

# Homework 3

Tongji University 2022 Class Computer Science and Technology College Software Engineering Major  
Machine Intelligence Direction Computer Vision Course Assignment

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## Nonlinear Least Square (NLS) Method

According to the problem, we have:

$$L(h) = \frac{1}{2} (f(x+h))^T f(x+h) + \frac{1}{2} \mu h^T h \quad (1)$$

$$= \frac{1}{2} (f(x))^T f(x) + h^T (J(x))^T f(x) + \frac{1}{2} h^T (J(x))^T J(x) h + \frac{1}{2} \mu h^T h \quad (2)$$

The first derivative can be derived as:

$$dL = (J(x))^T f(x) + (J(x))^T J(x) h + \mu h \quad (3)$$

And the second derivative is:

$$d^2 L = (J(x))^T J(x) + \mu I \quad (4)$$

where  $I$  is the identity matrix.

Let  $A = (J(x))^T J(x)$ , and replace  $J(x)$  with  $J$ . We can obtain:

For any  $x \neq 0$ , let  $y = Jx$ , then:

$$0 \leq y^T y = (Jx)^T Jx = x^T J^T Jx = x^T Ax$$

Thus,  $A$  is positive semi-definite.

For all eigenvalues  $(\lambda_i \geq 0, i = 1, 2, \dots, n)$  of  $A$ , we have:

$$Av_i = \lambda_i v_i$$

And it follows that:

$$(A + \mu I)v_i = (\lambda_i + \mu)v_i$$

All eigenvalues of  $(A + \mu I)$  satisfy  $(\lambda_i + \mu) > 0, i = 1, 2, \dots, n$ .

Therefore,  $(A + \mu I)$  is positive definite, i.e.:

$$(J^T J + \mu I)$$

is positive definite.

Since  $d^2 L = J^T J + \mu I$ , it can be concluded that  $L(h)$  is a strictly convex function.

## Speed Belt Ranging

After training with YOLO and obtaining the `best.pt` file, the folder contains a test video (HW3\_Pro2.mp4) with a bounding box. Below is the effect of one of the frames:



## Experimental Report on 3D Model Scanning and Data Processing

See folder contents for details: [.../CV\\_2251730\\_Liu Shuyi\\_Assignment3/HW3\\_Experiment3.pdf](#)