| KIMST | 자연어 명령어 기반 군집 로봇 제어 프레임워크 박범진, 최재식 한국군사과학기술학회 (KIMST), 2024 | [Drive] |
| KIMST | 배터리 효율성을 위한 강화학습 로봇 제어 장원준, 박범진, 최재식 한국군사과학기술학회 (KIMST), 2024 | [Drive] |
| ICROS | 멀티 에이전트 강화학습에서의 게이트 기반 메시지 교환 박범진, 강청웅, 최재식 Journal of Institute of Control, Robotics and Systems (ICROS), 2023 | [Drive] |
| KROS | 샘플 필터링을 통한 효율적인 강화학습 모델 지식 증류 박범진, 강청웅, 최재식 한국로봇학회 (KROS), 2023 | [Drive] |
| KIMST | 계층별 관련도 전파 기반 무인이동로봇 강화학습 의사결정 과정 자동 분석 강청웅, 박범진, 최재식 한국군사과학기술학회 (KIMST), 2022 | [Drive] |
| KIMST | 심층강화학습 기반 목표물 추적 시스템에서 다중 목적 함수 분석 강청웅, 박범진, 최재식 한국군사과학기술학회 (KIMST), 2021 | [Drive] |