Physics Exam Answers

Question 1

(a) Forces on Freight Trucks

Given: Three trucks of mass m each pulled by force F with negligible friction.

Solution:

- 1. Total mass of system = 3m
- 2. Acceleration of system (a) = F/(3m)
- 3. Force on first truck (closest to locomotive):

$$F_1 = ma = m(F/3m) = F/3$$
 (to the right)

4. Force on middle truck:

$$F_2 = 2ma - F_1 = 2m(F/3m) - F/3 = 2F/3 - F/3 = F/3$$
 (to the right)

5. Force on last truck:

$$F_3 = 3ma - F_1 - F_2 = F - F/3 - F/3 = F/3$$
 (to the right)

Answer: Each truck experiences a force of F/3 in the rightward direction.

(b) Moment of Inertia

Definition: Moment of inertia (I) of a body about an axis is the sum of the products of the mass of each particle and the square of its perpendicular distance from the axis.

Physical Significance:

- Rotational analogue of mass in linear motion
- Measures resistance to angular acceleration
- Depends on mass distribution relative to rotation axis
- Determines rotational kinetic energy $(K = \frac{1}{2}I\omega^2)$

(c) Work Done in Force Field

Given: Force field $\vec{F} = 3x^2\hat{i} + (2xz - y)\hat{j} + z\hat{k}$ along path (0, 0, 0) to (2, 1, 3)

Solution: Parametric equations of straight line: x = 2t, y = t, z = 3t (t from 0 to 1)

Work done $W = \int \vec{F} \cdot d\vec{r} = \int (3x^2dx + (2xz - y)dy + zdz)$

$$= \int_0^1 [3(2t)^2 (2dt) + (2(2t)(3t) - t)(dt) + 3t(3dt)]$$

$$= \int_0^1 (24t^2 + 12t^2 - t + 9t)dt$$

$$= \int_0^1 (36t^2 + 8t)dt$$

$$= \left[12t^3 + 4t^2\right]_0^1 = 16 \text{ J}$$

Answer: 16 Joules

(d) Astronaut's Effective Weight

Given: m = 70 kg, a = 5g upward

Solution: Effective weight = $m(g+a) = 70(9.81 + 5 \times 9.81) = 70 \times 6 \times 9.81 = 4120.2 \text{ N}$

Answer: 4120.2 N ($\approx 420 \text{ kg equivalent}$)

(e) Loss in Mechanical Energy

Given: Mass M, initial speed V_0 , spring constant k, $\mu = bx$

Solution: Initial energy $= \frac{1}{2}MV_0^2$ When comes to rest $(x = x_k)$: Work against friction $= \int \mu Mgdx = \int bxMgdx = \frac{1}{2}bMgx_k^2$ Spring energy $= \frac{1}{2}kx_k^2$ By energy conservation: $\frac{1}{2}MV_0^2 = \frac{1}{2}kx_k^2 + \frac{1}{2}bMgx_k^2$ Loss $= \text{Initial} - \text{Final} = \frac{1}{2}MV_0^2 - \frac{1}{2}kx_k^2 = \frac{1}{2}bMgx_k^2$

Answer: Loss = $\frac{1}{2}bMgx_k^2$ where x_k is compression at rest

(f) Sphere vs Cylinder on Incline

Solution: Acceleration on incline: $a = \frac{g \sin \theta}{1 + I/MR^2}$ For sphere: $I = \frac{2}{5}MR^2 \Rightarrow a_{\rm sphere} = \frac{5}{7}g \sin \theta$ For cylinder: $I = \frac{1}{2}MR^2 \Rightarrow a_{\rm cylinder} = \frac{2}{3}g \sin \theta$ Since 5/7 > 2/3, sphere accelerates faster.

Answer: The sphere reaches the bottom first.

(g) Relative Speed of Spaceships

Given: Both moving apart at 0.99c in observer frame

Solution: Use relativistic velocity addition:

$$v = \frac{v_1 + v_2}{1 + v_1 v_2 / c^2} = \frac{0.99c + 0.99c}{1 + 0.99^2} \approx 0.99995c$$

Answer: Approximately 0.99995c

Question 2

(a) Center of Mass Location

Answer: No, the center of mass doesn't necessarily lie within the body. Examples:

- A ring (COM at center where there's no material)
- A boomerang (COM often in empty space between arms)
- L-shaped object (COM may be outside main body)

(b) Bomb-shell Explosion

Proof:

- 1. Before explosion: Trajectory determined by initial velocity and gravity
- 2. During explosion: Internal forces act in pairs (Newton's 3rd law)
- 3. No external force (neglecting air resistance), so COM continues original path
- 4. Fragments' COM must follow same path as original shell

(c) Rocket Equation

Derivation: From momentum conservation:

MdV = udM (where u =exhaust velocity)

$$\int dV = u \int \frac{dM}{M} \Rightarrow \Delta V = u \ln \left(\frac{M_0}{M_f}\right)$$

Thus $\frac{M_f}{M_0} = e^{-\Delta V/u}$

Question 3

(a) Fictitious Forces

Definition: Apparent forces that appear in non-inertial frames. Examples:

- Centrifugal force (in rotating frames)
- Coriolis force (for moving objects in rotating frames)
- Euler force (when rotation rate changes)

(b) Potential Energy Curve

Importance:

- Shows stable/unstable equilibrium points
- Predicts motion without solving equations
- Indicates allowed regions of motion

Definitions:

- Turning point: Where total energy = potential energy (kinetic energy zero)
- Equilibrium points: Where dU/dx = 0
 - Stable: $d^2U/dx^2 > 0$
 - Unstable: $d^2U/dx^2 < 0$
 - Neutral: $d^2U/dx^2 = 0$

(c) Kepler's Laws & Satellite Velocity

Kepler's Laws:

- 1. Planets move in elliptical orbits with Sun at one focus
- 2. Radius vector sweeps equal areas in equal times
- 3. $T^2 \propto a^3$ for all planets

Satellite Velocity Derivation: Centripetal force = Gravity:

$$\frac{mv^2}{r} = \frac{GMm}{r^2} \Rightarrow v = \sqrt{\frac{GM}{r}}$$

Question 4

(a) Effective Gravity with Rotation

Solution:

$$g_{\rm eff} = g - \Omega^2 R \cos^2 \lambda$$

(where $\lambda =$ latitude, $\Omega =$ angular velocity)

(b) Angular Momentum Change

Given:
$$\vec{\tau} = (4, 4, 6), \vec{L_0} = (2, 7, 8), \Delta t = 6s$$

Solution:

$$\vec{\tau} = \frac{\Delta \vec{L}}{\Delta t} \Rightarrow \Delta \vec{L} = \vec{\tau} \Delta t = (24, 24, 36)$$

$$\vec{L_f} = \vec{L_0} + \Delta \vec{L} = (26, 31, 44) \text{ kg m}^2/\text{s}$$

(c) Cube Moment of Inertia

Solution: For cube about central axis: $I = \frac{Ma^2}{6}$

Question 5

(a) Collision Problem

Given: m_1 , $m_2 = 3m_1$, $v_{\rm cm} = 3$ m/s

Solution:

- 1. CM speed remains 3 m/s (no external force)
- 2. Elastic collision: relative velocity reverses
- 3. Final velocities:

$$v_1' = \frac{m_1 - m_2}{m_1 + m_2} v_1 + \frac{2m_2}{m_1 + m_2} v_2$$
$$v_2' = \frac{2m_1}{m_1 + m_2} v_1 + \frac{m_2 - m_1}{m_1 + m_2} v_2$$

Given $v_2 = 0$, $v_{\text{cm}} = \frac{m_1 v_1}{4m_1} = \frac{v_1}{4} \Rightarrow v_1 = 12 \text{ m/s}$ Thus $v_1' = -6 \text{ m/s}$, $v_2' = 6 \text{ m/s}$

(b) Conservative Force Proof

Given: $\vec{r} = a\cos(\omega t)\hat{i} + b\sin(\omega t)\hat{j}$

Solution:

- 1. Find acceleration: $\vec{a} = -\omega^2 \vec{r}$
- 2. Force $\vec{F} = m\vec{a} = -m\omega^2\vec{r}$
- 3. $\nabla \times \vec{F} = 0 \Rightarrow$ force is conservative

(c) Angular Momentum of System

Concept: Total angular momentum $\vec{L} = \sum (\vec{r_i} \times \vec{p_i})$ In absence of external torque: $\frac{d\vec{L}}{dt} = 0 \Rightarrow \vec{L}$ is conserved

Question 6

(a) Relativistic Length Contraction

Given: $v = 0.6c, \, \theta = 30^{\circ}$

Solution: Length contraction only in motion direction:

$$L_x' = L_x \sqrt{1 - v^2/c^2} = (1 \text{m} \cos 30^\circ)(0.8) = 0.693 \text{m}$$

$$L_y' = L_y = 1 \text{m} \sin 30^\circ = 0.5 \text{m}$$

$$\text{Total length } L' = \sqrt{0.693^2 + 0.5^2} \approx 0.853 \text{m}$$

$$\text{Orientation : } \tan \theta' = \frac{L_y'}{L_x'} \Rightarrow \theta' \approx 35.8^\circ$$

(b) Speed Limit of Light

Reasons:

- Relativistic mass increases toward infinity as $v \to c$
- \bullet Would require infinite energy to reach c
- Causality violations would occur if v > c
- Supported by all experimental evidence

(c) Einstein's Velocity Addition

Formula:

$$w = \frac{u+v}{1+uv/c^2}$$

Given: $KE = 3m_0c^2$

Solution: Total energy $E=m_0c^2+3m_0c^2=4m_0c^2=\gamma m_0c^2\Rightarrow \gamma=4$

$$\gamma = \frac{1}{\sqrt{1 - v^2/c^2}} \Rightarrow v = \frac{c\sqrt{15}}{4} \approx 0.968c$$