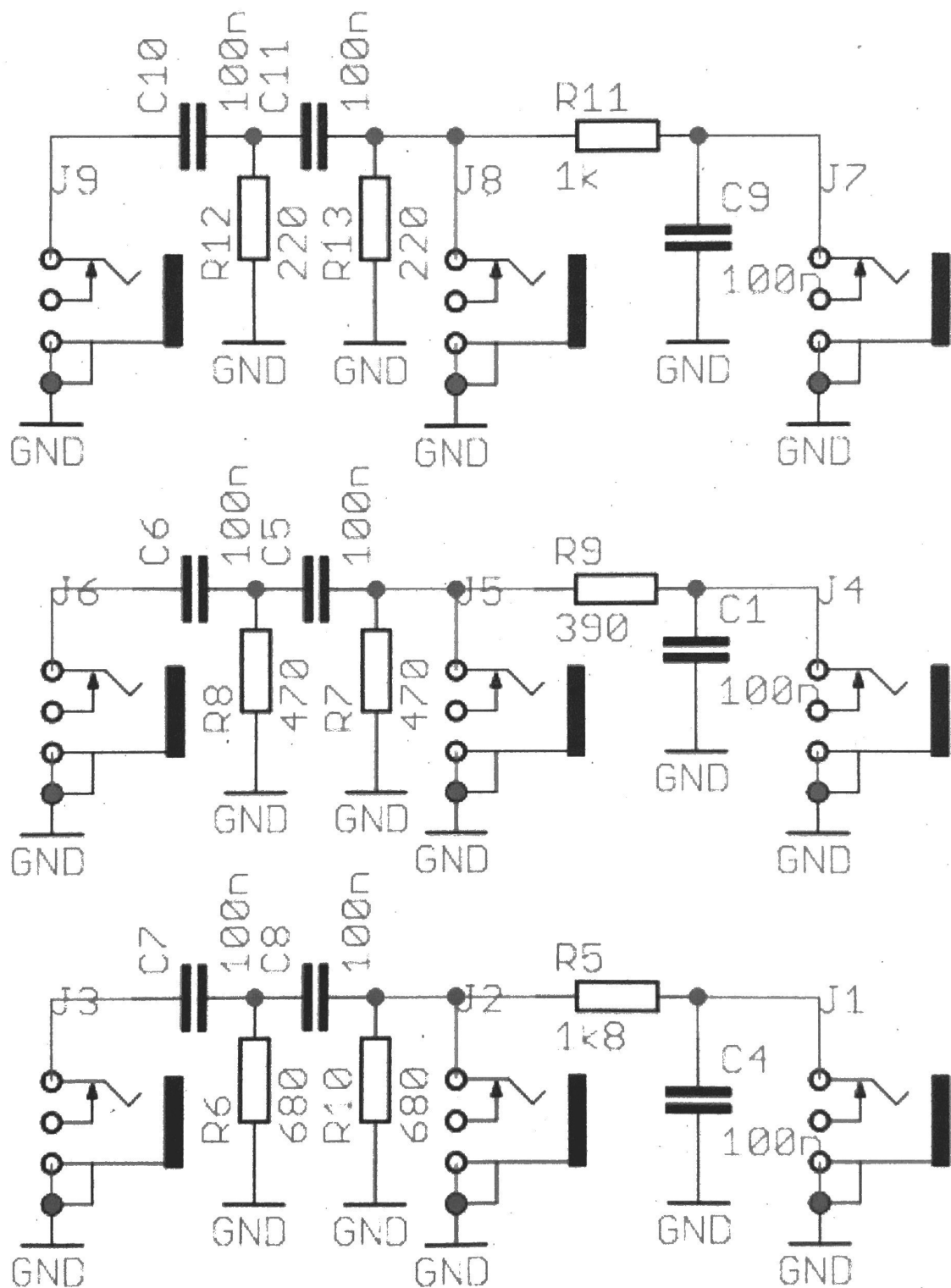


# Triple Passive Filter



# Triple Passive Filter ( $S_n \pm L$ )

