

```

graph = {}
edge_node = set()

def add_node(node):
    if node in graph:
        print(f"This node '{node}' already exists. Enter a new node:")
        return False
    graph[node] = []
    return True

def add_edge(u, v):
    edge = (u, v)
    if edge in edge_node:
        print(f"Edge {u}-{v} already exists. Enter a different edge.")
        return False
    if u not in graph or v not in graph:
        print("Enter nodes before connecting edges.")
        return False
    graph[u].append(v)
    edge_node.add(edge)
    return True

visited_bfs = []
queue = []

def bfs(start):
    visited_bfs.clear()
    queue.clear()
    queue.append(start)
    visited_bfs.append(start)
    while queue:
        node = queue.pop(0)
        print(node, end=" ")
        for neighbor in graph[node]:
            if neighbor not in visited_bfs:
                visited_bfs.append(neighbor)
                queue.append(neighbor)

visited_dfs = []

def dfs(start):
    visited_dfs.clear()
    _dfs_helper(start)

def _dfs_helper(node):
    visited_dfs.append(node)
    print(node, end=" ")
    for neighbor in graph[node]:
        if neighbor not in visited_dfs:
            _dfs_helper(neighbor)

```

```

# Input nodes
n = int(input("Enter number of nodes: "))
i = 0
while i < n:
    node = input(f"Enter node {i+1}: ").strip()
    if add_node(node):
        i += 1

# Input edges
e = int(input("Enter number of edges: "))
for i in range(e):
    while True:
        u, v = input(f"Enter edge {i+1} (two nodes separated by space): ").split()
        if add_edge(u, v):
            break

start = input("Enter starting node: ").strip()
if start in graph:
    print("BFS: ")
    bfs(start)
    print("\nDFS: ")
    dfs(start)
else:
    print("Start node not found.")

```

```

Enter number of nodes: 7
Enter node 1: 5
Enter node 2: 2
Enter node 3: 3
Enter node 4: 4
Enter node 5: 8
Enter node 6: 6
Enter node 7: 7
Enter number of edges: 6
Enter edge 1 (two nodes separated by space): 5 2
Enter edge 2 (two nodes separated by space): 5 3
Enter edge 3 (two nodes separated by space): 2 4
Enter edge 4 (two nodes separated by space): 2 8
Enter edge 5 (two nodes separated by space): 3 6
Enter edge 6 (two nodes separated by space): 8 7
Enter starting node: 5

```

```

BFS:
5 2 3 4 8 6 7
DFS:
5 2 4 8 7 3 6

```

```

def aStarAlgo(start_node, stop_node):
    open_set = set([start_node])
    closed_set = set()
    g = {}
    parents = {}
    g[start_node] = 0
    parents[start_node] = start_node
    while len(open_set) > 0:
        n = None
        for v in open_set:
            if n is None or g[v] + heuristic(v) < g[n] + heuristic(n):
                n = v
        if n is None:
            print('Path does not exist!')
            return None
        if n == stop_node:
            path = []
            while parents[n] != n:
                path.append(n)
                n = parents[n]
            path.append(start_node)
            path.reverse()
            print('Path found: {}'.format(path))
            return path
        for (m, weight) in get_neighbors(n) or []:
            if m not in open_set and m not in closed_set:
                open_set.add(m)
                parents[m] = n
                g[m] = g[n] + weight
            else:
                if g[m] > g[n] + weight:
                    g[m] = g[n] + weight
                    parents[m] = n
                    if m in closed_set:
                        closed_set.remove(m)
                        open_set.add(m)
        open_set.remove(n)
        closed_set.add(n)
    print('Path does not exist!')
    return None
def get_neighbors(v):
    if v in Graph_nodes:
        return Graph_nodes[v]
    else:
        return None
def heuristic(n):
    H_dist = {
        'A': 11,
        'B': 6,

```

```
'C': 99,
'D': 1,
'E': 7,
'G': 0,
}
return H_dist.get(n, float('inf'))
Graph_nodes = {
    'A': [(['B', 2), ('E', 3)],
    'B': [(['C', 1), ('G', 9)],
    'C': None,
    'E': [(['D', 6)],
    'D': [(['G', 1)],
    'G': None
}

aStarAlgo('A', 'G')

Path found: ['A', 'E', 'D', 'G']
['A', 'E', 'D', 'G']
```

```

from sys import maxsize
from itertools import permutations
v=4
def travellingSalesmanProblem(graph,s):
    vertex=[]
    for i in range(v):
        if i!=s:
            vertex.append(i)
    min_path=maxsize
    next_permutation=permutations(vertex)
    for i in next_permutation:
        current_pathweight=0
        k=s
        for j in i:
            current_pathweight+=graph[k][j]
            k=j
        current_pathweight+=graph[k][s]
        min_path=min(min_path,current_pathweight)
    return min_path
graph=[[0,3,6,8],[3,0,9,4],[6,9,0,2],[8,4,2,0]]
s=0
print(travellingSalesmanProblem(graph,s))

15

colors=['Red','Blue','Green']
states=['a','b','c','d']
neighbours={}
neighbours['a']=['b','c','d']
neighbours['b']=['a','d']
neighbours['c']=['a','d']
neighbours['d']=['c','b','a']
colors_of_states={}
def promising(state,color):
    for neighbour in neighbours.get(state):
        color_of_neighbour=colors_of_states.get(neighbour)
        if color_of_neighbour==color:
            return False
    return True
def get_color_for_state(state):
    for color in colors:
        if promising(state,color):
            return color
def main():
    for state in states:
        colors_of_states[state]=get_color_for_state(state)
    print(colors_of_states)
main()

{'a': 'Red', 'b': 'Blue', 'c': 'Blue', 'd': 'Green'}

```



```
from sympy import symbols, Or ,Not ,Implies ,Xor,satisfiable
Rain= symbols('Rain');
Harry_Visted_Hagrid = symbols('Harry_Visted_Hagrid')
Harry_Visted_Dumbledore=symbols('Harry_Visted_Dumbledore')
sentence_1= Implies(Not(Rain),Harry_Visted_Hagrid)
sentence_2=Xor(Harry_Visted_Hagrid,Harry_Visted_Dumbledore)
sentence_3=Harry_Visted_Dumbledore
knowledge_base =sentence_1 & sentence_2 & sentence_3
solution =satisfiable(knowledge_base,all_models=True)
for model in solution:
    if model[Rain]:
        print("it rained today:")
    else:
        print("there is no rain today")
it rained today:
```

```

P_burglary=0.002
P_earthquake=0.001
P_alarm_given_burglary_and_earthquake=0.94
P_alarm_given_bugrlary_and_no_earthquake=0.95
P_alarm_given_no_burglary_and_earthquake=0.31
P_alarm_given_no_burglary_and_no_earthquake=0.001
P_david_calls_given_alarm=0.91
P_david_does_not_call_given_alarm=0.09
P_david_calls_given_no_alarm=0.05
P_david_does_not_call_given_no_alarm=0.95
P_sophia_calls_given_alarm=0.75
P_sophia_does_not_call_given_alarm=0.25
P_sophia_calls_given_no_alarm=0.02
P_sophia_does_not_call_given_no_alarm=0.98
def joint_probability(alarm,burglary,earthquake,david_calls,sophia_calls):
    if alarm:
        if burglary and earthquake:
            P_alarm=P_alarm_given_burglary_and_earthquake
        elif burglary:
            P_alarm=P_alarm_given_bugrlary_and_no_earthquake
        elif earthquake:
            P_alarm=P_alarm_given_no_burglary_and_earthquake
        else:
            P_alarm=P_alarm_given_no_burglary_and_no_earthquake
    else:
        if burglary and earthquake:
            P_alarm=1-P_alarm_given_burglary_and_earthquake
        elif burglary:
            P_alarm=1-P_alarm_given_bugrlary_and_no_earthquake
        elif earthquake:
            P_alarm=1-P_alarm_given_no_burglary_and_earthquake
        else:
            P_alarm=1-P_alarm_given_no_burglary_and_no_earthquake
    P_david=(P_david_calls_given_alarm if david_calls else
P_david_does_not_call_given_alarm) if alarm else
(P_david_calls_given_no_alarm if david_calls else
P_david_does_not_call_given_no_alarm)
    P_sophia=(P_sophia_calls_given_alarm if sophia_calls else
P_sophia_does_not_call_given_alarm) if alarm else
(P_sophia_calls_given_no_alarm if sophia_calls else
P_sophia_does_not_call_given_no_alarm)
    return (P_burglary if burglary else 1- P_burglary)*(P_earthquake
if earthquake else 1-P_earthquake)*P_alarm*P_david*P_sophia
result=joint_probability(
    alarm=True,
    burglary=False,
    earthquake=False,
    david_calls=True,

```

```
    sophia_calls=True
)
print(f'{result:.8f}')
0.00068045
```

```

import numpy as np
class HMM:
    def __init__(self , states , observations):
        self.states = states
        self.n_states = len(states)
        self.n_obs = len(observations)
        self.state_index = {state: i for i, state in
enumerate(states)}
        self.obs_index = {obs: i for i, obs in
enumerate(observations)}
        self.A = np.array([[0.6,0.3,0.1],[0.2,0.5,0.3],[0.1,0.4,0.5]])
        self.B = np.array([[0.8,0.15,0.05],[0.3,0.4,0.3],
[0.1,0.2,0.7]])
        self.pi = np.array([0.5,0.3,0.2])
    def forward(self, obs_seq):
        n = len(obs_seq)
        alpha = np.zeros((n, self.n_states))
        alpha[0] = self.pi * self.B[:, obs_seq[0]]
        for t in range(1, n):
            for j in range(self.n_states):
                alpha[t, j] = (alpha[t-1] @ self.A[:, j]) * self.B[j,
obs_seq[t]]
        return alpha.sum(axis=1)[-1]
states = ['Sunny','Cloudy','Rainy']
observations = ['Umbrella','Normal', 'Raincoat']
hmm = HMM(states, observations)
obs_seq = ['Umbrella', 'Normal', 'Umbrella','Raincoat']
obs_seq_indices = [hmm.obs_index[obs] for obs in obs_seq]
prob = hmm.forward(obs_seq_indices)
print(f"Probability of the observation sequence '{obs_seq}':\n{prob:.4f}")

Probability of the observation sequence '['Umbrella', 'Normal',
'Umbrella', 'Raincoat']': 0.0133

```

```
import numpy as np
import pandas as pd
import matplotlib.pyplot as plt

dataset=pd.read_csv('Salary_Data.csv')
dataset.head()

    YearsExperience    Salary
0              1.1  39343.0
1              1.3  46205.0
2              1.5  37731.0
3              2.0  43525.0
4              2.2  39891.0

from sklearn.model_selection import train_test_split
x_train,x_test,y_train,y_test=train_test_split(x,y,test_size=1/3,random_state=0)
x_test

array([[ 1.5],
       [10.3],
       [ 4.1],
       [ 3.9],
       [ 9.5],
       [ 8.7],
       [ 9.6],
       [ 4. ],
       [ 5.3],
       [ 7.9]])

x=dataset.iloc[:, :-1].values
y=dataset.iloc[:, -1].values
x

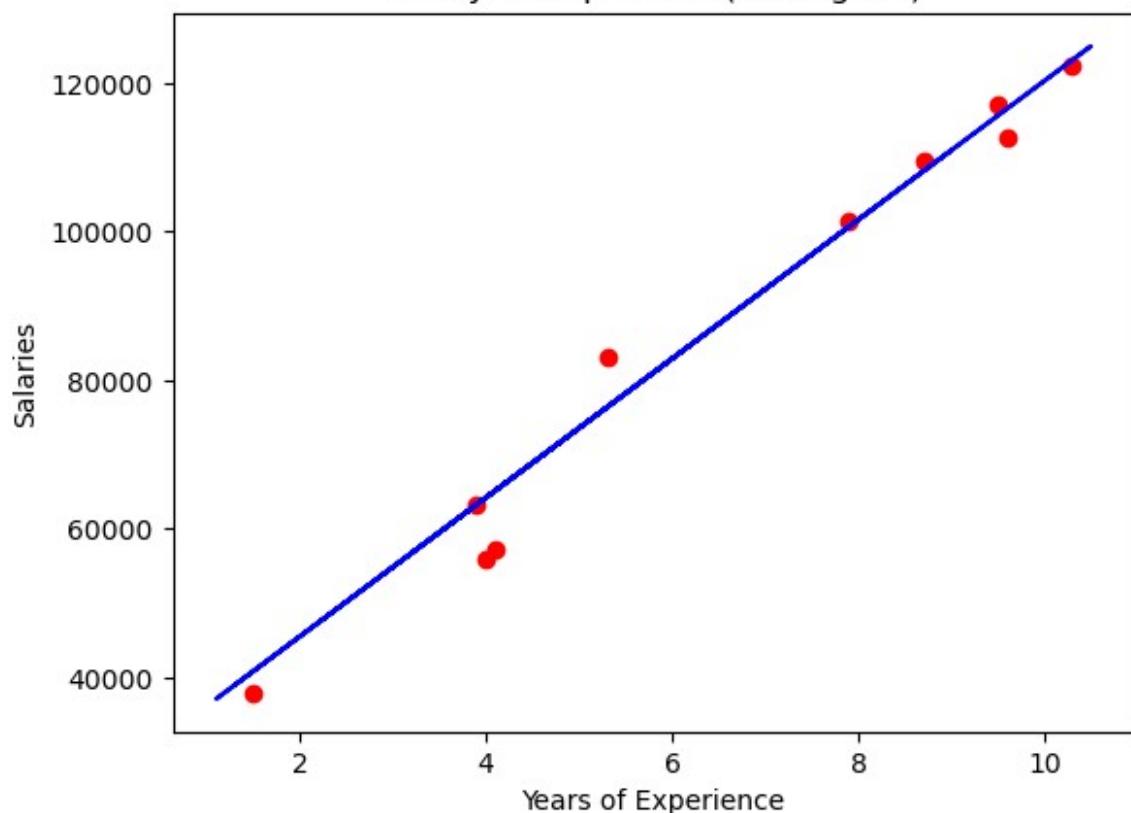
array([[ 1.1],
       [ 1.3],
       [ 1.5],
       [ 2. ],
       [ 2.2],
       [ 2.9],
       [ 3. ],
       [ 3.2],
       [ 3.2],
       [ 3.7],
       [ 3.9],
       [ 4. ],
       [ 4. ],
       [ 4.1],
       [ 4.5],
       [ 4.9],
       [ 5.1],
```

```
[ 5.3],  
[ 5.9],  
[ 6. ],  
[ 6.8],  
[ 7.1],  
[ 7.9],  
[ 8.2],  
[ 8.7],  
[ 9. ],  
[ 9.5],  
[ 9.6],  
[10.3],  
[10.5]))  
  
from sklearn.linear_model import LinearRegression  
regressor=LinearRegression()  
regressor.fit(x_train,y_train)  
  
LinearRegression()  
  
y_pred=regressor.predict(x_test)  
y_pred  
  
array([ 40835.10590871, 123079.39940819, 65134.55626083,  
63265.36777221,  
115602.64545369, 108125.8914992 , 116537.23969801,  
64199.96201652,  
76349.68719258, 100649.1375447 ])  
  
y_test  
  
array([ 37731., 122391., 57081., 63218., 116969., 109431., 112635.,  
55794., 83088., 101302.])  
  
plt.scatter(x_train,y_train,color='red')  
plt.plot(x_train,regressor.predict(x_train),color='blue')  
plt.title("Salary vs Experience(Training set)")  
plt.xlabel("Years of Experience")  
plt.ylabel("Salaries")  
plt.show()
```



```
plt.scatter(x_test,y_test,color='red')
plt.plot(x_train,regressor.predict(x_train),color='blue')
plt.title("Salary vs Experience(Testing set)")
plt.xlabel("Years of Experience")
plt.ylabel("Salaries")
plt.show()
```

Salary vs Experience(Testing set)



```

import pandas as pd
from collections import Counter
import math
from pprint import pprint

data={
    'Outlook':['Sunny','Sunny','Overcast','Rain'],
    'Humidity':['High','Normal','High','Normal'],
    'PlayTennis':['No','Yes','Yes','Yes']
}

df=pd.DataFrame(data)
df

   Outlook Humidity PlayTennis
0      Sunny     High        No
1      Sunny   Normal       Yes
2   Overcast     High       Yes
3       Rain   Normal       Yes

def entropy(probs):
    return sum(-prob * math.log(prob,2) for prob in probs if prob >0)

def entropy_of_list(a_list):
    cnt=Counter(a_list)
    num_instances=len(a_list)
    probs=[x/num_instances for x in cnt.values()]
    return entropy(probs)

def information_gain(df, split_attribute_name, target_attribute_name):
    df_split = df.groupby(split_attribute_name)
    nobs = len(df.index) * 1.0
    df_agg_ent = df_split[target_attribute_name].agg([entropy_of_list,
lambda x: len(x) / nobs])
    avg_info = sum(df_agg_ent['entropy_of_list'] * df_agg_ent['<lambda_0>'])
    old_entropy = entropy_of_list(df[target_attribute_name])
    return old_entropy - avg_info

def id3DT(df,target_attribute_name,attribute_names,default_class=None):
    cnt=Counter(df[target_attribute_name])
    if len(cnt)==1:
        return next(iter(cnt))
    elif df.empty or not attribute_names:
        return default_class
    else:
        default_class=max(cnt,key=cnt.get)
        gainz=[information_gain(df,attr,target_attribute_name) for
attr in attribute_names]
        index_of_max=gainz.index(max(gainz))

```

```
best_attr=attribute_names[index_of_max]
tree={best_attr:{}}
remaining_attributes=[i for i in attribute_names if i!=best_attr]
for attr_val, data_subset in df.groupby(best_attr):
    subtree=
id3DT(data_subset,target_attribute_name,remaining_attributes,default_class)
    tree[best_attr][attr_val]=subtree
return tree

attribute_names=list(df.columns)
attribute_names.remove('PlayTennis')
attribute_names

['Outlook', 'Humidity']

tree=id3DT(df, 'PlayTennis',attribute_names)
print("The Resultant Decision Tree is:")
pprint(tree)

The Resultant Decision Tree is:
{'Outlook': {'Overcast': 'Yes',
             'Rain': 'Yes',
             'Sunny': {'Humidity': {'High': 'No', 'Normal': 'Yes'}}}}
```





```

import numpy as np
def sigmoid(x):
    return 1/(1+np.exp(-x))
def sigmoid_derivative(x):
    return x*(1-x)
X=np.array([[0,0],[0,1],[1,0],[1,1]])
y=np.array([[0],[1],[1],[0]])
input_layer_neurons=2
hidden_layer_neurons=4
output_layer_neurons=1
epochhs=10000
learning_rate=0.1
np.random.seed(42)
wh=np.random.uniform(size=(input_layer_neurons,hidden_layer_neurons))
bh=np.random.uniform(size=(1,hidden_layer_neurons))
wout=np.random.uniform(size=(hidden_layer_neurons,output_layer_neurons))
bout=np.random.uniform(size=(1,output_layer_neurons))
for epoch in range(epochhs):
    hidden_layer_input=np.dot(X,wh)+bh
    hidden_layer_output=sigmoid(hidden_layer_input)
    output_layer_input=np.dot(hidden_layer_output,wout)+bout
    output=sigmoid(output_layer_input)
    error=y-output
    output_layer_gradient=sigmoid_derivative(output)
    d_output=error*output_layer_gradient
    hidden_layer_gradient=sigmoid_derivative(hidden_layer_output)
    d_hidden_layer=d_output.dot(wout.T)*hidden_layer_gradient
    wout+=hidden_layer_output.T.dot(d_output)*learning_rate
    bout+=np.sum(d_output, axis=0, keepdims=True)*learning_rate
    wh+=X.T.dot(d_hidden_layer)*learning_rate
    bh+=np.sum(d_hidden_layer, axis=0, keepdims=True)*learning_rate
    if epoch%1000==0:
        print(f"Epoch {epoch}, Error:{np.mean(np.abs(error))}")
print("Final predictions after training:")
print(output)

Epoch 0,Error:0.49914791405546904
Epoch 1000,Error:0.4989908274224632
Epoch 2000,Error:0.49392112204426847
Epoch 3000,Error:0.46086324847622706
Epoch 4000,Error:0.37081148754970517
Epoch 5000,Error:0.22936859341508165
Epoch 6000,Error:0.14117007926640454
Epoch 7000,Error:0.10187019467760634
Epoch 8000,Error:0.08085064924133509
Epoch 9000,Error:0.06790718296112103
Final predictions after training:
[[0.04690963]
 [0.95663392]]

```

[0.92548675]  
[0.07177571]]

```

import numpy as np
import matplotlib.pyplot as plt
from sklearn.svm import SVC
from sklearn.metrics import classification_report,accuracy_score

data=np.array([
    [1.5,2.0,1],
    [1.0,1.0,1],
    [2.0,2.5,1],
    [2.5,1.5,1],
    [3.0,1.0,0],
    [3.5,0.5,0],
    [4.0,1.0,0],
    [4.5,1.5,0]
])
X=data[:, :2]
y=data[:, 2]
svm_model=SVC(kernel='linear')
svm_model.fit(X,y)

SVC(kernel='linear')

y_pred=svm_model.predict(X)
print("Accuracy:",accuracy_score(y,y_pred))
print("\nClassification Report:\n",classification_report(y,y_pred))

Accuracy: 1.0

Classification Report:
      precision    recall  f1-score   support

       0.0       1.00     1.00     1.00      4
       1.0       1.00     1.00     1.00      4

  accuracy                           1.00      8
   macro avg       1.00     1.00     1.00      8
weighted avg       1.00     1.00     1.00      8

x_min,x_max=X[:,0].min()-1,X[:,0].max()+1
y_min,y_max=X[:,1].min()-1,X[:,1].max()+1
xx,yy=np.meshgrid(np.arange(x_min,x_max,0.01),np.arange(y_min,y_max,0.01))
print("xx=",xx)
print("yy=",yy)
Z=svm_model.predict(np.c_[xx.ravel(),yy.ravel()])
Z=Z.reshape(xx.shape)
print("Z=",Z)

```

```

xx= [[0.    0.01 0.02 ... 5.47 5.48 5.49]
 [0.    0.01 0.02 ... 5.47 5.48 5.49]
 [0.    0.01 0.02 ... 5.47 5.48 5.49]
 ...
 [0.    0.01 0.02 ... 5.47 5.48 5.49]
 [0.    0.01 0.02 ... 5.47 5.48 5.49]
 [0.    0.01 0.02 ... 5.47 5.48 5.49]]
yy= [[-0.5   -0.5   -0.5   ...  -0.5   -0.5   -0.5 ]
 [-0.49  -0.49  -0.49  ...  -0.49  -0.49  -0.49]
 [-0.48  -0.48  -0.48  ...  -0.48  -0.48  -0.48]
 ...
 [ 3.47   3.47   3.47   ...   3.47   3.47   3.47]
 [ 3.48   3.48   3.48   ...   3.48   3.48   3.48]
 [ 3.49   3.49   3.49   ...   3.49   3.49   3.49]]
Z= [[1.  1.  1.  ...  0.  0.  0.]
 [1.  1.  1.  ...  0.  0.  0.]
 [1.  1.  1.  ...  0.  0.  0.]
 ...
 [1.  1.  1.  ...  0.  0.  0.]
 [1.  1.  1.  ...  0.  0.  0.]
 [1.  1.  1.  ...  0.  0.  0.]]
plt.figure(figsize=(10,6))
plt.contourf(xx,yy,Z,alpha=0.2,cmap='coolwarm')
plt.scatter(X[:,0],X[:,1],c=y, cmap='coolwarm',edgecolor='k',s=100)
plt.xlabel("Feature 1 (e.g., Positivity Score)")
plt.ylabel("Feature 2 (e.g., Intensity Score)")
plt.title("SVM Decision Boundary on 2-Feature Sentiment Data")
plt.show()

```

SVM Decision Boundary on 2-Feature Sentiment Data

